# Chapter 7: Signal Design for Band-limited Channels





Graduate Program School of Electrical and Computer Engineering

#### **Overview- Signal Design for Band-limited Signal**

- Characterization of band-limited channels
- Signal design for band-limited channels
  - Criterion for No ISI The Nyquist criterion
  - Controlled ISI
- Signal design with distortion



- In the previous lectures, we saw transmission of digital information through *AWGN channels*
- Bandwidth constraints not considered on either
  - Communication system design or
  - Type of the information bearing signal
- We consider the problem of signal design when a channel is *band-limited* to some specified bandwidth of W Hz
- The channel may be modeled as a *linear filter* having an equivalent low-pass frequency response C(f) that is zero for | f | >W



• A linearly modulated signal in baseband is represented as

$$v(t) = \sum_{n} I_{n} g(t - nT)$$

- We consider the design of the signal pulse *g(t)* that efficiently utilizes the total available channel bandwidth W
- When the channel is *ideal* for  $|f| \le W$ , a signal pulse can be designed that permits the transmission at symbol rates comparable to or exceeding the channel bandwidth
- For *non-ideal channels*, transmission at symbol rate equal to or exceeding W results in *intersymbol interference* (ISI) among adjacent channels
- For such channels *coding can shape the spectrum* of the transmitted signal to avoid ISI



- Consider telephone channels that are characterized as band-limited linear filters
  - Appropriate when FDM is used
- Filtering is still used on the analog signal prior to sampling and encoding
- A band-limited channel can be characterized as a *linear filter* having an equivalent low-pass frequency-response C(f) and an equivalent LP impulse response c(t)
- If a signal of the form

$$s(t) = Re[v(t)e^{j2\pi f_c t}]$$



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 If transmitted over a band-pass channel, the received equivalent LP signal is given by

$$r_l(t) = \int_{-\infty}^{\infty} v(\tau)c(t-\tau)d\tau + z(t)$$

- Where z(t) denotes the additive noise
- Alternatively in frequency domain

$$R_l(f) = V(f)C(f)$$

- If the channel is band-limited to W Hz, then C(f) = 0 for
  | f | >W
  - Frequency component of V(f) above | f | =W will be filtered out by the channel
- Hence, need to limit the BW of transmitted signal to W Hz



• Within the bandwidth of the channel

$$C(f) = \left| C(f) \right| e^{j\theta(f)}$$

- Where |C(f)| is the *amplitude response* and θ(f) is the *phase* response characteristics
- Furthermore, the *envelope delay characteristic* is defined as

$$\tau(f) = -\frac{1}{2\pi} \frac{d \theta(f)}{df}$$

- A channel is said to be non-distorting or ideal if
  - |C(f)| is constant for all  $|f| \le W$  and
  - $\theta$  (f) is linear function of frequency or  $\tau(f)$  is constant for all  $|f| \leq W$

- If |C(f)| is not constant for all  $|f| \le W$ , the channel distorts the transmitted signal in amplitude
- If  $\tau(f)$  is not constant for all  $|f| \le W$ , the channel is said to *distort the signal V(f) in delay*
- The consequence of amplitude and phase distortion is to cause a *succession of pulses* transmitted at rates comparable to the bandwidth W to be smeared and become indistinguishable as well defined pulses at the receiver



- Example of distortion on transmitted signal shape
- ISI will be severe for PAM signals if transmitted through a channel having a *linear envelope delay* characteristics
- Effect of channel can be corrected through *equalization*



Effect of channel distortion: (a) channel input; (b) channel output; (c) equalizer output



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- Typical frequency response characteristics of the telephone channel are shown in the figure below
- Usable frequency band extends from about 0.3k to 3k Hz



Average amplitude and delay characteristics of medium-range telephone channel

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- The *impulse response* shown in the figure below extends over 10 ms band with 2500 symbols/s
- The ISI might extend over 20-30 symbols



#### Impulse response of average channel with amplitude and delay shown in the previous slide



- In addition to linear distortion, other impairments include:
  - Non-linear distortion
  - Frequency off-set
  - Phase jitter
  - Impulse and thermal noise
- Non-linear distortion Arises from non linearities in amplifiers and companders
  - Effect is small but difficult to correct
- *Frequency off-set* Approximately less than 5 Hz
  - Effect is severe in high speed transmission systems and synchronous coherent detection
- *Phase jitter* Low index frequency modulation with the low-frequency harmonics of the power line(50 Hz)



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### Signal Design for Band-Limited Channels

• Low-pass equivalent of transmitted signals for different modulation techniques have the common form

$$v(t) = \sum_{n} I_{n} g(t - nT)$$

- Where
  - $\{I_n\}$  Discrete information bearing sequence of symbols
  - g(t) Signal pulse assumed having a band-limited frequency response G(f) such that G(f)=0 for |f| > W
- And the channel characteristic is C(f) = 0 for |f| > W
- The received signal is then given by

$$r_l(t) = \sum_n I_n h(t - nT) + z(t)$$



Signal Design for Band-Limited Channels

• Where 
$$h(t) = \int_{-\infty}^{\infty} g(\tau) c(t-\tau) d\tau$$

- And *z*(*t*) is the AWGN
- Assume the received signal is passed through a matched filter with frequency response described by H\*(*f*)
- The output of the receiving filter is

$$y(t) = \sum_{n=0}^{\infty} I_n x(t - nT) + z'(t)$$

- Where
  - *x*(*t*) is the pulse representing the response of the receiving filter to the input *h*(*t*)
  - z'(t) is the response of the receiving filter to the noise z(t)



#### Signal Design for Band-Limited Channels

• The output of the filter is sampled at the rate of 1/T samples/second and the sampled output is given by

$$y(kT + \tau_0) \equiv y_k = \sum_n I_n x(kT - nT + \tau_0) + z'(kT + \tau_0)$$

• Or equivalently

$$y_k = \sum_n I_n x_{k-n} + z'_k$$
;  $k = 0, 1, 2, \dots$ 

• Where  $\tau_0$  is the transmission delay



#### Signal Design for Band-Limited Channels...

• The sample values can alternatively be expressed as

$$y_k = x_0(I_k + \frac{1}{x_0}\sum_{\substack{n=0\\n\neq k}}^{\infty} I_n x_{k-n}) + z'_k; \quad k = 0, 1, 2, \dots$$

 Where x<sub>0</sub> is an arbitrary scale factor which can be set to unity for convenience such that

$$y_k = I_k + \sum_{\substack{n=0\\n \neq k}}^{\infty} I_n x_{k-n} + z'_k; \quad k = 0, 1, 2, \dots$$

• The term  $I_k$  represents the desired information symbol at the  $k^{th}$  sampling instant

• And the term 
$$\sum_{\substack{n=0\\n\neq k}}^{\infty} I_n x_{k-n} + z'_k$$
 represents the ISI and AWGN

#### variable at the same sampling instant

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- Assume C(f)=1 for  $|f| \le W$  (channel response )
- The pulse x(t) is such that the frequency response is
  X(f)= |G(f)|<sup>2</sup> where

$$x(t) = \int_{-W}^{W} X(f) e^{j2\pi ft} df$$

We want to determine the spectral properties of the pulse x(t) and hence the transmitted pulse g(t) that results in no ISI



• For 
$$y_k = I_k + \sum_{\substack{n=0\\n \neq k}}^{\infty} I_n x_{k-n} + z'_k$$
;  $k = 0, 1, 2$ 

• The condition for No ISI is given by

$$x(t = kT) = x(kT) = x_k = \begin{cases} 1 & \mathbf{k} = \mathbf{0} \\ 0 & k \neq 0 \end{cases}$$

- The Nyquist pulse-shaping criterion or the Nyquist condition for zero ISI is stated as follows:
- A necessary & sufficient condition for x(t) to satisfy the above condition is that the Fourier transform of  $x(nT) \leftrightarrow X(f)$  should satisfy

$$\sum_{m=-\infty}^{\infty} X(f + \frac{m}{T}) = T$$



 Proof: Since X(f) is the Fourier transform of x(t), in general it is given by

$$x(t) = \int_{-\infty}^{\infty} X(f) e^{j2\pi f t} df$$

• At the sampling instant t=nT, this becomes

$$x(nT) = \int_{-\infty}^{\infty} X(f) e^{j 2\pi f nT} df$$

• Breaking up the integral into parts covering the infinite range of 1/T, we obtain

$$x(nT) = \sum_{m=-\infty}^{\infty} \int_{\frac{2m+1}{2T}}^{\frac{2m+1}{2T}} X(f) e^{j2\pi f nT} df = \sum_{m=-\infty}^{\infty} \int_{-\frac{1}{2T}}^{\frac{1}{2T}} X(f + \frac{m}{T}) e^{j2\pi f nT} df$$
$$= \int_{-\infty}^{\infty} \left[ \sum_{m=-\infty}^{\infty} X(f + \frac{m}{T}) \right] e^{j2\pi f nT} df = \int_{-\infty}^{\infty} B(f) e^{j2\pi f nT} df$$



• Where 
$$B(f) = \sum_{m=-\infty}^{\infty} X(f + \frac{m}{T})$$

 B(f) is periodic with period 1/T and therefore can be expanded in terms of its Fourier series coefficients {b<sub>n</sub>} as

$$B(f) = \sum_{n} b_n e^{j2\pi nfT}$$

• Where 
$$b_n = T \int B(f) e^{-j2\pi n fT} df$$

• Note that 
$$b_n = Tx(-nT)$$

• Therefore 
$$b_n = \begin{cases} T & n=0\\ 0 & n \neq 0 \end{cases}$$



 Which is the necessary condition that upon substituting in the expression for B(f) yields

$$B(f) = T$$
 or equivalently  $B(f) = \sum X(f + \frac{m}{T}) = T$ 



- Consider the different situations in terms of the relative values of T with respect to the signal bandwidth
  - 1. When T < 1/2W or 1/T > 2W, the bands of B(*f*) are *non-overlapping* and hence, *no choice of* X(f) *make* B(f)=T





2. When T = 1/2w, this gives the smallest value of T for which the ISI becomes zero





- Note that this function is *non-causal* & hence *non-realizable*
- To make it causal we use the *delayed version* of it, i.e.,

$$sinc\left[\frac{\pi(t-t_0)}{T}\right]$$

- Such that *x*(*t*) becomes essentially zero for t < 0
- Note that this function decays at the rate of 1/t



3. When T > 1/2w, there are numerous choices of X(f) so that B(f) = T



*Plot of B(f) for the case* T > 1/2W



• For T > 1/2W, the *raised cosine function* has the desired spectral properties



•  $\beta$  is called the *roll-off factor* and has values in the range  $0 \le \beta \le 1$ 



 Plots of this function with β as a parameter are shown below, both in the frequency and time domains





Pulses having a raised cosine spectrum



- The bandwidth occupied by the signal beyond the Nyquist frequency 1/2T is called *excess bandwidth* and is usually expressed as a percentage of the Nyquist frequency
- Thus for  $\beta = 0.5$ , the excess bandwidth is 50%; while it will be 100% for  $\beta = 1$
- The pulse having the raised cosine spectrum is given by

$$\mathbf{x(t)} = \frac{\sin(\pi t/T)}{\pi t/T} \frac{\cos(\pi\beta t/T)}{1 - 4\beta^2 t^2/T^2}$$
$$= \operatorname{sinc}(\pi t/T) \frac{\cos(\pi\beta t/T)}{1 - 4\beta^2 t^2/T^2}$$



- x(t) is normalized such that x(0) = 1
- Note that for  $\beta$ =0 the pulse reduces to the sinc function and the symbol rate is 1/T = 2w
- When  $\beta=1$ , the symbol rate is 1/T = w
- The tails of *x(t)* decay as 1/t<sup>3</sup> for β > 0 and mistiming error in sampling leads to a series of ISI components that converge to a finite value
- Also, since the raised cosine spectrum is smooth, it is possible to *design practical filters* for both the transmitter and receiver that approximate the desired frequency response



• In the case where the channel is ideal C(f) = 1 for  $|f| \le w$ 

$$X_{rc} = G_T(f)G_R(f)$$

• In the case where the receiver filter is matched to the transmitter filter

$$X_{rc} = |G_T|^2 \text{ since } G_R(f) = G_T^*(f)$$
$$G_T(f) = \sqrt{|X_{rc}|} e^{-j2\pi f t_0}$$

 Where t<sub>0</sub> is some nominal delay that is required to insure physical realizability of the filter



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#### **Controlled ISI**

- We have seen that for *zero ISI* 1/T < 2W the Nyquist rate
- Relaxing the condition of zero ISI, we can achieve a transmission rate of 2W symbols/s
- This can be achieved through allowing a controlled amount of ISI
- Allow a *non-zero value of ISI at one time* instant by permitting *one additional non-zero* value in the samples {x(nT)}



#### Controlled ISI ...

- Since the ISI we introduce is deterministic we can take this into account at the receiver
- One possible special case specified by the samples

$$x(\frac{n}{2w}) = x(nT) = \begin{cases} 1 & (n=0,1) \\ 0 & (otherwise) \end{cases}$$

• Or alternatively, 
$$b_n = \begin{cases} T & (n = 0, -1) \\ 0 & (otherwise) \end{cases}$$

• Which yields

$$B(f) = T + Te^{-j2\pi fT}$$



#### Controlled ISI ...

- Note: This relationship is impossible to satisfy for T < 1/2W
- However, for T = 1/2 W, we obtain



Thus 
$$x(t) = sinc(2\pi Wt) + sin[2\pi (Wt - \frac{1}{2})]$$



• This pulse is called a *duobinary pulse* and illustrated below



Time-domain and frequency-domain characteristics of a duobinary signal

• Note that the *spectrum decays to zero* smoothly, which means that the corresponding filter is physically realizable to achieve a symbol rate of 2W



#### Controlled ISI ...

• Another special case that leads to approximately realizable filter at both the transmitter and receiver is specified by

$$x(\frac{n}{2W}) = x(nT) = \begin{cases} 1 & (n = -1) \\ -1 & (n = 1) \\ 0 & (otherwise) \end{cases}$$

• Whose corresponding pulse is given by

$$x(t) = sinc\left(\frac{\pi(t+T)}{T}\right) - sinc\left(\frac{\pi(t-T)}{T}\right)$$



And its spectrum is



(a) Time-domain and frequency-domain characteristics of a modified duobinary signal



#### Controlled ISI ...

• In general, the class of band-limited signal having the form

$$x(t) = \sum_{n=-\infty}^{\infty} x(\frac{n}{2W}) \operatorname{sinc}\left(2\pi W(t - \frac{n}{2W})\right)$$

• And the corresponding spectra is

$$X(f) = \begin{cases} \frac{1}{2W} \sum_{n=-\infty}^{\infty} x(\frac{n}{2W}) e^{-j\pi\pi n f/} & |f| \le W\\ 0 & (otherwise) \end{cases}$$

 Are called *partial response signals*, when controlled ISI is purposely introduced by selecting two or more non-zero samples from {*x(n/2W)*}



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## Signal Design with Distortion

- Assume channel frequency response C(f) is known for
  | f |≤ W and C(f) =0 for | f | ≥ W
- Criterion for optimization of filter responses  $G_T(f)$  and  $G_R(f)$  is the *maximization* of the SNR at the output of the demodulation filter



#### Block diagram of modulator and demodulator for partial-response signals



#### Controlled ISI ...

$$G_T(f)C(f)G_R(f) = X_d(f)e^{-j2\pi ft_0} \quad for |f| \le W$$

- X<sub>d</sub> (f) Desired frequency response at the output and t<sub>0</sub> is the time delay necessary to ensure physical realizability
- X<sub>d</sub> (f) may be selected to yield either zero ISI or controlled ISI at the sampling instants
- For zero ISI select  $X_d(f) = X_{rc}(f)$  raised cosine spectrum with arbitrary roll-off factor  $\beta$
- The noise output of the demodulator filter is

$$v(t) = \int_{-\infty}^{\infty} n(t-\tau) g_R d\tau$$

• Where n(t) is zero-mean Gaussian and  $\phi_{vv}(f) = \phi_{nn}(f) |G_R(f)|^2$ 



#### Signal Design with Distortion ...

 If we consider binary PAM transmission, the sampled output of the matched filter can be expressed as

$$y_m = I_m + v_m = \pm d + v_m$$
$$\sigma_v^2 = \int_{-\infty}^{\infty} \phi_{nn}(f) |G_R(f)|^2 df$$

And the probability of error is

$$p_e = \frac{2}{\sqrt{2\pi}} \int_{\frac{d}{\sigma_v}} e^{-y^2} dy = Q\left(\sqrt{\frac{d^2}{\sigma^2}}\right)$$



### Signal Design with Distortion ...

- P<sub>e</sub> is minimized by maximizing the SNR =
- But the average power is given as

$$P_{av} = \frac{E(I^2)}{T} \int_{-\infty}^{\infty} g_T^2(t) dt = \frac{d^2}{T} \int_{-\infty}^{\infty} g_T^2(t) dt$$
$$\frac{1}{d^2} = \frac{1}{P_{av}T} \int_{-\infty}^{\infty} |G_T(f)|^2 df$$

 $d^2$ 

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### Signal Design with Distortion ...

Where G<sub>T</sub>(f) must be chosen to satisfy the zero ISI condition such that

$$\begin{aligned} \left|G_{T}(f)\right| &= \begin{cases} \frac{\left|X_{rc}(f)\right|}{\left|C(f)\right|\left|G_{R}(f)\right|} & \left|f\right| \leq W\\ 0 & (otherwise) \end{cases}\\ \frac{1}{d^{2}} &= \frac{1}{P_{av}T} \int_{-\infty}^{\infty} \frac{\left|X_{rc}(f)\right|^{2}}{\left|C(f)\right|^{2}\left|G_{R}(f)\right|^{2}} df \end{aligned}$$

 The noise—to-signal ratio to be minimized with respect to G<sub>R</sub>(*f*) within the band of frequencies W

$$\frac{\sigma_{v}^{2}}{d^{2}} = \frac{1}{P_{av}T} \int_{-W}^{W} \phi_{nn}(f) |G_{R}(f)| \int_{-W}^{2} \int_{-W}^{W} \frac{|X_{rc}(f)|^{2}}{|C(f)|^{2} |G_{R}(f)|^{2}} df$$

