## Robert M. White

## SPRINGER SERIES IN SOLID-STATE SCIENCES 32



Springer Series in
SOLID-STATE SCIENCES

## Springer Series in

## SOLID-STATE SCIENCES

Series Editors:<br>M. Cardona P. Fulde K. von Klitzing R. Merlin H.-J. Queisser H. Störmer

The Springer Series in Solid-State Sciences consists of fundamental scientific books prepared by leading researchers in the field. They strive to communicate, in a systematic and comprehensive way, the basic principles as well as new developments in theoretical and experimental solid-state physics.

| 136 | Nanoscale Phase Separation and Colossal Magnetoresistance The Physics of Manganites and Related Compounds | 144 | Physics of Transition Metal Oxides By S. Maekawa, T. Tohyama, S.E. Barnes, S. Ishihara, W. Koshibae, and G. Khaliullin |
| :---: | :---: | :---: | :---: |
|  | By E. Dagotto | 145 | Point-Contact Spectroscopy |
| 137 | Quantum Transport <br> in Submicron Devices <br> A Theoretical Introduction <br> By W. Magnus and W. Schoenmaker | 146 | By Y.G. Naidyuk and I.K. Yanson <br> Optics of Semiconductors and Their Nanostructures Editors: H. Kalt and M. Hetterich |
| 138 | Phase Separation <br> in Soft Matter Physics <br> Micellar Solutions, Microemulsions, <br> Critical Phenomena <br> By P.K. Khabibullaev and A.A. Saidov | 147 | Electron Scattering in Solid Matter A Theoretical and Computational Treatise By J. Zabloudil, R. Hammerling, L. Szunyogh, and P. Weinberger |
| 139 | Optical Response of Nanostructures Microscopic Nonlocal Theory By K. Cho | 148 | Physical Acoustics in the Solid State By B. Lüthi |
| 140 | Fractal Concepts in Condensed Matter Physics By T. Nakayama and K. Yakubo |  | in Complex Dispersive Media Theory • Simulation • Applications By V. Yu. Belashov and |
| 141 | Excitons in Low-Dimensional Semiconductors <br> Theory, Numerical Methods, Applications By S. Glutsch | 150 | S.V. Vladimirov <br> Topology in Condensed Matter Editor: M.I. Monastyrsky |
| 142 | Two-Dimensional Coulomb Liquids and Solids <br> By Y. Monarkha and K. Kono |  | Effects <br> By P. Sigmund <br> Magnetism |
| 143 | X-Ray Multiple-Wave Diffraction Theory and Application By S.-L. Chang |  | From Fundamentals to Nanoscale Dynamics By J. Stöhr and H.C. Siegmann |

[^0]Robert M. White

# Quantum Theory of Magnetism 

Magnetic Properties of Materials

Third, Completely Revised Edition

With 174 Figures and 10 Tables

Professor Dr. Robert M. White
Carnegie Mellon University, Electrical and Computer Engineering
Roberts Engineering Hall 247, Pittsburgh, PA 15213-3890, USA
E-mail: white@ece.cmu.edu

## Series Editors:

Professor Dr., Dres. h. c. Manuel Cardona
Professor Dr., Dres. h. c. Peter Fulde*
Professor Dr., Dres. h.c. Klaus von Klitzing
Professor Dr., Dres. h. c. Hans-Joachim Queisser
Max-Planck-Institut für Festkörperforschung, Heisenbergstrasse 1, 70569 Stuttgart, Germany

* Max-Planck-Institut für Physik komplexer Systeme, Nöthnitzer Strasse 38

01187 Dresden, Germany
Professor Dr. Roberto Merlin
Department of Physics, 5000 East University, University of Michigan
Ann Arbor, MI 48109-1120, USA

## Professor Dr. Horst Störmer

Dept. Phys. and Dept. Appl. Physics, Columbia University, New York, NY 10027 and Bell Labs., Lucent Technologies, Murray Hill, NJ 07974, USA

Title of the 1 . Edition: Quantum Theory of Magnetism © by McGraw-Hill, Inc., New York 1970

## ISSN 0171-1873

ISBN-10 3-540-65116-o Springer Berlin Heidelberg New York ISBN-13 978-3-540-65116-1 Springer Berlin Heidelberg New York

ISBN 3-540-11462-9 2nd Edition Springer Berlin Heidelberg New York

Library of Congress Control Number: 2006934861
This work is subject to copyright. All rights are reserved, whether the whole or part of the material is concerned, specifically the rights of translation, reprinting, reuse of illustrations, recitation, broadcasting, reproduction on microf ilm or in any other way, and storage in data banks. Duplication of this publication or parts thereof is permitted only under the provisions of the German Copyright Law of September 9, 1965, in its current version, and permission for use must always be obtained from Springer. Violations are liable to prosecution under the German Copyright Law.
Springer is a part of Springer Science+Business Media.
springer.com
© Springer-Verlag Berlin Heidelberg 2007
The use of general descriptive names, registered names, trademarks, etc. in this publication does not imply, even in the absence of a specific statement, that such names are exempt from the relevant protective laws and regulations and therefore free for general use.

Typesetting by the author and SPi using a Springer ${ }^{A T} T_{E} X$ macro package Cover concept and Design: eStudio Calamar Steinen

Printed on acid-free paper $\quad$ SPIN: $10120446 \quad$ 57/3100/SPi-543210

To Sara

## Preface

Perhaps as many as ten years ago a colleague of mine pointed out to me that the Second Edition of this book was "out of print". I mentioned this to my editor, who at that time was Helmut Lotsch, and he enthusiastically encouraged me to write a Third Edition. Thus began the long process that has finally resulted in this new edition. My primary goal was to get the book back into print, not necessarily to rewrite a new book. But I have taken the opportunity to change emphasis on some material as a result of recent developments and to add new material. For example, an entire chapter on thin film magnetic multilayers has been added.

The rationale for a book on magnetism is as valid today as it was when the first two editions were published. Magnetic phenomena continue to be discovered with deep scientific implications and novel applications. Since the Second Edition, for example, Giant Magneto Resistance (GMR) was discovered and the new field of "spintronics" is expanding rapidly. In addition, magnetic properties are often an important clue to our understanding of new materials. High temperature superconductors are a good example. The "parent" (undoped) compounds are antiferromagnetic. Their magnetic properties, studied by susceptibility measurements, nuclear magnetic resonance, neutron scattering, etc., have provided insight to the superconducting state. The purpose of this book is to provide a framework for understanding magnetic phenomena.

This framework is built upon linear response theory. In particular, mean field theory, or the random phase approximation, is used to determine the response of materials to magnetic fields. This approach provides a physical description of most magnetic phenomena. But it is not as powerful and elegant as other approaches applied to many interesting problems represented by magnetic systems. For example, I do not cover the renormalization group or the techniques used to obtain exact solutions to lower dimensional systems. Thus, this book may be thought of as a poor man's theory of magnetic phenomena.

One of the challenges of producing this edition was that the previous editions had been type-set, so the material did not exist in a digital format. This
meant retyping everything using LaTeX. I am extremely grateful to Ferna Hartman of Carnegie Mellon for recreating not only the text but the many equations as well. The figures also had to be scanned and new ones created. For this I am grateful to Dr. Chando Park. Sergio Rezende and Vladimir Safonov kindly read the entire manuscript and offered helpful suggestions. I want to thank Jeff Lynn for his comments on the chapter on neutron scattering; Luc Berger for reviewing the section on spin transfer; and Christian Ruegg for reading the section on quantum phase transitions. I would also like to thank the Materials Science and Engineering Department at Stanford, Shan Wang in particular, and the Geballe Laboratory for Advanced Materials for their hospitality during the final stage of writing.

## Contents

1 The Magnetic Susceptibility ..... 1
1.1 The Magnetic Moment ..... 2
1.2 The Magnetization ..... 7
1.3 The Generalized Susceptibility ..... 12
1.3.1 The Kramers-Kronig Relations ..... 14
1.3.2 The Fluctuation-Dissipation Theorem ..... 15
1.3.3 Onsager Relation ..... 20
1.4 Second Quantization ..... 21
1.4.1 Example: The Degenerate-Electron Gas ..... 26
1.4.2 Example: The Zeeman Interaction ..... 29
2 The Magnetic Hamiltonian ..... 33
2.1 The Dirac Equation ..... 33
2.2 Sources of Fields ..... 35
2.2.1 Uniform External Field ..... 35
2.2.2 The Electric Quadrupole Field ..... 36
2.2.3 The Magnetic Dipole (Hyperfine) Field ..... 41
2.2.4 Other Electrons on the Same Ion ..... 43
2.2.5 Crystalline Electric Fields ..... 44
2.2.6 Dipole-Dipole Interaction ..... 50
2.2.7 Direct Exchange ..... 51
2.2.8 Superexchange ..... 58
2.2.9 Molecular Magnets ..... 62
2.2.10 Double Exchange ..... 65
2.2.11 Exchange on a Surface ..... 66
2.3 The Spin Hamiltonian ..... 67
2.3.1 Transition-Metal Ions ..... 67
2.3.2 Rare-Earth Ions ..... 75
2.3.3 Semiconductors ..... 77
3 The Static Susceptibility of Noninteracting Systems ..... 85
3.1 Localized Moments ..... 85
3.1.1 Diamagnetism ..... 88
3.1.2 Paramagnetism of Transition-Metal Ions ..... 89
3.1.3 Paramagnetism of Rare-Earth Ions ..... 91
3.2 Metals ..... 94
3.2.1 Landau Diamagnetism ..... 94
3.2.2 The de Haas-van Alphen Effect ..... 98
3.2.3 Quantized Hall Conductance ..... 102
3.2.4 Pauli Paramagnetism ..... 106
3.3 Measurement of the Susceptibility ..... 112
3.4 Local Moments in Metals ..... 115
3.4.1 Virtual Bound States ..... 116
3.4.2 Anderson's Theory of Moment Formation ..... 119
3.4.3 The Kondo Effect ..... 124
4 The Static Susceptibility of Interacting Systems: Local Moments ..... 133
4.1 High Temperatures ..... 135
4.2 Low Temperatures ..... 146
4.3 Temperatures Near $T_{c}$ ..... 149
4.4 Landau Theory of Second-Order Transitions ..... 153
4.5 Critical Phenomena ..... 154
4.5.1 Order in 2D ..... 155
4.6 Stoner-Wohlfarth Model ..... 159
4.7 Dynamic Coercivity ..... 162
4.8 Magnetic Viscosity ..... 165
5 The Static Susceptibility of Interacting Systems: Metals ..... 169
5.1 Fermi Liquid Theory ..... 169
5.2 Heavy Fermion Systems ..... 176
5.3 Itinerant Magnetism ..... 177
5.3.1 The Stoner Model ..... 177
5.3.2 The Hubbard Model ..... 187
6 The Dynamic Susceptibility
of Weakly Interacting Systems: Local Moments ..... 193
6.1 Equation of Motion ..... 193
6.2 The Bloch Equations ..... 197
6.3 Resonance Line Shape ..... 202
6.3.1 The Method of Moments ..... 202
6.3.2 The Relaxation-Function Method ..... 206
6.3.3 Spin Diffusion ..... 210
6.4 Spin Echoes ..... 211
6.4.1 Measurement of $T_{1}$ ..... 211
6.4.2 Calculation of $T_{1}$ ..... 213
7 The Dynamic Susceptibility of Weakly Interacting Systems: Metals ..... 219
7.1 Paramagnons ..... 221
7.2 Fermi Liquid Theory ..... 223
7.3 Conduction-Electron Spin Resonance ..... 228
7.4 Spin Waves ..... 230
7.5 Local Moments in Metals ..... 231
7.6 Faraday Effect ..... 235
8 The Dynamic Susceptibility of Strongly Interacting Systems ..... 237
8.1 Broken Symmetry ..... 237
8.2 Insulators ..... 238
8.2.1 Spin-Wave Theory ..... 240
8.2.2 Coherent Magnon State ..... 248
8.2.3 Magnetostatic Modes ..... 249
8.2.4 Solitons ..... 250
8.2.5 Thermal Magnon Effects ..... 253
8.2.6 Nonlinear Processes ..... 255
8.2.7 Chaos ..... 259
8.2.8 Optical Processes ..... 262
8.3 High Temperatures ..... 266
8.4 Micromagnetics ..... 269
8.4.1 Magnetic Force Microscope ..... 270
8.4.2 Phenomenological Damping ..... 273
8.5 Metals ..... 274
9 Thin Film Systems ..... 281
9.1 Interfaces ..... 281
9.1.1 Exchange Bias ..... 281
9.1.2 Biquadratic Exchange ..... 284
9.2 Trilayers ..... 285
9.2.1 The RKKY Ineraction ..... 286
9.2.2 Quantum Well Model ..... 289
9.2.3 Giant Magnetoresistance (GMR) ..... 292
9.2.4 Tunneling ..... 300
9.2.5 Spin Transfer ..... 306
9.2.6 Spin Hall Effect ..... 310
10 Neutron Scattering ..... 315
10.1 Neutron Scattering Cross Section ..... 315
10.2 Nuclear Scattering ..... 317
10.2.1 Bragg Scattering ..... 318
10.2.2 Scattering of Phonons ..... 320
10.3 Magnetic Scattering ..... 324
10.3.1 Bragg Scattering ..... 328
10.3.2 Spin Dynamics ..... 333
10.4 Example: Manganese Oxides ..... 337
10.5 Example: Quantum Phase Transitions ..... 341
References ..... 345
Index ..... 355

## The Magnetic Susceptibility

Any system may be characterized by its response to external stimuli. For example, in electronics the proverbial "black box" is characterized by its measured output voltage when an input current is applied. This transfer impedance, as it is called, provides all the information necessary to understand the operation of the black box. If we know what is in the black box - for example, the detailed arrangement of resistors, diodes, etc. - then we can predict, through analysis, what the transfer impedance will be.

Similarly, a system of charges and currents, such as a crystal, may be characterized by a response function. In this text we shall be concerned mainly with the response of such a system to a magnetic field. In this case the "output" is the magnetization and the response function is the magnetic susceptibility. A complete analysis of the magnetic susceptibility is virtually impossible since the system consists of about $10^{21}$ particles. Therefore we usually look to a measured susceptibility for clues to the important mechanisms active in the system and then use these to analyze the system. In order to carry out such a program, we must know what possible mechanisms exist and what effect they have on the susceptibility.

Determination of the susceptibility entails evaluation of the magnetization produced by an applied magnetic field. In general, this applied field may depend on space and time. The resulting magnetization will also vary in space and time. If the spatial dependence of the applied field is characterized by a wave vector $\boldsymbol{q}$ and its time dependence is characterized by a frequency $\omega$, and if we restrict ourselves for the time being to the magnetization with this wave vector and frequency, we obtain the susceptibility $\chi(\boldsymbol{q}, \omega)$. As we shall see shortly, the magnetization is the average magnetic moment. The magnetic moment itself is a well-defined quantity. The problem, however, is the computation of its average value. In order to compute this average it is necessary to know the probabilities of the system being in its various configurations. This information is contained in the distribution function associated with the system.

We shall see in this chapter that the distribution function depends on the total energy, or Hamiltonian, of the system. Therefore the first step in understanding magnetic properties is the identification of those interactions relevant to magnetism. In Chap. 2 the origin of these interactions is discussed, and they are expressed in a form which facilitates their application in later chapters. The reader is asked to keep in mind that Chaps. 1 and 2 both constitute background material for the theoretical development which begins in Chap. 3. The motivation for the material in these first two chapters should become clear as this theory unfolds.

In the absence of time-dependent fields we may assume that the system is in thermal equilibrium. In this case the distribution function is easily obtained. In Chap. 3 this is used to compute the response of noninteracting moments to a static field. This computation leads to the susceptibility $\chi(\boldsymbol{q}, 0)$. In Chaps. 4 and 5 the response $\chi(\boldsymbol{q}, 0)$ of an interacting system of moments to a static field is investigated in the random-phase approximation.

In the presence of time-dependent fields the distribution function must be obtained from its equation of motion. In the case of localized moments this consists of solving the Bloch equations. For itinerant moments the distribution function is obtained from a Boltzmann equation. In Chaps. 6 and 7 these equations are solved for weakly interacting systems to obtain the generalized susceptibility $\chi(\boldsymbol{q}, \omega)$. Finally, in Chap. 8 the generalized susceptibility associated with strongly interacting systems is investigated. This function is of particular interest because its singularities determine the magnetic-excitation spectrum of the system.

With the development of thin film deposition techniques it became possible to fabricate inhomogeneous magnetic materials, particularly thin films. Chapter 9 describes some of the phenomena associated with such structures.

One of the most powerful techniques for studying the spatial and temporal behavior of magnetic materials is neutron scattering. While pulsed and "cold" sources have expanded the range of neutron studies since the first edition of this book, the scattering description provided in Chap. 10 remains valid.

The next few sections introduce the basic quantities with which we shall be concerned throughout this text. Since these quantities may be defined in various ways, the reader may find it informative to compare other approaches (especially the classic work [1]).

### 1.1 The Magnetic Moment

Let us begin by discussing the magnetic moment. To see why this particular object is of interest let us consider the classical description of a system of charges and currents. Such a system is governed by Maxwell's equations. The appropriate forms of these equations in a medium are the so-called macroscopic Maxwell equations, which are obtained from the microscopic equations by averaging over a large number of particles, see [2]. The microscopic equation
in which we shall be particularly interested is the one representing Ampere's law, which has the differential form

$$
\begin{equation*}
\nabla \times \boldsymbol{h}=\frac{4 \pi}{c} \boldsymbol{j}+\frac{\partial \boldsymbol{e}}{\partial t} \tag{1.1}
\end{equation*}
$$

We define the average fields

$$
\begin{align*}
\langle\boldsymbol{h}\rangle & \equiv \boldsymbol{B}, \\
\langle\boldsymbol{e}\rangle & \equiv \boldsymbol{E} . \tag{1.2}
\end{align*}
$$

Here $\langle\ldots\rangle$ is a spatial average over a region which is small compared with the size of the sample, yet large enough to contain many atomic systems (the lower limit to the macroscopic domain would typically be 10 nm ).

When we write $\boldsymbol{B}(\boldsymbol{r})$ or $\boldsymbol{E}(\boldsymbol{r})$, the coordinate $\boldsymbol{r}$ refers to the center of the region over which the average is taken. Thus the first equation of (1.2) might have been written as $\boldsymbol{B}(\boldsymbol{r})=\langle\boldsymbol{h}\rangle_{r}$. In this description it is assumed that any spatial variations are large in comparison with interatomic spacings. The actual details of the averaging will be discussed in Sect.1.2. With this notation the macroscopic version of (1.1) becomes

$$
\begin{equation*}
\nabla \times \boldsymbol{B}=\frac{4 \pi}{c}\langle\boldsymbol{j}\rangle+\frac{1}{c} \frac{\partial \boldsymbol{E}}{\partial t} . \tag{1.3}
\end{equation*}
$$

The objective now is to calculate the average current density. To do this we separate the total current density into two parts, that associated with conduction electrons and that localized at an ionic site. The average value of the conduction electron current density is the free current density $\boldsymbol{j}_{\text {free }}$.

The ionic current density may be further separated into two contributions. First of all, the ion may possess an electric-dipole moment which is characterized by a dipole charge density $\rho_{\text {dip }}$. If this charge density is time dependent, there is a polarization current density $\boldsymbol{j}_{\text {pol }}$ which satisfies the continuity equation

$$
\begin{equation*}
\nabla \cdot \boldsymbol{j}_{\mathrm{pol}}=-\frac{\partial \rho_{\mathrm{dip}}}{\partial t} \tag{1.4}
\end{equation*}
$$

Taking the average of this equation and assuming that the average commutes with the time and space derivatives, we obtain

$$
\begin{equation*}
\left\langle\sum_{\text {ions }} \boldsymbol{j}_{\mathrm{pol}}\right\rangle=\frac{\partial \boldsymbol{P}}{\partial t}, \tag{1.5}
\end{equation*}
$$

where the sum is over those ions within the averaging volume and $\boldsymbol{P}$ is the electric polarization defined by

$$
\left\langle\sum_{\mathrm{ions}} \rho_{\mathrm{dip}}\right\rangle=-\nabla \cdot \boldsymbol{P}
$$

The second contribution to the ionic current density arises from the internal motion of the ionic electrons. Since this current density $\boldsymbol{j}_{\text {mag }}$ is stationary, $\nabla \cdot \boldsymbol{j}_{\text {mag }}=0$. This is the current density responsible for the magnetic moment $\boldsymbol{m}$ of the ion. If the center of mass of the ion is at $\boldsymbol{R}$, the magnetic moment is defined as

$$
\begin{equation*}
\boldsymbol{m}=\frac{1}{2 c} \int d \boldsymbol{r}(\boldsymbol{r}-\boldsymbol{R}) \times \boldsymbol{j}_{\mathrm{mag}} \tag{1.6}
\end{equation*}
$$

A convenient representation for $\boldsymbol{j}_{\text {mag }}$ which has zero divergence and satisfies (1.6) is

$$
\begin{equation*}
\boldsymbol{j}_{\mathrm{mag}}=-c \boldsymbol{m} \times \nabla f(|\boldsymbol{r}-\boldsymbol{R}|), \tag{1.7}
\end{equation*}
$$

where $f(|\boldsymbol{r}-\boldsymbol{R}|)$ a smoothly varying function centered at $\boldsymbol{R}$ which goes to 0 at the ionic radius and is normalized to 1 . In Chap. 2 we shall see that this function has a quantum mechanical interpretation. Then

$$
\begin{equation*}
\left\langle\sum_{\text {ions }} \boldsymbol{j}_{\mathrm{mag}}\right\rangle=c\left\langle\sum_{\text {ions }} \nabla f(|\boldsymbol{r}-\boldsymbol{R}|) \times \boldsymbol{m}\right\rangle=c \nabla \times\left\langle\sum_{\text {ions }} f(|\boldsymbol{r}-\boldsymbol{R}|) \boldsymbol{m}\right\rangle . \tag{1.8}
\end{equation*}
$$

The last average in (1.8) is the magnetization $\boldsymbol{M}$, defined by

$$
\begin{equation*}
\boldsymbol{M} \equiv\left\langle\sum_{\text {ions }} f(|\boldsymbol{r}-\boldsymbol{R}|) \boldsymbol{m}\right\rangle \tag{1.9}
\end{equation*}
$$

Combining these results, we may now write (1.3) as

$$
\begin{equation*}
\nabla \times \boldsymbol{B}=\frac{4 \pi}{c} \boldsymbol{j}_{\text {free }}+\frac{4 \pi}{c} \frac{\partial \boldsymbol{P}}{\partial t}+4 \pi \nabla \times \boldsymbol{M}+\frac{1}{c} \frac{\partial \boldsymbol{E}}{\partial t} . \tag{1.10}
\end{equation*}
$$

Defining

$$
\begin{equation*}
\boldsymbol{H}=\boldsymbol{B}-4 \pi \boldsymbol{M} \tag{1.11}
\end{equation*}
$$

and

$$
\begin{equation*}
\boldsymbol{D}=\boldsymbol{E}+4 \pi \boldsymbol{P} \tag{1.12}
\end{equation*}
$$

we have the familiar result

$$
\begin{equation*}
\nabla \times \boldsymbol{H}=\frac{4 \pi}{c} \boldsymbol{j}_{\text {free }}+\frac{1}{c} \frac{\partial \boldsymbol{D}}{\partial t} \tag{1.13}
\end{equation*}
$$

Thus we see that the magnetization which appears in the macroscopic Maxwell's equations is the average of the ionic magnetic moment density. Since $f(|\boldsymbol{r}-\boldsymbol{R}|)$ is normalized to the volume the magnetization is the magnetic moment per unit volume.

As an example of the use of definition (1.6), let us neglect the possibility of nuclear currents and consider only the electron currents within the ion. Then


Fig. 1.1. Geometry envisioned in deriving the magnetic energy

$$
\begin{equation*}
\boldsymbol{j}_{\operatorname{mag}}(\boldsymbol{r})=\sum_{\alpha} e \boldsymbol{v}_{\alpha} \delta\left(\boldsymbol{r}-\boldsymbol{r}_{\alpha}\right) \tag{1.14}
\end{equation*}
$$

where $e$ is the charge on the electron, which is $-|e|$, and $\boldsymbol{v}_{a}$ is the velocity of the $\alpha$ th electron. From (1.6) we find for the total magnetic moment of the ion

$$
\begin{equation*}
\boldsymbol{m}=\frac{e}{2 c} \sum_{\alpha} \boldsymbol{r}_{\alpha} \times \boldsymbol{v}_{\alpha} \tag{1.15}
\end{equation*}
$$

Recalling that the orbital angular momentum of an electron is

$$
\begin{equation*}
\boldsymbol{l}_{\alpha}=\boldsymbol{r}_{\alpha} \times m \boldsymbol{v}_{\alpha}, \tag{1.16}
\end{equation*}
$$

we have

$$
\begin{equation*}
\boldsymbol{m}=\sum_{\alpha} \frac{e}{2 m c} \boldsymbol{l}_{\alpha} . \tag{1.17}
\end{equation*}
$$

Since $e=-|e|$, we see that the orbital magnetic moment of an electron is in the opposite direction to its orbital angular momentum.

We shall find it convenient to adopt a more general definition of the magnetic moment than that given by (1.6). This definition is based on the energy of the magnetic system (magnetic energy is discussed in [3] and [4]). The form of the magnetic energy depends upon the definition of the magnetic system. Let us define our magnetic system by the ionic magnetic current density $\boldsymbol{j}_{\text {mag }}$. This excludes the free currents, $\boldsymbol{j}_{\text {free }}$, which are assumed to be fixed and are the source of an external field $\boldsymbol{H}$ in which our magnetic ion is to be located. ${ }^{1}$ We now want to know the change in energy of this magnetic system when the field $\boldsymbol{H}$ is applied or, equivalently, we may think of bringing the currents $\boldsymbol{j}_{\text {mag }}$ in from infinity to a position in the field (see Fig. 1.1).

The energy difference results from the work done by the magnetic currents as they accommodate to the increasing external field. Since the magnetic field itself does no work on moving charges, we must use the induced electric field

[^1]which is present while the external magnetic field is being turned on (due to the relative motion). This is given by
\[

$$
\begin{equation*}
\nabla \times \boldsymbol{E}=-\frac{1}{c} \frac{\partial \boldsymbol{H}}{\partial t} \tag{1.18}
\end{equation*}
$$

\]

The work done by the magnetic currents in a time $\delta t$ is

$$
\begin{equation*}
\delta W=\int \boldsymbol{j}_{\mathrm{mag}} \cdot \boldsymbol{E} d \boldsymbol{r} \delta t \tag{1.19}
\end{equation*}
$$

Making use of the representation (1.7) for $\boldsymbol{j}_{\text {mag }}$, integrating by parts, and then using (1.18), we obtain

$$
\begin{equation*}
\delta W=-\int f(|\boldsymbol{r}-\boldsymbol{R}|) \boldsymbol{m} \cdot \delta \boldsymbol{H} d \boldsymbol{r} \tag{1.20}
\end{equation*}
$$

If the field $\boldsymbol{H}$ is uniform over the ionic dimension, $\delta \boldsymbol{H}$ may be taken outside the integral. Since $\boldsymbol{m}$ is just a constant vector and $f(|\boldsymbol{r}-\boldsymbol{R}|)$ is normalized to unity,

$$
\begin{equation*}
\delta W=-\boldsymbol{m} \cdot \delta \boldsymbol{H} \tag{1.21}
\end{equation*}
$$

This work corresponds to Kittel's "scheme A" for applying the field [4]. Kittel also calculates the work needed to create the magnetized material in zero field in the first place ("scheme B"). The work associated with scheme A is important because this is the work that results in the change in the energy of the system given by its quantum mechanical eigenvalues [4].

Neither of these results give the total change in energy of the system when the magnetic material is introduced into the field since they do not include the work done by the source in keeping $\boldsymbol{j}_{\text {free }}$ fixed. Jackson shows that the total change in energy is given by

$$
W=\frac{1}{2} \int \boldsymbol{M} \cdot \boldsymbol{H}_{0} d \boldsymbol{r}
$$

where $\boldsymbol{H}_{0}$ is the field $\left(\boldsymbol{B}_{0}\right)$ in the absence of the magnetic material, and the $\frac{1}{2}$ arises from an assumed linear relation between $\boldsymbol{M}$ and $\boldsymbol{B}$.

The resulting change in the energy of the magnetic system is $\delta E=W$. Thus from (1.21)

$$
\begin{equation*}
\boldsymbol{m}=-\frac{\partial E}{\partial \boldsymbol{H}} \tag{1.22}
\end{equation*}
$$

As an example of the application of this definition, consider the ionic system of electrons which gave rise to the current density of (1.14). In the presence of a uniform field $\boldsymbol{H}$, which may be obtained from a vector potential $\boldsymbol{A}$ by $\boldsymbol{H}=\nabla \times \boldsymbol{A}$, the energy of such a system is

$$
\begin{equation*}
E=\sum_{\alpha} \frac{1}{2} m \boldsymbol{v}_{\alpha}^{2}+\sum_{\alpha} e \phi_{\alpha} \tag{1.23}
\end{equation*}
$$

where $\phi_{\alpha}$ is the ionic potential. We see that the magnetic field $\boldsymbol{H}$ does not appear explicitly in this energy. However, the velocity is, in fact, a function of the field. In general, the task of finding the field dependence of the total energy of the system is a difficult one. However, in this case the actual field dependence is revealed by expressing the energy in terms of the canonical coordinates of the system. The reason for this is that in a slowly varying uniform field the canonical momentum does not change. When expressed in canonical coordinates, the energy is the same as the Hamiltonian function. For this reason the Hamiltonian $\mathcal{H}$ is often used in place of the energy $E$ in definition (1.22).

In Chap. 2 we shall find that the Hamiltonian is

$$
\begin{equation*}
\mathcal{H}=\sum_{\alpha} \frac{1}{2 m}\left(\boldsymbol{p}_{\alpha}-\frac{e}{c} \boldsymbol{A}\right)^{2}+\sum_{\alpha} e \phi_{\alpha} \tag{1.24}
\end{equation*}
$$

With the gauge $\boldsymbol{A}=\frac{1}{2} \boldsymbol{H} \times \boldsymbol{r}$ this becomes

$$
\begin{equation*}
\mathcal{H}=\sum_{a} \frac{p_{a}^{2}}{2 m}-\sum_{a} \frac{e}{2 m c}\left(\boldsymbol{r}_{a} \times \boldsymbol{p}_{a}\right) \cdot \boldsymbol{H}+\frac{e^{2}}{8 m c^{2}} \sum_{a}\left(\boldsymbol{H} \times \boldsymbol{r}_{a}\right)^{2}+\sum_{a} e \phi_{a} \tag{1.25}
\end{equation*}
$$

Differentiating with respect to $\boldsymbol{H}$ and using the fact that the canonical momentum is given by $\boldsymbol{p}_{\alpha}=m \boldsymbol{v}_{\alpha}+(e / c) \boldsymbol{A}$, we obtain (1.15).

### 1.2 The Magnetization

The magnetization is obtained by averaging the ionic moments over a region of space which is large enough to give such an average a meaning but smaller than spatial variations in the system. In order to perform this average we must know the ionic-current distributions. In general they are not known. In fact, herein lies the principle difficulty in the theory of magnetism. In any real system the motion of charge in one region is governed by the charge and currents throughout the system. Thus we have a many-body problem. Historically, there have been two ways of describing magnetic systems, that of localized moments and that of itinerant moments. The choice between these two descriptions depends on the nature of the material and in many cases is a difficult one to make.

In certain cases the relevant current distributions are localized within a lattice cell. In such cases the ionic magnetic moment is relatively unambiguous. The interaction with external charge and current distributions is then expressed in terms of this moment. This approach leads to the spin Hamiltonian, which has proved extremely useful. In other cases we begin by assuming that the current distributions are those associated with free electrons. Thus, although these electrons may extend throughout the lattice, the fact that they may be approximated as a "gas" provides a certain simplification. With these two types of current distributions-that corresponding to very
localized electrons and that corresponding to itinerant electrons-we can proceed to determine the average moment. The computation of averages necessarily relies on the techniques of statistical mechanics. Since this is not the place to develop such techniques, they will be introduced in a rather ad hoc manner. A more thorough derivation may be found in texts on statistical physics [5].

If the system possesses translational invariance, then the statistical average over numerous unit cells of the crystal is equivalent to the time average over one cell. This average is determined by the probability that the system will have some particular current distribution. For example, in the case of a magnetic insulator the average over a cell is an average of the magnetic ion. If this ion consists of $h$ electrons, then, classically, the state of the ion is characterized by the $6 h$ coordinates and momenta, $\left(q_{1}, \ldots, q_{3 h}, p_{1}, \ldots, p_{3 h}\right)$. The magnetization is obtained by multiplying the magnetic moment, which is a function of all the coordinates and momenta, by the probability that the system is in the state $\left(q_{1}, \ldots, p_{1}, \ldots\right)$ and then integrating over all the coordinates and momenta. This probability is determined by the ion's environment, which defines a temperature $T$. For the most part this will be the temperature of the lattice in which the ions are located. Classically, the equilibrium probability function is the Boltmann distribution function $\exp \left(-\beta \mathcal{H}_{\text {ion }}\right)$, where $\mathcal{H}_{\text {ion }}$, is the Hamiltonian for the ion and $\beta=1 / k_{B} T$. Therefore the equilibrium magnetization associated with $N / V$ ions per unit volume is

$$
\begin{equation*}
\boldsymbol{M}=\frac{N}{V}\langle\boldsymbol{m}\rangle=\frac{N}{V} \frac{\int \ldots \int \boldsymbol{m} \exp \left(-\beta \mathcal{H}_{\text {ion }}\right) d q_{1} \ldots d p_{1} \ldots}{\int \ldots \int \exp \left(-\beta \mathcal{H}_{\text {ion }}\right) d q_{1} \ldots d p_{1} \ldots} \tag{1.26}
\end{equation*}
$$

It is interesting that this classical averaging procedure leads to the conclusion that there can be no magnetism in thermodynamic equilibrium. The reason for this is that the integrals over the momenta in (1.26) run from $-\infty$ to $+\infty$. Therefore adding a vector potential may shift the momentum origin, but it will not affect the limits of integration. Since the vector potential always enters the integrand as an addition to the momentum, it may be transformed away. This is readily seen by considering the partition function $Z$, which is just the integral of $\exp \left(-\beta \mathcal{H}_{\text {ion }}\right)$ over phase space,

$$
\begin{equation*}
Z=\int_{-\infty}^{\infty} d x d y d z \int_{-\infty}^{\infty} d p_{x} d p_{y} d p_{z} \exp \left\{-\beta\left[p_{x}-(e / c) A_{x}\right]^{2} / 2 m+\ldots\right\} \tag{1.27}
\end{equation*}
$$

This function is of importance because the equilibrium thermodynamic properties of the system can be calculated from it. For example, the energy is $E=-\partial \ell n Z / \partial \beta$.

We introduce

$$
\begin{equation*}
u=p_{x}-\frac{e}{c} A_{x}, \ldots, \tag{1.28}
\end{equation*}
$$

where, in general, $\boldsymbol{A}$ may be a function of $\boldsymbol{r}$. Then

$$
\begin{equation*}
Z=V \int_{-\infty}^{\infty} d u d v d w \exp \left[-\beta\left(u^{2}+v^{2}+w^{2}\right) / 2 m\right] \tag{1.29}
\end{equation*}
$$

which is independent of $\boldsymbol{A}$. Therefore the derivative of $Z$ with respect to the field $\boldsymbol{H}$, which can be shown to be proportional to the magnetization, is 0 . This result, known as Miss van Leeuwen's theorem, forces us to consider the discreteness of the eigenvalues of the system and hence its quantum-mechanical nature. This interesting result has the following physical interpretation (see the discussion in [1] Sect. 26). In the presence of a magnetic field the electrons move in circular orbits in the plane perpendicular to the field. Those electrons that complete such orbits contribute a diamagnetic moment. However, those electrons which strike the boundary have their orbits interrupted with the result that they creep around the boundary giving rise to a paramagnetic moment. It turns out that this paramagnetic moment just cancels the diamagnetic moment. Furthermore, it is independent of the size and nature of the boundary.

Quantum mechanically, the magnetic system is described by a Hamiltonian operator $\mathcal{H}$ which has eigenfunctions $\psi$ with eigenvalues $E$. The total magnetic moment of the system when it is in the state $\psi$ is, according to (1.22),

$$
\begin{equation*}
\boldsymbol{M V}=-\frac{\partial E}{\partial \boldsymbol{H}} \tag{1.30}
\end{equation*}
$$

This may be written in a more useful form. First we differentiate the eigenvalue relation

$$
\begin{equation*}
(\mathcal{H}-E) \psi=0 \tag{1.31}
\end{equation*}
$$

with respect to $\boldsymbol{H}$ to obtain

$$
\begin{equation*}
\left(\frac{\partial \mathcal{H}}{\partial \boldsymbol{H}}-\frac{\partial E}{\partial \boldsymbol{H}}\right) \psi=-(\mathcal{H}-E) \frac{\partial \psi}{\partial \boldsymbol{H}} \tag{1.32}
\end{equation*}
$$

Forming the scalar product with $\psi$ and using the fact that $\mathcal{H}$ is a hermitian operator, i.e., $\mathcal{H}_{i j}=\mathcal{H}_{j i}^{*}$, we find

$$
\begin{align*}
\langle\psi| \frac{\partial \mathcal{H}}{\partial \boldsymbol{H}}|\psi\rangle-\frac{\partial E}{\partial \boldsymbol{H}} & =-\langle\psi|(\mathcal{H}-E)\left|\frac{\partial \psi}{\partial \boldsymbol{H}}\right\rangle \\
& =-\left\langle\frac{\partial \psi}{\partial \boldsymbol{H}}\right|(\mathcal{H}-E)|\psi\rangle^{*}=0 \tag{1.33}
\end{align*}
$$

Therefore

$$
\begin{equation*}
M V=-\langle\psi| \frac{\partial \mathcal{H}}{\partial \boldsymbol{H}}|\psi\rangle \tag{1.34}
\end{equation*}
$$

This leads us to define a magnetic-moment operator

$$
\begin{equation*}
\mathcal{M}=-\frac{\partial \mathcal{H}}{\partial \boldsymbol{H}} \tag{1.35}
\end{equation*}
$$

Hereafter $\boldsymbol{\mathcal { M }}$ will be understood to be an operator.

Since the derivation above was independent of the detailed form of the Hamiltonian and its eigenfunctions, the result (1.35) is quite general. For example, the magnetic-moment operator for a particle governed by the nonrelativistic Schrödinger Hamiltonian (1.25) is

$$
\begin{equation*}
\mathcal{M}_{z}=\frac{e}{2 m c}\left(x p_{y}-y p_{x}\right)-\frac{H e^{2}}{4 m c^{2}}\left(x^{2}+y^{2}\right)=\frac{e}{2 c}(x \dot{y}-y \dot{x}) . \tag{1.36}
\end{equation*}
$$

For a relativistic electron governed by the Dirac equation (which will be discussed briefly in Chap. 2) the magnetic moment becomes

$$
\begin{equation*}
\mathcal{M}_{z}=-\frac{e}{2}\left(\alpha_{x} y-\alpha_{y} x\right) \tag{1.37}
\end{equation*}
$$

Since the $\alpha$ 's are $4 \times 4$ matrices acting on negative as well as positive energy states, the physical meaning of the operator is not clear. However, if we apply a transformation to this operator which separates the positive and negative energy states, then we find that an intrinsic spin contribution to the magnetic moment emerges automatically.

To find the magnetization we must take the expectation value of the magnetic moment operator,

$$
\begin{equation*}
\langle\mathcal{M}\rangle=\int \psi^{*} \mathcal{M} \psi \prod_{i} d \boldsymbol{r}_{i} \tag{1.38}
\end{equation*}
$$

If we knew the wavefunction $\psi$ this would be straightforward. But the fact that we are describing the system at a temperature $T$ implies that the system is in equilibrium with some temperature bath. Let us describe the system in terms of its eigenfunctions, $\varphi_{k}\left(\boldsymbol{r}_{1}, \boldsymbol{r}_{2}, \ldots, \boldsymbol{r}_{N}\right)$. The effect of the temperature bath is to cause the system to move through different states $k$ much as a classical system moves through phase space. That is, the wavefunction $\psi$ may be written as a superposition of states,

$$
\begin{equation*}
\psi\left(\boldsymbol{r}_{1}, \boldsymbol{r}_{2}, \ldots, \boldsymbol{r}_{N}, t\right)=\sum_{k} c_{k}(t) \varphi_{k}\left(\boldsymbol{r}_{1}, \boldsymbol{r}_{2}, \ldots, \boldsymbol{r}_{N}\right) \tag{1.39}
\end{equation*}
$$

The expectation value then becomes

$$
\begin{equation*}
\langle\mathcal{M}\rangle=\sum_{k} \sum_{k^{\prime}} c_{k}^{*}(t) c_{k^{\prime}}(t) \mathcal{M}_{k k^{\prime}} \tag{1.40}
\end{equation*}
$$

where

$$
\begin{equation*}
\mathcal{M}_{k k^{\prime}}=\int \varphi_{k}^{*} \mathcal{M} \varphi_{k^{\prime}} \prod_{i} d \boldsymbol{r}_{i} \tag{1.41}
\end{equation*}
$$

When we measure the magnetization we actually do a time average,

$$
\begin{equation*}
\langle\overline{\mathcal{M}}\rangle=\sum_{k} \sum_{k^{\prime}} \overline{c_{k}^{*}(t) c_{k^{\prime}}(t)} \mathcal{M}_{k k^{\prime}} \tag{1.42}
\end{equation*}
$$

The quantity $\overline{c_{k}^{*}(t) c_{k^{\prime}}(t)}$ is defined as the statistical density matrix, $\rho_{k k^{\prime}}$. Thus

$$
\begin{equation*}
\langle\overline{\mathcal{M}}\rangle=\operatorname{Tr}(\rho \mathcal{M}) \tag{1.43}
\end{equation*}
$$

If the system is isolated from the temperature bath then the $c_{k}$ 's are independent of time and $\rho_{k k^{\prime}}=\left|c_{k}\right|^{2} \delta_{k k^{\prime}}$. The states comprise the microcanonical ensemble. In contact with the temperature bath $\rho_{k k^{\prime}}=\exp \left(-\beta E_{k}\right) \delta_{k k^{\prime}}$ and we speak of this weighted set of states as the canonical ensemble. In the presence of time-dependent fields it is necessary to solve for $\rho_{k k^{\prime}}$ from its equation of motion. From the Schrödinger equations

$$
\begin{align*}
i \hbar \frac{\partial \phi(t)^{*}}{\partial t} & =-\mathcal{H} \phi(t)^{*}  \tag{1.44}\\
i \hbar \frac{\partial \phi(t)}{\partial t} & =\mathcal{H} \phi(t) \tag{1.45}
\end{align*}
$$

we obtain the equations for the expansion coefficients. From our definition of the density matrix, we find that

$$
\begin{equation*}
i \hbar \frac{\partial \rho_{k^{\prime} k}}{\partial t}=-\sum_{k^{\prime \prime}} \rho_{k^{\prime} k^{\prime \prime}} \mathcal{H}_{k^{\prime \prime} k}+\sum_{k^{\prime \prime}} \mathcal{H}_{k^{\prime} k^{\prime \prime}} \rho_{k^{\prime \prime} k} \tag{1.46}
\end{equation*}
$$

or

$$
\begin{equation*}
i \hbar \frac{\partial \rho}{\partial t}=[\mathcal{H}, \rho] . \tag{1.47}
\end{equation*}
$$

This is often a more convenient approach to the density matrix, for, as we shall see below, when perturbation theory applies, (1.47) may be solved iteratively.

Notice that (1.42) gives the average of the magnetic moment over the entire system. If we are interested in the magnetization at point $\boldsymbol{r}, \boldsymbol{M}(\boldsymbol{r})$ this behavior can be projected out by introducing the Dirac delta function,

$$
\begin{equation*}
\mathcal{M}(\boldsymbol{r})=\frac{1}{2} \sum_{\alpha}\left[\boldsymbol{\mu}_{\alpha} \delta\left(\boldsymbol{r}-\boldsymbol{r}_{\alpha}\right)+\delta\left(\boldsymbol{r}-\boldsymbol{r}_{\alpha}\right) \boldsymbol{\mu}_{\alpha}\right] . \tag{1.48}
\end{equation*}
$$

Since the delta functions have dimensions of a reciprocal volume, $\boldsymbol{\mathcal { M }}(\boldsymbol{r})$ is the magnetic-moment operator per unit volume. Here $\boldsymbol{\mu}_{a}$ is the magneticmoment operator associated with the $\alpha$ th electron. Notice that since this is a function of $\boldsymbol{r}_{\alpha}$ and $\boldsymbol{p}_{\alpha}$, we must form the symmetric product denoted by $\{\cdots\}$. Therefore the magnetization becomes

$$
\begin{equation*}
\boldsymbol{M}(\boldsymbol{r})=\operatorname{Tr}\{\rho \mathcal{M}(\boldsymbol{r})\} . \tag{1.49}
\end{equation*}
$$

### 1.3 The Generalized Susceptibility

When we speak of a susceptibility, we are usually referring to a medium in which the response is proportional in some sense to the excitation. If the medium is linear, the response is directly proportional to the excitation. If the medium is nonlinear, the proportionality involves higher powers of the excitation. However, if the excitation is very small, the response will be given to a good approximation by the linear susceptibility. Since time- and spacevarying magnetic fields are generally quite small, a linear response theory is usually adequate. Nonlinear effects become important in dealing with hysteresis phenomena or high-power absorption in magnetic materials. For the most part, then, we shall be concerned with a linear response theory. In this section we shall define the wave-vector-dependent frequency-dependent linear susceptibility and investigate some of its properties.

Let us consider the magnetization $\boldsymbol{M}(\boldsymbol{r}, t)$ associated with a particular magnetic field $\boldsymbol{H}(\boldsymbol{r}, t)$. These quantities are related to their Fourier components by

$$
\begin{align*}
\boldsymbol{M}(\boldsymbol{r}, t) & =\frac{1}{2 \pi V} \sum_{k} \int d \Omega \boldsymbol{M}(\boldsymbol{k}, \Omega) e^{i(\boldsymbol{k} \cdot \boldsymbol{r}-\Omega t)},  \tag{1.50}\\
\boldsymbol{H}(\boldsymbol{r}, t) & =\frac{1}{2 \pi V} \sum_{\boldsymbol{q}} \int d \omega \boldsymbol{H}(\boldsymbol{q}, \omega) e^{i(\boldsymbol{q} \cdot \boldsymbol{r}-\omega t)} \tag{1.51}
\end{align*}
$$

To invert these expansions we use the following relations:

$$
\begin{gather*}
\int d \boldsymbol{r} e^{i\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \cdot \boldsymbol{r}}=V \Delta\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right),  \tag{1.52}\\
\int d t e^{-i\left(\Omega-\Omega^{\prime}\right) t}=2 \pi \delta\left(\Omega-\Omega^{\prime}\right),  \tag{1.53}\\
\sum_{\boldsymbol{k}} e^{i \boldsymbol{k} \cdot\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}\right)}=\frac{V}{(2 \pi)^{3}} \int d \boldsymbol{k} e^{i \boldsymbol{k} \cdot\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}\right)}=V \delta\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}\right) . \tag{1.54}
\end{gather*}
$$

Here $\Delta\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right)$ is the Kronecker delta function and $\delta\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}\right)$ is the Dirac delta function.

We now define the generalized wave-vector-dependent frequency-dependent susceptibility by

$$
\begin{equation*}
M_{\nu}(\boldsymbol{k}, \Omega)=\sum_{q} \int d \omega \sum_{\mu} \chi_{\nu \mu}(\boldsymbol{k}, \boldsymbol{q} ; \Omega, \omega) H_{\mu}(\boldsymbol{q}, \omega) \tag{1.55}
\end{equation*}
$$

where $\nu$ and $\mu=x, y$, or $z$. This may be written in the more convenient dyadic form

$$
\boldsymbol{M}(\boldsymbol{k}, \Omega)=\sum_{q} \int d \omega \boldsymbol{\chi}(\boldsymbol{k}, \boldsymbol{q} ; \Omega, \omega) \cdot \boldsymbol{H}(\boldsymbol{q}, \omega)
$$

In general $\boldsymbol{\chi}(\boldsymbol{k}, \boldsymbol{q} ; \Omega, \omega)$ will depend on the particular form of $\boldsymbol{H}(\boldsymbol{r}, t)$, or equivalently, $\boldsymbol{H}(\boldsymbol{q}, \omega)$; that is, the susceptibility is a functional of the field. The susceptibility is also a tensor. Furthermore, since the magnetization may be out of phase with the exciting field, the susceptibility is also complex. Substituting this expression into (1.50) gives

$$
\begin{equation*}
\boldsymbol{M}(\boldsymbol{r}, t)=\frac{1}{2 \pi V} \sum_{\boldsymbol{k}} \int d \Omega \sum_{\boldsymbol{q}} \int d \omega \chi(\boldsymbol{k}, \boldsymbol{q} ; \Omega, \omega) \cdot \boldsymbol{H}(\boldsymbol{q}, \omega) e^{i(\boldsymbol{k} \cdot \boldsymbol{r}-\Omega t)} \tag{1.56}
\end{equation*}
$$

or

$$
\begin{align*}
\boldsymbol{M}(\boldsymbol{r}, t)= & \iint d \boldsymbol{r}^{\prime} d t^{\prime} \\
& \times\left\{\left[\frac{1}{2 \pi V} \sum_{k} \int d \Omega \sum_{q} \int d \omega \boldsymbol{\chi}(\boldsymbol{k}, \boldsymbol{q} ; \Omega,) e^{i \boldsymbol{k} \cdot\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}\right)} e^{-i \Omega\left(t-t^{\prime}\right)}\right]\right. \\
& \left.\times e^{i(\boldsymbol{k}-\boldsymbol{q}) \cdot \boldsymbol{r}^{\prime}} e^{-i(\Omega-\omega) t^{\prime}}\right\} \cdot \boldsymbol{H}\left(\boldsymbol{r}^{\prime}, t^{\prime}\right) \tag{1.57}
\end{align*}
$$

where the quantity in braces defines a general spatial-temporal susceptibility density $\chi\left(\boldsymbol{r}, \boldsymbol{r}^{\prime} ; t, t^{\prime}\right)$.

If the magnetic medium possesses translational invariance, then this susceptibility must be a function only of the relative coordinate $\boldsymbol{r}-\boldsymbol{r}^{\prime}$. From the expression above we see that this implies that in the wave-vector-dependent susceptibility $\boldsymbol{q}$ is equal to $\boldsymbol{k}$. Furthermore, if the medium is stationary, it can be shown that the temporal dependence is $t-t^{\prime}$, which implies a monochromatic response to a monochromatic excitation with the same frequency, that is, $\Omega=\omega$. Therefore, when these conditions are satisfied, the susceptibility takes the form

$$
\chi(\boldsymbol{k}, \boldsymbol{q} ; \Omega, \omega)=\chi(\boldsymbol{q}, \omega) \Delta(\boldsymbol{k}-\boldsymbol{q}) \delta(\Omega-\omega)
$$

Thus

$$
\begin{equation*}
\boldsymbol{M}(\boldsymbol{r}, t)=\iint d \boldsymbol{r}^{\prime} d t^{\prime} \boldsymbol{\chi}\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}, t-t^{\prime}\right) \cdot \boldsymbol{H}\left(\boldsymbol{r}^{\prime}, t^{\prime}\right) \tag{1.58}
\end{equation*}
$$

where

$$
\begin{equation*}
\chi\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}, t-t^{\prime}\right)=\frac{1}{2 \pi V} \sum_{\boldsymbol{q}} \int d \omega \boldsymbol{\chi}(\boldsymbol{q}, \omega) e^{i \boldsymbol{q} \cdot\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}\right)} e^{-i \omega\left(t-t^{\prime}\right)} \tag{1.59}
\end{equation*}
$$

and its Fourier transform is

$$
\begin{equation*}
\chi(\boldsymbol{q}, \omega)=\int d\left(t-t^{\prime}\right) \int d\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}\right) \boldsymbol{\chi}\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}, t-t^{\prime}\right) e^{-i \boldsymbol{q} \cdot\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}\right)} e^{i \omega\left(t-t^{\prime}\right)} \tag{1.60}
\end{equation*}
$$

The more general susceptibility is required whenever the presence of impurities destroys the translational invariance. The response of a typical paramagnet is such a case.

Since the susceptibility has such a general nature, it should not be surprising that there are various important theorems involving this quantity. We shall consider three of these now. The first theorem, known as the Kramers-Kronig relations, relates the real and imaginary parts of the susceptibility. The second is the fluctuation-dissipation theorem, which relates the susceptibility to thermal fluctuations in the magnetization. Finally, we shall present a derivation of the so-called Onsager relation that describes the symmetry of the susceptibility tensor.

### 1.3.1 The Kramers-Kronig Relations

As a consequence of some rather general properties of

$$
\chi(\boldsymbol{q}, \omega)=\chi^{\prime}(\boldsymbol{q}, \omega)+i \chi^{\prime \prime}(\boldsymbol{q}, \omega)
$$

its real part $\chi^{\prime}(\boldsymbol{q}, \omega)$ and its imaginary part $\chi^{\prime \prime}(\boldsymbol{q}, \omega)$ are connected on the real axis $\omega$ by integral relations known as the Kramers-Kronig relations, or just as dispersion relations. To the electrical engineer, the real and imaginary parts of the response function are related by the Hilbert transform. Let us consider a medium which is linear and stationary (and translationally invariant, although this is not a necessary condition). Then $\boldsymbol{\chi}(\boldsymbol{q}, \omega)$ is related to $\chi\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}, t-t^{\prime}\right)$ by (1.60). If the system obeys the principle of causality, then $\chi\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}, t-t^{\prime}\right)=0$ for $t<t^{\prime}$. Hence the time integral in (1.60) runs only from 0 to $\infty$; that is,

$$
\begin{equation*}
\chi(\boldsymbol{q}, \omega)=\int_{0}^{\infty} d t \boldsymbol{\chi}(\boldsymbol{q}, t) e^{i \omega t} \tag{1.61}
\end{equation*}
$$

Therefore the function $\boldsymbol{\chi}(\boldsymbol{q}, \omega)$ is a complex function of $\omega$ which has no singularities at the ends of the real axis, provided that

$$
\int_{0}^{\infty} \boldsymbol{\chi}(\boldsymbol{q}, t) d t
$$

is finite. This is equivalent to the assumption that the response to a finite excitation is finite. The finite values of $\boldsymbol{\chi}(\boldsymbol{q}, \omega)$ at the ends of the real axis may be identified with the real part of the susceptibility $\boldsymbol{\chi}^{\prime}(\boldsymbol{q}, \infty)$. The fact that $\chi^{\prime \prime}(\boldsymbol{q}, \omega)$ vanishes as $\omega \rightarrow \infty$ may be obtained from the following physical argument. As we shall see in Chap. 5 , the rate of energy absorption by a magnetic system is proportional to $\omega \chi^{\prime \prime}(\boldsymbol{q}, \omega)$. If this is to remain finite as $\omega \rightarrow \infty$, then $\chi^{\prime \prime}(\boldsymbol{q}, \omega)$ must go to 0 as $\omega \rightarrow \infty$. This result may also be derived from the finite-response assumption.

There is no reason for the real part of the susceptibility to vanish as $\omega \rightarrow \infty$. Therefore let us define $\lim _{\omega \rightarrow \infty} \chi^{\prime}(\boldsymbol{q}, \omega)=\chi(\boldsymbol{q}, \infty)$. The quantity $\chi(\boldsymbol{q}, \omega)-\chi(\boldsymbol{q}, \infty)$ is then a complex function which vanishes at the ends of the real axis. The theory of complex variables tells us that the function
$\chi(\boldsymbol{q}, z)-\chi(\boldsymbol{q}, \infty)$, where $z$ is a complex variable, will be analytic in the upper half plane. The residue theorem then says

$$
\begin{equation*}
\oint_{c} \frac{\chi(\boldsymbol{q}, z)-\chi(\boldsymbol{q}, \infty)}{z-\omega} d z=0 \tag{1.62}
\end{equation*}
$$

where the contour $C$ runs from $-\infty$ to $+\infty$ along the real axis and closes in the upper half plane. In terms of its principal value, this integral may be written as

$$
\begin{equation*}
\mathcal{P} \int_{-\infty}^{\infty} \frac{\chi\left(\boldsymbol{q}, \omega^{\prime}\right)-\chi(\boldsymbol{q}, \infty)}{\omega^{\prime}-\omega} d \omega^{\prime}-i \pi[\chi(\boldsymbol{q}, \omega)-\chi(\boldsymbol{q}, \infty)]=0 \tag{1.63}
\end{equation*}
$$

Equating the real and imaginary parts to 0 separately gives the result

$$
\begin{align*}
\chi^{\prime}(\boldsymbol{q}, \omega)-\chi(\boldsymbol{q}, \infty) & =\frac{1}{\pi} \mathcal{P} \int_{-\infty}^{\infty} \frac{\chi^{\prime \prime}\left(\boldsymbol{q}, \omega^{\prime}\right)}{\omega^{\prime}-\omega} d \omega^{\prime}  \tag{1.64}\\
\chi^{\prime \prime}(\boldsymbol{q}, \omega) & =\frac{1}{\pi} \mathcal{P} \int_{-\infty}^{\infty} \frac{\chi^{\prime}\left(\boldsymbol{q}, \omega^{\prime}\right)-\chi(\boldsymbol{q}, \infty)}{\omega^{\prime}-\omega} d \omega^{\prime} . \tag{1.65}
\end{align*}
$$

The usefulness of this result lies in the fact that $\chi^{\prime \prime}$ is proportional to the absorption spectrum of the medium. Therefore (1.64) tells us, for example, that the static susceptibility may be obtained by integrating over the absorption spectrum. This is, in fact, an experimental technique used to obtain the static susceptibility of certain systems.

Since the response $\boldsymbol{M}(\boldsymbol{r}, t)$, is a real quantity, it follows that $\chi^{\prime}(\boldsymbol{q}, \omega)$ is an even function of $\omega$ while $\chi^{\prime \prime}(\boldsymbol{q}, \omega)$ is odd. This enables us to express the Kramers-Kronig relations in terms of integrals over positive frequencies. In particular,

$$
\begin{equation*}
\chi^{\prime \prime}(\boldsymbol{q}, \omega)=-\frac{2 \omega}{\pi} \mathcal{P} \int_{0}^{\infty} \frac{\chi^{\prime}\left(\boldsymbol{q}, \omega^{\prime}\right)}{\omega^{\prime 2}-\omega^{2}} d \omega^{\prime} \tag{1.66}
\end{equation*}
$$

The term involving $\chi(\boldsymbol{q}, \infty)$ vanishes because the principal value of the integral of $1 /\left(\omega^{\prime^{2}}-\omega^{2}\right)$ is zero.

### 1.3.2 The Fluctuation-Dissipation Theorem

It is well known that a colloidal suspension of particles exhibits Brownian motion; that is, the particles move about irregularly because they are being bombarded by the molecules of the liquid. Now, suppose that these particles are charged, and we attempt to accelerate them with an external electric field. Because of the impacts with the molecules, the particles experience a resistive force which is proportional to their velocity. Thus the mechanism that produces the random fluctuations in the position of the particle is also
responsible for its response to an external excitation. The relationship between the response of a system and its thermal fluctuation spectrum is called the fluctuation-dissipation theorem. This relationship is a very general one, and we shall consider only its specific application to a magnetic medium.

Let us consider a linearly polarized magnetic field of amplitude $H_{\mu} \cos (\boldsymbol{q} \cdot \boldsymbol{r})$ oscillating at a frequency $\omega$ in the $\mu$ direction, $H_{\mu} \cos (\boldsymbol{q} \cdot \boldsymbol{r}) \cos \omega t$. Since we have a linear system, the principle of superposition applies. Therefore we may construct the response to an arbitrary field if we know the response to this particular field. The response in the $\nu$ direction to such an excitation is given by (1.55). Since

$$
\begin{align*}
H_{\mu}\left(\boldsymbol{q}^{\prime}, \omega^{\prime}\right)= & \frac{\pi H_{1} V}{2}\left[\Delta\left(\boldsymbol{q}^{\prime}-\boldsymbol{q}\right) \delta\left(\omega^{\prime}+\omega\right)+\Delta\left(\boldsymbol{q}^{\prime}-\boldsymbol{q}\right) \delta\left(\omega^{\prime}-\omega\right)\right. \\
& \left.+\Delta\left(\boldsymbol{q}^{\prime}+\boldsymbol{q}\right) \delta\left(\omega^{\prime}+\omega\right)+\Delta\left(\boldsymbol{q}^{\prime}+\boldsymbol{q}\right) \delta\left(\omega^{\prime}-\omega\right)\right] \tag{1.67}
\end{align*}
$$

we obtain

$$
\begin{align*}
\boldsymbol{M}_{\nu}(\boldsymbol{k}, \Omega)= & \frac{\pi H_{1} V}{2}\left[\chi_{\nu \mu}(\boldsymbol{k}, \boldsymbol{q} ; \Omega,-\omega)+\chi_{\nu \mu}(\boldsymbol{k}, \boldsymbol{q} ; \Omega, \omega)\right. \\
& \left.+\chi_{\nu \mu}(\boldsymbol{k},-\boldsymbol{q} ; \Omega,-\omega)+\chi_{\nu \mu}(\boldsymbol{k},-\boldsymbol{q} ; \Omega, \omega)\right] \tag{1.68}
\end{align*}
$$

Let us now compute $M_{\nu}(\boldsymbol{k}, \Omega)$, using the prescription given in Sect.1.2. The magnetization is

$$
\begin{equation*}
\boldsymbol{M}_{\nu}(\boldsymbol{r}, t)=\operatorname{Tr}\left\{\rho \mathcal{M}_{\nu}(\boldsymbol{r})\right\} \tag{1.69}
\end{equation*}
$$

Although $\rho$ is a function of time, we shall not display this dependence explicitly, for a reason that will be apparent later. Since the time-varying field now disrupts the thermodynamic equilibrium, we must solve for $\rho$. We write the total Hamiltonian as

$$
\begin{equation*}
\mathcal{H}=\mathcal{H}_{0}+\mathcal{H}_{1} \tag{1.70}
\end{equation*}
$$

where $\mathcal{H}_{1}=-\int d \boldsymbol{r} \boldsymbol{\mathcal { M }}(\boldsymbol{r}) \cdot \boldsymbol{H}(\boldsymbol{r}, t)$. For the particular field we are considering this becomes
$\mathcal{H}_{1}=-\boldsymbol{H}_{1} \int d \boldsymbol{r} \mathcal{M}_{\mu}(\boldsymbol{r}) \cos (\boldsymbol{q} \cdot \boldsymbol{r}) \cos \omega t=-\frac{H_{1}}{2}\left[\mathcal{M}_{\mu}(\boldsymbol{q})+\mathcal{M}_{\mu}(-\boldsymbol{q})\right] \cos \omega t$.
The equation of motion for the density matrix is

$$
\begin{equation*}
\frac{\partial \rho}{\partial t}=\frac{i}{\hbar}\left[\rho, \mathcal{H}_{0}+\mathcal{H}_{1}\right] . \tag{1.72}
\end{equation*}
$$

It is now convenient to introduce

$$
\begin{equation*}
\rho(t) \equiv \exp \left(\frac{i \mathcal{H}_{0} t}{\hbar}\right) \rho \exp \left(\frac{-i \mathcal{H}_{0} t}{\hbar}\right) \tag{1.73}
\end{equation*}
$$

Differentiating (1.73) and using (1.72) gives

$$
\begin{equation*}
\frac{d \rho(t)}{d t}=\frac{i}{\hbar}\left[\rho(t), \exp \left(\frac{i \mathcal{H}_{0} t}{\hbar}\right) \mathcal{H}_{1} \exp \left(\frac{-i \mathcal{H}_{0} t}{h}\right)\right] \tag{1.74}
\end{equation*}
$$

This has the solution

$$
\begin{equation*}
\rho(t)=\rho(-\infty)+\frac{i}{\hbar} \int_{-\infty}^{t}\left[\rho\left(t^{\prime}\right), \exp \left(\frac{i \mathcal{H}_{0} t^{\prime}}{\hbar}\right) \mathcal{H}_{1} \exp \left(\frac{-i \mathcal{H}_{0} t^{\prime}}{\hbar}\right)\right] d t^{\prime} \tag{1.75}
\end{equation*}
$$

If the interaction is turned on adiabatically, then $\rho(-\infty)=\rho_{0}$, which is the equilibrium density matrix $\rho_{0}=\exp \left(-\beta \mathcal{H}_{0}\right) / Z$ where $Z=\operatorname{Tr}\left\{\exp \left(-\beta \mathcal{H}_{0}\right)\right\}$. Inverting (1.75), using (1.71), and replacing $\rho$ within the commutator by $\rho_{0}$, we have
$\rho \simeq \rho_{0}-i \frac{H_{1}}{2 \hbar} \int_{0}^{\infty}\left\{\rho_{0}, \exp \left(\frac{-i \mathcal{H}_{0} t^{\prime}}{\hbar}\right)\left[\mathcal{M}_{\mu}(\boldsymbol{q})+\mathcal{M}_{\mu}(-\boldsymbol{q})\right] \exp \left(\frac{i \mathcal{H}_{0} t^{\prime}}{\hbar}\right)\right\}$.
The magnetization is obtained from (1.69). If the system is ordered in the absence of the applied field, then $\operatorname{Tr}\left\{\rho_{0} \mathcal{M}_{\nu}\right\} \equiv M_{\nu}(-\infty)$ is nonzero. The response of such a system is then defined by the difference $M_{\nu}(\boldsymbol{r}, t)-M_{\nu}(-\infty)$ resulting from the applied field. In the following we shall understand $M_{\nu}(\boldsymbol{r}, t)$ to be the response to the applied field. Then,

$$
\begin{align*}
M_{\nu}(\boldsymbol{r}, t)= & -i \frac{H_{1}}{2 \hbar} \\
& \times \operatorname{Tr}\left\{\int _ { 0 } ^ { \infty } \left\{\rho_{0}, \exp \left(\frac{-i \mathcal{H}_{0} t^{\prime}}{\hbar}\right)\left[\mathcal{M}_{\mu}(\boldsymbol{q})+\mathcal{M}_{\mu}(-\boldsymbol{q})\right]\right.\right. \\
& \left.\left.\times \exp \left(\frac{i \mathcal{H}_{0} t^{\prime}}{\hbar}\right)\right\} \mathcal{M}_{\nu}(\boldsymbol{r})\right\} \cos \omega\left(t-t^{\prime}\right) d t^{\prime} \tag{1.77}
\end{align*}
$$

Taking the Fourier transform of this equation gives

$$
\begin{align*}
M_{\nu}(\boldsymbol{k}, \Omega)= & -\frac{\pi H_{1}}{2 \hbar} \operatorname{Tr}\left\{\int_{0}^{\infty}\left[\rho_{0}, \mathcal{M}_{\mu}\left(\boldsymbol{q},-t^{\prime}\right)\right] \mathcal{M}_{\nu}(\boldsymbol{k})\right\} e^{i \omega t^{\prime}} d t^{\prime} \delta(\Omega+\omega) \\
& +(\text { terms involving }-\boldsymbol{q} \text { and }-\omega) \tag{1.78}
\end{align*}
$$

Here $\mathcal{M}_{\mu}(\boldsymbol{q}, t)$ is defined in a manner identical to (1.73). The delta function involving the frequency results from our having linearized the expression for $\rho$ when we replaced $\rho$ by $\rho_{0}$ within the commutator.

If we now commute the integral with the trace in (1.78) and make use of the cyclic invariance of the trace, we have

$$
\begin{align*}
& \operatorname{Tr}\left\{\int_{0}^{\infty}\left[\rho_{0}, \mathcal{M}_{\mu}\left(\boldsymbol{q},-t^{\prime}\right)\right] \mathcal{M}_{\nu}(\boldsymbol{k})\right\} e^{-i \omega t^{\prime}} d t^{\prime} \\
& =\int\left\langle\left[\mathcal{M}_{\mu}\left(\boldsymbol{q},-t^{\prime}\right), \mathcal{M}_{\nu}(\boldsymbol{k})\right]\right\rangle e^{i \omega t^{\prime}} d t^{\prime} \tag{1.79}
\end{align*}
$$

By comparing the resulting expression for $M_{\nu}(\boldsymbol{k}, \Omega)$ with (1.68) we make the following identification:

$$
\begin{equation*}
\chi_{\nu \mu}(\boldsymbol{k}, \boldsymbol{q} ; \Omega, \omega)=\frac{i}{\hbar V} \int_{0}^{\infty}\left\langle\left[\mathcal{M}_{\nu}(\boldsymbol{k}, t), \mathcal{M}_{\mu}(-\boldsymbol{q})\right]\right\rangle e^{i \omega t} d t \delta(\Omega-\omega) . \tag{1.80}
\end{equation*}
$$

Since the $\boldsymbol{q}$ component of the applied field couples to the $-\boldsymbol{q}$ component of the magnetization, let us consider $\chi_{\nu \mu}(\boldsymbol{q}, \boldsymbol{q}, \omega)$ which we write as $\chi_{\nu \mu}(\boldsymbol{q}, \omega)$. Therefore,

$$
\begin{equation*}
\chi_{\nu \mu}(\boldsymbol{q}, \omega)=\frac{i}{\hbar V} \int_{0}^{\infty}\left\langle\left[\mathcal{M}_{\nu}(\boldsymbol{q}, t), \mathcal{M}_{\mu}(-\boldsymbol{q})\right]\right\rangle e^{i \omega t} d t \tag{1.81}
\end{equation*}
$$

The quantity

$$
(i / \hbar)\left\langle\left[\mathcal{M}_{\nu}(\boldsymbol{q}, t), \mathcal{M}_{\mu}(-\boldsymbol{q})\right]\right\rangle
$$

or equivalently

$$
\frac{i}{\hbar} \operatorname{Tr}\left\{\left[\mathcal{M}_{\mu}(-\boldsymbol{q}), \rho_{0}\right] \mathcal{M}_{\nu}(\boldsymbol{q}, t)\right\}
$$

is referred to in the literature as the response function of the system. The susceptibility may also be written as an integral over the full range of time by multiplying the integrand by the theta function $\theta(t)$ which equals 1 for $t>0$ and 0 for $t<0$. The product of the response function and this theta function is called the double-time-retarded Green's function and represented by double angular brackets:

$$
\left\langle\left\langle\mathcal{M}_{\nu}(\boldsymbol{q}, t), \mathcal{M}_{\mu}(-\boldsymbol{q})\right\rangle\right\rangle \equiv-i\left\langle\left[\mathcal{M}_{\nu}(\boldsymbol{q}, t), \mathcal{M}_{\mu}(-\boldsymbol{q})\right]\right\rangle \theta(t) .
$$

These functions are very useful in calculating thermodynamic properties but are beyond the scope of this monograph.

Since the response function does not have a classical analog and is not a well-defined observable, it is more convenient to relate the susceptibility to the correlation function $\left\langle\left\{\mathcal{M}_{\nu}(\boldsymbol{q}, t) \mathcal{M}_{\mu}(-\boldsymbol{q})\right\}\right\rangle$, where $\{\cdots\}$ is the symmetrized product, which is defined by

$$
\left\{\mathcal{M}_{\nu}(\boldsymbol{q}, t) \mathcal{M}_{\mu}(-\boldsymbol{q})\right\} \equiv \frac{1}{2}\left[\mathcal{M}_{\nu}(\boldsymbol{q}, t) \mathcal{M}_{\mu}(-\boldsymbol{q})+\mathcal{M}_{\mu}(-\boldsymbol{q}) \mathcal{M}_{\nu}(\boldsymbol{q}, t)\right]
$$

In order to relate the response function to the correlation function let us consider their Fourier transforms,

$$
\begin{align*}
& f_{\nu \mu}(\boldsymbol{q}, \omega)=\frac{i}{\hbar} \int_{-\infty}^{\infty}\left\langle\left[\mathcal{M}_{\nu}(\boldsymbol{q}, t), \mathcal{M}_{\mu}(-\boldsymbol{q})\right]\right\rangle e^{i \omega t} d t  \tag{1.82}\\
& g_{\nu \mu}(\boldsymbol{q}, \omega)=\int_{-\infty}^{\infty}\left\langle\left\{\mathcal{M}_{\nu}(\boldsymbol{q}, t) \mathcal{M}_{\mu}(-\boldsymbol{q})\right\}\right\rangle e^{i \omega t} d t \tag{1.83}
\end{align*}
$$

We can rewrite (1.82) by using the following relation:

$$
\begin{align*}
& \int_{-\infty}^{\infty} d t\left\langle\mathcal{M}_{\mu}(-\boldsymbol{q}) \mathcal{M}_{\nu}(\boldsymbol{q}, t)\right\rangle e^{i \omega t} \\
& =\int_{-\infty}^{\infty} d t \operatorname{Tr}\left\{\exp \left(-\beta \mathcal{H}_{0}\right) \mathcal{M}_{\mu}(\boldsymbol{q}) \exp \left(\frac{i \mathcal{H}_{0} t}{\hbar}\right) \mathcal{M}_{\nu}(\boldsymbol{q}) \exp \left(\frac{-i \mathcal{H}_{0} t}{\hbar}\right)\right\} e^{i \omega t} \\
& =\int_{-\infty}^{\infty} d t \operatorname{Tr}\left\{\exp \left(-\beta \mathcal{H}_{0}\right) \exp \left(\frac{i \mathcal{H}_{0}(t-i \hbar \beta)}{\hbar}\right) \mathcal{M}_{\nu}(\boldsymbol{q})\right. \\
& \left.\quad \times \exp \left[\frac{-i \mathcal{H}_{0}(t-i \hbar \beta)}{\hbar}\right] \mathcal{M}_{\mu}(-\boldsymbol{q})\right\} e^{i \omega t} \\
& =e^{-\beta \hbar \omega} \int_{-\infty}^{\infty} d t\left\langle\mathcal{M}_{\nu}(\boldsymbol{q}, t) \mathcal{M}_{\mu}(-\boldsymbol{q})\right\rangle e^{i \omega t} \tag{1.84}
\end{align*}
$$

Therefore

$$
\begin{equation*}
f_{\nu \mu}(\boldsymbol{q}, \omega)=\frac{i}{\hbar}\left(1-e^{-\beta \hbar \omega}\right) \int_{-\infty}^{\infty} d t\left\langle\mathcal{M}_{\nu}(\boldsymbol{q}, t) \mathcal{M}_{\mu}(-\boldsymbol{q})\right\rangle e^{i \omega t} \tag{1.85}
\end{equation*}
$$

From the definition of $g_{\nu \mu}$ we see that its relation to $f_{\nu \mu}$ is

$$
\begin{equation*}
g_{\nu \mu}(\boldsymbol{q}, \omega)=(\hbar / 2 i) \operatorname{coth}(\beta \hbar \omega / 2) f_{\nu \mu}(\boldsymbol{q}, \omega) . \tag{1.86}
\end{equation*}
$$

We can also relate $f_{\nu \mu}$ to the susceptibility by separating the time integral as follows:

$$
\begin{align*}
f_{\nu \mu}(\boldsymbol{q}, \omega)= & \frac{i}{\hbar} \int_{0}^{\infty} d t\left\langle\left[\mathcal{M}_{\nu}(\boldsymbol{q}, t), \mathcal{M}_{\mu}(-\boldsymbol{q})\right]\right\rangle e^{i \omega t} \\
& +\frac{i}{\hbar} \int_{-\infty}^{0} d t\left\langle\left[\mathcal{M}_{\nu}(\boldsymbol{q}, t), \mathcal{M}_{\mu}(-\boldsymbol{q})\right]\right\rangle e^{i \omega t} \tag{1.87}
\end{align*}
$$

If we now make the transformation $t \rightarrow-t$ in the second integral and use the fact that $\chi_{\mu \nu}(-\boldsymbol{q},-\omega)=\chi_{\mu \nu}^{*}(\boldsymbol{q}, \omega)$, which follows from (1.81), then

$$
f_{\nu \mu}(\boldsymbol{q}, \omega)=\left[\chi_{\nu \mu}(\boldsymbol{q}, \omega)-\chi_{\mu \nu}^{*}(\boldsymbol{q}, \omega)\right] V
$$

and

$$
g_{\nu \mu}(\boldsymbol{q}, \omega)=(\hbar V / 2 i) \operatorname{coth}(\beta \hbar \omega / 2)\left[\chi_{\nu \mu}(\boldsymbol{q}, \omega)-\chi_{\mu \nu}^{*}(\boldsymbol{q}, \omega)\right] .
$$

Therefore

$$
\int_{-\infty}^{\infty} d t\left\langle\left\{\mathcal{M}_{\nu}(\boldsymbol{q}, t) \mathcal{M}_{\mu}(-\boldsymbol{q})\right\}\right\rangle_{s} e^{i \omega t}=\hbar V \operatorname{coth}(\beta \hbar \omega / 2) \chi_{\nu \mu}^{\prime \prime}(\boldsymbol{q}, \omega)_{s},(1.88)
$$

where the subscript $s$ indicates the symmetric part of the tensor.

This is the result we had set out to find. It tells us that the Fourier transform of the correlation function is proportional to the imaginary part of the susceptibility. The derivation has been presented here in detail because it is a very important relationship, and we shall make frequent reference to this result throughout the text.

The imaginary part of the susceptibility describes the absorptive or lossy, response of the magnetic system. The fluctuation-dissipation theorem therefore relates the fluctuations in the magnetization to energy loss. This is a general result that applies to many systems. One example that may be familiar to the reader is Johnson noise. This is the noise associated with thermal fluctuations in a resistive electrical circuit element. The voltage noise power is given by $\left\langle v^{2}\right\rangle / R$. Since this power is due to thermal fluctuations it may also be expressed as the unit of thermal energy, $k_{B} T$, divided by the measurement time, which is the reciprocal of the frequency bandwidth, $\Delta f$. A rigorous derivation gives

$$
\left\langle v^{2}\right\rangle=4 k_{B} T R \Delta f
$$

This form of the fluctuation-dissipation theorem is known as the Nyquist theorem.

### 1.3.3 Onsager Relation

Generally, when we probe a magnetic system it is in the presence of a dc field $\boldsymbol{H}$. Therefore $\mathcal{H}_{0}$ and hence the response function, is a function of this field. In 1931 Onsager pointed out that microscopic reversibility requires the simultaneous reversal of both the magnetic field and time. To see this, consider the response function for the susceptibility:

$$
\left\langle\left[\mathcal{M}_{\nu}(\boldsymbol{q}, t), \mathcal{M}_{\mu}(-\boldsymbol{q})\right]\right\rangle=\sum_{n}\langle n| \rho_{0}\left(\mathcal{H}_{0}\right)\left[\mathcal{M}_{\nu}(\boldsymbol{q}, t), \mathcal{M}_{\mu}(-\boldsymbol{q})\right]|n\rangle
$$

Let us introduce time reversal through the time reversal operator, $T$, which satisfies the relation

$$
\begin{equation*}
\langle\psi \mid \varphi\rangle=\langle T \psi \mid T \varphi\rangle^{*} \tag{1.89}
\end{equation*}
$$

Therefore

$$
\begin{equation*}
\left\langle\left[\mathcal{M}_{\nu}(\boldsymbol{q}, t), \mathcal{M}_{\mu}(-\boldsymbol{q})\right]\right\rangle=\sum_{n}\langle T n| T \rho_{0}\left(\mathcal{H}_{0}\right)\left[\mathcal{M}_{\nu}(\boldsymbol{q}, t), \mathcal{M}_{\mu}(-\boldsymbol{q})\right]|n\rangle^{*} \tag{1.90}
\end{equation*}
$$

We now insert $T^{-1} T$ between all the factors. If the system is invariant under time reversal then $T \rho_{0}\left(\mathcal{H}_{0}\right) T^{-1}=\rho_{0}\left(\mathcal{H}_{0}\right)$, where any magnetic field has been reversed. Let us display this explicitly as $\rho_{0}(-H)$. We also have factors like $T \mathcal{M}_{\nu}(\boldsymbol{q}, t) T^{-1}$. Since the magnetic moment changes sign under time reversal,

$$
\begin{equation*}
T \mathcal{M}_{\nu}(\boldsymbol{q}, t) T^{-1}=-\mathcal{M}_{\nu}(\boldsymbol{q},-t) \tag{1.91}
\end{equation*}
$$

If we also recognize that the state $T \mid n>$ is some eigenstate $\mid m>$, then the sum over $n$ is the same as the sum over $m$, which can then be relabled as $n$. These steps enable us to carry out all the time reversal operations in the expression for the response function above,

$$
\begin{equation*}
\left\langle\left[\mathcal{M}_{\nu}(\boldsymbol{q}, t), \mathcal{M}_{\mu}(-\boldsymbol{q})\right]\right\rangle=\sum_{n}\langle n| \rho_{0}(-H)\left[\mathcal{M}_{\nu}(\boldsymbol{q}, t), \mathcal{M}_{\mu}(-\boldsymbol{q})\right]|n\rangle^{*} . \tag{1.92}
\end{equation*}
$$

To remove the complex conjugation we introduce the Hermitian adjoint $0^{\dagger}$ of an arbitrary operator 0 by the relation

$$
\begin{equation*}
\langle\psi| 0|\varphi\rangle^{*}=\langle\varphi| 0^{\dagger}|\psi\rangle . \tag{1.93}
\end{equation*}
$$

The first term in the commutator becomes

$$
\begin{align*}
\left(\rho_{0}(-H) \mathcal{M}_{\nu}(\boldsymbol{q},-t) \mathcal{M}_{\mu}(-\boldsymbol{q})\right)^{\dagger} & =\mathcal{M}_{\mu}(-\boldsymbol{q})^{\dagger} \mathcal{M}_{\nu}(\boldsymbol{q},-t)^{\dagger} \rho_{0}(-H)^{\dagger} \\
& =\mathcal{M}_{\mu}(\boldsymbol{q}) \mathcal{M}_{\nu}(-\boldsymbol{q},-t) \rho_{0}(-H) \tag{1.94}
\end{align*}
$$

where we have used the fact that the magnetic moment and the Hamiltonian are Hermitian operators. We now use the cyclic invariance of the trace to write

$$
\begin{align*}
\left\langle\left[\mathcal{M}_{\nu}(\boldsymbol{q}, t), \mathcal{M}_{\mu}(-\boldsymbol{q})\right]\right\rangle & =\sum_{n}\langle n| \rho_{0}\left(-H\left[\mathcal{M}_{\mu}(\boldsymbol{q}), \mathcal{M}_{\nu}(-\boldsymbol{q},-t)\right]|n\rangle\right. \\
& =\sum_{n}\langle n| \rho_{0}(-H)\left[\mathcal{M}_{\mu}(\boldsymbol{q}, t), \mathcal{M}_{\nu}(-\boldsymbol{q})\right]|n\rangle . \tag{1.95}
\end{align*}
$$

Therefore we have the relation

$$
\begin{equation*}
\chi_{\nu \mu}(\boldsymbol{q}, \omega, H)=\chi_{\mu \nu}(\boldsymbol{q}, \omega,-H) \tag{1.96}
\end{equation*}
$$

which is known as the Onsager relation. Note that this tells us immediately that the diagonal components of the susceptibility tensor must be even functions of the field.

### 1.4 Second Quantization

Magnetism, particularly in metals, is a many-body phenomenon. It is therefore important to incorporate the fermion statistics of the electrons that govern the magnetic behavior. In this section we shall briefly develop the technique of second quantization which facilitates this description. We shall have occasion to use these results later, particularly in setting up the so-called Anderson and Hubbard Hamiltonians.

Let us begin by considering a system of $N$ interacting particles described by the Hamiltonian

$$
\begin{equation*}
\mathcal{H}=\sum_{i=1}^{N} T\left(\boldsymbol{r}_{i}, \dot{\boldsymbol{r}}_{i}\right)+\frac{1}{2} \sum_{\substack{i, j=1 \\ i \neq j}}^{N} V\left(\boldsymbol{r}_{i}, \boldsymbol{r}_{j}\right) \tag{1.97}
\end{equation*}
$$

The many-body wave function $\psi\left(\boldsymbol{r}_{i}, \ldots, \boldsymbol{r}_{N}, t\right)$ satisfies the Schrödinger equation

$$
\begin{equation*}
i \hbar \frac{\partial}{\partial t} \psi\left(\boldsymbol{r}_{1}, \ldots \boldsymbol{r}_{N}, t\right)=\mathcal{H} \psi\left(\boldsymbol{r}_{1}, \ldots, \boldsymbol{r}_{N}, t\right) \tag{1.98}
\end{equation*}
$$

We now expand this wave function in terms of products of single-particle wave functions characterized by quantum numbers $E_{i}$,

$$
\begin{equation*}
\psi\left(\boldsymbol{r}_{1}, \ldots, \boldsymbol{r}_{N}, t\right)=\sum_{\left(E_{1}, \ldots, E_{N}\right)} c\left(E_{1}, \ldots, E_{N}, t\right) \varphi_{E_{1}}\left(\boldsymbol{r}_{1}\right) \varphi_{E_{2}}\left(\boldsymbol{r}_{2}\right) \ldots \varphi_{E_{N}}\left(\boldsymbol{r}_{N}\right) \tag{1.99}
\end{equation*}
$$

where the sum is over all possible sets of quantum numbers. The statistical nature of the particles is contained in the coefficients $c\left(E_{1}, \ldots, E_{N}, t\right)$. For example, if the particles are bosons, the sign of the coefficient is invariant under particle interchange,

$$
\begin{equation*}
c\left(E_{1}, \ldots, E_{k}, \ldots, E_{i}, \ldots, E_{N}, t\right)=c\left(E_{1}, \ldots, E_{i}, \ldots, E_{k}, \ldots, E_{N}, t\right) \tag{1.100}
\end{equation*}
$$

and any number of particles may occupy a given state. If the particles are fermions,

$$
\begin{equation*}
c\left(E_{1}, \ldots, E_{k}, \ldots, E_{i}, \ldots, E_{N}, t\right)=-c\left(E_{1}, \ldots, E_{i}, \ldots, E_{k}, \ldots, E_{N}, t\right) \tag{1.101}
\end{equation*}
$$

This insures that there may not be more than one particle in a particular state.

Since we shall be concerned mainly with electrons, which are fermions, we shall be faced with the problem of keeping track of the minus sign introduced when two electrons are interchanged. It is to facilitate this bookkeeping that the concept of second quantization is introduced.

The coefficients in the expansion of $\psi$ above are characterized by the set of $N$ quantum numbers. We could just as well, however, have chosen coefficients characterized by the number of electrons in each of the possible states. That is, instead of the set of $N$ numbers $\left\{E_{1}, \ldots, E_{N}\right\}$ we could have used the infinite set of numbers $\left\{n_{1}, \ldots, n_{\infty}\right\}$, where for fermions $n=0$ or 1 . We must be very careful in making this transcription. For example, suppose that the electron at $\boldsymbol{r}_{i}$ is in a state $E_{i}$ and the electron $\boldsymbol{r}_{k}$ is in a state $E_{k}$. In this case the occupation-number description would be the same as if the electron at $\boldsymbol{r}_{i}$, were in state $E_{k}$ and the electron at $\boldsymbol{r}_{k}$ were in state $E_{i}$. However,

$$
\begin{equation*}
c\left(E_{1}, \ldots, E_{k}, \ldots, E_{i}, \ldots, E_{N}, t\right)=-c\left(E_{1}, \ldots, E_{i}, \ldots, E_{k}, \ldots, E_{N}, t\right) . \tag{1.102}
\end{equation*}
$$

If we wish to use the occupation-number scheme, we must account for this minus sign. This is done by arbitrarily assigning a certain order to the particular set of quantum numbers $\left\{E_{1}, \ldots, E_{N}\right\}$. Then the relative sign of any permutation of the electrons from this order is automatically given by writing the single-particle wave functions as a Slater determinant:

$$
\begin{align*}
& c\left(E_{1}, \ldots, E_{N}, t\right) \varphi_{E_{1}}\left(\boldsymbol{r}_{1}\right) \ldots \varphi_{E_{N}}\left(\boldsymbol{r}_{N}\right) \\
& \quad+\left(\text { all permutations within the set }\left\{E_{1}, \ldots, E_{N}\right\}\right) \\
& =f\left(n_{1}, \ldots, n_{\infty}, t\right)\left|\begin{array}{l}
\varphi_{E_{1}}\left(\boldsymbol{r}_{1}\right) \cdots \varphi_{E_{1}}\left(\boldsymbol{r}_{N}\right) \\
\cdots \cdots \cdots \ldots \ldots \\
\varphi_{E_{N}}\left(\boldsymbol{r}_{1}\right) \cdots \varphi_{E_{N}}\left(\boldsymbol{r}_{N}\right)
\end{array}\right| \tag{1.103}
\end{align*}
$$

where $f\left(n_{1}, \ldots, n_{\infty}, t\right)$ has the sign and magnitude of the first $c$. Summing over all sets $\left\{E_{1}, \ldots, E_{N}\right\}$ is equivalent to summing over all combinations of occuped states. Therefore

$$
\psi\left(\boldsymbol{r}_{1}, \ldots, \boldsymbol{r}_{N}, t\right)=\sum_{n_{1}, \cdots, n_{\infty}} f\left(n_{1}, \ldots, n_{\infty}, t\right) \frac{1}{\sqrt{N!}}\left|\begin{array}{l}
\varphi_{E_{1}}\left(\boldsymbol{r}_{1}\right) \cdots \varphi_{E_{1}}\left(\boldsymbol{r}_{N}\right)  \tag{1.104}\\
\cdots \cdots \cdots \cdots \ldots \ldots \\
\varphi_{E_{N}}\left(\boldsymbol{r}_{1}\right) \cdots \varphi_{E_{N}}\left(\boldsymbol{r}_{N}\right)
\end{array}\right|
$$

The states used in constructing the determinant are, of course, those occupied.
By using this occupation-number description we have succeeded in moving the statistics from the expansion coefficients into the basis functions, which, in fact, form an orthonormal antisymmetric set.

Let us now define an abstract vector space, or Hilbert space, spanned by vectors $\left|n_{1}, n_{2}, \ldots, n_{\infty}\right\rangle$. We introduce operators which satisfy the anticommutation relations

$$
\begin{equation*}
\left\{a_{i}, a_{j}^{\dagger}\right\} \equiv a_{i} a_{j}^{\dagger}+a_{j}^{\dagger} a_{i}=\delta_{i j}, \quad\left\{a_{i}, a_{j}\right\}=\left\{a_{i}^{\dagger} a_{j}^{\dagger}\right\}=0 . \tag{1.105}
\end{equation*}
$$

From these relations it can be shown that $a_{i}^{\dagger}$ creates an entry in position $i$ (provided one does not already exist there) and $a_{i}$ destroys an entry at $i$. Therefore we may represent a basis vector of our Hilbert space as

$$
\begin{equation*}
\left|n_{1}, \ldots, n_{\infty}\right\rangle=\left(a_{1}^{\dagger}\right)^{n_{1}}\left(a_{2}^{\dagger}\right)^{n_{2}}\left(a_{\infty}^{\dagger}\right)^{n_{\infty}}|0\rangle . \tag{1.106}
\end{equation*}
$$

Now consider operating on this with $a_{k}$. If $n_{k}=0$, then $a_{k}$ can be commuted all the way over to the "vacuum", where it gives 0 . If $n_{k}=1$, then $a_{k}$ will commute until it comes to $a_{k}^{\dagger}$.

Here $\sum_{k}=n_{1}+n_{2}+\cdots n_{k-1}$ accounts for all the sign changes that $a_{k}$ left in its wake as it commuted over to $a_{k}^{\dagger}$. We now use $a_{k} a_{k}^{\dagger}=1-a_{k}^{\dagger} a_{k}$. In the second term $a_{k}$ may again commute over to the vacuum to give 0 . Thus we are left with

$$
a_{k}\left|n_{1}, \ldots, n_{k}, \ldots, n_{\infty}\right\rangle= \begin{cases}0 & n_{k}=0  \tag{1.108}\\ (-1)^{\sum_{k}}\left|n_{1}, \ldots, n_{k}-1, \ldots, n_{\infty}\right\rangle & n_{k}=1\end{cases}
$$

Similarly,

$$
a_{k}^{\dagger}\left|n_{1}, \ldots, n_{k}, \ldots, n_{\infty}\right\rangle= \begin{cases}\left.(-1)^{\sum_{k} \mid n_{1}}, \ldots, n_{k}+1, \ldots, n_{\infty}\right\rangle & n_{k}=0  \tag{1.109}\\ 0 & n_{k}=1\end{cases}
$$

Since it can be shown that $a_{k}^{\dagger} a_{k}$ has the eigenvalue $n_{k}$, we can simplify these results by writing

$$
\begin{align*}
& \left.a_{k}\left|n_{1}, \ldots, n_{k}, \ldots, n_{\infty}\right\rangle=(-1)^{\sum_{k} \sqrt{n_{k}} \mid n_{1}}, \ldots, n_{k}-1, \ldots, n_{\infty}\right\rangle \\
& a_{k}^{\dagger}\left|n_{1}, \ldots, n_{k}, \ldots, n_{\infty}\right\rangle=(-1)^{\sum_{k} \sqrt{n_{k}+1}\left|n_{1}, \ldots, n_{k}+1, \ldots n_{\infty}\right\rangle} . \tag{1.110}
\end{align*}
$$

Having developed the properties of the Hilbert space, we now use the expansion coefficients $f\left(n_{1}, \ldots, n_{\infty}, t\right)$ to define the abstract state vector

$$
\begin{equation*}
|\psi(t)\rangle=\sum_{n_{1}, \cdots, n_{\infty}} f\left(n_{1}, \ldots, n_{\infty} t\right)\left|n_{1}, \ldots, n_{\infty}\right\rangle \tag{1.111}
\end{equation*}
$$

The reason for this becomes clear when we consider the equation of motion of this state vector. Taking the time derivative, we have

$$
\begin{equation*}
i \hbar \frac{\partial|\psi(t)\rangle}{\partial t}=i \hbar \sum_{n_{1}, \cdots, n_{\infty}} \frac{\partial f\left(n_{1}, \ldots, n_{\infty}, t\right)}{\partial t}\left|n_{1}, \ldots, n_{\infty}\right\rangle \tag{1.112}
\end{equation*}
$$

To evaluate this we go back to the real-space Schrödinger equation,

$$
\begin{align*}
& i \hbar \frac{\partial\left|\psi\left(\boldsymbol{r}_{1}, \ldots, \boldsymbol{r}_{N}, t\right)\right\rangle}{\partial t} \\
& =i \hbar \sum_{\left(n_{1}, \cdots, n_{\infty}\right)} \frac{\partial\left(n_{1}, \ldots, n_{\infty}, t\right)}{\partial t} \frac{1}{\sqrt{N!}}\left|\begin{array}{l}
\varphi_{E_{1}}\left(\boldsymbol{r}_{1}\right) \cdots \varphi_{E_{1}}\left(\boldsymbol{r}_{N}\right) \\
\cdots \cdots \cdots \cdots \cdots \cdots \cdots \cdots \\
\varphi_{E_{N}}\left(\boldsymbol{r}_{1}\right) \cdots \varphi_{E_{N}}\left(\boldsymbol{r}_{N}\right)
\end{array}\right|, \\
& =\mathcal{H} \sum_{n_{1}, \cdots, n_{\infty}} f\left(n_{1}, \ldots, n_{\infty}, t\right) \frac{1}{\sqrt{N!}}\left|\begin{array}{l}
\varphi_{E_{1}}\left(\boldsymbol{r}_{1}\right) \cdots \varphi_{E_{1}}\left(\boldsymbol{r}_{N}\right) \\
\cdots \cdots \cdots \cdots \cdots \cdots \cdots \\
\varphi_{E_{N}}\left(\boldsymbol{r}_{1}\right) \cdots \varphi_{E_{N}}\left(\boldsymbol{r}_{N}\right)
\end{array}\right| \tag{1.113}
\end{align*}
$$

We now multiply through from the left by the conjugate Slater determinant appropriate for some particular set of occupation numbers $\left\{n_{1}, \ldots, n_{\infty}\right\}$. The left-hand side just gives

$$
\begin{equation*}
i \hbar \frac{\partial f\left(n_{1}, \ldots, n_{\infty}, t\right)}{\partial t} \tag{1.114}
\end{equation*}
$$

Consider the one-particle terms of the right-hand side of (1.113), which arise from the $T\left(\dot{\boldsymbol{r}}_{i}\right)$ term in (1.97). We write the Slater determinant as

$$
\begin{equation*}
\frac{1}{\sqrt{N!}} \sum_{p}(-1)^{p} P \varphi_{E_{1}}\left(\boldsymbol{r}_{1}\right) \varphi_{E_{2}}\left(\boldsymbol{r}_{2}\right) \cdots \varphi_{E_{N}}\left(\boldsymbol{r}_{N}\right) \tag{1.115}
\end{equation*}
$$

where $P$ is an operator which permutes the order of the electrons and $p$ is the number of such permutations. Then the matrix element becomes

$$
\begin{align*}
& \frac{1}{N!} \sum_{i} \sum_{n_{1}^{\prime}, \cdots, n_{\infty}^{\prime}} \sum_{p, p^{\prime}}(-1)^{p+p^{\prime}} f\left(n_{1}^{\prime}, \ldots, n_{\infty}^{\prime}, t\right) \\
& \times \int P \varphi_{E_{1}}^{*}\left(\boldsymbol{r}_{1}\right) \cdots T\left(\dot{\boldsymbol{r}}_{i}\right) P^{\prime} \varphi_{E_{1}^{\prime}}\left(\boldsymbol{r}_{1}\right) \cdots d r_{1} \cdots d r_{N} \tag{1.116}
\end{align*}
$$

Since $T\left(\dot{\boldsymbol{r}}_{i}\right)$ is a one-particle operator, the set of numbers $\left\{n_{1}^{\prime}, \ldots, n_{\infty}^{\prime}\right\}$ cannot differ from the particular set $\left\{n_{1}, \ldots, n_{\infty}\right\}$ by more than two numbers. In particular, let the set $\left\{n_{1}^{\prime}, \ldots, n_{\infty}^{\prime}\right\}$ contain the state $E_{i}$ and the set $\left\{n_{1}, \ldots, n_{\infty}\right\}$ contain the state $E_{k}$. The sums over $i, p$, and $p^{\prime}$ give $N!$, leaving us with

Therefore

$$
\begin{align*}
i \hbar \frac{\partial|\psi(t)\rangle}{\partial t}= & \sum_{n_{1}, \cdots, n_{\infty}} \sum_{k, l}\langle k| T|l\rangle  \tag{1.118}\\
& \times f\left(n_{1}, \ldots, n_{k}=0, \ldots, n_{l}=1, \ldots, n_{\infty}, t\right)(-1)^{\sum_{k}+\sum_{l}} \\
& \times\left|n_{1}, \ldots, n_{k}=1, \ldots, n_{l}=0, \ldots, n_{\infty}\right\rangle+\text { (interaction terms) }
\end{align*}
$$

We now recall from above that

$$
\begin{align*}
& (-1)^{\sum_{k}+\sum_{l}\left|n_{1}, \ldots, n_{k}, \ldots n_{l}, \ldots, n_{\infty}\right\rangle} \\
& =a_{k}^{\dagger} a_{l}\left|n_{1}, \ldots, n_{k}-1, \ldots, n_{l}+1, \ldots, n_{\infty}\right\rangle \tag{1.119}
\end{align*}
$$

Substituting this into the equation for $\partial|\psi(t)\rangle / \partial t$, we see that the sum over $\left\{n_{1}, \ldots, n_{\infty}\right\}$ just gives $|\psi(t)\rangle$. Carrying through the same arguments for the two-particle interaction terms, we find

$$
\begin{equation*}
i \hbar \frac{\partial|\psi(t)\rangle}{\partial t}=\mathcal{H}|\psi(t)\rangle \tag{1.120}
\end{equation*}
$$

where

$$
\begin{equation*}
\mathcal{H}=\sum_{k, l}\langle k| T|l\rangle a_{k}^{\dagger} a_{l}+\frac{1}{2} \sum_{k, l, s, t}\langle k l| V|s t\rangle a_{k}^{\dagger} a_{l}^{\dagger} a_{t} a_{s} \tag{1.121}
\end{equation*}
$$

Thus we have the important result that in this occupation-number space the state vector $|\psi(t)\rangle$, as defined above, also satisfies a Schrödinger-like equation, with the Hamiltonian expressed in this second-quantized form. It is easy to show that the matrix elements of such second-quantized operators between occupation-number states are the same as the matrix elements of "first-quantized" operators between the usual states.

Since we shall often have occasion to express an operator in secondquantized form, let us develop a prescription for doing this. For this purpose it is convenient to define what is called the field operator in our Hilbert space,

$$
\begin{equation*}
\psi(\boldsymbol{r})=\sum_{k} \varphi_{k}(\boldsymbol{r}) a_{k} \tag{1.122}
\end{equation*}
$$

Here again the $\varphi_{k}(\boldsymbol{r})$ are a complete set of single-particle states characterized by the quantum numbers $k$, and $a_{k}$ is the fermion operator introduced above. To second quantize a one-particle operator such as $T\left(\dot{\boldsymbol{r}}_{i}\right)$ we write $\boldsymbol{r}_{i} \rightarrow \boldsymbol{r}$, sandwich this operator between $\psi^{\dagger}(\boldsymbol{r})$ and $\psi(\boldsymbol{r})$, and integrate over all space. For a two-particle operator such as $V\left(\boldsymbol{r}_{i}, \boldsymbol{r}_{j}\right)$ we let $\boldsymbol{r}_{i} \rightarrow \boldsymbol{r}$ and $\boldsymbol{r}_{j} \rightarrow \boldsymbol{r}^{\prime}$, sandwich it between $\psi^{\dagger}(\boldsymbol{r}) \psi^{\dagger}\left(\boldsymbol{r}^{\prime}\right)$ and $\psi\left(\boldsymbol{r}^{\prime}\right) \psi(\boldsymbol{r})$, and integrate over $d \boldsymbol{r}$ and $d \boldsymbol{r}^{\prime}$.

### 1.4.1 Example: The Degenerate-Electron Gas

As an example of the use of this prescription let us second quantize the Hamiltonian for a gas of electrons moving in the field of a uniform positive charge distribution. The total Hamiltonian is

$$
\begin{equation*}
\mathcal{H}=\mathcal{H}_{e 1-e 1}+\mathcal{H}_{e 1-n}+\mathcal{H}_{n-n} \tag{1.123}
\end{equation*}
$$

The electron-electron Hamiltonian is

$$
\begin{equation*}
\mathcal{H}_{e 1-e 1}=\sum_{i} \frac{p_{i}^{2}}{2 m}+\frac{e^{2}}{2} \sum_{i \neq j} \frac{\exp \left(-\mu\left|\boldsymbol{r}_{i}-\boldsymbol{r}_{j}\right|\right)}{\left|\boldsymbol{r}_{i}-\boldsymbol{r}_{j}\right|} \tag{1.124}
\end{equation*}
$$

where a screening factor has been inserted for mathematical convenience. The interaction of the electrons with the positive background due to the nuclei is

$$
\begin{equation*}
\mathcal{H}_{e 1-n}=-e^{2} \sum_{i} \int \frac{\rho\left(\boldsymbol{r}^{\prime}\right)}{\left|\boldsymbol{r}_{i}-\boldsymbol{r}^{\prime}\right|} \exp \left(-\mu\left|\boldsymbol{r}_{i}-\boldsymbol{r}^{\prime}\right|\right) d \boldsymbol{r}^{\prime} \tag{1.125}
\end{equation*}
$$

where $\rho(\boldsymbol{r})$ is the positive charge density, which for a uniform distribution is

$$
\begin{equation*}
\rho(\boldsymbol{r})=\frac{N}{V} \tag{1.126}
\end{equation*}
$$

Thus $\mathcal{H}_{e 1-n}$ becomes

$$
\begin{equation*}
\mathcal{H}_{e 1-n}=-e^{2}\left(\frac{N}{V}\right) \sum_{i} \int \frac{\exp \left(-\mu\left|\boldsymbol{r}_{i}-\boldsymbol{r}^{\prime}\right|\right)}{\left|\boldsymbol{r}_{i}-\boldsymbol{r}^{\prime}\right|} d \boldsymbol{r}^{\prime} \tag{1.127}
\end{equation*}
$$

If $\mu^{-1}$ is much smaller than $L$, where $L$ is the sample dimension, we may replace the integral over $d \boldsymbol{r}^{\prime}$ by one over $d\left(\boldsymbol{r}^{\prime}-\boldsymbol{r}_{i}\right)$, which gives

$$
\begin{equation*}
\mathcal{H}_{e 1-n}=-e^{2} \frac{N^{2}}{V} \frac{4 \pi}{\mu^{2}} \tag{1.128}
\end{equation*}
$$

Finally, the self-energy of the background charge is

$$
\begin{equation*}
\mathcal{H}_{n-n}=-\frac{1}{2} e^{2} \int \frac{\rho(\boldsymbol{r}) \rho\left(\boldsymbol{r}^{\prime}\right)}{\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|} e^{-\mu\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|} d \boldsymbol{r} d \boldsymbol{r}^{\prime}=\frac{e^{2}}{2} \frac{N^{2}}{2} \frac{4 \pi}{\mu^{2}} \tag{1.129}
\end{equation*}
$$

We must now decide what functions to use as a basis for our field operator. Since the eigenfunctions for a gas of free electrons are plane waves, we shall use these as our basis. These states are characterized by their wave vector $\boldsymbol{k}$ and spin quantum number $\sigma$. Thus

$$
\begin{equation*}
\psi(\boldsymbol{r})=\sum_{\boldsymbol{k}, \sigma} \frac{1}{\sqrt{V}} e^{i \boldsymbol{k} \cdot \boldsymbol{r}} \eta_{\sigma} a_{\boldsymbol{k} \sigma} \tag{1.130}
\end{equation*}
$$

where

$$
\begin{equation*}
\eta_{\uparrow}=\binom{1}{0} \quad \text { and } \quad \eta_{\downarrow}=\binom{0}{1} \tag{1.131}
\end{equation*}
$$

Notice that

$$
\begin{equation*}
\int \psi^{\dagger}(\boldsymbol{r}) \psi(\boldsymbol{r}) d \boldsymbol{r}=\sum_{\boldsymbol{k} \sigma} a_{\boldsymbol{k} \sigma}^{\dagger} a_{\boldsymbol{k}_{\sigma}}=N \tag{1.132}
\end{equation*}
$$

Since the terms $\mathcal{H}_{e 1-n}$ and $\mathcal{H}_{n-n}$ do not involve any electron coordinates, they are carried over directly into our Hilbert space. The kinetic energy of the electron-electron Hamiltonian becomes

$$
\begin{equation*}
\sum_{\boldsymbol{k} \sigma} \frac{\hbar^{2} k^{2}}{2 m} a_{\boldsymbol{k} \sigma}^{\dagger} a_{\boldsymbol{k} \sigma} \tag{1.133}
\end{equation*}
$$

For the Coulomb interaction we have

$$
\begin{align*}
& \frac{e^{2}}{2} \frac{1}{V^{2}} \sum_{\boldsymbol{k} \sigma} \sum_{\boldsymbol{k}^{\prime} \sigma^{\prime}} \sum_{\boldsymbol{k}^{\prime \prime}, \sigma^{\prime \prime}} \sum_{\boldsymbol{k}^{\prime \prime \prime} \cdot \sigma^{\prime \prime \prime}} \int d \boldsymbol{r} \int d \boldsymbol{r}^{\prime} e^{-i\left(\boldsymbol{k} \cdot \boldsymbol{r}+\boldsymbol{k}^{\prime} \cdot \boldsymbol{r}^{\prime}\right)} \frac{e^{-\mu\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|}}{\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|} e^{i\left(\boldsymbol{k}^{\prime \prime \prime} \cdot \boldsymbol{r}^{\prime}+\boldsymbol{k}^{\prime \prime} \cdot \boldsymbol{r}\right)} \\
& \quad \times \eta_{\sigma}^{\dagger}(\boldsymbol{r}) \eta_{\sigma^{\prime}}^{\dagger}\left(\boldsymbol{r}^{\prime}\right) \eta_{\sigma^{\prime \prime \prime}}\left(\boldsymbol{r}^{\prime}\right) \eta_{\sigma^{\prime \prime}}(\boldsymbol{r}) a_{\boldsymbol{k} \sigma}^{\dagger} a_{\boldsymbol{k}^{\prime} \sigma^{\prime}}^{\dagger} a_{\boldsymbol{k}^{\prime \prime \prime} \sigma^{\prime \prime \prime}} a_{\boldsymbol{k}^{\prime \prime} \sigma^{\prime \prime}} \\
& =\frac{e^{2}}{2} \frac{1}{V^{2}} \sum_{\boldsymbol{k}, \sigma} \sum_{\boldsymbol{k}^{\prime}, \sigma^{\prime}} \sum_{\boldsymbol{k}^{\prime \prime}, \sigma^{\prime \prime}} \sum_{\boldsymbol{k}^{\prime \prime \prime}, \sigma^{\prime \prime \prime}} \delta_{\sigma, \sigma^{\prime \prime}} \delta_{\sigma^{\prime}, \sigma^{\prime \prime \prime}} \int d \boldsymbol{r} \int d \boldsymbol{r}^{\prime} e^{-i\left(\boldsymbol{k}+\boldsymbol{k}^{\prime}-\boldsymbol{k}^{\prime \prime}-\boldsymbol{k}^{\prime \prime \prime}\right) \cdot \boldsymbol{r}} \\
& \quad \times \frac{e^{i\left(\boldsymbol{k}^{\prime}-\boldsymbol{k}^{\prime \prime \prime}\right) \cdot\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}\right)} e^{-\mu\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|}}{\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|} a_{\boldsymbol{k} \sigma}^{\dagger} a_{\boldsymbol{k}^{\prime} \sigma^{\prime}}^{\dagger} a_{\boldsymbol{k}^{\prime \prime \prime} \sigma^{\prime \prime \prime}} a_{\boldsymbol{k}^{\prime \prime} \sigma^{\prime \prime}} . \tag{1.134}
\end{align*}
$$

If we again treat $\boldsymbol{r}$ and $\boldsymbol{r}-\boldsymbol{r}^{\prime}$ as independent variables, the integrations may be carried out separately to give

$$
\begin{align*}
& \frac{e^{2}}{2} \frac{1}{V} \sum_{\boldsymbol{k}, \sigma} \sum_{\boldsymbol{k}^{\prime}, \sigma^{\prime}} \sum_{\boldsymbol{k}^{\prime \prime}, \sigma^{\prime \prime}} \sum_{\boldsymbol{k}^{\prime \prime \prime}, \sigma^{\prime \prime \prime}} \delta_{\sigma, \sigma^{\prime \prime \prime}} \delta_{\sigma^{\prime}, \sigma^{\prime \prime \prime}} \Delta\left(\boldsymbol{k}+\boldsymbol{k}^{\prime}-\boldsymbol{k}^{\prime \prime}-\boldsymbol{k}^{\prime \prime \prime}\right) \\
& \times \frac{4 \pi}{\left(\boldsymbol{k}^{\prime}-\boldsymbol{k}^{\prime \prime \prime}\right)^{2}+\mu^{2}} a_{\boldsymbol{k} \sigma}^{\dagger} a_{\boldsymbol{k}^{\prime} \sigma^{\prime}}^{\dagger} a_{\boldsymbol{k}^{\prime \prime \prime} \sigma^{\prime \prime \prime}} a_{\boldsymbol{k}^{\prime \prime} \sigma^{\prime \prime}} . \tag{1.135}
\end{align*}
$$

If we define $\boldsymbol{k}^{\prime}-\boldsymbol{k}^{\prime \prime \prime} \equiv \boldsymbol{q}$ and collect all the terms, we obtain the total secondquantized Hamiltonian,

$$
\begin{align*}
\mathcal{H}= & \sum_{\boldsymbol{k} \sigma} \frac{\hbar^{2} k^{2}}{2 m} a_{\boldsymbol{k} \sigma}^{\dagger} a_{\boldsymbol{k} \sigma}+\frac{e^{2}}{2 V} \sum_{\boldsymbol{k}} \sum_{\boldsymbol{k}^{\prime}} \sum_{\boldsymbol{q}} \sum_{\sigma, \sigma^{\prime}} \frac{4 \pi}{\boldsymbol{q}^{2}+\mu^{2}} \\
& \times a_{\boldsymbol{k}-\boldsymbol{q}, \sigma}^{\dagger} a_{\boldsymbol{k}^{\prime}+\boldsymbol{q}, \sigma^{\prime}}^{\dagger} a_{\boldsymbol{k}^{\prime}, \sigma^{\prime}} a_{\boldsymbol{k}, \sigma}-\frac{e^{2} N^{2}}{2 V} \frac{4 \pi}{\mu^{2}} \tag{1.136}
\end{align*}
$$

It is convenient to introduce an equivalent electron radius $\boldsymbol{r}_{0}$ by

$$
\begin{equation*}
\frac{4}{3} \pi r_{0}^{3}=\frac{V}{N} \tag{1.137}
\end{equation*}
$$

This is made dimensionless by dividing it by the Bohr radius $a_{0}=\hbar^{2} / m e^{2}$. We also define $r_{0} / a_{0}=r_{s}$ and $V / r_{0}^{3} \equiv \Omega$. Since 1 Rydberg $=m e^{4} / \hbar^{2}=e^{2} / 2 a_{0}$, the Hamiltonian expressed in Rydbergs is

$$
\begin{align*}
\mathcal{H}= & \frac{1}{r_{s}^{2}} \sum_{\boldsymbol{k}, \sigma}\left(r_{0} \boldsymbol{k}\right)^{2} a_{\boldsymbol{k} \sigma}^{\dagger} a_{\boldsymbol{k}_{\sigma}}+\frac{1}{r_{s} \Omega} \sum_{\boldsymbol{k}, \sigma} \sum_{\boldsymbol{k}^{\prime}, \sigma^{\prime}} \sum_{\boldsymbol{q}} \frac{4 \pi}{r_{0}^{2}\left(\boldsymbol{q}^{2}+\mu^{2}\right)} \\
& \times a_{\boldsymbol{k}-\boldsymbol{q}, \sigma}^{\dagger} a_{\boldsymbol{k}^{\prime}+\boldsymbol{q}, \sigma^{\prime}}^{\dagger} a_{\boldsymbol{k}^{\prime}, \sigma^{\prime}} a_{\boldsymbol{k}, \sigma}-\frac{N^{2}}{r_{s} \Omega} \frac{4 \pi}{\left(r_{0} \mu\right)^{2}} \tag{1.138}
\end{align*}
$$

Notice that the electron-electron interaction for $\boldsymbol{q}=0$ gives a term proportional to $N^{2}$, which cancels the contribution from the positive background,
plus a term proportional to $N$, which vanishes by virtue of the condition $\mu^{-1} \ll L$. Thus we finally have

$$
\mathcal{H}=\sum_{\boldsymbol{k}, \sigma} \varepsilon_{\boldsymbol{k}} a_{\boldsymbol{k}, \sigma}^{\dagger} a_{\boldsymbol{k}, \sigma}+\sum_{\boldsymbol{k}, \sigma} \sum_{\boldsymbol{k}^{\prime}, \sigma^{\prime}} \sum_{\boldsymbol{q} \neq 0} V(\boldsymbol{q}) a_{\boldsymbol{k}-\boldsymbol{q}, \sigma^{\prime}}^{\dagger} a_{\boldsymbol{k}^{\prime}+\boldsymbol{q}, \sigma^{\prime}}^{\dagger} a_{\boldsymbol{k}^{\prime}, \sigma^{\prime}} a_{\boldsymbol{k}, \sigma}, \text { (1.139) }
$$

where $\epsilon_{k} \equiv\left(r_{0} k / r_{s}\right)^{2}$ and $V(q) \equiv 4 \pi /\left[r_{s} \Omega\left(r_{0} q\right)^{2}\right]$.
Aside from its advantages for handling particle statistics, the secondquantization formalism also lends itself readily to graphical interpretation. For example, the interaction term above corresponds to the destruction of two particles in states $(\boldsymbol{k}, \sigma)$ and $\left(\boldsymbol{k}^{\prime}, \sigma\right)$ and the creation of two particles in states $\left(\boldsymbol{k}^{\prime}+\boldsymbol{q}, \sigma^{\prime}\right)$ and $(\boldsymbol{k}-\boldsymbol{q}, \sigma)$. This may be represented as


In general, we shall also have particle-hole interactions which have the form


We shall see that long-range magnetic order may be characterized as a coherent electron-hole state just as superconductivity is characterized as a coherent electron-electron state.

### 1.4.2 Example: The Zeeman Interaction

Finally, let us apply this second quantization prescription to the interaction of an electron spin with a magnetic field $H \cos (\boldsymbol{q} \cdot \boldsymbol{r})$. In the next chapter we shall show that this interaction has the form

$$
\mathcal{H}=\mu_{B} \sigma_{z} H \cos (\boldsymbol{q} \cdot \boldsymbol{r}),
$$

where $\mu_{B}$ is the Bohr magneton and $\sigma_{z}$ the Pauli matrix

$$
\sigma_{z}=\left(\begin{array}{rr}
1 & 0 \\
0 & -1
\end{array}\right) .
$$

In terms of the field operators (1.122) this becomes

$$
\mathcal{H}=\frac{1}{2} \mu_{B} H \sum_{k}\left(a_{k+q, \uparrow}^{\dagger} a_{k \uparrow}-a_{k+q, \downarrow}^{\dagger} a_{k \downarrow}+a_{k-q, \uparrow}^{\dagger} a_{k \uparrow}+a_{k-q, \downarrow}^{\dagger} a_{k \downarrow}\right) .
$$

Since $\mathcal{H}_{0}=0$ in this simple example, $\sigma_{z}(t)=\sigma_{z}$ and the calculation of the longitudinal susceptibility using (1.81) simply involves terms of the form $\left\langle a_{k \uparrow}^{\dagger} a_{k+q \uparrow} a_{k+q, \uparrow}^{\dagger} a_{k \uparrow}\right\rangle$. This has the diagammatic representation


In more complex systems it is convenient to characterize various approximations in terms of their diagrammatic representations.

## Problems

1.1. The current density $j$ associated with a wave function $\psi$ is given by

$$
j=e R e\left(\psi^{*} \frac{\hbar}{i m} \nabla \psi\right)
$$

Assuming a hydrogenic wave function of the form

$$
\psi(r-R)=R_{n \ell}(r-R) Y_{\ell}^{m}(\theta, \varphi)
$$

calculate the magnetic moment from (1.6).
1.2. Consider a two-dimensional harmonic oscillator with the Hamiltonian

$$
\mathcal{H}=\frac{1}{2 m}\left(p_{x}^{2}+m^{2} \omega^{2} x^{2}\right)+\frac{1}{2 m}\left(p_{y}^{2}+m^{2} \omega^{2} y^{2}\right)
$$

Introduce the operators

$$
\begin{aligned}
& a_{\mu}=\left(\frac{m \omega}{2 \hbar}\right)^{\frac{1}{2}} \mu+i(2 m \hbar \omega)^{-\frac{1}{2}} p_{\mu} \\
& a_{\mu}^{\dagger}=\left(\frac{m \omega}{2 \hbar}\right)^{\frac{1}{2}} \mu-i(2 m \hbar \omega)^{-\frac{1}{2}} p_{\mu}, \quad(\mu=x, y)
\end{aligned}
$$

(a) Compute the commutation relation $\left[a_{\mu}, a_{\mu}^{\dagger}\right]$ recalling $\left[\mu, p_{\mu}\right]=i \hbar$.
(b) Express the Hamiltonian in terms of the operators $a_{\mu}, a_{\mu}^{\dagger}$
(c) Let $\left|n_{\mu}\right\rangle$ be an eigenvector of $a_{\mu}^{\dagger} a_{\mu}$ with eigenvalue $n_{\mu}$. The spectrum of these eigenvalues consists of the set of non-negative integers. Sketch the lowest lying eigenvalues of the oscillator indicating any degeneracies.
(d) Treat the second term in (1.25) as a perturbation and calculate its affect on the first excited state.
1.3. If $\chi^{\prime}(\omega)=\frac{1}{1+\omega^{2} \tau^{2}}$ find $\chi^{\prime \prime}(\omega)$ from the relation (1.65).

Hint: The principal value is given by

$$
\begin{aligned}
& \lim _{R \rightarrow \infty}\left[\int_{-R}^{\omega-\epsilon} \frac{\chi^{\prime}}{\omega^{\prime}-\omega} d \omega^{\prime}+\int_{\omega+\epsilon}^{R} \frac{\chi^{\prime}}{\omega^{\prime}-\omega} d \omega^{\prime}\right] \\
& =\oint \frac{\chi^{\prime}}{\omega^{\prime}-\omega} d \omega^{\prime}-\int_{c} \frac{\chi^{\prime}}{\omega^{\prime}-\omega} d \omega^{\prime}-\int_{c^{\prime}} \frac{\chi^{\prime}}{\omega^{\prime}-\omega} d \omega^{\prime}
\end{aligned}
$$

where the contour of integration is shown in the figure on page 31. Show that the form (1.66) gives the same answer.

1.4. Consider a gas of electrons. The particle density is

$$
\rho(\boldsymbol{r})=\sum_{i} \delta\left(\boldsymbol{r}-\boldsymbol{r}_{i}\right) .
$$

The dynamic form factor is defined as

$$
\left.S(\boldsymbol{q}, \omega)=\sum_{n}\left|\langle n| \rho_{\boldsymbol{q}}^{\dagger}\right| 0\right\rangle\left.\right|^{2} \delta\left(\omega-\omega_{n_{0}}\right),
$$

where the states $|n\rangle$ are the eigenstates of the electron system. We shall show later that the scattering of electrons or neutrons from a metal is proportional to this form factor.
(a) Second quantize

$$
\rho_{\boldsymbol{q}}^{\dagger}=\int d^{3} r \rho(\boldsymbol{r}) e^{-i \boldsymbol{q} \cdot \boldsymbol{r}}
$$

in terms of normalized free electron plane wave states.
(b) Evaluate the form factor $S_{0}(\boldsymbol{q}, \omega)$ for a free electron system characterized by a Fermi sphere of radius $k_{F}$.

## The Magnetic Hamiltonian

Most of the magnetic properties that we shall consider arise from electrons. In this chapter we shall develop the Hamiltonian which pertains to the magnetic behavior of a system of electrons. It has been found experimentally that the electron possesses an intrinsic magnetic moment, or spin. The existence of such a moment is a consequence of relativistic considerations. Therefore it is essential that we look for a relativistic description of the motion of an electron. This is given by the Dirac wave equation. We shall limit our discussion of the Dirac equation to the origin of the spin and the form of the spin-orbit interaction (for a more thorough treatment see [6]).

### 2.1 The Dirac Equation

The objective in developing a relativistic quantum theory of the electron is to ensure that space coordinates and time enter the theory symmetrically. There are several ways of doing this. One way is to start with the general wave equation

$$
\begin{equation*}
i \hbar \frac{\partial \psi(\boldsymbol{r}, t)}{\partial t}=\mathcal{H} \psi(\boldsymbol{r}, t) \tag{2.1}
\end{equation*}
$$

Since the first derivative with respect to time enters on the left, the Hamiltonian must contain a linear space derivative, that is, the Hamiltonian must be linear in the momentum, $\boldsymbol{p}=-i \hbar \boldsymbol{\nabla}$. Thus we assume that the Hamiltonian has the form

$$
\begin{equation*}
\mathcal{H}=c \boldsymbol{\alpha} \cdot \boldsymbol{p}+\beta m c^{2} \tag{2.2}
\end{equation*}
$$

where $\alpha$ and $\beta$ are arbitrary coefficients. By imposing certain requirements on the solutions of (2.1), such as that it gives the correct energy-momentum relation $E^{2}=p^{2} c^{2}+m^{2} c^{4}$ we obtain conditions on the quantities $\boldsymbol{\alpha}$ and $\beta$. These conditions may be satisfied by the $4 \times 4$ representations

$$
\beta=\left[\begin{array}{rr}
\mathbf{1} & 0  \tag{2.3}\\
0 & -\mathbf{1}
\end{array}\right] \quad \text { and } \quad \alpha=\left[\begin{array}{cc}
0 & \boldsymbol{\sigma} \\
\boldsymbol{\sigma} & 0
\end{array}\right]
$$

where the $\sigma_{i}$ are the Pauli matrices

$$
\sigma_{x}=\left[\begin{array}{ll}
0 & 1  \tag{2.4}\\
1 & 0
\end{array}\right], \quad \sigma_{y}=\left[\begin{array}{rr}
0 & -i \\
i & 0
\end{array}\right], \quad \sigma_{z}=\left[\begin{array}{rr}
1 & 0 \\
0 & -1
\end{array}\right], \quad \mathbf{1}=\left[\begin{array}{ll}
1 & 0 \\
0 & 1
\end{array}\right] .
$$

Thus the wave function $\psi$ must be a four-component object. Two of the components correspond to positive-energy solutions and the other two correspond to negative-energy solutions. Holes in the negative-energy spectrum correspond to positrons and require energies of the order of $m c^{2}$ for their production.

From a Lagrangian formulation we find that the effect of an external electromagnetic field described by the vector potential $\boldsymbol{A}$ and the scalar potential $\phi$ may be included by making the substitutions $\boldsymbol{p} \rightarrow \boldsymbol{p}-(e / c) \boldsymbol{A}$ and adding $e \phi$ to the Hamiltonian. Thus the Dirac equation becomes

$$
\begin{equation*}
i \hbar \frac{\partial \psi}{\partial t}=\left[c \boldsymbol{\alpha} \cdot\left(\boldsymbol{p}-\frac{e}{c} \boldsymbol{A}\right)+\beta m c^{2}+e \phi\right] \psi . \tag{2.5}
\end{equation*}
$$

Since the energies encountered in magnetic phenomena are much smaller than $m c^{2}$, it is convenient to decouple the positive- and negative-energy solutions. This is accomplished by a canonical transformation due to Foldy and Wouthuysen [7]. The resulting Hamiltonian associated with the positive-energy solutions has the form

$$
\begin{align*}
\mathcal{H}= & {\left[m c^{2}+\frac{1}{2 m}\left(\boldsymbol{p}-\frac{e}{c} \boldsymbol{A}\right)^{2}-\frac{p^{4}}{8 m^{3} c^{2}}\right]+e \phi-\frac{e \hbar}{2 m c} \boldsymbol{\sigma} \cdot \boldsymbol{H} } \\
& -i \frac{e \hbar^{2}}{8 m^{2} c^{2}} \boldsymbol{\sigma} \cdot \boldsymbol{\nabla} \times \boldsymbol{E}-\frac{e \hbar}{4 m^{2} c^{2}} \boldsymbol{\sigma} \cdot \boldsymbol{E} \times \boldsymbol{p}-\frac{e \hbar^{2}}{8 m^{2} c^{2}} \boldsymbol{\nabla} \cdot \boldsymbol{E} . \tag{2.6}
\end{align*}
$$

The interesting terms in this Hamiltonian are the last four. The term

$$
-(e \hbar / 2 m c) \boldsymbol{\sigma} \cdot \boldsymbol{H}
$$

corresponds to the interaction of the intrinsic spin of the electron with the external field $\boldsymbol{H}$. The next two terms are spin-orbit terms. In a stationary vector potential $\boldsymbol{\nabla} \times \boldsymbol{E}=0$. And, if the scalar potential, $V(r)$, is spherically symmetric,

$$
\boldsymbol{\sigma} \cdot \boldsymbol{E} \times \boldsymbol{p}=-\frac{1}{r} \frac{\partial V}{\partial r} \boldsymbol{\sigma} \cdot \boldsymbol{r} \times \boldsymbol{p}=-\frac{\hbar}{r} \frac{\partial V}{\partial r} \boldsymbol{\sigma} \cdot \boldsymbol{l}
$$

where $\hbar \boldsymbol{l}=\boldsymbol{r} \times \boldsymbol{p}$. Thus, the spin-orbit terms reduce to

$$
\begin{equation*}
\frac{e \hbar^{2}}{4 m^{2} c^{2}} \frac{1}{r} \frac{\partial V}{\partial r} \boldsymbol{\sigma} \cdot \boldsymbol{l} \tag{2.7}
\end{equation*}
$$

This is what would be expected for an electron spin interacting with the field produced by its orbital motion, except that it is reduced by a factor
of $\frac{1}{2}$ due to relativistic kinematics, also known as the Thomas precession. The last term in (2.6), the so-called Darwin term, represents a correction to the Coulomb interaction due to fluctuations (zitterbewegung) in the electron position arising from the presence of the negative-energy component in the wave function.

The term $p^{4} / 8 m^{3} c^{2}$ in (2.6) is very small, and along with the Darwin term, it may be neglected for our purposes. If we define the zero of energy as the rest-mass energy, the Hamiltonian which governs the magnetic behavior of an electron is

$$
\begin{equation*}
\mathcal{H}=\frac{1}{2 m}\left(\boldsymbol{p}-\frac{e}{c} \boldsymbol{A}\right)^{2}+e \phi-\frac{e \hbar}{2 m c} \boldsymbol{\sigma} \cdot \boldsymbol{H}+\zeta \boldsymbol{l} \cdot \boldsymbol{\sigma} \tag{2.8}
\end{equation*}
$$

where we have introduced the spin-orbit parameter

$$
\zeta=\frac{e \hbar^{2}}{4 m^{2} c^{2}} \frac{1}{r} \frac{\partial V}{\partial r}
$$

The wave functions associated with (2.8) have two components. These two component functions transform differently under rotations in 3-dimensional space, as we shall see below, than vectors. They are called spinors.

### 2.2 Sources of Fields

In developing the general Hamiltonian for a single electron we found that the interaction of an electron with its environment is described by the scalar potential $\phi$ and the vector potential $\boldsymbol{A}$. Both these potentials are functions of the position of the electron under consideration as well as of the coordinates and momenta of any other particles in the system, that is,

$$
\phi\left(\boldsymbol{r} ; \boldsymbol{r}_{1}, \boldsymbol{r}_{2}, \ldots, \boldsymbol{p}_{1}, \boldsymbol{p}_{2}, \ldots\right) \quad \text { and } \quad \boldsymbol{A}\left(\boldsymbol{r} ; \boldsymbol{r}_{1}, \boldsymbol{r}_{2}, \ldots, \boldsymbol{p}_{1}, \boldsymbol{p}_{2}, \ldots\right) .
$$

In this section we shall investigate the form these potentials take in a crystalline solid. Our objective is to catalog all the interactions that enter into the magnetic properties of solids so that we shall be free to draw on these results later.

### 2.2.1 Uniform External Field

The simplest potentials are those arising from uniform external fields. For an electric field $\boldsymbol{E}$, uniform over all space, the interaction $e \phi$ becomes $-e \boldsymbol{r} \cdot \boldsymbol{E}$, where $e \boldsymbol{r}$ is the electric-dipole-moment operator.

For a uniform magnetic field $\boldsymbol{H}$ the magnetic vector potential is not uniquely defined. However, it is convenient to take $\boldsymbol{A}=\frac{1}{2} \boldsymbol{H} \times \boldsymbol{r}$. In this gauge $\nabla \cdot \boldsymbol{A}=0$. Thus $(\boldsymbol{p}-e \boldsymbol{A} / c)^{2} / 2 m$ becomes

$$
\begin{equation*}
\frac{p^{2}}{2 m}-\frac{e}{2 m c}(\boldsymbol{r} \times \boldsymbol{p}) \cdot \boldsymbol{H}+\frac{e^{2}}{8 m c^{2}}(\boldsymbol{H} \times \boldsymbol{r})^{2} \tag{2.9}
\end{equation*}
$$

The first term is the kinetic-energy term. The second term is a paramagnetic term. Since $\boldsymbol{r} \times \boldsymbol{p}=\hbar \boldsymbol{l}$ is related to the electron's orbital moment $\boldsymbol{\mu}_{l}$, by

$$
\begin{equation*}
\boldsymbol{\mu}_{l}=\frac{e}{2 m c} \boldsymbol{r} \times \boldsymbol{p}=-\frac{|e| \hbar}{2 m c} \boldsymbol{l}=-\mu_{B} \boldsymbol{l} \tag{2.10}
\end{equation*}
$$

where

$$
\mu_{B} \equiv \frac{|e| \hbar}{2 m c}
$$

is the Bohr magneton, this second term may be written as $\mu_{B} \boldsymbol{l} \cdot \boldsymbol{H}$. The third term is a diamagnetic term. When $\boldsymbol{H}$ is in the $z$ direction, that is, $\boldsymbol{H}=H \hat{\boldsymbol{z}}$, then this term reduces to $\left(e^{2} H^{2} / 8 m c^{2}\right)\left(x^{2}+y^{2}\right)$. This gives, for the total Hamiltonian of an electron in a uniform magnetic field,

$$
\begin{equation*}
\mathcal{H}=\frac{p^{2}}{2 m}+\mu_{B}(\boldsymbol{l}+\boldsymbol{\sigma}) \cdot \boldsymbol{H}+\frac{e^{2} H^{2}}{8 m c^{2}} \cdot\left(x^{2}+y^{2}\right)+\zeta \boldsymbol{l} \cdot \boldsymbol{\sigma} \tag{2.11}
\end{equation*}
$$

### 2.2.2 The Electric Quadrupole Field

Let us now look into the potentials the electron sees as it moves around or past a nucleus. If we assume that the electron remains outside the nuclear charge and current distributions, we may expand $\left|\boldsymbol{r}-\boldsymbol{r}_{n}\right|^{-1}$ in spherical harmonics, which results in a multipole expansion.

Let us first consider the charge distribution. If $\rho\left(\boldsymbol{r}_{n}\right)$ is the charge density at a point $\boldsymbol{r}_{n}$ inside the nucleus, the electrostatic potential becomes

$$
\begin{align*}
\phi(\boldsymbol{r}) & =\int d \boldsymbol{r}_{n} \frac{\rho\left(\boldsymbol{r}_{n}\right)}{\left|\boldsymbol{r}-\boldsymbol{r}_{n}\right|} \\
& =4 \pi \sum_{l=0}^{\infty} \sum_{m=-l}^{l} \frac{Y_{l}^{m}(\theta, \varphi)}{(2 l+1) r^{l+1}} \int d \boldsymbol{r}_{n} \rho\left(\boldsymbol{r}_{n}\right) Y_{l}^{m^{*}}\left(\theta_{n}, \varphi_{n}\right) r_{n}^{l} \tag{2.12}
\end{align*}
$$

where $Y_{l}^{m}(\theta, \varphi)$ is the sperical harmonic (see Table 2.1). Writing out the first few terms explicitly, we have

$$
\begin{align*}
\phi(\boldsymbol{r})= & 4 \pi \frac{Y_{0}^{0}(\theta, \varphi)}{r} \int d \boldsymbol{r}_{n} \rho\left(\boldsymbol{r}_{n}\right) Y_{0}^{0^{*}}\left(\theta_{n}, \varphi_{n}\right) \\
& +4 \pi \sum_{m=-1}^{1} \frac{Y_{1}^{m}(\theta, \varphi)}{3 r^{2}} \int d \boldsymbol{r}_{n} \rho\left(\boldsymbol{r}_{n}\right) r_{n} Y_{1}^{m^{*}}\left(\theta_{n}, \varphi_{n}\right) \\
& +4 \pi \sum_{m=-2}^{2} \frac{Y_{2}^{m}(\theta, \varphi)}{5 r^{3}} \int d \boldsymbol{r}_{n} \rho\left(\boldsymbol{r}_{n}\right) \boldsymbol{r}_{n}^{2} Y_{2}^{m^{*}}\left(\theta_{n}, \varphi_{n}\right)+\ldots \tag{2.13}
\end{align*}
$$

Table 2.1. Spherical Harmonics

| $Y_{0}^{0}$ | $\sqrt{(1 / 4 \pi)}$ | $\sqrt{(1 / 4 \pi)}$ |
| :--- | :---: | :---: |
| $Y_{1}^{-1}$ | $\sqrt{(3 / 8 \pi)} \sin \theta e^{-i \varphi}$ | $\sqrt{(3 / 8 \pi)}(x-i y) / r$ |
| $Y_{1}^{0}$ | $\sqrt{(3 / 4 \pi)} \cos \theta$ | $\sqrt{(3 / 4 \pi)}(z / r)$ |
| $Y_{1}^{1}$ | $-\sqrt{(3 / 8 \pi)} \sin \theta e^{i \varphi}$ | $-\sqrt{(3 / 8 \pi)}(x+i y) / r$ |
| $Y_{2}^{-2}$ | $\sqrt{(15 / 32 \pi)} \sin ^{2} \theta e^{-2 i \varphi}$ | $\sqrt{(15 / 32 \pi)}\left[(x-i y)^{2} / r^{2}\right]$ |
| $Y_{2}^{-1}$ | $\sqrt{(15 / 8 \pi)} \sin \theta \cos \theta e^{-i \varphi}$ | $\sqrt{(15 / 8 \pi)}\left[z(x-i y) / r^{2}\right]$ |
| $Y_{2}^{0}$ | $\sqrt{(5 / 16 \pi)}\left(3 \cos ^{2} \theta-1\right)$ | $\sqrt{(5 / 16 \pi)}\left[\left(3 z^{2}-r^{2}\right) / r^{2}\right]$ |
| $Y_{2}^{1}$ | $-\sqrt{(15 / 8 \pi)} \sin \theta \cos \theta e^{i \varphi}$ | $-\sqrt{(15 / 8 \pi)}\left[z(x+i y) / r^{2}\right]$ |
| $Y_{2}^{2}$ | $\sqrt{(15 / 32 \pi)} \sin ^{2} \theta e^{2 i \varphi}$ | $\sqrt{(15 / 32 \pi)}\left[(x+i y)^{2} / r^{2}\right]$ |

Since $Y_{0}^{0}(\theta, \varphi)=1 / \sqrt{4 \pi}$, the first term becomes

$$
\begin{equation*}
\frac{1}{r} \int d \boldsymbol{r}_{n} \rho\left(\boldsymbol{r}_{n}\right)=\frac{Z e}{r} \tag{2.14}
\end{equation*}
$$

which is just the field arising from a point charge at the origin. We can make use of the spherical-harmonic addition theorem

$$
\begin{equation*}
\frac{4 \pi}{2 l+1} \sum_{m=-l}^{l} Y_{l}^{m^{*}}\left(\theta_{1}, \varphi_{1}\right) Y_{l}^{m}\left(\theta_{2}, \varphi_{2}\right)=P_{l}\left(\cos \theta_{12}\right) \tag{2.15}
\end{equation*}
$$

to write the second term as

$$
\begin{equation*}
\frac{\hat{\boldsymbol{r}}}{r^{2}} \cdot \int d \boldsymbol{r}_{n} \rho\left(\boldsymbol{r}_{n}\right) \boldsymbol{r}_{n} \tag{2.16}
\end{equation*}
$$

The integral is the electric-dipole-moment operator of the nucleus. If the nuclear states have definite parity, the diagonal matrix elements of this operator vanish by symmetry. The third term is the quadrupole term.

Since we shall eventually be interested in computing matrix elements of the quadrupole term, as well as various other similar operators, it is appropriate to digress for a moment to develop a technique known as operator equivalents, for rewriting such operators in a form which greatly facilitates the evaluation of their matrix elements. This technique is based on the transformation properties of these operators.
Operator Equivalents. Suppose we consider a rotation of our coordinate system through some angle $\theta$ about an axis defined by $\hat{\boldsymbol{n}}$. Let this rotation be defined by a linear operator $R$ which rotates any vector $r$ into $R r$. If $\theta$ is regarded as infinitesimally small, then

$$
\begin{equation*}
R \boldsymbol{r}=\boldsymbol{r}+\theta \hat{\boldsymbol{n}} \times \boldsymbol{r} \tag{2.17}
\end{equation*}
$$

Under such a rotation a scalar wave function $\psi(\boldsymbol{r})$ is transformed into a new wave function $\psi^{\prime}(R r)$. If the system is invariant under rotation, then

$$
\begin{equation*}
\psi^{\prime}(R \boldsymbol{r})=\psi(\boldsymbol{r}) \tag{2.18}
\end{equation*}
$$

This change may be characterized by a transformation $U_{R}(\theta)$ defined by

$$
\begin{equation*}
U_{R}(\theta) \psi(\boldsymbol{r})=\psi^{\prime}(\boldsymbol{r}) \tag{2.19}
\end{equation*}
$$

Using (2.18) this becomes

$$
\begin{equation*}
U_{R}(\theta) \psi(\boldsymbol{r})=\psi\left(R^{-1} \boldsymbol{r}\right) \tag{2.20}
\end{equation*}
$$

Expanding the right side,

$$
\begin{aligned}
U_{R}(\theta) \psi(\boldsymbol{r})=\psi(\boldsymbol{r}-\theta \hat{\boldsymbol{n}} \times \boldsymbol{r}) & \simeq \psi(\boldsymbol{r})-(\theta \hat{\boldsymbol{n}} \times \boldsymbol{r}) \cdot \nabla \psi(\boldsymbol{r}) \\
& \simeq \psi(\boldsymbol{r})-\frac{i}{\hbar}(\theta \hat{\boldsymbol{n}} \times \boldsymbol{r}) \cdot \boldsymbol{p} \psi(\boldsymbol{r}) .
\end{aligned}
$$

Therefore

$$
\begin{equation*}
U_{R}(\theta) \simeq 1-i \theta \hat{\boldsymbol{n}} \cdot \boldsymbol{l} \tag{2.21}
\end{equation*}
$$

where $l$ is the orbital angular momentum in units of $\hbar$. For this reason we refer to $l$ as the "generator" of infinitesimal rotations. This argument may be extended to finite rotations with the result

$$
\begin{equation*}
U_{R}(\theta)=\exp (-i \theta \hat{\boldsymbol{n}} \cdot \boldsymbol{l}) \tag{2.22}
\end{equation*}
$$

Since the spinor wave function associated with the Dirac equation is defined with respect to a definite axis, a rotation in ordinary three-dimensional space will also transform the components of this wave function. Rotation in the complex two-dimensional space is described by $2 \times 2$ complex unitary matrices. For example, the matrix for a clockwise rotation of $\theta$ about the $z$-axis is [13], p. 109

$$
\left(\begin{array}{cc}
\cos \frac{\theta}{2}-i \sin \frac{\theta}{2} & 0 \\
0 & \cos \frac{\theta}{2}+i \sin \frac{\theta}{2}
\end{array}\right)=\mathbf{1} \cos \frac{\theta}{2}-i \sigma_{z} \sin \frac{\theta}{2} .
$$

Since $\sigma_{z}^{2 n}=1$ and $\sigma_{z}^{2 n+1}=\sigma_{z}$, where $n$ is an integer, this matrix expression is equivalent to $\exp \left(-\frac{1}{2} i \theta \sigma_{z}\right)$ which may be generalized to

$$
\begin{equation*}
\exp (-i \theta \hat{\boldsymbol{n}} \cdot \boldsymbol{\sigma} / 2) \tag{2.23}
\end{equation*}
$$

Since $\boldsymbol{\sigma} / 2$ is therefore the generator for rotations in spinor space we identify it as the spin angular momentum, $s$. The total angular momentum then becomes

$$
j=l+s
$$

and the transformation generalizes to

$$
\begin{equation*}
U_{R}(\theta)=\exp (-i \theta \hat{\boldsymbol{n}} \cdot \boldsymbol{j}) \tag{2.24}
\end{equation*}
$$

The orbital part, $\boldsymbol{l}$, acts on the $\boldsymbol{r}$-dependence of the wave function while $s$ rearranges the components of the wave function.

For many-electron systems, such as atoms or ions, the total angular momentum is the vector sum of the angular momenta of the individual electrons,

$$
\begin{equation*}
\boldsymbol{L}=\sum_{i} \boldsymbol{l}_{i}, \quad \boldsymbol{S}=\sum_{i} s_{i} \tag{2.25}
\end{equation*}
$$

and $\boldsymbol{J}=\boldsymbol{L}+\boldsymbol{S}$.
Let $|J M\rangle$ be an eigenfunction of $\boldsymbol{J}^{2}$ and $J_{z}$. (Since $\boldsymbol{J}^{2}$ commutes with $J_{z}$ one can form a complete set of common eigenfunctions of $\boldsymbol{J}^{2}$ and $J_{z}$.) Then

$$
\begin{equation*}
U_{R}(\theta)|J M\rangle=\exp (-i \theta \hat{\boldsymbol{n}} \cdot \boldsymbol{J})|J M\rangle \tag{2.26}
\end{equation*}
$$

Inserting the identity in the form

$$
\sum_{M^{\prime}}\left|J M^{\prime}\right\rangle\left\langle J M^{\prime}\right|=1
$$

on the right gives
$U_{R}(\theta)|J M\rangle=\sum_{M^{\prime}}\left\langle J M^{\prime}\right| \exp (-i \theta \hat{\boldsymbol{n}} \cdot \boldsymbol{J})|J M\rangle\left|J M^{\prime}\right\rangle=\sum_{M^{\prime}} D_{M M^{\prime}}^{j}(\alpha \beta \gamma)\left|J M^{\prime}\right\rangle$.
Thus the rotation operator transforms the function $|J M\rangle$ into a linear combination of the states $\left|J M^{\prime}\right\rangle$ whose coefficients are the matrix elements of the rotation operator itself, $D_{M M^{\prime}}^{J}(\alpha \beta \gamma)$, where $\alpha, \beta$, and $\gamma$ are the Euler angles that specify the rotation.

Under the rotation $U_{R}$ an operator $O$ is transformed into $U_{R} O U_{R}^{-1}$. If the operator $O$ consists of $2 J+1$ functions $T_{J M}(M=-J,-J+1, \ldots, J)$, and if it transforms according to

$$
\begin{equation*}
U_{R} T_{J M} U_{R}^{-1}=\sum_{M^{\prime}} D_{M M^{\prime}}^{J}(\alpha \beta \gamma) T_{J M^{\prime}} \tag{2.28}
\end{equation*}
$$

then it is called an irreducible tensor operator of rank $J$. This may seem a rather restrictive definition. However, it turns out that many operators encountered in physical situations are, in fact, tensor operators. For example, a vector is a tensor of rank 1 ; moments of inertia and quadrupole moments are tensors of rank 2. An example of an operator which may not be a tensor is the density operator discussed earlier.

Tensors have their own algebra, including various theorems. One of the most useful of these for our purposes is the Wigner-Eckart theorem. This states
that the matrix element of a tensor operator may be factored into a part which involves the projection quantum numbers and is independent of the tensor itself, and a part not involving the projection quantum numbers, called the reduced matrix element. The first part is, in fact, just the Clebsch-Gordan coefficient encountered in the coupling of angular momenta. Thus we have

$$
\begin{equation*}
\left\langle J^{\prime} M^{\prime}\right| T_{J^{\prime \prime} M^{\prime \prime}}|J M\rangle=C\left(J J^{\prime \prime} J^{\prime} ; M M^{\prime \prime} M^{\prime}\right)\left\langle J^{\prime}\left\|T_{J^{\prime \prime}}\right\| J\right\rangle \tag{2.29}
\end{equation*}
$$

where $C\left(J J^{\prime \prime} J^{\prime} ; M M^{\prime \prime} M^{\prime}\right)$ is the Clebsch-Gordan coefficient and $\left\langle J^{\prime}\left\|T_{J^{\prime \prime}}\right\| J\right\rangle$ is the reduced matrix element. Notice that if $T^{\prime}$ is also a tensor operator of the same rank as $T$, then the matrix elements of $T$ are proportional to those of $T^{\prime}$. This result has immense practical application to our magnetic Hamiltonian.

Let us return now to the quadrupole terms in $\phi(\boldsymbol{r})$. Writing the nuclear charge density as

$$
\begin{equation*}
\rho\left(\boldsymbol{r}_{n}\right)=e \sum_{i} \delta\left(\boldsymbol{r}_{n}-\boldsymbol{r}_{i}\right) \tag{2.30}
\end{equation*}
$$

where $\boldsymbol{r}_{i}$ is the coordinate of a proton, the quadrapole moment $Q_{2}^{M}$ becomes

$$
\begin{equation*}
Q_{2}^{M}=\sqrt{\frac{4 \pi}{5}} \sum_{i} e r_{i}^{2} Y_{2}^{M}\left(\theta_{i}, \varphi_{i}\right) \tag{2.31}
\end{equation*}
$$

Since the quadrupole moment operators $Q_{2}^{M}$ are proportional to the spherical harmonics, they are tensor operators of rank 2 . We can also form a tensor of rank 2 from the components of the total nuclear angular momentum $\boldsymbol{I}$. Thus if

$$
\begin{equation*}
T_{2}^{+1}=Q_{2}^{+1}=\frac{\sqrt{6}}{4} \sum_{i} z_{i}\left(x_{i}+i y_{i}\right) \tag{2.32}
\end{equation*}
$$

this suggests that we form

$$
\begin{equation*}
\left(T^{\prime}\right)_{2}^{+1}=\frac{\sqrt{6}}{4}\left(I_{z} I^{+}+I^{+} I_{z}\right) \tag{2.33}
\end{equation*}
$$

Notice that (2.33) is written in the symmetrized form. The reason for this is that the coordinates entering (2.32) commute with each other, whereas the angular momenta do not. Therefore, in order to preserve this symmetry, we must symmetrize the operator equivalent. By the Wigner-Eckart theorem, the matrix elements of these two operators must be proportional. Thus

$$
\begin{equation*}
\left\langle I M^{\prime}\right| Q_{2}^{+1}|I M\rangle=\alpha\left\langle I M^{\prime}\right| \frac{\sqrt{6}}{4}\left(I_{z} I^{+}+I^{+} I_{z}\right)|I M\rangle \tag{2.34}
\end{equation*}
$$

or,

$$
\begin{equation*}
\left\langle I M^{\prime}\right| Q_{2}^{+1}|I M\rangle=\alpha \frac{\sqrt{6}}{4}(2 M+1) \sqrt{(I-M)(I+M+1)} \delta_{M^{\prime}, M+1} \tag{2.35}
\end{equation*}
$$

It is customary to define the particular matrix element $\langle I I| Q_{2}^{0}|I I\rangle$ as $e Q$. The proportionality constant $\alpha$ then becomes $e Q / I(2 I-1)$.

As long as we remain within a manifold in which $I$ is a good quantum number, we may also equate the operators themselves. Thus

$$
\begin{equation*}
Q_{2}^{+1}=\frac{e Q}{I(2 I-1)} \frac{\sqrt{6}}{4}\left(I_{z} I^{+}+I^{+} I_{z}\right) \tag{2.36}
\end{equation*}
$$

with similar expressions for the other operators. The corresponding term in the quadrupole potential is therefore

$$
\begin{equation*}
-\sqrt{\frac{4 \pi}{5}} \frac{Y_{2}^{-1}}{r^{3}} \frac{e Q}{I(2 I-1)} \frac{\sqrt{6}}{4}\left(I_{z} I^{+}+I^{+} I_{z}\right) . \tag{2.37}
\end{equation*}
$$

It is obvious that we could now write the electron part in terms of the total orbital angular momentum of the electron state $[8,9]$. Thus,

$$
e \phi(\boldsymbol{r})=-\frac{Z e^{2}}{r}+e^{2} Q \xi\left[3(\boldsymbol{l} \cdot \boldsymbol{I})^{2}+3 / 2(\boldsymbol{l} \cdot \boldsymbol{I})-l(l+1) I(I+1)\right]
$$

where $\xi$ is a constant that is proportional to the reduced matrix element of the electronic angular momentum. Notice that an $s$-state electron is not affected by the quadrupole field of the nucleus. The quadrupole field is, in general, small compared with other fields acting on the electron. From the point of view of the nucleus, however, this interaction is very important. If the electron is in a nondegenerate state characterized by the orbital quantum numbers $l, m_{l}$, and the coordinates are chosen to lie along the principal axes of the tensor $l_{\mu} l_{\nu}$, then the nuclear Hamiltonian becomes

$$
\begin{equation*}
\mathcal{H}_{\mathcal{Q}}=\frac{e^{2} q Q}{4 I(2 I-1)}\left[3 I_{z}^{2}-I(I-1)+\frac{1}{2} \eta\left(I_{+}^{2}+I_{-}^{2}\right)\right] \tag{2.38}
\end{equation*}
$$

where

$$
q=\xi\left\langle l_{z}^{2}\right\rangle \quad \text { and } \quad \eta=\frac{\left(\left\langle l_{x}^{2}\right\rangle-\left\langle l_{y}^{2}\right\rangle\right)}{\left\langle l_{z}^{2}\right\rangle}
$$

The same expression also characterizes the interaction with a more general surrounding charge distribution. In this case $q$ is proportional to the electric field gradient produced by this charge distribution.

### 2.2.3 The Magnetic Dipole (Hyperfine) Field

The vector potential arising from the nuclear currents may also be expanded to yield

$$
\begin{align*}
\boldsymbol{A}(\boldsymbol{r})= & \int d \boldsymbol{r}_{n} \frac{\rho\left(\boldsymbol{r}_{n}\right) \boldsymbol{v}\left(\boldsymbol{r}_{n}\right)}{c\left|\boldsymbol{r}-\boldsymbol{r}_{n}\right|} \\
= & \frac{1}{c r} \int d \boldsymbol{r}_{n} \rho\left(\boldsymbol{r}_{n}\right) \boldsymbol{v}\left(\boldsymbol{r}_{n}\right)+\frac{1}{2 c r^{3}} \int d \boldsymbol{r}_{n} \rho\left(\boldsymbol{r}_{n}\right) \\
& \times\left\{\left(\boldsymbol{r} \cdot \boldsymbol{r}_{n}\right) \boldsymbol{v}\left(\boldsymbol{r}_{n}\right)+\left[\boldsymbol{r} \cdot \boldsymbol{v}\left(\boldsymbol{r}_{n}\right)\right] \boldsymbol{r}_{n}\right\} \\
& -\frac{\boldsymbol{r}}{r^{3}} \times \frac{1}{2 c} \int d \boldsymbol{r}_{n} \rho\left(\boldsymbol{r}_{n}\right)\left[\boldsymbol{r}_{n} \times \boldsymbol{v}\left(\boldsymbol{r}_{n}\right)\right]+\ldots \tag{2.39}
\end{align*}
$$

If the current distribution is stationary with respect to the angular-momentum axis, then the first two terms vanish, leaving only the third. The integral in this term is the nuclear magnetic dipole moment $\boldsymbol{\mu}_{I}$, which is related to the nuclear angular momentum by

$$
\boldsymbol{\mu}_{I}=g_{N} \mu_{N} \boldsymbol{I}=\gamma_{N} \hbar \boldsymbol{I}
$$

where $\mu_{N}$ is the nuclear magneton, $\gamma_{N}$ is the nuclear gyromagnetic ratio, and $g_{N}$ is the nuclear $g$ value.

Notice that the nuclear angular momentum $\boldsymbol{I}$ is in units of $\hbar$. Thus

$$
\begin{equation*}
\boldsymbol{A}(\boldsymbol{r})=\boldsymbol{\mu}_{I} \times \frac{\boldsymbol{r}}{r^{3}} \tag{2.40}
\end{equation*}
$$

Substituting this into the expression

$$
\begin{equation*}
\frac{1}{2 m}\left(\boldsymbol{p}-\frac{e}{c} \boldsymbol{A}\right)^{2}-\frac{e \hbar}{2 m c} \boldsymbol{\sigma} \cdot \boldsymbol{\nabla} \times \boldsymbol{A} \tag{2.41}
\end{equation*}
$$

and recognizing that $\nabla \cdot \boldsymbol{A}(\boldsymbol{r})=0$, we obtain

$$
\begin{equation*}
\frac{\boldsymbol{p}^{2}}{2 m}-\frac{e}{m c} \frac{\left(\boldsymbol{\mu}_{I} \times \boldsymbol{r}\right) \cdot \boldsymbol{p}}{r^{3}}+\frac{e \hbar}{2 m c} \boldsymbol{\sigma} \cdot\left[\frac{\boldsymbol{\mu}_{I}}{r^{3}}-3 \frac{\left(\boldsymbol{r} \cdot \boldsymbol{\mu}_{I}\right) \boldsymbol{r}}{r^{5}}\right] \tag{2.42}
\end{equation*}
$$

Interchanging the dot and cross products in the second term gives the orbital hyperfine interaction

$$
\begin{equation*}
2 \mu_{B} \frac{\boldsymbol{\mu}_{I} \cdot \boldsymbol{\ell}}{r^{3}} \tag{2.43}
\end{equation*}
$$

The last term in (2.42) containing the square brackets is the dipolar hyperfine interaction.

If the electron is in an $s$ state, then the matrix elements of the orbital hyperfine interaction will clearly vanish. Similarly, the matrix elements of the dipolar hyperfine interaction also vanish for an $s$-state electron. However, there is an additional interaction for $s$-state electrons that is not included in expansion (2.39), since it is valid only for charge distributions which vanish at the nucleus. To obtain this additional interaction we consider the matrix element of the hyperfine interaction for an electron orbital state $\psi(\boldsymbol{r})$ :

$$
\begin{align*}
& -\frac{e \hbar}{2 m c} \int_{\text {all space }} d \boldsymbol{r} \psi^{*}(\boldsymbol{r}) \boldsymbol{\sigma} \cdot \boldsymbol{\nabla} \times \boldsymbol{A}(\boldsymbol{r}) \psi(\boldsymbol{r}) \\
& =-\frac{e \hbar}{2 m c} \int_{r<R} d \boldsymbol{r} \psi^{*}(\boldsymbol{r}) \boldsymbol{\sigma} \cdot \boldsymbol{\nabla} \times \boldsymbol{A}(\boldsymbol{r}) \psi(\boldsymbol{r}) \\
& -\frac{e \hbar}{2 m c} \int_{r>R} d \boldsymbol{r} \psi^{*}(\boldsymbol{r}) \boldsymbol{\sigma} \cdot \boldsymbol{\nabla} \times \boldsymbol{A}(\boldsymbol{r}) \psi(\boldsymbol{r}) . \tag{2.44}
\end{align*}
$$

The radius $R$ defines a sphere which encloses the nucleus. Outside this sphere $\boldsymbol{A}(\boldsymbol{r})$ has the form $\left(\boldsymbol{\mu}_{I} \times \boldsymbol{r}\right) / r^{3}$. The second term in (2.44) gives the dipolar hyperfine interaction derived previously. The first term is the additional interaction, which may be rewritten as

$$
\begin{equation*}
-\frac{e \hbar}{2 m c} \int_{r<R} d \boldsymbol{r} \nabla \cdot(\boldsymbol{A} \times \boldsymbol{\sigma})|\psi(\boldsymbol{r})|^{2}=-\frac{e \hbar}{2 m c} \boldsymbol{\sigma} \cdot \int d \boldsymbol{S} \times \boldsymbol{A}|\psi(\boldsymbol{r})|^{2} . \tag{2.45}
\end{equation*}
$$

Because the sphere of integration has been chosen to lie outside the nucleus, $\boldsymbol{A}(\boldsymbol{r})$ has the form $\left(\boldsymbol{\mu}_{I} \times \boldsymbol{r}\right) / R^{3}$. Since $\psi(\boldsymbol{r})$ is essentially constant over this surface and is equal to $\psi(0)$, the interaction becomes

$$
\begin{align*}
-\frac{e \hbar}{2 m c} \boldsymbol{\sigma} \cdot \int \frac{\boldsymbol{r} \times\left(\boldsymbol{\mu}_{I} \times \boldsymbol{r}\right)}{R^{2}} d \Omega|\psi(0)|^{2} & =-\frac{8 \pi}{3} \frac{e \hbar}{2 m c} \boldsymbol{\sigma} \cdot \boldsymbol{\mu}_{I}|\psi(0)|^{2} \\
& =\frac{16 \pi}{3} g_{N} \mu_{B} \mu_{N} \boldsymbol{I} \cdot \boldsymbol{\sigma}|\psi(0)|^{2} \tag{2.46}
\end{align*}
$$

This is the contact hyperfine interaction, often written as the operator

$$
(8 \pi / 3) g_{N} \mu_{B} \mu_{N} \boldsymbol{I} \cdot \boldsymbol{\sigma} \delta(\boldsymbol{r}) .
$$

Combining these results gives us the total hyperfine interaction,

$$
\begin{align*}
\mathcal{H}_{\text {hyper }}= & 2 g_{N} \mu_{B} \mu_{N} \frac{\boldsymbol{l} \cdot \boldsymbol{I}}{r^{3}}-g_{N} \mu_{B} \mu_{N} \boldsymbol{\sigma} \cdot\left[\frac{\boldsymbol{I}}{r^{3}}-3 \frac{(\boldsymbol{r} \cdot \boldsymbol{I}) \boldsymbol{r}}{r^{5}}\right] \\
& +\frac{8 \pi}{3} g_{N} \mu_{B} \mu_{N} \boldsymbol{\sigma} \cdot \boldsymbol{I} \delta(\boldsymbol{r}) \tag{2.47}
\end{align*}
$$

The Hamiltonian (2.11) plus the interactions (2.38), (2.47) determine the behavior of a single electron in the presence of a nucleus.

### 2.2.4 Other Electrons on the Same Ion

Let us now consider the effect of other electrons. One of the most important sources of the electric field felt by an ionic electron is the Coulomb field arising from the other electrons on the same ion,

$$
\begin{equation*}
\phi(\boldsymbol{r})=\sum_{i} \frac{e}{\left|\boldsymbol{r}-\boldsymbol{r}_{i}\right|} . \tag{2.48}
\end{equation*}
$$

In ionic materials this interaction leads to the term levels (the determination of these many-electron states in terms of their Coulomb integrals is discussed in [10]). In itinerant-electron materials it is often assumed that the electrons experience a Coulomb repulsion only if they both happen to be in the same ionic cell. We shall consider the corresponding Hamiltonian for this situation later.

### 2.2.5 Crystalline Electric Fields

The Coulomb interactions between each electron and all the charges external to the ion are described by the electrostatic potential $V(\boldsymbol{r})$. In the case of irongroup ions the magnetic electrons (the $3 d$ electrons) are outermost and hence are strongly affected by such a potential. In the case of rare-earth ions the magnetic $4 f$ electrons are shielded by the $5 s^{2} 5 p^{6}$ shells and are less affected.

Since the charge distribution associated with neighboring ions may overlap that of the electron in question, the full treatment of this problem is very complex. The external charge distributions of these neighboring ions are called ligands, and their effects are computed by means of ligand field theory [11]. However, for our purposes, it will be sufficient to treat the neighboring ions as point charges; the problem may then be handled by crystal field theory. The advantage of using point charges is that $V(\boldsymbol{r})$ satisfies Laplace's equation and may be expanded in spherical harmonics as

$$
\begin{equation*}
V(r, \theta, \varphi)=\sum_{L^{\prime}} \sum_{M^{\prime}} A_{L^{\prime}}^{M^{\prime}} r^{L^{\prime}} Y_{L^{\prime}}^{M^{\prime}}(\theta, \varphi) \tag{2.49}
\end{equation*}
$$

The number of terms that need be considered is greatly reduced, for the following reasons. Suppose we consider an iron-group ion in a crystal field. Then we shall eventually be interested in matrix elements of the form $\int \chi^{*} V \psi d \tau$, where $\chi$ and $\psi$ are $d$-electron wave functions. Since the density $\chi^{*} \psi$, when expanded in spherical harmonics will not contain terms with $L^{\prime}>4$, the integrals with $L^{\prime}>4$ will vanish by orthogonality of the spherical harmonics. Similarly, the integral vanishes for all terms in $V$ which have $L^{\prime}$ odd. The term for $L^{\prime}=0$ is usually dropped because it is an additive constant. If we are considering several $3 d$ electrons within a term, then $L_{\max }^{\prime}$ is determined by the $L$ value of this term (for example, $L^{\prime} \leq 6$ for an $F$-state ion, i.e., $L^{\prime} \leq 2 L$ ).

The potential energy of a charge $q^{\prime}$ at $(r, \theta, \varphi)$, in a potential due to charges $q$ at a distance $d$ from the origin and arranged in a cubic coordination, is

$$
\begin{align*}
V_{c}(r, \theta, \varphi)= & D_{4}^{\prime}\left\{Y_{4}^{0}(\theta, \varphi)+\sqrt{\frac{5}{14}}\left[Y_{4}^{4}(\theta, \varphi)+Y_{4}^{-4}(\theta, \varphi)\right]\right\} \\
& +D_{6}^{\prime}\left\{Y_{6}^{0}(\theta, \varphi)-\sqrt{\frac{7}{2}}\left[Y_{6}^{4}(\theta, \varphi)+Y_{6}^{-4}(\theta, \varphi)\right]\right\} \tag{2.50}
\end{align*}
$$

where, for example, $D_{4}^{\prime}=+\frac{7}{3} \sqrt{\pi} q^{\prime} r^{4} / d^{5}$ for sixfold coordination. The coefficients in such expansions have been tabulated by Hutchings [12]. The potential may also be expressed in terms of cartesian coordinates (see Table 2.1). Thus the above potential may be written as

$$
\begin{align*}
V_{c}(x, y, z)= & C_{4}\left[\left(x^{4}+y^{4}+z^{4}\right)-\frac{3}{5} r^{4}\right]+C_{6}\left[\left(x^{6}+y^{6}+z^{6}\right)\right.  \tag{2.51}\\
& \left.+\frac{15}{4}\left(x^{2} y^{4}+x^{2} z^{4}+y^{2} x^{4}+y^{2} z^{4}+z^{2} x^{4}+z^{2} y^{4}\right)-\frac{15}{14} r^{6}\right]
\end{align*}
$$

where $C_{4}=+\frac{35}{4} q q^{\prime} / d^{5}$ for sixfold coordination.
We are now faced with the problem of calculating the matrix elements of this potential. This is easily accomplished by the operator-equivalent method, which makes use of the fact that the matrix elements of operators involving $x, y$, and $z$ within a given $L$ or $J$ manifold are proportional to those of $L_{x}, L_{y}$, and $L_{z}$ or $J_{x}, J_{y}$, and $J_{z}$. As pointed out earlier, the fact that the angularmomentum operators do not commute necessitates some care in constructing the operator equivalents. Fortunately there are tables for these (a good source is [12]). For example, within a manifold where $L$ is constant the sum of the potential energies of all the electrons contributing to $L$ is

$$
\begin{align*}
& \sum\left(x^{4}+y^{4}+z^{4}-\frac{3}{5} r^{4}\right) \\
& \Rightarrow \frac{\beta \overline{r^{4}}}{8}\left[35 L_{z}^{4}-30 L(L+1) L_{z}^{2}+25 L_{z}^{2}-6 L(L+1)+3 L^{2}(L+1)^{2}\right] \\
& \quad+\frac{\beta \overline{r^{4}}}{8}\left[\left(L^{+}\right)^{4}+\left(L^{-}\right)^{4}\right] \equiv \frac{\beta \overline{r^{4}}}{20} O_{4}^{0}+\frac{\beta \overline{r^{4}}}{4} O_{4}^{4}=B_{4}^{0} O_{4}^{0}+B_{4}^{4} O_{4}^{4} \tag{2.52}
\end{align*}
$$

where $\overline{r^{4}}$ is the average value of the fourth power of the electron radius. The operators $O_{n}^{m}$ appear frequently in the literature. The ground state $\beta$ is a constant which depends on the term; for a ${ }^{2} D$ or a ${ }^{5} D$ term $\beta=\frac{2}{63}$.

Consider a single $3 d$ electron. This has the term ${ }^{2} D$, which is fivefold orbitally degenerate, with states ${ }^{2} D\left(L_{z}, S_{z}\right)$. The matrix elements of $V_{c}$ are [12]

$$
\frac{\beta \overline{r^{4}}}{20}\left[\begin{array}{c}
{ }^{2} D(2)^{2} D(1)^{2} D(0)^{2} D(-1)^{2} D(-2) \\
{\left[\begin{array}{rrrrr}
12 & 0 & 0 & 0 & 60 \\
0 & -48 & 0 & 0 & 0 \\
0 & 0 & 72 & 0 & 0 \\
0 & 0 & 0 & -48 & 0 \\
60 & 0 & 0 & 0 & 12
\end{array}\right] .} \tag{2.53}
\end{array}\right.
$$

The eigenvalues and eigenvectors are easily found to be

$$
\begin{aligned}
& \text { Energy } \\
& \frac{12}{5} \beta \overline{r^{4}}\left\{\begin{array}{c}
\text { Eigenfunctions } \\
{ }^{2} D\left(1, S_{z}\right) \\
{ }^{2} D\left(-1, S_{z}\right) \\
\frac{1}{\sqrt{2}}\left[\begin{array}{c}
2 \\
\end{array}\left(2, S_{z}\right)-{ }^{2} D\left(-2, S_{z}\right)\right]
\end{array}\right. \\
& -\frac{18}{5} \beta \overline{r^{4}}\left\{\begin{array}{c}
{ }^{2} D\left(0, S_{z}\right) \\
\frac{1}{\sqrt{2}}\left[{ }^{2} D\left(2, S_{z}\right)+{ }^{2} D\left(-2, S_{z}\right)\right]
\end{array}\right.
\end{aligned}
$$

The quantity $6 \beta$ is often written as $\Delta$. Therefore we find that the ${ }^{2} D$ term is split into two states separated by $C_{4} \overline{r^{4}} \Delta$. Notice that $C_{4}$ can be positive or negative, depending on the coordination. This is illustrated in Fig. 2.1.

The nature of such splittings obviously depends on the symmetry of the crystal field. For this reason group theory is a powerful tool in determining the degeneracies associated with various symmetries. Group theory as applied to crystal wave functions is discussed fully elsewhere [13], Chap. 4, but it is worth our while to digress again briefly to introduce some of the group-theory terminology and notation which will enter our discussions from time to time.

Symmetry Representations. The symmetry of a system is generally specified by those operations which leave its physical appearance unchanged. For example, the symmetry operations which leave an equilateral triangle unchanged are listed in Table 2.2. A collection of symmetry operations that satisfies certain conditions is called a group. In order to take advantage of the powerful


Fig. 2.1. Splitting of a $D$ state in a cubic crystal field for (a) sixfold coordination and (b) eightfold coordination

Table 2.2. Symmetry operations associated with an equilateral triangle

$$
\begin{aligned}
E & =\text { identity } \\
C_{2}^{A} & =\text { rotation of } \pi \text { around the A-axis } \\
C_{2}^{B} & =\text { rotation of } \pi \text { around the B-axis } \\
C_{2}^{C} & =\text { rotation of } \pi \text { around the C-axis } \\
C_{3}^{z} & =\text { rotation of } 2 \pi / 3 \text { around the z-axis } \\
\left(C_{3}^{z}\right)^{2} & =\text { rotation of } 4 \pi / 3 \text { around the z-axis }
\end{aligned}
$$

theorems associated with group theory we always work with those symmetry operations which do, in fact, constitute a group. These operations may be specifically represented by matrices which describe how a coordinate point transforms under the particular symmetry operation. Thus, if $\boldsymbol{r}$ represents a rotation and $t$ represents a translation, the most general coordinate transformation is $\boldsymbol{x}^{\prime}=\boldsymbol{r} \boldsymbol{x}+\boldsymbol{t}$. Such a collection of operations is called a space group. The rotational part, obtained by setting $\boldsymbol{t}=0$, itself forms a group, called the point group. When we are dealing with noninteracting ions, the point group is sufficient to characterize the properties of the system. However, for interacting systems the full space group must be employed. Fortunately, since the point groups in a crystal must be compatible with translational symmetry, there are only 32 such groups [13], p. 55. Our equilateral triangle is characterized by the point group labeled $D_{3}$ in the so-called Schöflies notation, or 32 in the "international" notation.

Now, let us consider a function whose form depends on the arrangement of the system. For example, suppose that three protons are located at the vertices of an equilateral triangle. The energy of an electron in such an environment depends on the positions of the protons, but this energy is unchanged under any permutation of the protons. Notice that there are 3!, or six, such permutations. These are just the result of the six symmetry operations which leave the triangle invariant. If a figure is defined by some arrangement of identitical particles, the operations which leave it invariant also leave the interaction energy between these two particles and other particles invariant. Thus it is convenient to introduce a new group, isomorphic to the coordinate-transformations group, in which the group elements are operators which operate on functions rather than on coordinates. These operators are defined by

$$
\begin{equation*}
P_{R} f(\boldsymbol{x}) \equiv f\left(\boldsymbol{r}^{-1} \boldsymbol{x}\right) \tag{2.54}
\end{equation*}
$$

The particular function with which we shall be concerned is the energy in its operator form, the Hamiltonian $\mathcal{H}$. Those symmetry operations which leave the Hamiltonian invariant comprise the "group of the Schrödinger equation".

If $P_{R}$ leaves $\mathcal{H}$ invariant, then it must commute with $\mathcal{H}$. Therefore

$$
\begin{equation*}
P_{R} \mathcal{H} \psi_{n}=\mathcal{H} P_{R} \psi_{n}=E_{n} P_{R} \psi_{n} \tag{2.55}
\end{equation*}
$$

Thus any function $P_{R} \psi_{n}$ obtained by operating on an eigenfunction $\psi_{n}$ with a symmetry operator of the group of the Schrödinger equation will also be an eigenfunction having the same energy. Suppose that the state $n$ is $l_{n}$-fold degnerate. Then the function $P_{R} \psi_{n}$ must be a linear combination of $l_{n}$ orthonormal eigenfunctions, which we shall denote $\psi_{\mu}^{(n)}\left(\mu=1, \ldots, l_{n}\right)$. Therefore

$$
\begin{equation*}
P_{R} \psi_{\mu}^{(n)}=\sum_{\nu=1}^{l} \boldsymbol{\Gamma}^{(n)}(\boldsymbol{r})_{\mu \nu} \psi_{\nu}^{(n)} \tag{2.56}
\end{equation*}
$$

The transformation coefficients constitute a set of matrices which form an irreducible representation of the group of the Schrödinger equation. Furthermore, we see that the $n$th representation is associated with the $n$th eigenstate, and the dimensionality of the representation is equal to the degeneracy of this eigenstate. This representation is irreducible, since there is always an operator in the group that will transform each function into any other function. If this were not true, we could construct smaller sets of states which would, in general, have different eigenvalues, contradicting our original hypothesis.

Because of the relation (2.56), we speak of the $\psi^{(n)}$ as "transforming according to $\Gamma^{(n)}$ ". For this reason energy eigenstates are labeled by their irreducible representations. Also, since the representations are generated from the eigenfunctions, we say that the $l_{n}$ degenerate eigenfunctions $\psi_{\mu}^{(n)}$ form a basis for an $l_{n}$-dimensional representation $\Gamma^{(n)}$ of the group of the Schrödinger equation.

The number and nature of the irreducible representations associated with the various symmetry groups have all been tabulated in what is known as a character table. The character $\chi_{n}(\boldsymbol{r})$ associated with the operation $\boldsymbol{r}$ belonging to the $n$th irreducible representation is merely the trace of the matrix of that representation, that is,

$$
\begin{equation*}
\chi_{n}(\boldsymbol{r})=\sum_{\mu} \Gamma^{(n)}(\boldsymbol{r})_{\mu \mu} \tag{2.57}
\end{equation*}
$$

One of the powerful features of group theory is that it enables us to determine the irreducible representations and all their characters without ever having to know specifically the basis functions. The character table for the equilateraltriangle symmetry group $D_{3}$ is given in Table 2.3. To see what this character table implies, let us suppose that we have a single electron, bound, say, to some ionic core giving rise to certain eigenstates. Since this system has complete rotational symmetry, these states are labeled by the familiar $s, p, d$, etc. Let us surround the system by three protons located at the vertices of an equilateral triangle. The symmetry of this system is $D_{3}$. The character table for $D_{3}$ tells us that the eigenfunctions of the electron are now labeled by the irreducible

Table 2.3. Character table for the point group $D_{3}$

| Symmetry Group | Operations |  |  |
| :---: | :---: | :---: | :---: |
| $D_{3}$ | $E$ | $2 C_{3}$ | $3 C_{3}^{\prime}$ |


| Irreducible |  |  |  |
| :---: | :---: | ---: | ---: |
| representations | Characters |  |  |
| $A_{1}$ | 1 | 1 | 1 |
| $A_{2}$ | 1 | 1 | -1 |
| $E$ | 2 | -1 | 0 |

representations $A_{1}, A_{2}$, or $E$. The character associated with the identity operation, $E$, tells us the degeneracy of the various representations. For example, $A_{1}$ and $A_{2}$ are nondegenerate states, and $E$ is doubly degenerate.

Exactly how the original states decompose into the new types of states depends on the original states themselves and on the symmetry group characterizing the environment. Fortunately, such decompositions have been tabulated for a great number of situations. For example, in Fig. 2.1 we saw that a $D$ state, when exposed to a cubic crystal field, splits into a doublet labeled by $E$ and a triplet labeled by $T_{2}$. Group theory, however, does not tell us the ordering of the states or their relative separations. Such specific information can be obtained only by doing a calculation, as we did at the beginning of this section.

Quenching. At this point it is convenient to introduce a general property of angular momentum. This might be stated as a theorem:

The matrix element of the orbital angular momentum between non-degenerate states has an arbitrary phase. In particular, it may be pure real or pure imaginary.
To prove this let us consider the time-reversal operator $T$ acting on a state $\psi$ [13], p. 141. If we neglect the spin, then $T \psi=\psi^{*}$. Furthermore, if the Hamiltonian of the system is Hermitian, then $\psi^{*}$ has the same eigenvalue as $\psi$, but if $\psi$ is nondegenerate, then $\psi$ and $\psi^{*}$ must be linearly dependent. That is, $\psi^{*}=c \psi$, where $c$ is a coefficient of proportionality. Operating on this relation with $T$ gives $\psi=|c|^{2} \psi$ which requires that $|c|^{2}=1$ or $c=e^{i \varphi}$, where $\varphi$ is a real quantity.

Now consider the matrix element $\langle n| \boldsymbol{L}|m\rangle$. Inserting the identity operator $T^{-1} T$, we may write this as $\langle n| T^{-1} T \boldsymbol{L} T^{-1} T|m\rangle$. Under time reversal the angular momentum changes sign, $T \boldsymbol{L} T^{-1}=-\boldsymbol{L}$. Also, since $T$ satisfies $\langle n| T^{-1}|m\rangle=\langle T n \mid m\rangle^{*}$, we obtain

$$
\langle n| \boldsymbol{L}|m\rangle=-\exp \left[i\left(\varphi_{n}-\varphi_{m}\right)\right]\langle n| \boldsymbol{L}|m\rangle^{*}
$$

Since the phases are arbitrary we could, for example, choose $\varphi_{n}-\varphi_{m}=0$, in which case this matrix element would be the negative of its complex conjugate,
which would make it pure imaginary. If $\varphi_{n}-\varphi_{m}=\pi / 2$, then it would be pure real.

This theorem has an important corollary:
The expectation value of $\boldsymbol{L}$ for any nondegenerate state is 0 .
In the theorem, if $|m\rangle=|n\rangle$, then $\langle n| \boldsymbol{L}|n\rangle$ must be pure imaginary. But $\langle n| \boldsymbol{L}|n\rangle$ is a physical observable. Therefore it must be 0 .

Thus if the crystal field has sufficiently low symmetry to remove all the orbital degeneracy, then, to lowest order, the orbital angular momentum is 0 , and we say that the crystal field has completely quenched it. For this reason the static susceptibility of iron-group salts is found experimentally to arise predominantly from the spin.

### 2.2.6 Dipole-Dipole Interaction

The magnetic neighbors surrounding a given ion will contribute to the vector potential a term similar to that which we found for the electron-nucleus magnetic coupling, (2.42). If the ions have moments $\boldsymbol{\mu}_{i}$, the dipole-dipole interaction has the form

$$
\begin{equation*}
\mathcal{H}_{\mathrm{dip}}=\sum_{i, j \neq j} \frac{1}{r_{i j}^{3}}\left[\boldsymbol{\mu}_{i} \cdot \boldsymbol{\mu}_{j}-3\left(\boldsymbol{\mu}_{i} \cdot \hat{\boldsymbol{r}}_{i j}\right)\left(\boldsymbol{\mu}_{j} \cdot \hat{\boldsymbol{r}}_{i j}\right)\right] . \tag{2.58}
\end{equation*}
$$

It is convenient to separate this into various terms, the meaning of which will become evident later. Assuming the moments arise from spin, $\boldsymbol{\mu}_{i}=g \mu_{B} \boldsymbol{S}_{i}$, and (2.58) becomes

$$
\begin{align*}
\mathcal{H}_{\mathrm{dip}}= & g^{2} \mu_{B}^{2} \sum_{i>j}\left\{-\frac{3 \cos ^{2} \theta_{i j}-1}{r_{i j}^{3}} S_{i}^{z} S_{j}^{z}\right. \\
& +\frac{3 \cos ^{2} \theta_{i j}-1}{4 r_{i j}^{3}}\left(S_{i}^{+} S_{j}^{-}+S_{i}^{-} S_{j}^{+}\right) \\
& -\frac{3}{2} \frac{\sin \theta_{i j} \cos \theta_{i j} \exp \left(-i \varphi_{i j}\right)}{r_{i j}^{3}}\left(S_{i}^{z} S_{j}^{+}+S_{i}^{+} S_{j}^{z}\right) \\
& -\frac{3}{2} \frac{\sin \theta_{i j} \cos \theta_{i j} \exp \left(-i \varphi_{i j}\right)}{r_{i j}^{3}}\left(S_{i}^{z} S_{j}^{-}+S_{i}^{-} S_{j}^{z}\right) \\
& \left.-\frac{3}{2} \frac{\sin ^{2} \theta_{i j}}{r_{i j}^{3}}\left[\exp \left(-2 i \varphi_{i j}\right) S_{i}^{+} S_{j}^{+}+\exp \left(2 i \varphi_{i j}\right) S_{i}^{-} S_{j}^{-}\right]\right\} \tag{2.59}
\end{align*}
$$

where $\theta_{i j}$ and $\varphi_{i j}$ are the angles that $\boldsymbol{r}_{i j}$ makes with the fixed coordinate system.

### 2.2.7 Direct Exchange

The exchange energy is the contribution to the interaction energy of a system of electrons which arises from the use of antisymmetrized wave functions, as opposed to single products of one-electron wave functions. Under certain conditions the same effect may be achieved with single-product wave functions if an exchange-interaction term is added to the Hamiltonian. This effect was discovered simultaneously and independently by Dirac and Heisenberg in 1926. Since then a great deal of work has been done on this subject, particularly in developing the appropriate Hamiltonian [14]. In this section we shall discuss the origin of exchange and indicate the approximations under which it may be represented by an effective interaction Hamiltonian.

Let us begin by considering two electrons interacting with each other and a fixed positive point charge $Z e$. Let us assume that we know the eigenfunctions of the one-electron Hamiltonian $\mathcal{H}_{0}(\boldsymbol{r}, \boldsymbol{\sigma})$. For the time being let us assume that this does not include the spin-orbit interaction. Then $\mathcal{H}_{0}(\boldsymbol{r}, \boldsymbol{\sigma})=\mathcal{H}_{0}(\boldsymbol{r})$ and we may write the eigenfunctions as products of an orbital function $\varphi_{n}(\boldsymbol{r})$ and a spinor $\eta_{\mu}(\boldsymbol{\sigma})$. We shall consider the modifications introduced by the spin-orbit interaction later.

The two-electron Hamiltonian is

$$
\begin{equation*}
\mathcal{H}=\mathcal{H}_{0}\left(\boldsymbol{r}_{1}\right)+\mathcal{H}_{0}\left(\boldsymbol{r}_{2}\right)+\frac{e^{2}}{\left|\boldsymbol{r}_{1}-\boldsymbol{r}_{2}\right|} \tag{2.60}
\end{equation*}
$$

Let us assume that the electron-electron interaction is, on average, smaller than $\mathcal{H}_{0}$, so that it may be treated by perturbation theory. We must now determine what functions to use as the basis for computing the matrix elements of the electron-electron interaction. The fact that the Hamiltonian without the electron-electron interaction is separable suggests that we try product wave functions. Thus, if electron 1 is in an orbital state $n$ with spin up and electron 2 is in an orbital state $m$, also with spin up, we might try $\varphi_{n}\left(\boldsymbol{r}_{1}\right) \alpha\left(\boldsymbol{\sigma}_{1}\right) \varphi_{m}\left(\boldsymbol{r}_{2}\right) \alpha\left(\boldsymbol{\sigma}_{2}\right)$, where $\alpha$ is the spin-up spinor. However, the Pauli exclusion principle requires that the wave functions be antisymmetric with respect to particle interchanges. This condition may be satisfied by writing the wave function as a normalized Slater determinant. If the single-electron wave functions are orthogonal, the appropriate determinantal wave function is

$$
\frac{1}{\sqrt{2}}\left|\begin{array}{ll}
\varphi_{n}\left(\boldsymbol{r}_{1}\right) \alpha\left(\boldsymbol{\sigma}_{1}\right) & \varphi_{n}\left(\boldsymbol{r}_{2}\right) \alpha\left(\boldsymbol{\sigma}_{2}\right)  \tag{2.61}\\
\varphi_{m}\left(\boldsymbol{r}_{1}\right) \alpha\left(\boldsymbol{\sigma}_{1}\right) & \varphi_{m}\left(\boldsymbol{r}_{2}\right) \alpha\left(\boldsymbol{\sigma}_{2}\right)
\end{array}\right| .
$$

Since there are an infinite number of orbital states, we could construct an infinite number of such Slater determinants. The general wave function would be a linear combination of such determinants. However, if the electron-electron interaction is small, we may neglect this admixture of other orbital states. In particular, let us assume that electron 1 has a low-lying nondegenerate
orbital state $\varphi_{a}$ with energy $E_{a}$ and electron 2 has a similar low-lying nondegenerate orbital state $\varphi_{b}$ with energy $E_{b}$. If both spin functions are up, the determinantal wave function becomes

$$
\psi_{1}=\frac{1}{\sqrt{2}}\left|\begin{array}{l}
\varphi_{a}\left(\boldsymbol{r}_{1}\right) \alpha\left(\boldsymbol{\sigma}_{1}\right) \varphi_{a}\left(\boldsymbol{r}_{2}\right) \alpha\left(\boldsymbol{\sigma}_{2}\right)  \tag{2.62}\\
\varphi_{b}\left(\boldsymbol{r}_{1}\right) \alpha\left(\boldsymbol{\sigma}_{1}\right) \varphi_{b}\left(\boldsymbol{r}_{2}\right) \alpha\left(\boldsymbol{\sigma}_{2}\right)
\end{array}\right|
$$

If the spin function associated with orbital $a$ is down, then

$$
\psi_{2}=\frac{1}{\sqrt{2}}\left|\begin{array}{l}
\varphi_{a}\left(\boldsymbol{r}_{1}\right) \beta\left(\boldsymbol{\sigma}_{1}\right) \varphi_{a}\left(\boldsymbol{r}_{2}\right) \beta\left(\boldsymbol{\sigma}_{2}\right)  \tag{2.63}\\
\varphi_{b}\left(\boldsymbol{r}_{1}\right) \alpha\left(\boldsymbol{\sigma}_{1}\right) \varphi_{b}\left(\boldsymbol{r}_{2}\right) \alpha\left(\boldsymbol{\sigma}_{2}\right)
\end{array}\right|
$$

There are two additional possible spin configurations which lead to wave functions $\psi_{3}$ and $\psi_{4}$. These four functions form a complete orthonormal set and therefore constitute an appropriate bais with which to evaluate the matrix elements of $\mathcal{H}$. The result is

$$
H=\left[\begin{array}{cccc}
E_{a}+E_{b}+K_{a b}-J_{a b} & 0 & 0 & 0  \tag{2.64}\\
0 & E_{a}+E_{b}+K_{a b}-J_{a b} & 0 \\
0 & -J_{a b} & E_{a}+E_{b}+K_{a b} & 0 \\
0 & 0 & 0 & E_{a}+E_{b}+K_{a b}-J_{a b}
\end{array}\right]
$$

where

$$
\begin{equation*}
K_{a b}=\iint d \boldsymbol{r}_{1} d \boldsymbol{r}_{2} \frac{e^{2}}{r_{12}}\left|\varphi_{a}\left(\boldsymbol{r}_{1}\right)\right|^{2}\left|\varphi_{b}\left(\boldsymbol{r}_{2}\right)\right|^{2} \tag{2.65}
\end{equation*}
$$

and

$$
\begin{equation*}
J_{a b}=\iint d \boldsymbol{r}_{1} d \boldsymbol{r}_{2} \varphi_{a}^{*}\left(\boldsymbol{r}_{1}\right) \varphi_{b}^{*}\left(\boldsymbol{r}_{2}\right) \frac{e^{2}}{r_{12}} \varphi_{b}\left(\boldsymbol{r}_{1}\right) \varphi_{a}\left(\boldsymbol{r}_{2}\right) \tag{2.66}
\end{equation*}
$$

Diagonalizing this matrix gives a singlet with energy

$$
\begin{equation*}
E_{s}=E_{a}+E_{b}+K_{a b}+J_{a b} \tag{2.67}
\end{equation*}
$$

and a triplet with energy

$$
\begin{equation*}
E_{t}=E_{a}+E_{b}+K_{a b}-J_{a b} \tag{2.68}
\end{equation*}
$$

Since $J_{a b}$ is the self-energy of the charge distribution $e \varphi_{a}^{*}(\boldsymbol{r}) \varphi_{b}(\boldsymbol{r})$, it is positive definite. Therefore the triplet always has a lower energy than the singlet. This is the origin of Hund's rule, which says that the ground state of an atom has maximum multiplicity.

Dirac noticed that the eigenvalues (2.67), (2.68) could be obtained with a basis consisting only of products of spin functions if an exchange interaction were added to the Hamiltonian. To obtain the form of this effective interaction
term we notice that just as any $2 \times 2$ matrix may be expressed as a linear combination of Pauli matrices plus the unit matrix, any $4 \times 4$ matrix may be written as a quadratic function of direct products of Pauli matrices [13], p. 320. For example, if

$$
\sigma_{1 x}=\left[\begin{array}{ll}
0 & 1  \tag{2.69}\\
1 & 0
\end{array}\right] \quad \text { and } \quad \sigma_{2 x}=\left[\begin{array}{ll}
0 & 1 \\
1 & 0
\end{array}\right]
$$

then

$$
\sigma_{1 x} \otimes \sigma_{2 x}=\left[\begin{array}{llll}
0 & 0 & 0 & 1  \tag{2.70}\\
0 & 0 & 1 & 0 \\
0 & 1 & 0 & 0 \\
1 & 0 & 0 & 0
\end{array}\right]
$$

We are particularly interested in that quadratic form which gives three equal eigenvalues. Such a form is

$$
\boldsymbol{\sigma}_{1} \cdot \boldsymbol{\sigma}_{2}=\left[\begin{array}{rrrr}
1 & 0 & 0 & 0  \tag{2.71}\\
0 & -1 & 2 & 0 \\
0 & 2 & -1 & 0 \\
0 & 0 & 0 & 1
\end{array}\right]
$$

Therefore the Hamiltonian which will produce in a spinor basis the same eigenvalues as (2.52) evaluated in a fully antisymmetrized basis is

$$
\begin{equation*}
\overline{\mathcal{H}}=\frac{1}{4}\left(E_{s}+E_{t}\right)-\frac{1}{4}\left(E_{s}-E_{t}\right) \boldsymbol{\sigma}_{1} \cdot \boldsymbol{\sigma}_{2}=\text { const. }-\frac{1}{4} J \boldsymbol{\sigma}_{1} \cdot \boldsymbol{\sigma}_{2} . \tag{2.72}
\end{equation*}
$$

Thus the exchange interaction, which is a purely electrostatic effect, may be expressed as a spin-spin interaction. The exchange parameter $J$ is $E_{s}-E_{t}$. If $J$ is positive, we say that the interaction is ferromagnetic.

In obtaining the exchange interaction (2.72) we have made two important assumptions. The first was that we could restrict ourselves to a certain subset of nondegenerate orbital states. There is no real justification for this, as the Coulomb interaction does, in fact, couple different orbital states. We shall see this more clearly in our discussion of exchange in the $N$-electron system. The second assumption was that the orbital functions were orthogonal. When we are dealing with wave functions that have a common origin, as in an atom, this is usually the case. However, as soon as we begin talking about electrons centered at different sites the problem becomes very complex.

The hydrogen molecule is perhaps the simplest example of such a twocenter problem. This was first considered by Heitler and London in 1927 [15]. In the limit of infinite separation we shall assume we have two neutral hydrogen atoms. The Hamiltonian for a single hydrogen atom located at $\boldsymbol{r}_{a}$ is

$$
\begin{equation*}
\mathcal{H}_{\infty}(\boldsymbol{r})=-\frac{\hbar^{2} \nabla^{2}}{2 m}-\frac{e^{2}}{\left|\boldsymbol{r}-\boldsymbol{r}_{a}\right|} \tag{2.73}
\end{equation*}
$$

The corresponding orbital eigenfunctions are $\varphi\left(\boldsymbol{r}-\boldsymbol{r}_{a}\right) \equiv a(r)$. The Hamiltonian for the two-proton system is

$$
\begin{align*}
\mathcal{H}= & -\frac{\hbar^{2} \nabla_{1}^{2}}{2 m}-\frac{\hbar^{2} \nabla_{2}^{2}}{2 m}-\frac{e^{2}}{\left|\boldsymbol{r}_{1}-\boldsymbol{r}_{a}\right|}-\frac{e^{2}}{\left|\boldsymbol{r}_{1}-\boldsymbol{r}_{b}\right|}-\frac{e^{2}}{\left|\boldsymbol{r}_{2}-\boldsymbol{r}_{a}\right|}-\frac{e^{2}}{\left|\boldsymbol{r}_{2}-\boldsymbol{r}_{b}\right|} \\
& +\frac{e^{2}}{\left|\boldsymbol{r}_{1}-\boldsymbol{r}_{2}\right|}+\frac{e^{2}}{\left|\boldsymbol{r}_{a}-\boldsymbol{r}_{b}\right|} . \tag{2.74}
\end{align*}
$$

Heitler and London assumed basis functions of the form (2.61) but rather than taking eigenfunctions of noninteracting electrons in the field of two nuclei, they took the eigenfunctions of isolated free atoms. Thus, if both electrons are "up",

$$
\psi_{1}=\frac{1}{\sqrt{2-2 \ell^{2}}}\left|\begin{array}{ll}
a(1) \alpha(1) & a(2) \alpha(2)  \tag{2.75}\\
b(1) \alpha(1) & b(2) \alpha(2)
\end{array}\right|
$$

where $\ell=\int d \boldsymbol{r} a^{*}(r) b(r)$ is the overlap integral. If one spin is "up" and the other "down" there are two Slater determinants

$$
\phi_{1}=\left|\begin{array}{ll}
a(1) \alpha(1) & a(2) \alpha(2)  \tag{2.76}\\
b(1) \beta(1) & b(2) \beta(2)
\end{array}\right|
$$

and

$$
\phi_{2}=\left|\begin{array}{ll}
a(1) \beta(1) & a(2) \beta(2)  \tag{2.77}\\
b(1) \alpha(1) & b(2) \alpha(2)
\end{array}\right|
$$

Due to the overlap, these are not orthogonal, i.e.,

$$
\begin{equation*}
\left\langle\phi_{1} \mid \phi_{2}\right\rangle=-2 \ell^{2} . \tag{2.78}
\end{equation*}
$$

An orthogonalized pair of basis functions is

$$
\begin{align*}
\psi_{2} & =\frac{1}{2 \sqrt{1-\ell^{2}}}\left(\phi_{1}+\phi_{2}\right)  \tag{2.79}\\
\psi_{3} & =\frac{1}{2 \sqrt{1-\ell^{2}}}\left(\phi_{1}-\phi_{2}\right) \tag{2.80}
\end{align*}
$$

The fourth basis function is identical to (2.75) with $\beta$ in place of $\alpha$. In this basis the Hamiltonian matrix is, in fact, diagonal:

$$
H=\left(\begin{array}{cccc}
E_{t} & 0 & 0 & 0  \tag{2.81}\\
0 & E_{t} & 0 & 0 \\
0 & 0 & E_{s} & 0 \\
0 & 0 & 0 & E_{t}
\end{array}\right)
$$

where

$$
\begin{align*}
& E_{t}=E_{a}^{0}+E_{b}^{0}+\frac{e^{2}}{\left|\boldsymbol{r}_{a}-\boldsymbol{r}_{b}\right|}-\frac{K-\Delta_{a}-\Delta_{b}-2 \ell \Delta_{a b}-J}{1-\ell^{2}}  \tag{2.82}\\
& E_{s}=E_{a}^{0}+E_{b}^{0}+\frac{e^{2}}{\left|\boldsymbol{r}_{a}-\boldsymbol{r}_{b}\right|}+\frac{K-\Delta_{a}-\Delta_{b}-2 \ell \Delta_{a b}+J}{1+\ell^{2}} \tag{2.83}
\end{align*}
$$

Here $\Delta_{a}$ and $\Delta_{b}$ represent shifts in the distant-atom eigenvalues, $E_{a}^{0}$ and $E_{b}^{0}$, respectively, due to the other core. $\Delta_{a b}$ is the interaction of the "overlap charge density", $a(r) b(r)$, with a core, and

$$
\begin{equation*}
K=\iint d \boldsymbol{r}_{1} d \boldsymbol{r}_{2}\left|a\left(r_{1}\right)\right|^{2}\left|b\left(r_{2}\right)\right|^{2} \frac{e^{2}}{\left|\boldsymbol{r}_{1}-\boldsymbol{r}_{2}\right|} \tag{2.84}
\end{equation*}
$$

and

$$
\begin{equation*}
J=\iint d \boldsymbol{r}_{1} d \boldsymbol{r}_{2} a^{*}\left(r_{1}\right) b^{*}\left(r_{2}\right) \frac{e^{2}}{\left|\boldsymbol{r}_{1}-\boldsymbol{r}_{2}\right|} b\left(r_{1}\right) a\left(r_{2}\right) \tag{2.85}
\end{equation*}
$$

The difference between the singlet and the triplet is

$$
\begin{equation*}
E_{s}-E_{t}=-2 \frac{\left(K-\Delta_{a}-\Delta_{b}-2 \ell \Delta_{a b}\right) \ell^{2}-J}{1-\ell^{4}} \tag{2.86}
\end{equation*}
$$

Notice that this may be positive or negative, depending upon the relative sizes of the various parameters. Thus, it is not obvious whether the ground state will be ferromagnetic or antiferromagnetic. Actual evaluation shows that for realistic separations the singlet lies lowest. As the nuclei are brought together, and $\ell$ increases, the denominators in $E_{t}$ and $E_{s}$ cause $E_{t}$ to increase and $E_{s}$ to decrease. Eventually, internuclear repulsion also causes $E_{s}$ to increase:


Equation (2.86) can be evaluated exactly for the case of hydrogenic wave functions. It is found that for very large separations the triplet has lower energy. This cannot be, for, as Herring pointed out, the lowest eigenvalue of a semibounded Sturm-Liouville differential operator, such as (2.74), must be free of nodes. This means it must always be a singlet. This would be a good description of the chemical bond, but would not explain magnetism. The problem arises from the oversimplified nature of the Heitler-London states. The exchange coupling measures the rate at which two identifiable electrons
exchange places by tunneling through the barrier separating them. In the Heitler-London approximation this tunneling is uncorrelated. In reality, however, the two electrons will tend to avoid one another. This reduces the amplitude of the wave function for configurations with both electrons close to the internuclear line. Fortunately, however, (2.85) is a reasonably good approximation for separations generally encountered.

In considering more than two electrons we find that difficulties arise from the nonorthogonality of the wave functions we have been using thus far. When the Heitler-London method is applied to a very large system the nonorthogonality integrals enter the secular equation with high powers and lead to an apparent divergence. This "nonorthogonality catastrophy" is a purely mathematical difficulty [14], and Herring has reviewed various treatments that show that even for large systems the energies and eigenstates are given by the exchange interaction with exchange constants having the same values as for a two-site system.

One approach to the problem of exchange among many sites is to give up our well-defined but nonorthogonal functions and work with functions which are orthogonal. An example of such a set of orthogonal functions are Wannier functions. The Wannier function $\phi_{n \lambda}\left(\boldsymbol{r}-\boldsymbol{r}_{a}\right)$ resembles the $n$th atomic orbital with spin $\lambda$ near the $\alpha$ th lattice site, but it falls off throughout the crystal in such a way that it is orthogonal to similar functions centered at other sites. Since the exchange interaction is essentially a quantum-statistical effect the technique of second quantization discussed in Chap. 1 is very convenient for obtaining the exchange Hamiltonian.

Let us consider $N$ electrons reasonably localized on $N$ lattice sites. The Hamiltonian for such a system is

$$
\begin{equation*}
\mathcal{H}=\sum_{i} \frac{p_{i}^{2}}{2 m}-\sum_{i, a} \frac{Z e^{2}}{\left|\boldsymbol{r}_{i}-\boldsymbol{r}_{a}\right|}+\frac{1}{2} \sum_{i, j} \frac{e^{2}}{\left|\boldsymbol{r}_{i}-\boldsymbol{r}_{j}\right|} . \tag{2.87}
\end{equation*}
$$

In Chap. 1 we found that the prescription for second quantizing such a Hamiltonian entailed introducing a field operator which could be expanded in terms of a complete set of single-particle wave functions. In this case the appropriate set of functions are the Wannier functions. Thus the field operator (1.122) becomes

$$
\begin{equation*}
\psi(\boldsymbol{r})=\sum_{\alpha, n, \lambda} \phi_{n \lambda}\left(\boldsymbol{r}-\boldsymbol{r}_{\alpha}\right) a_{n \lambda}\left(\boldsymbol{r}_{\alpha}\right) \tag{2.88}
\end{equation*}
$$

where $a_{n \lambda}\left(\boldsymbol{r}_{\alpha}\right)$ annihilates an electron in orbital state $n$ and spin state $\lambda$ at the lattice site $\alpha$. The interaction part of the Hamiltonian (2.87) becomes

$$
\begin{align*}
& \frac{1}{2} \sum_{\substack{\alpha_{1}, \alpha_{2}, \alpha_{3}, \alpha_{4} \\
n_{1}, n_{2}, n_{3}, n_{4} \\
\lambda_{1}, \lambda_{2}}}\left\langle\alpha_{1} n_{1} ; \alpha_{2} n_{2}\right| V\left|\alpha_{3} n_{3} ; \alpha_{4} n_{4}\right\rangle \\
& \quad \times a_{n_{1} \lambda_{1}}^{\dagger}\left(\boldsymbol{r}_{\alpha_{1}}\right) a_{n_{2} \lambda_{2}}^{\dagger}\left(\boldsymbol{r}_{\alpha_{2}}\right) a_{n_{4} \lambda_{2}}\left(\boldsymbol{r}_{\alpha_{4}}\right) a_{n_{3} \lambda_{1}}\left(\boldsymbol{r}_{\alpha_{3}}\right) . \tag{2.89}
\end{align*}
$$

Since the Wannier states are localized to within a unit cell, the main contributions to (2.89) arise from those terms in which $\alpha_{3}=\alpha_{1}$ and $\alpha_{4}=\alpha_{2}$ or $\alpha_{3}=\alpha_{2}$ and $\alpha_{4}=\alpha_{1}$. The remaining terms involve various orbital excitations induced by the Coulomb interaction. These lead to off-diagonal exchange. Just as in the two-electron case, we shall restrict each electron to a definite orbital state. That is, we shall keep only those terms in which $n_{3}=n_{1}$ and $n_{4}=n_{2}$ or $n_{3}=n_{2}$ and $n_{4}=n_{1}$. If, for simplicity, we also neglect orbital-transfer terms, in which two electrons interchange orbital states, then (2.89) reduces to

$$
\begin{align*}
& \frac{1}{2} \sum_{\substack{\alpha, \alpha^{\prime} \\
n, n^{\prime} \\
\lambda, \lambda^{\prime}}}\left[\left\langle\alpha, n ; \alpha^{\prime}, n^{\prime}\right| V\left|\alpha, n ; \alpha^{\prime}, n^{\prime}\right\rangle a_{n \lambda}^{\dagger}\left(\boldsymbol{r}_{\alpha}\right) a_{n^{\prime} \lambda^{\prime}}^{\dagger}\left(\boldsymbol{r}_{\alpha^{\prime}}\right) a_{n^{\prime} \lambda^{\prime}}\left(\boldsymbol{r}_{\alpha^{\prime}}\right) a_{n \lambda}\left(R_{\alpha}\right)\right. \\
& \left.+\left\langle\alpha, n ; \alpha^{\prime}, n^{\prime}\right| V\left|\alpha^{\prime}, n^{\prime} ; \alpha, n\right\rangle a_{n \lambda}^{\dagger}\left(\boldsymbol{r}_{\alpha}\right) a_{n^{\prime} \lambda^{\prime}}^{\dagger}\left(\boldsymbol{r}_{\alpha^{\prime}}\right) \alpha_{n, \lambda^{\prime}}\left(\boldsymbol{r}_{\alpha}\right) a_{n^{\prime} \lambda}\left(\boldsymbol{r}_{\alpha^{\prime}}\right)\right] . \tag{2.90}
\end{align*}
$$

The first term is called the direct term and the second is the exchange term. Using the fermion anticommutation relation

$$
\begin{equation*}
\left\{a_{n \lambda}^{\dagger}\left(\boldsymbol{r}_{\alpha}\right), a_{n^{\prime} \lambda^{\prime}}\left(\boldsymbol{r}_{\alpha^{\prime}}\right)\right\}=\delta_{\alpha \alpha^{\prime}} \delta_{n n^{\prime}} \delta_{\lambda \lambda^{\prime}}, \tag{2.91}
\end{equation*}
$$

we may write the exchange term as

$$
\begin{equation*}
-\frac{1}{2} \sum_{\substack{\alpha, \alpha^{\prime} \\ n, n^{\prime} \\ \lambda, \lambda^{\prime}}} J_{n n^{\prime}}\left(\boldsymbol{r}_{\alpha}, \boldsymbol{r}_{\alpha^{\prime}}\right) a_{n \lambda}^{\dagger}\left(\boldsymbol{r}_{\alpha}\right) a_{n \lambda^{\prime}}\left(\boldsymbol{r}_{\alpha}\right) a_{n^{\prime} \lambda^{\prime}}^{\dagger}\left(\boldsymbol{r}_{\alpha^{\prime}}\right) a_{n^{\prime} \lambda}\left(\boldsymbol{r}_{\alpha^{\prime}}\right) . \tag{2.92}
\end{equation*}
$$

When the spin sum is expanded, we obtain four terms. These may be written in a particularly revealing way by noting the following. First of all, if we allow only one electron to occupy each orbital, then

$$
\begin{equation*}
N_{n \uparrow}\left(\boldsymbol{r}_{\alpha}\right)+N_{n \downarrow}\left(\boldsymbol{r}_{\alpha}\right)=1, \tag{2.93}
\end{equation*}
$$

where $N_{n \lambda}\left(\boldsymbol{r}_{\alpha}\right)=a_{n \lambda}^{\dagger}\left(\boldsymbol{r}_{\alpha}\right) a_{n \lambda}\left(\boldsymbol{r}_{\alpha}\right)$ is the number operator associated with the $n$th orbital with spin $\lambda$ at the site $\alpha$. We also have

$$
\begin{equation*}
N_{n \uparrow}\left(\boldsymbol{r}_{\alpha}\right)-N_{n \downarrow}\left(\boldsymbol{r}_{\alpha}\right)=\sigma_{z}\left(\boldsymbol{r}_{\alpha}\right) . \tag{2.94}
\end{equation*}
$$

Combining these two relations gives

$$
\begin{equation*}
N_{n \uparrow}\left(\boldsymbol{r}_{\alpha}\right) N_{n^{\prime} \uparrow}\left(\boldsymbol{r}_{\alpha^{\prime}}\right)+N_{n^{\prime} \downarrow}\left(\boldsymbol{r}_{\alpha}\right) N_{n^{\prime} \downarrow}\left(\boldsymbol{r}_{\alpha^{\prime}}\right)=\frac{1}{2} \sigma_{z}\left(\boldsymbol{r}_{\alpha}\right) \sigma_{z}\left(\boldsymbol{r}_{\alpha^{\prime}}\right)+\frac{1}{2} . \tag{2.95}
\end{equation*}
$$

We also note that

$$
\begin{equation*}
a_{n \uparrow}^{\dagger}\left(\boldsymbol{r}_{\alpha}\right) a_{n \downarrow}\left(\boldsymbol{r}_{\alpha}\right)=\frac{1}{2} \sigma^{+}\left(\boldsymbol{r}_{\alpha}\right) \tag{2.96}
\end{equation*}
$$

and

$$
\begin{equation*}
a_{n \downarrow}^{\dagger}\left(\boldsymbol{r}_{\alpha}\right) a_{n \uparrow}\left(\boldsymbol{r}_{\alpha}\right)=\frac{1}{2} \sigma^{-}\left(\boldsymbol{r}_{\alpha}\right) . \tag{2.97}
\end{equation*}
$$

With these results the exchange interaction (2.92) becomes

$$
\begin{equation*}
\sum_{\substack{\alpha \alpha^{\prime} \\ n n^{\prime}}} J_{n n^{\prime}}\left(\boldsymbol{r}_{\alpha}, \boldsymbol{r}_{\alpha^{\prime}}\right)\left[\frac{1}{4}+\frac{1}{4} \boldsymbol{\sigma}\left(\boldsymbol{r}_{\alpha}\right) \cdot \boldsymbol{\sigma}\left(\boldsymbol{r}_{\alpha^{\prime}}\right)\right] . \tag{2.98}
\end{equation*}
$$

This is the many-electron generalization of our earlier result for two electrons. Since the wave functions used in $J_{n n^{\prime}}$ are orthogonal, this exchange is always ferromagnetic. In the next section on superexchange we shall see that when we allow for the fact that an electron can hop onto a neighboring site giving it a double occupancy, the result is an exchange of the form (2.98) but with an antiferromagnetic coupling.

In most practical situations we do not have just $N$ electrons each localized on one of $N$ lattice sites, but rather $N h$ electrons, where $h$ is the number of unpaired electrons on each ion. If these $h$ electrons all have the same exchange integrals with all the other electrons, then the interaction may be expressed in terms of the total ionic spin,

$$
\begin{equation*}
\mathcal{H}_{\mathrm{ex}}=-\sum_{\substack{\alpha, \alpha^{\prime} \\ n, n^{\prime}}} J_{n n^{\prime}}\left(\boldsymbol{r}_{\alpha}, \boldsymbol{r}_{\alpha^{\prime}}\right)\left[\frac{1}{4}+\boldsymbol{S}\left(\boldsymbol{r}_{\alpha}\right) \cdot \boldsymbol{S}\left(\boldsymbol{r}_{\alpha^{\prime}}\right)\right] \tag{2.99}
\end{equation*}
$$

As Van Vleck has pointed out, this form is also valid if the unfilled shells of each ion are half full and the atom is in its state of maximum multiplicity [16]. Such a situation is always true for $S$-state ions but may also arise as a result of quenching by crystal fields. We shall consider an example of this in our discussion on effective exchange. Equation (2.99), usually referred to as the Heisenberg exchange interaction, often forms the starting point for discussions of ferromagnetism or antiferromagnetism in insulators. The fact that it is valid only under certain conditions does not seem to deter its application. In fact, it works surprisingly well, as we shall see in later chapters.

### 2.2.8 Superexchange

The exchange constant in (2.99) involves essentially an eigenfunction of the whole crystal. Needless to say, such a function is difficult to obtain. Let us therefore consider an approach which has proven useful in discussing exhange in insulators. The transition-metal flourides $\mathrm{MnF}_{2}, \mathrm{FeF}_{2}$, and $\mathrm{CoF}_{2}$ are all observed to be antiferromagnets at low temperatures, with crystal structure and spin configuration indicated in Fig. 2.2. This exchange is difficult


Fig. 2.2. Spin configuration of the transition-metal flourides


Fig. 2.3. Schematic representations of one of the intermediate states in superexchange
to understand in terms of direct exchange between the cations because of the intervening flourine anions. A similar situation arises in the case of magnetic oxides. In 1934 Kramers proposed the explanation that the cation wave functions were being strongly admixed with the flourine wave functions, enabling the cations to couple indirectly with each other. Kramers applied perturbation theory to obtain the effective exchange resulting from this mechanism. Let us consider two $\mathrm{Mn}^{2+}$ ions and an intervening $\mathrm{F}^{-}$ion. Because of the overlap of their wave functions, one of the $p$ electrons from the $\mathrm{F}^{-}$hops over to one of the $\mathrm{Mn}^{2+}$ ions. The remaining unpaired $p$ electron on the F then enters into a direct exchange with the other $\mathrm{Mn}^{2+}$ ion. This excited state is illustrated in Fig. 2.3 for the case in which the exchange between the unpaired $p$ electron and the $\mathrm{Mn}^{2+}$ is antiferromagnetic. By using such excited states in a perturbation calculation of the total energy of the system we obtain an effective exchange between the $\mathrm{Mn}^{2+}$ ions. The sign of this exchange depends on the nature of the orbitals involved. However, a number of general features that have evolved through the work of Goodenough [17] and Kanamori [18] enable us to qualitatively predict the nature of the superexchange. Two such features are that the electron transfer can take place only if the cation and anion orbitals are nonorthogonal, and that if the cation-anion orbitals are orthogonal, the direct exchange referred to above is positive (ferromagnetic); otherwise it is negative (antiferromagnetic).

As an example of the application of these rules, let us consider the antiferromagnet $\mathrm{CaMnO}_{3}$. In this material the manganese occurs in the tetravelent state $\mathrm{Mn}^{4+}$, which means that we have three $d$ electrons. The crystal field at
the $\mathrm{Mn}^{4+}$ sites is cubic. The $d$ electrons are strongly affected by this crystal field. In fact, the approximation is often made that the crystal field is stronger than the intraionic Coulomb interaction, so that the latter may be neglected. Then each electron may be considered separately. The effect of a cubic field on the fivefold orbitally degenerate $d$ state of a single electron is to split this state into a threefold degenerate state labeled $t_{2 g}$ and a twofold degenerate state labeled $e_{g}$. This splitting with the associated wave functions is shown in Fig. 2.4. There is, in fact, some intraionic Coulomb interaction, which leads to a Hund's rule coupling of the spins. Therefore, since the $t_{2 g}$ state lies lowest for the particular coordination in $\mathrm{CaMnO}_{3}$, the three electrons will each go into one of the $t_{2 g}$ orbitals with their spins up.

The superexchange in this case involves the $p$ electrons of the $O^{2-}$. The $p$ orbitals are illustrated in Fig. 2.5. Examination of the wave functions in Fig. 2.4, shows that the $p_{z}$ orbital is orthogonal to all the cation orbitals except $d_{x^{2}-y^{2}}$. Therefore, if a $p_{z}$ electron hops over to a $\mathrm{Mn}^{4+}$, it must go into this $e_{g}$ orbital. Since Hund's rule requires that the total spin be a maximum, it is the up spin from the $p_{z}$ orbital that transfers if the spins of the $\mathrm{Mn}^{4+}$ to which it is going are up. The remaining $p_{z}$ down spin, since it is orthogonal to $e_{g}$ orbitals, couples ferromagnetially to the other $\mathrm{Mn}^{4+}$. As a result, we find that the $p_{z}$ orbital has produced a net antiferromagnetic coupling between the cations themselves. It turns out that the contributions from the $p_{x}$ orbitals are much smaller.

The Goodenough-Kanamori rules predict that $180^{\circ}$ superexchange between electronic configurations $d^{3}-d^{5}$ bridged via an oxygen is ferromagnetic.


Fig. 2.4. Representations of the eigenvalues and eigenfunctions of a $d$ electron in a cubic crystal field


Fig. 2.5. Representations of the $p$ orbitals

An example is $\mathrm{Fe}^{3+}$ and $\mathrm{Cr}^{3+}$ introduced alternately on the $B$ sites of the perovskites, $\mathrm{ABO}_{3}$. Attempts to synthesize a ferromagnet with $\mathrm{LaCr}_{0.5} \mathrm{Fe}_{0.5} \mathrm{O}_{3}$ originally failed because the material phase separates into the antiferromagnets $\mathrm{LaCrO}_{3}$ and $\mathrm{LaFeO}_{3}$. However, with new thin film fabrication techniques, such as laser molecular beam epitaxy, it is possible to deposit alternating monolayers of $\mathrm{LaCrO}_{3}$ and $\mathrm{LaFeO}_{3}$. The resulting superlatttice is indeed a ferromagnet with a Curie temperature of 375 K [19].

Anderson [20] reformulated Kramer's theory in an attempt to avoid the high order perturbation expansion, and his results suggest that antiferromagnetism may be more common than Kramer's theory implies. Anderson worked in a basis of ligand wave functions which are a covalent admixture of cation and anion functions. In Anderson's theory magnetism is the result of the interplay between two effects-the hopping of electrons between ligand complexes, characterized by a hopping matrix element $t_{\alpha \alpha^{\prime}}$, and an average Coulomb interaction $U$ between electrons on the same complex. In the limit where the hopping may be treated as a perturbation, Anderson found that the super-exchange interaction has the same spin dependence as (2.99) but with a coefficient $-t_{\alpha \alpha^{\prime}}^{2} / U$.

In recent years chemists have recast superexchange in terms of molecular orbitals. Hay et al. [21] for example, have shown that the exchange interaction between two spin $\frac{1}{2}$ ions can be expressed as

$$
\begin{equation*}
J=J_{a b}-\frac{\left(\epsilon_{1}-\epsilon_{2}\right)^{2}}{K_{a a}-K_{b b}} . \tag{2.100}
\end{equation*}
$$

The exchange $J_{a b}$ involves orthogonalized molecular orbitals and is therefore inherently ferromagnetic. The energies $\epsilon_{1}$ and $\epsilon_{2}$ are the bonding and antibonding energies associated with the molecular orbitals on the two metal ions. The $K$ 's are defined in terms of molecular orbitals analogous to (2.84). Since $K_{a a}>K_{b b}$ the nature of the exchange depends upon the magnitude of $\epsilon_{1}-\epsilon_{2}$. This quantity turns out to be a sensitive function of the metal-ligand-metal angle. Willett [22] and his co-workers have exploited this fact to synthesize a


Fig. 2.6. Exchange interactions between Eu-Eu pairs in Eu monochalcogenides versus the pair separation $R_{\tau}$. The horizontal arrows indicate the range of $R_{\tau}$ values from the oxides to the tellurides. Open symbols indicate results deduced assuming only second-nearest-neighbor coupling [23]. Units are degrees K
variety of pseudo-one-dimensional magnetic systems based on copper dimeric species.

In semiconductors the anion energies form bands. As a result the superexchange can extend to distant neighbors as illustrated in Fig. 2.6. These results were deduced from the measured spin-wave dispersion relations just as atomic force constants are deduced from phonon dispersion relations. We shall discuss spin-waves in Chap. 8.

### 2.2.9 Molecular Magnets

Ordinarily we do not associate magnetism with organic or molecular-based materials. Recently, however, chemists have synthesized materials with interesting magnetic properties. One approach has been to synthesize organic molecules with large numbers of unpaired spins that are in a high-spin state. Examples include a hexacarbene with $S=6$ and a nonocarbene with $S=9$. Incorporating these molecules into solids is still a challenge.

A more successful approach has been the synthesis of organometallic solids comprised of linear chains of alternating metallocenium donors and cyanocarbon acceptors. One such system is $\left[\mathrm{FeCp}_{2}^{*}\right]^{+}[\mathrm{TCNE}]^{-}$based on decamethyferrocene $\left(\mathrm{Cp}^{*}=\mathrm{C}_{5}\left(\mathrm{CH}_{3}\right)_{5}\right)$ and tetracyanoethylene, shown in Fig. 2.7.


Fig. 2.7. Alternating donor/acceptor linear chain structure observed for $\left[F e C p_{2}^{*}\right]^{+}[T C N E]^{-}$. Open circles $=H$, solid circles $=C$, small hatched circles $=N$, and larged hatched circles $=F e[\mathrm{~J}$. Miller $]$

There are many variations in which the iron is replaced by other transition metals ions and the radical anion is replaced by other radical anions such as TCNQ (tetracyano-p-quinodimethanide) or DDQ (dichloro-5,6dicyanobenzoquinone). As their long names suggest, the magnetic species are widely separated which means that the magnetization, or magnetic moment per unit volume is small. The magnetization of $\left[\mathrm{FeCp}_{2}^{*}\right]^{+}[\mathrm{TCNE}]^{-}$
is $47 \mathrm{emu} / \mathrm{cm}^{3}$ which is to be compared with that of iron of $1715 \mathrm{emu} / \mathrm{cm}^{3}$. The large separation between cations is also responsible for relatively weak exchange interactions as reflected in low ordering temperatures. The Curie temperature of our example Fig. 2.7 is 4.8 K. It may be surprising that these materials show any coupling, considering that the transition metal ion sits in the center of a relatively large molecule. The point is, however, that the wavefunctions of these molecules are molecular orbitals with charge density and spin density that extends throughout the molecule. These molecular orbitals have been calculated for the similar, but simpler, molecule, ferrocene, $\mathrm{Fe}\left(\mathrm{C}_{5} \mathrm{H}_{5}\right)_{2}$, usually written $\mathrm{Fe}(\mathrm{Cp})_{2}$. The structure consists of two planar $\mathrm{C}_{5} \mathrm{H}_{5}$ rings with the iron sandwiched in between. There are low-lying bonding states associated with the $\mathrm{C}_{5}$ rings. The states involving the $\mathrm{Fe}^{\mathrm{III}}$ are:

$\mathrm{Fe}^{\text {III }}$ has the low spin $\mathrm{d}^{5}$ configuration. These five electrons fill the orbitals as shown, giving a molecular spin of $1 / 2$. The $\mathrm{TCNE}^{-}$also has one unpaired electron.

There is some overlap of the cation and anion orbitals that gives rise to an exchange interaction. McConnell [24] was the first to point out that such ionic crystals could have ferromagnetic exchange. The mechanism McConnell proposed is based on the virtual charge transfer. Suppose, for example, the anion $(\mathrm{A}=$ acceptor $)$ and cation $(\mathrm{D}=$ donor $)$ spins are ferromagnetically aligned:


Then the charge transfer $D^{+} A^{-} \rightarrow D^{+2} A^{-2}$ leads to an intermediate state, in which there are two electrons in orthogonal orbitals with parallel spin on the cation:


Had we started with an antiferromagnetic alignment:

then the intermediate state would have antiparallel spins on the cation:


The parallel configuration has the lower energy (Hund's rule). Therefore the charge transfer favors the ferromagnetic state.

The unpaired electron on the anion could also transfer back to the cation (i.e., $D^{+} A \rightarrow D^{\circ} A^{\circ}$ ). This favors antiferromagnetic coupling. Consistant with the observed data the exchange is governed more by the $D \rightarrow A$ transfer. There are also various interchain exchange interactions that could influence the nature of the 3-dimensional ordering. However, it appears that the ordering in these salts is governed by the intrachain exchange.

Much of the recent work on these molecular magnets has been done by Miller and Epstein [25] who have also discovered a polymeric magnet involving vanadium with a Curie temperature about 400 K .

### 2.2.10 Double Exchange

In Anderson's formulation of superexchange, the electron hopping is a virtual process. If, however, we actually have carriers in the magnetic material, then the hopping matrix element $t_{\alpha \alpha^{\prime}}$ enters directly into the band energy in a tight-binding approximation. If we assume that the intra-atomic exchange is so strong that the spin of a carrier is parallel to the local ionic spin then the band energy is dependent upon the ionic spin configuration. This correlation between the magnetism and the conductivity was first addressed by Zener [26] and subsequently in more detail by Anderson and Hasegawa [27]. To determine how the magnetic order affects a conduction electron, we recall our discussion of how the spinor part of the electron wavefunction transforms under rotations. Let us consider the following geometry:


The ionic spin is assumed to be rotated by an angle $\theta$ about the $y$-axis. If the spinor at site $\alpha$ is $\binom{1}{0}$, then at site $\alpha^{\prime}$, it is given by the matrix for a rotation about the $y$-axis,

$$
\left(\begin{array}{rr}
\cos \frac{\theta}{2} & \sin \frac{\theta}{2} \\
-\sin \frac{\theta}{2} & \cos \frac{\theta}{2}
\end{array}\right)\binom{1}{0}=\binom{\cos \frac{\theta}{2}}{-\sin \frac{\theta}{2}} .
$$

Since we assume electron hopping can only occur if the electron hops into the $\binom{1}{0}$ state, the orbital transfer integral $b_{\alpha \alpha^{\prime}}$ is multiplied by $\cos \frac{\theta}{2}$. Thus,

$$
\begin{equation*}
t_{\alpha \alpha^{\prime}}=b_{\alpha \alpha^{\prime}} \cos \frac{\theta}{2} \tag{2.101}
\end{equation*}
$$

If the ionic spins have an exchange, $J$, then the tipping between $\alpha$ and $\alpha^{\prime}$ gives an exchange energy proportional to $J \cos \theta$. DeGennes has shown [28] that minimizing the kinetic energy associated with the hopping and the exchange energy can lead to a canted spin structure. Distortion of the spin lattice around the hopping electron results in a magnetic polaron. This is discussed in Sect. 10.4.

### 2.2.11 Exchange on a Surface

Recent developments in nanotechnology enable one to experimentally study the exchange interaction between individual atoms. Figure 2.8 shows the tip on a scanning tunneling microscope which is used to position Mn atoms next to one another ( 0.36 nm apart) on an insulating surface. The tip can also be


Fig. 2.8. CuN surface showing how a scanning tunneling microscope can be used to position two manganese atoms next to one another (C.F. Hirjibehedin)
used to measure the conductance of these artificially created Mn clusters. The inelastic electron tunneling spectra for a dimer shows structure that has been indentified as an excitation between an antiparallel ground state involving two spin $5 / 2$ moments and a parallel excited state ref [29]. The voltage at which this structure occurs enables a determination of the exchange interaction between the two Mn moments. This has the values 2.7 meV or 6.4 meV at 0.6 K depending upon where the dimer sits on the CuN surface. The insert in Fig. 2.8 shows the cross-section of the charge density as calculated from a "first-principles" calculation. The Mn $3 d$ electrons couple to this surrounding charge density through an "s-d" exchange interaction, $J_{s d} \mathbf{S}$.s. This provides an effective exchange between the two Mn moments of the order of $J_{s d}^{2} / E_{g}$, where $E_{g}$ is the bandgap of the CuN. Since $J_{s d}$ is of order 0.1 eV and $E_{g}$ is several eV the $\mathrm{Mn}-\mathrm{Mn}$ exchange is of order of several meV as observed.

### 2.3 The Spin Hamiltonian

The Hamiltonian developed in the preceding section is completely general, and a knowledge of its eigenvalues would accurately describe the magnetic properties of any material. Unfortunately, because of the large number of particles involved, such a knowledge is beyond us at this time. Therefore we try to project out of the Hamiltonian those terms which adequately describe the situation and yet are amenable to calculation. Experimentalists in particular often propose "phenomenological" Hamiltonians to explain certain observations, leaving to theoreticians the job of establishing the legitimacy of such forms. In the remainder of this chapter we shall indicate the origin of such phenomenological Hamiltonians.

### 2.3.1 Transition-Metal Ions

The first row of transition-metal ions and their electronic configurations are listed in Table 2.4. The important feature about transition-metal ions is that the magnetic, or unpaired, electrons lie in the outermost shell of the ion. Therefore they are easily influenced by any external field produced by neighboring ligands. That is, the crystal field is likely to be one of the largest terms in the Hamiltonian. Thus we might expect that the contributions to the Hamiltonian, in order of descending strength, are

$$
\begin{equation*}
\mathcal{H}=\mathcal{H}_{\text {intraatomic Coulomb }}+\mathcal{H}_{\text {crystal field }}+\mathcal{H}_{\text {spin-orbit }}+\mathcal{H}_{\text {Zeeman }} \tag{2.102}
\end{equation*}
$$

Of course, depending on the situation, we may have to consider additional terms, such as the hyperfine interaction. However, let us consider the eigenstates of the Hamiltonian (2.102). First of all, the intraatomic Coulomb interaction leads to spectroscopic energy levels, the lowest of which is determined by Hund's rules. This ground state is indicated in the last column of Table 2.4.

For most magnetic properties it is sufficient to consider only the lowest term. This is because term energies are of the order of tens of thousands of wave numbers, whereas magnetic energies are at most tens of wave numbers.

The behavior of a given term in the crystal field may be calculated by the technique developed in the last section. Cubic symmetry is the predominant symmetry encountered in most crystals, and Fig. 2.9 indicates how group theory predicts splitting of the various terms of Table 2.4 in such a case. The eigenfunctions of $\mathcal{H}_{\text {intra }}+\mathcal{H}_{\text {cryst }}$ will be denoted as $\left|\Gamma, \gamma ; S, M_{S}\right\rangle$, where $\Gamma$ is the irreducible representation of the point-group symmetry.

Consider, for example, the $3 d^{3}$ configuration. From Hund's rules, the ground state is

$$
\begin{equation*}
\left|L, M_{L} ; S, M_{S}\right\rangle=\left|3, M_{L} ; \frac{3}{2}, M_{S}\right\rangle \tag{2.103}
\end{equation*}
$$

which is $(2 L+1)(2 S+1)=28$-fold degenerate. In the presence of a cubic crystal field this state splits as shown in Fig. 2.9. Thus the ground state would be denoted as $\left|A_{2}, \gamma ; \frac{3}{2}, M_{S}\right\rangle$.
The $g$ Tensor. Now consider the spin-orbit and Zeeman terms. Since we are considering matrix elements only within a given $L S$ term, the matrix elements of

$$
\sum_{i} \xi\left(\boldsymbol{r}_{i}\right) \boldsymbol{l}_{i} \cdot \boldsymbol{s}_{i}
$$

are proportional to those of $\boldsymbol{L} \cdot \boldsymbol{S}$, by the Wigner-Eckhart theorem. Thus the spin-orbit Hamiltonian may be written

$$
\begin{equation*}
\mathcal{H}_{\mathrm{sp}-\text { orb }}=\lambda \boldsymbol{L} \cdot \boldsymbol{S} \tag{2.104}
\end{equation*}
$$

Table 2.4. Configuration of the iron-group ions

| $\mathrm{Ti}^{3+}, \mathrm{V}^{4+}$ | $3 d^{1}$ | ${ }^{2} D$ |  |
| :---: | :---: | :---: | :---: |
| $\mathrm{V}^{3+}$ | $3 d^{2}$ | ${ }^{3} \mathrm{~F}$ |  |
| $\mathrm{Cr}^{3+}, \mathrm{V}^{2+}$ | $3 d^{3}$ | ${ }^{4} F$ | 2 \% |
| $\mathrm{Mn}^{3+}, \mathrm{Cr}^{2+}$ | $3 d^{4}$ | ${ }^{5} \mathrm{D}$ | $1-i / 5$ it i |
| $\mathrm{Fe}^{3+}, \mathrm{Mn}^{2+}$ | $3 d^{5}$ | ${ }^{6} S$ | 0 L, , , - V |
| $\mathrm{Fe}^{2+}$ | $3 d^{6}$ | ${ }^{5}$ D | $024 d^{n} 68$ |
| $\mathrm{Co}^{2+}$ | $3 d^{7} n$ | ${ }^{5} D$ |  |
| $\mathrm{Co}^{2+}$ | $3 d^{7} n$ | ${ }^{5} \mathrm{D}$ |  |
| $\mathrm{Co}^{2+}$ | $3 d^{7} n$ | ${ }^{4} F$ |  |
| $\mathrm{Ni}^{2+}$ | $3 d^{8}$ | ${ }^{3} F$ |  |
| $\mathrm{Cu}^{2+}$ | $3 d^{9}$ | ${ }^{2}$ D |  |

where $\lambda$ is the spin-orbit parameter. Similarly, the Zeeman Hamiltonian is

$$
\begin{equation*}
\mathcal{H}_{Z}=\mu_{B}(\boldsymbol{L}+2 \boldsymbol{S}) \cdot \boldsymbol{H} \tag{2.105}
\end{equation*}
$$

We now transform $\mathcal{H}_{\mathrm{sp}-\mathrm{orb}}+\mathcal{H}_{Z}$ into the so-called spin Hamiltonian by a method proposed by Pryce, in which we project out the orbital dependence. Since neither $\mathcal{H}_{\text {intra }}$ nor $\mathcal{H}_{\text {cryst }}$ has mixed orbital and spin states, our eigenfunctions are products of the form $|\Gamma, \gamma\rangle\left|S, M_{S}\right\rangle$. Let us evaluate the expectation value of $\mathcal{H}_{\mathrm{sp}-\text { orb }}+\mathcal{H}_{Z}$ for an orbitally nondegenerate ground state $|\Gamma, \gamma\rangle$. To second order in perturbation theory,

$$
\begin{align*}
\mathcal{H}_{\mathrm{eff}} & =\langle\Gamma, \gamma| \mathcal{H}_{\mathrm{sp}-\mathrm{orb}}+\mathcal{H}_{Z}|\Gamma, \gamma\rangle \\
& =2 \mu_{B} \boldsymbol{H} \cdot \boldsymbol{S}-\sum_{\Gamma^{\prime}, \gamma^{\prime}} \frac{\left.\left|\left\langle\Gamma^{\prime}, \gamma^{\prime}\right| \mu_{B} \boldsymbol{H} \cdot \boldsymbol{L}+\lambda \boldsymbol{L} \cdot \boldsymbol{S}\right| \Gamma, \gamma\right\rangle\left.\right|^{2}}{E_{\Gamma^{\prime}, \gamma^{\prime}}-E_{\Gamma, \gamma}} \tag{2.106}
\end{align*}
$$

Expanding the square gives

$$
\begin{equation*}
\mathcal{H}_{\mathrm{eff}}=2 \mu \boldsymbol{H} \cdot \boldsymbol{S}-2 \mu_{B} \lambda \sum_{\mu, \nu} \Lambda_{\mu \nu} S_{\mu} H_{\nu}-\lambda^{2} \sum_{\mu, \nu} \Lambda_{\mu \nu} S_{\mu} S_{\nu}-\mu_{B}^{2} \sum_{\mu, \nu} H_{\mu} H_{\nu} \tag{2.107}
\end{equation*}
$$

where

$$
\begin{equation*}
\Lambda_{\mu \nu}=\sum_{\Gamma^{\prime} \gamma^{\prime}} \frac{\langle\Gamma, \gamma| L_{\mu}\left|\Gamma^{\prime}, \gamma^{\prime}\right\rangle\left\langle\Gamma^{\prime}, \gamma^{\prime}\right| L_{\nu}|\Gamma, \gamma\rangle}{E_{\Gamma^{\prime}, \gamma^{\prime}}-E_{\Gamma, \gamma}} \tag{2.108}
\end{equation*}
$$



Fig. 2.9. Crystal-field splittings of the iron-group ion ground states. The first set of splittings are the result of a cubic crystal field. Subsequent splittings are due to an additional tetragonal distortion

This may be written as

$$
\begin{equation*}
\mathcal{H}_{\mathrm{eff}}=\sum_{\mu, \nu}\left(\mu_{B} g_{\mu \nu} H_{\mu} S_{\nu}-\lambda^{2} A_{\mu \nu} S_{\mu} S_{\nu}-\mu_{B}^{2} \Lambda_{\mu \nu} H_{\mu} H_{\nu}\right) \tag{2.109}
\end{equation*}
$$

where $g_{\mu \nu}$ is the $g$ tensor

$$
\begin{equation*}
g_{\mu \nu}=2\left(\delta_{\mu \nu}-\lambda \Lambda_{\mu \nu}\right) \tag{2.110}
\end{equation*}
$$

The fact that $g_{\mu \mu}$ differs from 2 tells us that owing to the spin-orbit interaction, the magnetization is now no longer spin only. That is, a small amount of orbital angular momentum has been admixed back into the ground state.

The $g$ value of the free electron is not precisely 2 . There are quantum electrodynamic corrections which lead to the value $g=2.002319$.

As an example of how this value is changed in a solid let us consider the semiconductor silicon. In the ideal crystalline state each silicon atom has four valence electrons which form bonds with four neighboring silicon atoms. If this ideal crystal is irradiated, with high-energy electrons, for example, defects are introduced. One of these is the divacancy illustrated in Fig. 2.10a. The removal of the two atoms $A$ and $B$ leaves six broken bonds, or unpaired electrons. Those electrons associated with atoms 2 and 3 and those associated with 5 and 6 reconstruct bonds as indicated in the figure. The remaining two electrons from atoms 1 and 4 then form an "extended" bond across the vacancy. If one of these latter two electrons is removed by some means, leaving the defect with a net positive charge, the remaining electron is found to have the $g$ value [30]


Fig. 2.10. Defects in (a) crystalline and (b) amorphous silicon having nearly free electron $g$ values

$$
\begin{aligned}
& g_{1}=2.0004 \\
& g_{2}=2.0020 \\
& g_{3}=2.0041
\end{aligned}
$$

If the silicon is prepared as an amorphous film, by the decomposition of silane gas, for example, then the atomic disorder sometimes leaves a silicon atom with only three other silicon neighbors as illustrated schematically in Fig. 2.10b. The fourth unpaired electron is referred to as a "dangling" bond. This electron is found to have the average $g$ value [31]

$$
g=2.0055
$$

Although these $g$ values differ by less than $1 \%$ these differences are easily measured, as we shall discuss in Chap. 5, and provide an extremely important characterization of the electronic center.
Anisotropy. The second term in (2.109) represents the fine-structure or singleion anisotropy. Notice that $\wedge_{\mu \nu}$ reflects the symmetry of the crystal. The spin Hamiltonian must also display this symmetry; for example, in a cubic crystal $\wedge_{x x}=\wedge_{y y}=\wedge_{z z}$. Thus the anisotropy term reduces to a constant. For axial symmetry $\wedge_{x x}=\wedge_{y y}=\wedge_{\perp}$ and $\wedge_{z z}=\wedge_{\| \mid}$. Thus, if we neglect the last term, the effective axial Hamiltonian is

$$
\begin{align*}
\mathcal{H}_{\mathrm{eff}}= & g_{\| \mid} \mu_{B} H_{z} S_{z}+g_{\perp} \mu_{B}\left(H_{x} S_{x}+H_{y} S_{y}\right)+D\left[S_{z}^{2}-\frac{1}{3} S(S+1)\right] \\
& +\frac{1}{3} S(S+1)\left(2 \wedge_{\perp}+\Lambda_{\| \|}\right) \lambda^{2} \tag{2.111}
\end{align*}
$$

where $D=\lambda^{2}\left(\wedge_{\|}-\wedge_{\perp}\right)$. A Hamiltonian of this form based on the symmetry of the crystal is usually taken as the starting point in describing paramagnetic systems involving transition-metal ions. Thus such ions in crystals are characterized by their $g, D$, etc., parameters.

An important experimental fact is that these crystal-field parameters do not change appreciably for concentrated versions of the same salt. Hence, we shall find these paramagnetic states useful when we discuss ferromagnetism. For example, we can see from the discussion above that the anisotropy constants depend on the energy levels, which in turn depend on the positions of the neighboring ions. Thus, if these ions move because of the presence, say, of phonons, then we have a coupling between this motion and the spins.

The last term in the Hamiltonian (2.109) will survive the two field derivatives leading to the static susceptibility, resulting in the so-called Van Vleck susceptibility, which is temperature independent.

As an example of the application of the spin Hamiltonian, let us consider a spin $\frac{3}{2}$ in an axially symmetric system with an external field applied along the $c$ axis. If we assume that the crystal field is of sufficiently low symmetry


Fig. 2.11. Representation of the effect of the spin-orbit and Zeeman interactions on an orbital singlet with spin $\frac{3}{2}$
to remove any orbital degeneracy of the ground state, then (2.111) applies. Dropping the constant part, we have

$$
\begin{equation*}
\mathcal{H}_{\mathrm{eff}}=g_{\|} \mu_{B} H S_{z}+D\left[S_{z}^{2}-\frac{1}{3} S(S+1)\right] \tag{2.112}
\end{equation*}
$$

The matrix of $\mathcal{H}_{\text {eff }}$ in the basis $\left|\frac{3}{2}, M_{S}\right\rangle$ is

$$
\mathcal{H}_{\text {eff }}=\begin{gather*}
\left|-\frac{3}{2}\right\rangle  \tag{2.113}\\
\left\langle-\frac{3}{2}\right| \\
\left\langle-\frac{1}{2}\right| \\
\left\langle\frac{1}{2}\right| \\
\left\langle\frac{3}{2}\right|
\end{gather*}\left[\begin{array}{cccc}
D-\frac{3}{2} g_{\| \mid} \mu_{B} H & 0 & \left|\frac{1}{2}\right\rangle & \left|\frac{3}{2}\right\rangle \\
0 & -D-\frac{1}{2} g_{\| \mid} \mu_{B} H & 0 & 0 \\
0 & 0 & -D+\frac{1}{2} g_{\|} \mu_{B} H & 0 \\
0 & 0 & 0 & D+\frac{3}{2} g_{\| \mid} \mu_{B} H
\end{array}\right] .
$$

The eigenvalues are shown in Fig. 2.11. We see that there is a zero-field splitting of $2 D$.

Effective Exchange. In our discussion of exchange in the last section we neglected spin-orbit effects as well as off-diagonal exchange effects. We found above that the spin-orbit interaction leads to important contributions to the spin Hamiltonian. It can also modify the form of the exchange interaction. To illustrate these effects, let us consider the exchange between a $\mathrm{Mn}^{2+}$ impurity and a neighboring $\mathrm{Co}^{2+}$ ion in $\mathrm{CoCl}_{2} \cdot 2 \mathrm{H}_{2} \mathrm{O}$ [32]. $\mathrm{Co}^{2+}$ has seven $d$ electrons which correspond to three holes in the $d$ shell. These holes behave just as electrons would. Therefore we find that the intraatomic Coulomb interaction leads to a ${ }^{4} F$ ground state with a spin of $\frac{3}{2}$. The crystal field in $\mathrm{CoCl}_{2} \cdot 2 \mathrm{H}_{2} \mathrm{O}$ is predominantly cubic, with a small tetragonal distortion. The cubic part splits the ${ }^{4} F$ into three states, the lowest being ${ }^{4} T_{1}$, which has a threefold
orbital degeneracy. As mentioned above, crystal-field effects on the transitionmetal ions are rather large. Therefore, in so far as we are concerned only with magnetic properties, we may restrict our considerations to this ${ }^{4} T_{1}$ ground state.

We now investigate how the tetragonal crystal-field component and the spin-orbit interaction affect this level. Any threefold orbitally degenerate state behaves as though it had an effective quantum number $L=1$. We saw earlier that if we restrict ourselves to a manifold of states in which, say, $L$ is a good quantum number, then we may express the crystal-field Hamiltonian in powers of $L_{x}, L_{y}$, and $L_{z}$. The same argument applies even if $L$ is only a good effective quantum number. Thus the effect of a tetragonal crystal field upon our ${ }^{4} T_{1}$ ground state may be described by the Hamiltonian

$$
\begin{equation*}
\mathcal{H}_{\mathrm{tetra}}=-\delta\left(L_{z}^{2}-\frac{3}{2}\right) \tag{2.114}
\end{equation*}
$$

where $\delta$ is a phenomenological crystal-field parameter and $L=1$. The spinorbit interaction may also be expressed in terms of the effective orbital angular momentum,

$$
\begin{equation*}
\mathcal{H}_{\mathrm{sp}-\mathrm{orb}}=\lambda^{\prime} \boldsymbol{L} \cdot \boldsymbol{S}_{\mathrm{Co}} \tag{2.115}
\end{equation*}
$$

where $\lambda^{\prime}$ is an effective spin-orbit parameter. The operators $L^{+}$and $L^{-}$are the raising and lowering operators for the components of the ${ }^{4} T_{1}$, just as the corresponding real operators would connect the components of a real $P$ state. This technique of writing Hamiltonians in terms of effective-angular-momentum operators is an extremely useful tool for understanding the qualitative features of the electromagnetic absorption spectra of magnetic systems.

The basis functions for our ${ }^{4} T_{1}$ state have the form $\left|M_{L}, M_{S}\right\rangle$, where $M_{L}=-1,0$, or +1 , and $M_{S}= \pm \frac{1}{2}$ or $\pm \frac{3}{2}$. The effect of $\mathcal{H}_{\text {tetra }}+\mathcal{H}_{\mathrm{sp}-\text { orb }}$ is to split the ${ }^{4} T_{1}$ into six doublets. Again, for magnetic considerations, we consider the lowest of these. The eigenfunctions have the form

$$
\begin{equation*}
\psi^{ \pm}=a\left|\mp 1, \pm \frac{3}{2}\right\rangle+b\left|0, \pm \frac{1}{2}\right\rangle+c\left| \pm 1, \mp \frac{1}{2}\right\rangle \tag{2.116}
\end{equation*}
$$

where $a, b$, and $c$ are certain mixing coefficients which may, in general, be complex. We now inquire how the exchange with the neighboring $\mathrm{Mn}^{2+}$ affects this doublet. Since it is a doublet, the exchange should be expressible as an effective spin of $\frac{1}{2}$ interacting with the $\mathrm{Mn}^{2+}$ spin. The purpose of this example is to show that when the exchange is in fact expressed in terms of an effective spin of $\frac{1}{2}$, it does not have the simple isotropic form we have so far been using.

The first thing we must do is establish an expression for the exchange which we know to be correct. Recall the the ${ }^{4} T_{1}$ state has a threefold orbital degeneracy, and that the three $d$ holes can be treated just as electrons. Therefore we have a situation in which there is only one state of maximum multiplicity, which means that the total spin is a good quantum number. Also, since
the ground state of $\mathrm{Mn}^{2+}$ is an $S$ state, the total spin of this ion is a good quantum number. Therefore the exchange interaction may be written as

$$
\begin{equation*}
\mathcal{H}_{\mathrm{ex}}=-\sum_{M_{L} M_{L}^{\prime}} J\left(M_{L}, M_{L}^{\prime}\right) \boldsymbol{S}_{\mathrm{Mn}} \cdot \boldsymbol{S}_{\mathrm{Co}} \tag{2.117}
\end{equation*}
$$

Notice that we are explicitly including the possibility of off-diagonal exchange. Thus, in terms of actual electron interchange, the exchange integral $J\left(M_{L}, M_{L}^{\prime}\right)$ would characterize the interchange in which an electron from a $\mathrm{Co}^{2+}$ in the state $M_{L}$ jumps over to the $\mathrm{Mn}^{2+}$, while an electron from the $\mathrm{Mn}^{2+}$ jumps back to the $\mathrm{Co}^{2+}$ and in so doing changes it to the $M_{L}^{\prime}$ state. These offdiagonal exchange integrals may be complex. As long as the orbital states so connected lie within the ${ }^{4} T_{1}$ manifold, the scalar spin product may be used even to describe this off-diagonal exchange.

We now wish to know what form this exchange takes when expressed in terms of the effective spin $\frac{1}{2}$ of the $\mathrm{Co}^{2+}$ ground state. The most general interaction has the form

$$
\begin{equation*}
\mathcal{H}_{\mathrm{eff}}=-\boldsymbol{S}_{\mathrm{eff}} \cdot \mathcal{J} \cdot \boldsymbol{S}_{\mathrm{Mn}} \tag{2.118}
\end{equation*}
$$

where $\mathcal{J}$ is an exchange dyadic. If we evaluate the matrix elements of (2.117) in the basis $\left|\psi^{ \pm}, M_{S}\right\rangle$, where $M_{S}$ is the $\mathrm{Mn}^{2+}$ spin quantum number $\left(S=\frac{5}{2}\right)$, and compare them with the matrix elements of (2.118) evaluated in the basis $\left| \pm \frac{1}{2}, M_{S}\right\rangle$, we find that all the elements of $\mathcal{J}_{\mu \nu}$ are nonzero. For example,

$$
\begin{equation*}
\mathcal{J}_{x y}=-2 c^{2} \operatorname{Im}\{J(1,-1)\} \tag{2.119}
\end{equation*}
$$

The general matrix $\mathcal{J}_{\mu \nu}$ may be separated into a symmetric and an antisymmetric part. The antisymmetric exchange may be written as

$$
\begin{equation*}
\boldsymbol{D} \cdot \boldsymbol{S}_{\mathrm{eff}} \times \boldsymbol{S}_{\mathrm{Mn}} \tag{2.120}
\end{equation*}
$$

where the vector coupling coefficient $\boldsymbol{D}$ is related to $\mathcal{J}_{\mu \nu}$. This exchange is also referred to as the Dzialoshinski-Moriya exchange [33]. If the elements of the symmetric exchange are different, we speak of this as anisotropic exchange. There are two limiting forms that are popularly used: the Ising model

$$
\mathcal{H}_{\text {Ising }}=-2 J \sum_{i, \delta} S_{i}^{z} S_{i+\delta}^{z},
$$

and the $X Y$ model

$$
\mathcal{H}_{X Y}=-2 J \sum_{i, \delta}\left(S_{i}^{x}, S_{i+\delta}^{x}+S_{i}^{y} S_{i+\delta}^{y}\right)
$$

Here $\delta$ refers to a nearest neighbor. Thus we see that when the exchange interaction is expressed in terms of the effective spin of the ground state, it may have a very general form owing to the presence of orbital effects.

Table 2.5. Configurations of the rare-earth ions


### 2.3.2 Rare-Earth Ions

The electronic configurations of the rare-earth ions are listed in Table 2.5. For these ions we see that the unpaired electrons lie inside the $5 s^{2} p^{6}$ shells. Consequently they are not very strongly affected by crystal fields, and we might expect the Hamiltonian to consist of the following terms, in order of descending strength:

$$
\begin{equation*}
\mathcal{H}=\mathcal{H}_{\text {intraatomic Coulomb }}+\mathcal{H}_{\text {spin-orbit }}+\mathcal{H}_{\text {crystal field }}+\mathcal{H}_{\text {Zeeman }} \tag{2.121}
\end{equation*}
$$

The intraatomic Coulomb interaction produces states characterized by $L, M_{L}$, $S$, and $M_{S}$. When the spin-orbit interaction is added, only the total angular momentum $\boldsymbol{J}=\boldsymbol{L}+\boldsymbol{S}$ is conserved. Therefore the states have the form $\left|J, M_{J} ; L, S\right\rangle$.

Let us consider, for the moment, the effect of the Zeeman term in the absence of any crystal field,

$$
\begin{equation*}
\mathcal{H}_{Z}=\mu_{B}(\boldsymbol{L}+2 \boldsymbol{S}) \cdot \boldsymbol{H} \tag{2.122}
\end{equation*}
$$

Since the states are characterized by the eigenvalues of $\boldsymbol{J}$, we rewrite this as

$$
\begin{equation*}
\mathcal{H}_{\text {Zeeman }}=g_{J} \mu_{B} \boldsymbol{J} \cdot \boldsymbol{H} \tag{2.123}
\end{equation*}
$$

where $g_{J}$ is the Landé $g$ value, defined by $g_{J} \boldsymbol{J}=\boldsymbol{L}+2 \boldsymbol{S}$. This has the value

$$
\begin{equation*}
g_{J}=1+\frac{J(J+1)+S(S+1)-L(L+1)}{2 J(J+1)} . \tag{2.124}
\end{equation*}
$$

Thus the state $\left|J, M_{J}\right\rangle$ is split into $2 J+1$ equally spaced states with the separation $g_{J} \mu_{B} H$. For $\mathrm{Ce}^{3+}$, for example, $g_{J}=\frac{6}{7}$.
In the presence of a crystal field the splitting of the state $\left|J, M_{J}\right\rangle$ is easily determined by expressing the crystal field in operator equivalents of $\boldsymbol{J}$. Thus for a crystal field of $D_{2}$ symmetry we have

$$
\begin{align*}
\mathcal{H}_{\text {cryst }}= & B_{2}^{0} O_{2}^{0}+B_{2}^{2} O_{2}^{2}+B_{4}^{0} O_{4}^{0}+B_{4}^{2} O_{4}^{2}+B_{4}^{4} O_{4}^{4} \\
& +B_{6}^{0} O_{6}^{0}+B_{6}^{2} O_{6}^{2}+B_{6}^{4} O_{6}^{4}+B_{6}^{6} O_{6}^{6} \tag{2.125}
\end{align*}
$$

where the operators $0_{n}^{m}$ were defined in (2.52).
The matrix of $\mathcal{H}_{\text {cryst }}$ in the basis $\left|J, M_{J} ; L, S\right\rangle$ is easily constructed from tables in [12]. The result for $\mathrm{Ce}^{3+}$ is

$$
\left|\frac{5}{2}\right\rangle \quad\left|\frac{1}{2}\right\rangle \quad\left|-\frac{3}{2}\right\rangle\left|-\frac{5}{2}\right\rangle \quad\left|-\frac{1}{2}\right\rangle \quad\left|\frac{3}{2}\right\rangle
$$

$\left.\begin{array}{r|l|l}\left\langle\frac{5}{2}\right| \\ \left\langle\frac{1}{2}\right| \\ \left\langle-\frac{3}{2}\right| & & \\ \left\langle-\frac{5}{2}\right| & & 0 \\ \left\langle-\frac{1}{2}\right| & & \\ \left\langle\frac{3}{2}\right|\end{array}\right]$
where

$$
B \equiv\left[\begin{array}{ccc}
10 B_{2}^{0}+60_{4}^{B} & \sqrt{10} B_{2}^{2}+9 \sqrt{10} B_{4}^{2} & 12 \sqrt{5} B_{4}^{4} \\
\sqrt{10} B_{2}^{2}+9 \sqrt{10} B_{4}^{2} & -8 B_{2}^{0}+120 B_{4}^{0} & 3 \sqrt{2} B_{2}^{2}-15 \sqrt{2} B_{4}^{2} \\
12 \sqrt{5} B_{4}^{4} & 3 \sqrt{2} B_{2}^{2}-15 \sqrt{2} B_{4}^{2} & -2 B_{2}^{0}-180 B_{4}^{0}
\end{array}\right]
$$

This gives three doublets which have the form

$$
\begin{align*}
& \psi_{n}^{+}=a_{n}\left|\frac{5}{2}\right\rangle+b_{n}\left|\frac{1}{2}\right\rangle+c_{n}\left|-\frac{3}{2}\right\rangle,  \tag{2.127a}\\
& \psi_{n}^{-}=a_{n}\left|-\frac{5}{2}\right\rangle+b_{n}\left|-\frac{1}{2}\right\rangle+c_{n}\left|\frac{3}{2}\right\rangle . \tag{2.127b}
\end{align*}
$$

In terms of the states $\left|m_{l} m_{z}\right\rangle$, these may be written as

$$
\begin{align*}
\psi_{n}^{+} & =\varphi_{1} \alpha+\varphi_{2} \beta  \tag{2.128a}\\
\psi_{n}^{-} & =\varphi_{2}^{*} \alpha-\varphi_{1}^{*} \beta \tag{2.128b}
\end{align*}
$$

where $\varphi_{1}^{*}=\varphi_{1}$ and $\varphi_{2}^{*}=-\varphi_{2}$. Under the time-reversal operator $T=i K \sigma_{y}$, where $K$ is the conjugation operator, these states are related by

$$
\begin{align*}
& T \psi_{n}^{+}=\psi_{n}^{-}  \tag{2.129a}\\
& T \psi_{n}^{-} \tag{2.129b}
\end{align*}=-\psi_{n}^{+} .
$$

Such a pair of states is said to form a Kramers doublet. The states (2.116) also formed a Kramers doublet.

Let us now consider the behavior of the lowest Kramers doublet in an external magnetic field. The Hamiltonian is

$$
\begin{equation*}
\mathcal{H}_{Z}=\mu_{B}(\boldsymbol{l}+2 \boldsymbol{s}) \cdot \boldsymbol{H} \tag{2.130}
\end{equation*}
$$

Since we are within a manifold where $J$ is a good quantum number, this may be written as

$$
\begin{equation*}
\mathcal{H}_{Z}=g_{J} \mu_{B} J_{z} H \tag{2.131}
\end{equation*}
$$

The Zeeman matrix for the lowest doublet is

$$
\left[\begin{array}{cc}
g_{J} \mu_{B} H\left(\frac{5}{2} a_{1}^{2}+\frac{1}{2} b_{1}^{2}-\frac{3}{2} c_{1}^{2}\right) & 0  \tag{2.132}\\
0 & -g_{J} \mu_{B} H\left(\frac{5}{2} a_{1}^{2}+\frac{1}{2} b_{1}^{2}-\frac{3}{2} c_{1}^{2}\right)
\end{array}\right]
$$

Therefore the doublet splits linearly in the field. An effective $g$ value is often introduced by defining the splitting of two levels in a field as $g_{\text {eff }} \mu_{B} H$. In this case the effective $g$ value would be

$$
\begin{equation*}
g_{\mathrm{eff}}=g_{J}\left(5 a_{1}^{2}+b_{1}^{2}-3 c_{1}^{2}\right) \tag{2.133}
\end{equation*}
$$

Notice that the $g$ value depends directly on the coefficients in the wave function (2.127). For this reason measurements of the $g$ value provide a sensitive test of the ground-state wave function.

### 2.3.3 Semiconductors

It is interesting to carry out the calculation for the $g$ value of an electron moving in the periodic potential, $V(\boldsymbol{r})$, of a crystal lattice. The Hamiltonian is

$$
\begin{equation*}
\mathcal{H}=\mathcal{H}_{\text {kinetic }}+\mathcal{H}_{\text {crystal }}+\mathcal{H}_{\text {spin-orbit }}+\mathcal{H}_{\text {zeeman }} \tag{2.134}
\end{equation*}
$$

The eigenfunctions of an electron moving in a periodic potential have the Bloch form $u_{n k}(\boldsymbol{r}) \exp (i \boldsymbol{k} \cdot \boldsymbol{r})$ which give rise to energy bands characterized by band indices $n$ and wave vector $\boldsymbol{k}$. In the absence of the Zeeman term the function $u_{n k}(\boldsymbol{r})$ satisfies

$$
\begin{equation*}
\left[\frac{1}{2 m}(\boldsymbol{p}+\hbar \boldsymbol{k})^{2}+V(\boldsymbol{r})+\frac{\hbar}{4 m^{2} c^{2}} \boldsymbol{\sigma} \times \nabla V(\boldsymbol{r}) \cdot(\boldsymbol{p}+\hbar \boldsymbol{k})\right] u_{n k}(\boldsymbol{r})=\epsilon_{n k} u_{n k}(\boldsymbol{r}) \tag{2.135}
\end{equation*}
$$

In the case of the "three-five" semiconductors, which are composed of elements from the third and fifth columns of the period table (e.g., GaAs, InSb ) the valence band is $p$-like while the conduction band is $s$-like. The band structure in the vicinity of $\boldsymbol{k}=0$ is illustrated in Fig. 2.12. The labels $\Gamma_{6}$, etc., indicate the irreducible representations according to which the wave functions at $\boldsymbol{k}=0$ transform. The first feature to note is that the spin-orbit interaction has split the threefold degeneracy of the $p$-like valence band. Secondly, the curvatures of these bands are different. This curvature is a measure of the effective mass of the electron. We may obtain an estimate of this mass by treating the term $(\hbar / m) \boldsymbol{k} \cdot \boldsymbol{p}$ in (2.135) as a perturbation.

Calculating the second-order correction to the energy of the conduction band leads to the effective mass tensor [34a],

$$
\begin{equation*}
\left(\frac{m}{m^{*}}\right)_{\mu \nu}=\delta_{\mu \nu}+\frac{2}{m} \sum_{\Gamma} \frac{\left\langle\Gamma_{6}\right| p_{\mu}|\Gamma\rangle\langle\Gamma| p_{\nu}\left|\Gamma_{6}\right\rangle}{\epsilon_{\Gamma_{6}}-\epsilon_{\Gamma}} \tag{2.136}
\end{equation*}
$$



Fig. 2.12. Energy bands near $\boldsymbol{k}=0$ for zinc-blende crystals

The valence band wave functions are linear combinations of the usual $x, y$, and $z$ components of the $p$ state. Since the III-V compounds have the cubic zinc-blende structure, if we restrict our consideration only to the bands shown in Fig. 2.12 then there is only one parameter,

$$
\left.\frac{2}{m}\langle\Gamma, \mu| p_{\mu}|s\rangle\right|^{2} \equiv P^{2}
$$

and the effective mass becomes

$$
\begin{equation*}
\frac{m}{m^{*}}=1+\frac{P^{2}}{3} \frac{3 E_{g}+2 \Delta}{E_{g}\left(E_{g}+\Delta\right)} \tag{2.137}
\end{equation*}
$$

Let us now consider the orbital moment associated with an electron at the bottom of the conduction band,

$$
\begin{equation*}
\left\langle\Gamma_{6}\right| L_{z}\left|\Gamma_{6}\right\rangle=\sum_{\Gamma}\left[\left\langle\Gamma_{6}\right| x|\Gamma\rangle\langle\Gamma| p_{y}\left|\Gamma_{6}\right\rangle-\left\langle\Gamma_{6}\right| y|\Gamma\rangle\langle\Gamma| p_{x}\left|\Gamma_{6}\right\rangle\right] \tag{2.138}
\end{equation*}
$$

This may be rewritten by noting that

$$
\begin{equation*}
[x, \mathcal{H}]=\frac{i}{m} p_{x}+\frac{i \hbar}{4 m^{2} c^{2}}(\boldsymbol{\sigma} \times \nabla V)_{x} \tag{2.139}
\end{equation*}
$$

Neglecting the spin-orbit contribution, which can be shown to be small, the matrix elements of (2.139) satisfy

$$
\begin{equation*}
\langle\Gamma| x\left|\Gamma_{6}\right\rangle=\frac{1}{m} \frac{\langle\Gamma| p_{x}\left|\Gamma_{6}\right\rangle}{\epsilon_{\Gamma_{6}}-\epsilon_{\Gamma}} . \tag{2.140}
\end{equation*}
$$

This enables us to convert the orbital angular-momentum matrix element into a form similar to the effective mass. In particular, eliminating the linear-momentum matrix element between these two expressions leads to the relation [34b]

$$
\begin{equation*}
g^{*}=\frac{\mu^{*}}{\mu_{B}}=1+\left\langle\Gamma_{6}\right| L_{z}\left|\Gamma_{6}\right\rangle=2\left[1-\frac{\Delta}{3 E_{g}+2 \Delta}\left(\frac{m}{m^{*}}-1\right)\right] \tag{2.141}
\end{equation*}
$$

In general, one must include additional bands, in which case the relationship between the effective $g$ value and the effective mass is not as simple. Nevertheless, when the effective mass is very small the $g$ value can become quite large. In InSb, for example, $m^{*} / m=-0.014$ and $g^{*}=-51.4$. Herring [35] has shown that the angular momentum (2.138) may be spatially decomposed into intraatomic and interatomic contributions. The large $g$ values were shown to be associated with the latter, corresponding to interatomic circulating currents.

In this chapter we have seen the origins of various terms in the Hamiltonian that may influence the magnetic response of a system. In the remaining chapters we shall investigate how these terms manifest themselves when the system is excited with a space-and/or time-varying magnetic field.

## Problems

2.1. While the discussion in Sect.2.2.2 dealt mainly with the effect of the nuclear charge on the electron, the electron also affects the nucleus. $\mathrm{Co}^{57}$, for example, is radio-active with a half-life of 270 days. It captures an electron to form $\mathrm{Fe}^{57}$ which decays by $\gamma$-radiation to an excited state with $I=3 / 2$ which quickly $\left(1.4 \times 10^{-7} \mathrm{~s}\right)$ decays to the ground state with $I=1 / 2$.

Ordinarily when the nucleus emits a $\gamma$-ray it recoils. However in 1958, R.L. Mossbauer discovered that nuclei embedded in solids can emit and absorb $\gamma$-rays without transferring recoil energy to the lattice. The basic experimental arrangement for measuring the $\gamma$-ray energy consists of a moving source, an absorber, and a detector placed beyond the absorber. The transmitted intensity is plotted as a function of velocity. The $14.4 \mathrm{KeV} \gamma$-ray has a natural linewidth of $5 \times 10^{-9} \mathrm{eV}$ which corresponds to a Doppler velocity of $1 \mathrm{~mm} / \mathrm{s}$.
(a) In Sect. 2.2.2 we also assumed that there was no electron charge at the nucleus. But, in fact, $s$-electrons do have nonzero amplitude, $\psi(0)$, at the origin. Assuming the electron has a constant charge density, e $|\psi(0)|^{2}$, and interacts with the nuclear charge through a Coulomb potential $Z e / r$, out to a radius $r_{A}$ for the excited state and $r_{B}$ for the ground state, calculate the shift in the $\gamma$-ray energy due to this electronic charge density.
(b) If the emitter and the absorber have the same electronic structure their shifts will be the same. Therefore to observe this shift, called the isomer shift, the electronic charge density at the emitter nucleus, e $\left|\psi_{e}(0)\right|^{2}$ must be different from that at the absorber nucleus, $e\left|\psi_{a}(0)\right|^{2}$. Calculate the observed isomer shift, $\delta$, in terms of these wavefunctions.
(c) Suppose the electronic charge distribution produces an electric field gradient at the $\mathrm{Fe}^{57}$ nucleus. Using (2.38), sketch the effect of this gradient on the energy levels in Fig. 2.13. Assuming dipole transition selection rules, i.e., $\Delta m_{I}= \pm 1$, sketch the Mossbauer spectrum.
(d) In order to simplify the Mossbauer spectrum, either the source or absorber should have an unsplit line. $\mathrm{Co}^{57}$ diffused into stainless steel is such a case. Figure 2.14 shows the absorption of $\mathrm{Fe}^{57}$ in $\mathrm{Fe}_{2} \mathrm{O}_{3}$ of $\gamma$-rays emitted from a stainless steel source. What is the effective magnetic field at the nucleus? Discuss the origin of this field in the context of (2.38).
2.2. As an example of the usefulness of character tables consider an atomic electron surrounded by an environment that has cubic symmetry. In particular, suppose it has sixfold coordination as shown in Fig. 2.1a. The symmetry elements which take this environment into itself are the identity (E), eight rotations by $2 \pi / 3$ about the cube body diagonals (C3), three rotations by $\pi$ about the cube axis( C 2 ), six rotations by $\pi / 2$ about these same axes (C4) and six rotations by $\pi$ about axes through the origin parallel to face diagonals (C2). These operations constitute a group, generally labelled O. The number of elements of the group, denoted by $h$, is 24 in this case. Notice that


Fig. 2.13. Decay scheme of $\mathrm{Co}^{57}$ and $\mathrm{Fe}^{57}$


Fig. 2.14. The absorption of $\mathrm{Fe}^{57}$ bound in $\mathrm{Fe}_{2} \mathrm{O}_{3}$ of the 14.4 keV gamma ray emitted in the decay of $\mathrm{Fe}^{57}$ bound in stainless steel as a function of relative sourceabsorber velocity
the elements group themselves into classes, $G_{k}$, with $N_{k}$ elements. It can be shown that the number of irreducible representations is equal to the number of classes. Thus the character table will always be "square". The character table for this group is Table 2.6. An electron simply in a Coulomb potential has complete spherical symmetry. The set of rotations in three-dimensional space forms an infinite group. The eigenfunctions are spherical harmonics which transform into each other under rotation,

$$
U_{R}(\alpha) Y_{l}^{m}=\sum \Gamma^{(l)}(\alpha)_{m m^{\prime}} Y_{\lambda}^{m^{\prime}},
$$

where $\Gamma^{l}(\alpha)_{m m^{\prime}}=e^{i m \alpha} \delta_{m, m^{\prime}}$. Therefore the character is

$$
\chi^{l}(\alpha)=\frac{\sin (l+1 / 2) \alpha}{\sin (\alpha / 2)}
$$

Notice that the character associated with the identity operation, $E$, i.e., $\alpha=$ 0 , is

$$
\chi^{(l)}(0)=\lim _{\alpha \rightarrow 0} \frac{\sin (l+1 / 2) \alpha}{\sin (\alpha / 2)}=2 l+1
$$

In the presence of the lower cubic symmetry this $(2 l+1)$-dimensional representation is reducible to the irreducible representations of the O group. The decomposition of the reducible character is given by

$$
\chi(R)=\sum_{i} a_{i} \chi^{(l)}(R)
$$

where $\chi^{l}(R)$ is the character of the $i^{\text {th }}$ representation for the group element $R$. The coefficient $a_{i}$ is:

$$
a_{i}=(1 / h) \sum_{\boldsymbol{k}} N_{K} \chi^{(i)}\left(G_{K}\right)^{*} \chi\left(G_{K}\right) .
$$

Suppose, for example, we have an $s$-state $(1=0)$ electron in a cubic environment. Then the character $\chi^{(l)}(R)=1$ for each of the five classes, and the representation is simply $A_{1}$ :

$$
\frac{s}{\text { free space }} \quad \frac{A_{1}}{\text { cubic environment }} .
$$

Calculate how the $2 l+1$ degeneracies of $p, d$, and $f$ electrons are split in a cubic environment. Which have the potential for complete quenching?
2.3. Consider the sixfold coordination shown in Fig. 2.1a. If we elongate the neighbors in the $z$-direction, this corresponds to a tetragonal distortion and adds a term to the potential (2.50) proportional to $Y_{2}^{0}$. In cartesian coordinates this becomes

$$
C_{2}\left(3 z^{2}-r^{2}\right), \quad C_{2}=q q^{\prime}\left[\frac{1}{a_{1}^{3}}-\frac{1}{a_{2}^{3}}\right]
$$

for the sixfold tetragonal coordination we are considering. The corresponding operator equivalent is

Table 2.6. Character table for the point group O

|  | $E$ | $8 C_{3}$ | $3 C_{2}=3 C_{4}^{2}$ | $6 C_{2}$ | $6 C_{4}$ |
| :--- | ---: | ---: | :---: | ---: | ---: |
| $A_{1}$ | 1 | 1 | 1 | 1 | 1 |
| $A_{2}$ | 1 | 1 | 1 | -1 | -1 |
| $E$ | 2 | -1 | 2 | 0 | 0 |
| $T_{1}$ | 3 | 0 | -1 | -1 | 1 |
| $T_{2}$ | 3 | 0 | -1 | 1 | -1 |

$$
\sum\left(3 z^{2}-r^{2}\right) \Rightarrow \alpha \overline{r^{2}}\left[3 L_{z}^{2}-L(L+1)\right]
$$

where $\alpha= \pm 2 / 21$ for $D$ states, and where the negative sign applies for $T_{2}$ states and the plus sign for $E$ states.

Calculate the new eigenvalues and eigenfunctions resulting from this distortion, and plot the resulting splitting of the levels in Fig. 2.1 as a function of $C_{2} \alpha \overline{r^{2}}$.
2.4. The dipole-dipole interaction (2.58) can also give rise to anisotropy. Assuming all the spins are parallel and are characterized by direction cosines $\alpha_{x}, \alpha_{y}, \alpha_{z}$, express the anisotropy energy in terms of these cosines. Show that in a system with cubic anistropy the dipole interaction does not contribute to the anisotropy. In what sorts of materials would you expect to find dipolar anisotropy?
2.5. An alternative set of basis states for calculating the effect of electronelectron interactions are molecular orbitals. Consider the bonding and antibonding orbitals,

$$
\begin{aligned}
\varphi_{b}(\boldsymbol{r}) & =1 \sqrt{2(1+l)}\left[\varphi_{1}(\boldsymbol{r})+\varphi_{2}(\boldsymbol{r})\right] \\
\varphi_{a}(\boldsymbol{r}) & \left.=1 / \sqrt{2(1-l)}\left[\varphi_{1}\right)(\boldsymbol{r})-\varphi_{2}(\boldsymbol{r})\right]
\end{aligned}
$$

Each orbital can hold two electrons. Assume that one electron is in the bonding orbital and the other in the antibonding orbital. Calculate the matrix analogous to (2.81) and diagonalize to obtain the singlet and the triplet eigenvalues. What is the difference between the singlet and triplet energies? What is the role of the "exchange" integral $J_{12}$ ?
2.6. Using arguments similar to that used for $\left[\mathrm{FeCp}_{2}^{*}\right]^{+}[\mathrm{TCNE}]^{-}$, predict the magnetic order for the salts involving $\mathrm{Cr}, \mathrm{Mn}, \mathrm{Co}$, and Ni. The spin for these materials are $3 / 2,1,0$ and $1 / 2$, respectively, in accord with their electronic structures:

$$
\begin{aligned}
\mathrm{Cr}: & a_{1 g} e_{2 g}^{2} \\
\mathrm{Mn}: & a_{1 g} e_{2 g}^{3} \\
\mathrm{Co}: & a_{1 g}^{2} e_{2 g}^{4} \\
\mathrm{Ni}: & a_{1 g}^{2} e_{2 g}^{4} e_{1 g} .
\end{aligned}
$$

## The Static Susceptibility of Noninteracting Systems

In this chapter we shall investigate the static susceptibility of systems described by Hamiltonians which may be written as the sum of noninteracting terms. Our approach here, and in later discussions, will be to perturb the system with a magnetic field and then compute the response to this field. In this chapter we shall discuss the effect of a time-independent field $\boldsymbol{H}$.

In the literature of magnetism a distinction is often made between insulators and conductors. This distinction is basically an operational one. That is, insulators are characterized by charge distributions that are reasonably well localized to unit cells; such systems may be described by localized effective spins. Metals are characterized by itinerant electrons which require an entirely different description. Of course, there are materials, such as metals containing rare-earth ions, in which both types of charge distributions coexist. For the present, however, we shall follow tradition and discuss the response to local moments and itinerant systems separately.

### 3.1 Localized Moments

Let us consider a system of $N$ noninteracting identical ions or molecules each having $h$ electrons. In the absence of an external field each ion or molecule is characterized by a Hamiltonian $\mathcal{H}_{i}^{0}$. We are interested in the response of this system to a small static magnetic field. Therefore we add a Zeeman term to the Hamiltonian to give a total Hamiltonian,

$$
\begin{equation*}
\mathcal{H}=\sum_{i} \mathcal{H}_{i}=\sum_{i}\left(\mathcal{H}_{i}^{0}+\mathcal{H}_{i}^{Z}\right) . \tag{3.1}
\end{equation*}
$$

The magnetization is given by (1.49) as

$$
\begin{equation*}
\boldsymbol{M}(\boldsymbol{r})=\operatorname{Tr}\{\rho \boldsymbol{\mathcal { M }}(\boldsymbol{r})\} \tag{3.2}
\end{equation*}
$$

where

$$
\begin{equation*}
\mathcal{M}(\boldsymbol{r})=\frac{1}{2} \sum_{i=1}^{N} \sum_{\alpha=1}^{h}\left[\boldsymbol{\mu}_{i \alpha} \delta\left(\boldsymbol{r}-\boldsymbol{r}_{i \alpha}\right)+\delta\left(\boldsymbol{r}-\boldsymbol{r}_{i \alpha}\right) \boldsymbol{\mu}_{i \alpha}\right] . \tag{3.3}
\end{equation*}
$$

Here $\mu_{i \alpha}$ is the magnetic-moment operator associated with the $\alpha$ th electron on the $i$ th ion. Since the ionic electrons interact with one another, the appropriate basis in which to evaluate (3.2) consists of the ionic eigenfunctions. Therefore we make use of the Wigner-Eckhart theorem and replace (3.3) by

$$
\begin{equation*}
\mathcal{M}(\boldsymbol{r})=\sum_{i=1}^{N} \boldsymbol{\mu}_{i} \delta\left(\boldsymbol{r}-\boldsymbol{r}_{i}\right) . \tag{3.4}
\end{equation*}
$$

We have assumed that the ionic moments have no spatial extent. As long as the wavelength of the applied field is larger than an atomic dimension, (3.4) is valid. However, when we talk about neutron scattering in Chap. 10 this assumption will have to be modified.

Since we are applying a static field, the density matrix is independent of time. Therefore $[\mathcal{H}, \rho]=0$. The equilibrium solution of this equation may be written as [36]

$$
\begin{equation*}
\rho=\exp [\beta(F-\mathcal{H})], \tag{3.5}
\end{equation*}
$$

where $F$ is the free energy

$$
\begin{equation*}
F=-k_{B} T \ln Z \tag{3.6}
\end{equation*}
$$

and $Z$ is the partition function

$$
\begin{equation*}
Z=\operatorname{Tr}\{\exp (-\beta \mathcal{H})\} \tag{3.7}
\end{equation*}
$$

The solution (3.5) for the density matrix, known as the canonical distribution, is the quantum-mechanical generalization of the classical Gibbs distribution. Using (3.6), (3.7), we may write this as

$$
\begin{equation*}
\rho=\frac{\exp (-\beta \mathcal{H})}{\operatorname{Tr}\{\exp (-\beta \mathcal{H})\}} \tag{3.8}
\end{equation*}
$$

which, because of the form of the Hamiltonian (3.1), may be factored as

$$
\begin{equation*}
\rho=\frac{\Pi_{i} \exp \left(-\beta \mathcal{H}_{i}\right)}{\operatorname{Tr}\left\{\prod_{i} \exp \left(-\beta \mathcal{H}_{i}\right)\right\}}=\Pi_{i} \rho_{i} . \tag{3.9}
\end{equation*}
$$

Therefore

$$
\begin{equation*}
\boldsymbol{M}(\boldsymbol{r})=\sum_{i} \operatorname{Tr}\left\{\rho_{i} \boldsymbol{\mu}_{i} \delta\left(\boldsymbol{r}-\boldsymbol{r}_{i}\right)\right\}, \tag{3.10}
\end{equation*}
$$

which defines the ionic moment

$$
\begin{equation*}
\boldsymbol{M}_{i}=\operatorname{Tr}\left\{\rho_{i} \boldsymbol{\mu}_{i}\right\} . \tag{3.11}
\end{equation*}
$$

In writing (3.10) we have assumed that we may interchange the operations of taking the trace and summing over the ions. This neglects the possibility that an electron on one ion may hop over to a neighboring ion. If the electrons were distinct, as labeled by their positions in the lattice, such hopping would be forbidden. Therefore our assumption of interchangeability is, in this sense, equivalent to the assumption that the ionic electrons are distinguishable. The importance of this assumption will become evident in Sect.3.2.

So far we have not said anything about the spatial variation of the applied field. Let us assume that it has the wavelike form

$$
\begin{equation*}
\boldsymbol{H}(\boldsymbol{r})=\boldsymbol{H} \cos \left(\boldsymbol{q}_{0} \cdot \boldsymbol{r}\right) . \tag{3.12}
\end{equation*}
$$

We shall always assume that the wave vector $\boldsymbol{q}_{0}$ is one of the discrete wave vectors lying within the first Brillouin zone associated with the lattice under consideration. Let us keep in mind that we may have moments at only a few of the available lattice sites. If the applied field does not vary appreciably over a unit cell, the ionic eigenvalues will correspond to those of a uniform field with the value $\boldsymbol{H}_{i}=\boldsymbol{H} \cos \left(\boldsymbol{q}_{0} \cdot \boldsymbol{r}_{i}\right)$. The corresponding moment is

$$
\begin{equation*}
\boldsymbol{\mu}_{i}=\frac{\partial \mathcal{H}_{i}}{\partial \boldsymbol{H}_{i}} \tag{3.13}
\end{equation*}
$$

If the eigenvalues associated with the $i$ th ion are $E_{n}$, then the ionic moment in the direction of the applied field is

$$
\begin{equation*}
M_{i} \equiv \operatorname{Tr}\left\{\rho_{i} \mu_{i}\right\}=\frac{\sum_{n} \exp \left(-\beta E_{n}\right)\left(\partial E_{n} / \partial H_{i}\right)}{\sum_{n} \exp \left(-\beta E_{n}\right)} \tag{3.14}
\end{equation*}
$$

Since the eigenvalues $E_{n}$ are functions of the field $H_{i}$, let us expand in powers of the field:

$$
\begin{equation*}
E_{n}=E_{n}^{(0)}+E_{n}^{(1)} H_{i}+E_{n}^{(2)} H_{i}^{2}+\ldots \tag{3.15}
\end{equation*}
$$

Since the magnetic field is only a probe, we may make it as small as we like. In particular, let us assume that the field-dependent corrections to the energy in (3.15) are smaller than the thermal energy. Then

$$
\begin{equation*}
\exp \left(-\beta E_{n}\right)=\exp \left(-\beta E_{n}^{(0)}\right)\left(1-\beta E_{n}^{(1)} H_{i}-\ldots\right) \tag{3.16}
\end{equation*}
$$

and (3.14) becomes

$$
\begin{equation*}
\boldsymbol{M}_{i}=\frac{\sum_{n} \exp \left(-\beta E_{n}^{(0)}\right)\left(1-\beta E_{n}^{(1)} H_{i}-\ldots\right)\left(E_{n}^{(1)}+2 E_{n}^{(2)} H_{i}+\ldots\right)}{\sum_{n} \exp \left(-\beta E_{n}^{(0)}\right)\left(1-\beta E_{n}^{(1)} H_{i}-\ldots\right)} \tag{3.17}
\end{equation*}
$$

Assuming that the ion has no moment in the absence of the field and retaining only those terms linear in the field, we have

$$
\begin{equation*}
\boldsymbol{M}_{i}=\frac{\sum_{i}\left(\beta E_{n}^{(1) 2}-2 E_{n}^{(2)}\right) \exp \left(-\beta E_{n}^{(0)}\right)}{\sum_{n} \exp \left(-\beta E_{n}^{(0)}\right)} H_{i} \equiv \chi_{i} H_{i} \tag{3.18}
\end{equation*}
$$

which defines the quantity $\chi_{i}$. Substituting this expression back into (3.10) and taking the spatial Fourier transform, we obtain

$$
\boldsymbol{M}_{z}(\boldsymbol{k})=\sum_{i} \boldsymbol{M}_{i} \exp \left(-i \boldsymbol{k} \cdot \boldsymbol{r}_{i}\right)
$$

which may be written as

$$
\boldsymbol{M}_{z}(\boldsymbol{k})=\sum_{i}\left[\frac{1}{V} \sum_{i} \chi_{i} \exp [-i(\boldsymbol{k}-\boldsymbol{q})] \cdot \boldsymbol{r}_{i}\right] H(\boldsymbol{q})
$$

where

$$
H(\boldsymbol{q})=\frac{H V}{2}\left[\Delta\left(\boldsymbol{q}+\boldsymbol{q}_{0}\right)+\Delta\left(\boldsymbol{q}-\boldsymbol{q}_{0}\right)\right]
$$

Therefore

$$
\chi(\boldsymbol{k}, \boldsymbol{q})=\frac{1}{V} \sum_{i} \chi_{i} \exp \left[-i(\boldsymbol{k}-\boldsymbol{q}) \cdot \boldsymbol{r}_{i}\right]
$$

If there is a moment at each lattice site, then the sum in this expression gives $N \Delta(\boldsymbol{k}-\boldsymbol{q})$, and

$$
\begin{equation*}
\chi(\boldsymbol{q})=\frac{N}{V} \frac{\sum_{n}\left(\beta E_{n}^{(1) 2}-2 E_{n}^{(2)}\right) \exp \left(-\beta E_{n}^{(0)}\right)}{\sum_{n} \exp \left(-\beta E_{n}^{(0)}\right)} \equiv \chi \tag{3.19}
\end{equation*}
$$

The fact that this is independent of $\boldsymbol{q}$ is a consequence of our assumption that the magnetization is everywhere proportional to the local field. Thus it is not surprising that

$$
\begin{equation*}
\chi\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}\right)=\frac{1}{V} \sum_{\boldsymbol{q}} \exp \left[i \boldsymbol{q} \cdot\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}\right)\right] \chi(\boldsymbol{q})=\frac{N}{V} \chi \delta\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}\right) \tag{3.20}
\end{equation*}
$$

Let us now consider some specific applications of (3.19).

### 3.1.1 Diamagnetism

In Sect. 2.2 we found that the Zeeman Hamiltonian for an ionic or molecular system of electrons was

$$
\begin{equation*}
\mathcal{H}_{i}^{Z}=\sum_{\alpha}\left[\mu_{B} \boldsymbol{l}_{\alpha} \cdot \boldsymbol{H}_{i}+\frac{e^{2} H_{i}^{2}}{8 m c^{2}}\left(x_{\alpha}^{2}+y_{\alpha}^{2}\right)+\mu_{B} \boldsymbol{\sigma}_{\alpha} \cdot \boldsymbol{H}_{i}\right] . \tag{3.21}
\end{equation*}
$$

The effect of this interaction on the eigenvalues may be obtained from perturbation theory, with the eigenfunctions of $\mathcal{H}_{i}^{0}$ as the unperturbed states.

A diamagnetic system is one in which all the matrix elements of the orbital and spin angular momenta are 0 . Therefore the only correction to the energy arises from the second term in (3.21). If the eigenfunctions of $\mathcal{H}_{i}^{0}$ are written as $|n\rangle$, then

$$
\begin{equation*}
E_{n}^{(2)}=\frac{e^{2}}{8 m c^{2}}\langle n| \sum_{\alpha}\left(x_{\alpha}^{2}+y_{\alpha}^{2}\right)|n\rangle . . \tag{3.22}
\end{equation*}
$$

Notice that the susceptibility involves the statistical average of

$$
\sum_{\alpha}\left(x_{\alpha}^{2}+y_{\alpha}^{2}\right)
$$

This is usually written as $\frac{2}{3} Z$ times the mean square radius $\left\langle r^{2}\right\rangle$. Therefore the diamagnetic contribution to the quantity $\chi$ in the generalized susceptibility (3.19) is

$$
\begin{equation*}
\chi_{\text {diamag }}=-\frac{Z e^{2}}{6 m c^{2}}\left\langle r^{2}\right\rangle \tag{3.23}
\end{equation*}
$$

This negative response is just a manifestation of Lenz's law, which states that in the presence of a changing flux a system of charges will develop currents in such a direction as to oppose the flux change. These currents are the source of the diamagnetic moment.

In dielectric solids the molar susceptibility is of the order of $-10^{-5} \mathrm{~cm}^{3}$ / mole. This corresponds to an induced moment per atom of $10^{-8} H_{i}$ Bohr magneton, which is very small.

Notice that the diagmagnetic susceptibility appears to depend on the choice of the origin for computing $\left\langle r^{2}\right\rangle$. This ambiguity is, unfortunately, real. Van Vleck has shown that the change in diamagnetic susceptibility resulting from a change in origin is just compensated for by a corresponding change in the Van Vleck paramagnetic susceptibility, to be discussed in the next section [37]. For a single atom or ion the origin is usually taken at the nucleus. In this case the Van Vleck contribution is small, and the diamagnetic susceptibility is well described by (3.23). However for polyatomic molecules both contributions to the susceptibility must be considered together.

### 3.1.2 Paramagnetism of Transition-Metal Ions

In the preceding discussion we assumed that all the matrix elements, both diagonal and off-diagonal, of the orbital and spin angular moments were 0 . The interesting aspects of magnetism arise, however, when these matrix elements are nonzero. Let us now examine the response of such ions to a static field. Since crystal fields have important effects on the orbital angular momentum, it is convenient to discuss transition-metal ions and rare-earth ions separately.

In Sect. 2.3 we found that a transition-metal ion could be described by a spin Hamiltonian. Let us consider the particular case where the crystal field has removed all the orbital degeneracy. The spin Hamiltonian which describes the lowest orbital state then has the form

$$
\begin{equation*}
\mathcal{H}_{\mathrm{eff}}=g_{\|} \mu_{B} H S_{z}-\mu_{B}^{2} \wedge_{\|} H^{2} \tag{3.24}
\end{equation*}
$$

If we take the eigenfunctions of $S_{z}$ as our unperturbed states, then our orbital singlet splits into the $2 S+1$ states characterized by the spin-projection quantum number $M_{S}$,

$$
\begin{equation*}
E_{M_{S}}=E_{M_{S}}^{0}+g_{\| \mid} \mu_{B} M_{S} H-\mu_{B}^{2} \wedge_{\|} H^{2} \tag{3.25}
\end{equation*}
$$

Making the identifications with (3.15) and using (3.14), we find that the ( $\boldsymbol{k}=0, \boldsymbol{q}=0$ ) susceptibility may be written as the sum of the Langevin susceptibility and the Van Vleck susceptibility,

$$
\begin{equation*}
\chi(0,0)=\chi_{\text {Langevin }}+\chi_{V V} \tag{3.26}
\end{equation*}
$$

where

$$
\begin{equation*}
\chi_{\text {Langevin }}=\frac{N}{V} \frac{g_{\|}^{2} \mu_{B}^{2}}{k_{B} T} \frac{\sum_{M=-S}^{S} M_{s}^{2}}{2 S+1}=\frac{N}{V} \frac{g_{\|}^{2} \mu_{B}^{2} S(S+1)}{3 k_{B} T} \equiv \frac{C}{T} \tag{3.27}
\end{equation*}
$$

which defines the Curie constant $C$, and

$$
\begin{equation*}
\chi_{V V}=\frac{N}{V} 2 \mu_{B}^{2} \wedge_{\|} \tag{3.28}
\end{equation*}
$$

The Van Vleck susceptibility arises from that part of the orbital moment which has been admixed back into the ground state by the orbital Zeeman effect. The fact that this contribution is temperature independent is a result of the assumption that the energy difference between the ground state and the higher-lying orbital state entering $\wedge_{\|}$is larger than $k_{B} T$. If this condition does not hold, then the energy shift of this upper state must be considered, with the result that the Van Vleck susceptibility will acquire a temperature dependence.

The inverse temperature dependence of the Langevin susceptibility was first observed experimentally by Pierre Curie in 1895 and is referred to as

Table 3.1. Effective moments associated with transition-metal ions [38]

|  | $\mathrm{Ti}^{3+}$ | $\mathrm{V}^{3+}$ | $\mathrm{Cr}^{3+}$ | $\mathrm{Mn}^{3+}$ | $\mathrm{Mn}^{2+}, \mathrm{Fe}^{3+}$ | $\mathrm{Fe}^{2+}$ | $\mathrm{Co}^{2+}$ | $\mathrm{Ni}^{2+}$ | $\mathrm{Cu}^{2+}$ |
| :--- | ---: | ---: | ---: | ---: | :---: | ---: | ---: | ---: | ---: |
| $2 \sqrt{S(S+1)}$ | 1.73 | 2.83 | 3.87 | 4.00 | 5.92 | 4.90 | 3.87 | 2.83 | 1.73 |
| $\mu_{\text {eff }}(\exp )$ | 1.80 | 2.80 | 3.80 | 4.90 | 5.90 | 5.40 | 4.80 | 3.20 | 1.90 |
| $g_{J} \sqrt{J(J+1)}$ | 1.55 | 1.63 | 0.77 | 0 | 5.92 | 6.70 | 6.63 | 5.59 | 3.55 |
| $\lambda\left[\mathrm{~cm}^{-1}\right]$ | 154 | 105 | 91 | 88 | - | -103 | -178 | -325 | -829 |

Curie's law. The Curie constant $C$ is used experimentally to determine an effective moment in units of Bohr magnetons by the relation

$$
\begin{equation*}
\mu_{\mathrm{eff}}=\sqrt{\frac{3 k_{B} C}{(N / V) \mu_{B}^{2}}} . \tag{3.29}
\end{equation*}
$$

If the experimental values of $\mu_{\text {eff }}$ are compared with the spin-only theoretical values in Table 3.1, we see that the quenching is nearly complete for the first half of the periodic table. Orbital contributions become more important in the last half of the row because the spin-orbit coupling constant is becoming larger.

Because of the availability of high-static magnetic fields and low temperatures it is relatively easy to reach the nonlinear region of saturation. To describe this situation we must use the more general expression for the ionic moment given by (3.14). The Van Vleck susceptibility is unchanged. However, the Langevin susceptibility becomes

$$
\begin{align*}
\chi_{\text {Langevin }} & =-\frac{N g_{\|} \mu_{B} S}{H V} \frac{\sum_{M_{S}=-S}^{S}\left[\exp \left(-\beta g_{\|} \mu_{B} H M_{S}\right)\right] M_{S} / S}{\sum_{M_{S}=-S}^{S} \exp \left(-\beta g_{\|} \mu_{B} H M_{S}\right)} \\
& =\frac{N g_{\|} \mu_{B} S}{H V} B_{S}\left(\frac{g_{\|} \mu_{B} S H}{k_{B} T}\right) \tag{3.30}
\end{align*}
$$

where $B_{S}\left(g_{\|} \mu_{B} S H / k_{B} T\right)$ defines the Brillouin function,

$$
\begin{equation*}
B_{S}(x)=\frac{2 S+1}{2 S} \operatorname{coth}\left(\frac{(2 S+1) x}{2 S}\right)-\frac{1}{2 S} \operatorname{coth}\left(\frac{x}{2 S}\right) \tag{3.31}
\end{equation*}
$$

For $S=1 / 2, B_{1 / 2}=\tanh (x)$.
It is customary for experimentalists to plot the inverse susceptibility against temperature. In Fig. 3.1 we have plotted $1 / \chi$ for a spin of $\frac{3}{2}$ in a field of $30,000 \mathrm{Oe}$. Since the Curie constant is of the order of unity, the Van Vleck contribution becomes important only for $T>\chi_{V V}^{-1}$. Normally, the Van Vleck susceptibility is of the order of $10^{-5}$. However, the larger value of $10^{-3}$ has been chosen in Fig. 3.1 to illustrate its effect.

The only approximation in obtaining (3.17) was that the Zeeman energy be smaller than the thermal energy. Therefore this expression also applies if the thermal energy exceeds the crystal-field energy. In this case we must be careful to use the proper energies $E_{n}$. We shall consider an example of how to include excited-state effects in the next section.

### 3.1.3 Paramagnetism of Rare-Earth Ions

The effect of crystal fields on rare-earth ions is generally quite small in comparison with the spin-orbit interaction. Let us therefore consider our rareearth ion as described by eigenstates characterized by the quantum numbers $J, M_{J}, L$, and $S$. The perturbing Zeeman Hamiltonian has the form


Fig. 3.1. Inverse susceptibility as a function of temperature for a spin $\frac{3}{2}$ in a field of $30,000 \mathrm{Oe}$

$$
\begin{equation*}
\mathcal{H}_{Z}=\mu_{B}(\boldsymbol{L}+2 \boldsymbol{S}) \cdot \boldsymbol{H} \tag{3.32}
\end{equation*}
$$

If we restrict ourselves to the lowest $J$ manifold and define the $z$ direction as the direction of the applied field, then this Hamiltonian becomes

$$
\begin{equation*}
\mathcal{H}_{Z}=g_{J} \mu_{B} H J_{z} . \tag{3.33}
\end{equation*}
$$

The effect of this interaction is to split the $J$ state into its $2 J+1$ Zeeman components, with energies

$$
\begin{equation*}
E_{J, M_{J}}=g_{J} \mu_{B} M_{J} H \tag{3.34}
\end{equation*}
$$

From (3.15), (3.19) we find

$$
\begin{equation*}
\chi(0,0)=\frac{N}{V} \frac{g_{J}^{2} \mu_{B}^{2} J(J+1)}{3 k_{B} T}, \tag{3.35}
\end{equation*}
$$

and from (3.29) we obtain the effective moment,

$$
\begin{equation*}
\mu_{\mathrm{eff}}=g_{J} \sqrt{J(J+1)} . \tag{3.36}
\end{equation*}
$$

Most of the rare-earth ions exhibit moments in good agreement with (3.36). However, a notable exception is $\mathrm{Eu}^{3+}$. This has a $4 f^{6}$ configuration, which corresponds to a ${ }^{7} F_{0}$ ground state. Therefore $J=0$, and $\mu_{\text {eff }}$ should also be 0 . Experimentally, however, a moment of 3.4 Bohr magnetons has been found at room temperature. To account for this difference we note that the ${ }^{7} F_{1}$ excited state lies $\Delta / k_{B} \simeq 350 \mathrm{~K}$ above the ground state. Therefore we


Fig. 3.2. Effect of the Zeeman interaction on the low-lying states of Eu ${ }^{3+}$
must include the influence of this state on our susceptibility. There are two effects to be considered, the addition of the terms in (3.19) associated with the excited state and the shift in the ground-state energy produced by the Zeeman coupling to the excited state.

From perturbation theory we find that the first-order corrections to the energies are

$$
\begin{equation*}
E_{J, M_{J}}^{(1)} H=g_{J} \mu_{B} H\left\langle J, M_{J}\right| J_{z}\left|J, M_{J}\right\rangle \tag{3.37}
\end{equation*}
$$

and the second-order corrections are

$$
\begin{equation*}
E_{J, M_{J}}^{(2)} H^{2}=\mu_{B}^{2} H^{2} \sum_{J^{\prime}, M_{J^{\prime}}^{\prime}} \frac{\left.\left|\left\langle J, M_{J}\right| L_{z}+2 S_{z}\right| J^{\prime}, M_{J^{\prime}}^{\prime}\right\rangle\left.\right|^{2}}{E_{J, M_{J}}^{(0)}-E_{J^{\prime}, M_{J^{\prime}}^{\prime}}^{(0)}} \tag{3.38}
\end{equation*}
$$

From the properties of angular momentum [39] we find that the matrix element in (3.38) is nonvanishing only for $J^{\prime}=J \pm 1$ and $M_{J^{\prime}}^{\prime}=M_{J}$. Therefore only the $|0,0\rangle$ and $|1,0\rangle$ states are coupled in second order. This matrix element is $\langle 0,0| L_{z}+2 S_{z}|1,0\rangle=2$. The resulting eigenvalues are

$$
\begin{align*}
E_{0,0} & =-\frac{4 \mu_{B}^{2} H^{2}}{\Delta} \\
E_{1,-1} & =\Delta-g_{1} \mu_{B} H \\
E_{1,0} & =\Delta+\frac{4 \mu_{B}^{2} H^{2}}{\Delta} \\
E_{1,1} & =\Delta+g_{1} \mu_{B} H \tag{3.39}
\end{align*}
$$

where $g_{1}$ is the Landé $g$ value (2.124) for $J=1$. These eigenvalues are indicated in Fig. 3.2. Substituting these results into (3.19) leads to an effective moment at room temperature of 3.2 Bohr magnetons, in much better agreement with the experimental value.

In conclusion, we have found that the susceptibility of an insulator containing noninteracting ionic moments is

$$
\begin{equation*}
\chi(T)=\chi_{\text {diamag }}+\chi(T)_{\text {Langevin }}+\chi_{V V} . \tag{3.40}
\end{equation*}
$$

The temperature dependence arises primarily from the Langevin or Curie part.

### 3.2 Metals

We now turn to the response of a nonmagnetic metal to an applied field. The static response to a uniform field was first investigated by Pauli, who considered the spin paramagnetism, and by Landau, who considered the orbital diamagnetism.

### 3.2.1 Landau Diamagnetism

Let us consider the orbital moment induced in a free-electron metal by a static applied field. For the time being we shall neglect the spin associated with the electrons in a metal. As mentioned in Sect. 1.2, the classical approach to this problem leads to the conclusion that the metal shows no response to the applied field. Landau was the first to show that a quantum-mechanical approach indicates that a free-electron system does in fact respond to the applied field, and that this response is diamagnetic [40]. What he did was to solve the Schrödinger equation for a single electron in a magnetic field; with the resulting eigenvalues he was able to compute the free energy, from which he obtained the magnetization. The corresponding susceptibility was found to be $-\frac{1}{3}$ that obtained by Pauli for the spin contribution. This relationship is valid for all temperatures in degenerate as well as nondegenerate free-electron systems.

Peierls extended Landau's calculation to the case of electrons that are nearly bound by a periodic lattice potential [41], and Wilson considered nearly free electrons [42]. It was found that the effect of the lattice was, essentially, to modify Landau's result by a factor $m / m^{*}$, where $m^{*}$ is the electron effective mass at the Fermi surface.

It is interesting to consider why Miss van Leeuwen's theorem, which we mentioned in Sect. 1.2, does not hold in the quantum-mechanical case. The reason is that those electrons whose orbits are interrupted by the boundary have, in general, high quantum numbers. Therefore, their energy is also high which makes them thermo-dynamically less important than the "bulk" electrons. Consequently, the diamagnetic moments now dominate the paramagnetic moments arising from the "boundary" electrons.

The problem of boundary effects arises when one calculates the susceptibility by first solving the Schrödinger equation for the energy levels explicitly and then using them to calculate the partition function. Sondheimer and Wilson
have pointed out that the whole question of boundary effects may be avoided by calculating the partition function without explicit knowledge of the energy levels [43].

We shall now calculate the Landau susceptibility by another method [44] that is more in keeping with our linear response philosophy. Let us assume that we have a free-electron system characterized by a spherical Fermi surface. To this system we apply a static external magnetic field $\boldsymbol{H}_{0}(\boldsymbol{r})$, which arises from an external current density $\boldsymbol{j}_{0}(\boldsymbol{r})$ according to the Maxwell equation

$$
\begin{equation*}
\nabla \times \boldsymbol{H}_{0}(\boldsymbol{r})=\frac{4 \pi}{c}\left\langle\boldsymbol{j}_{0}(\boldsymbol{r})\right\rangle \tag{3.41}
\end{equation*}
$$

This field induces a current density $\boldsymbol{j}(\boldsymbol{r})$ in the electron system, which in turn acts as the source for an additional magnetic field. The resulting total local field, denoted by $\boldsymbol{H}(\boldsymbol{r})$, is also related to its current sources by the Maxwell equation

$$
\begin{equation*}
\nabla \times \boldsymbol{H}(\boldsymbol{r})=\frac{4 \pi}{c}\left\langle\boldsymbol{j}_{0}(\boldsymbol{r})+\boldsymbol{j}(\boldsymbol{r})\right\rangle \tag{3.42}
\end{equation*}
$$

The local field defined in this manner has zero divergence. Therefore it may be expressed in terms of a vector potential as

$$
\begin{equation*}
\boldsymbol{H}(\boldsymbol{r})=\nabla \times \boldsymbol{A}(\boldsymbol{r}) . \tag{3.43}
\end{equation*}
$$

In the presence of this potential the electron velocity becomes

$$
\begin{equation*}
\boldsymbol{v}_{i}=\frac{1}{m}\left[\boldsymbol{p}_{i}-\frac{e}{c} \boldsymbol{A}\left(\boldsymbol{r}_{i}\right)\right] \tag{3.44}
\end{equation*}
$$

The induced-current-density operator is related to this velocity by

$$
\begin{equation*}
\boldsymbol{j}(\boldsymbol{r})=\frac{e}{2} \sum_{i}\left[\boldsymbol{v}_{i} \delta\left(\boldsymbol{r}-\boldsymbol{r}_{i}\right)+\delta\left(\boldsymbol{r}-\boldsymbol{r}_{i}\right) \boldsymbol{v}_{i}\right] \tag{3.45}
\end{equation*}
$$

According to (1.8), the average value of this current density determines the magnetization,

$$
\begin{equation*}
\langle\boldsymbol{j}(\boldsymbol{r})\rangle=c \nabla \times \boldsymbol{M}(\boldsymbol{r}) \tag{3.46}
\end{equation*}
$$

Using the Fourier transforms of (3.42), (3.43), (3.46) and the definition of the susceptibility, $\left.\boldsymbol{M}(\boldsymbol{q})=\boldsymbol{\chi}(\boldsymbol{q}) \cdot \boldsymbol{H}_{0} \boldsymbol{q}\right)$, we obtain

$$
\begin{equation*}
\chi(\boldsymbol{q})=\frac{1}{4 \pi} \frac{\langle\boldsymbol{j}(\boldsymbol{q})\rangle}{\langle\boldsymbol{j}(\boldsymbol{q})\rangle-\left(c q^{2} / 4 \pi\right) \boldsymbol{A}(\boldsymbol{q})} \tag{3.47}
\end{equation*}
$$

Therefore, if we can compute the average current density to lowest order in the vector potential, we shall have an expression for the susceptibility.

Introducing the Fourier momentum operator $\boldsymbol{p}_{\boldsymbol{q}}$, defined by

$$
\begin{equation*}
\boldsymbol{p}_{\boldsymbol{q}} \equiv \frac{1}{2} \sum_{i}\left[\boldsymbol{p}_{i} \exp \left(-i \boldsymbol{q} \cdot \boldsymbol{r}_{i}\right)+\exp \left(-i \boldsymbol{q} \cdot \boldsymbol{r}_{i}\right) \boldsymbol{p}_{i}\right] \tag{3.48}
\end{equation*}
$$

we find from (3.45) that

$$
\begin{equation*}
\langle\boldsymbol{j}(\boldsymbol{q})\rangle=\frac{e}{m}\left\langle\boldsymbol{p}_{\boldsymbol{q}}\right\rangle-\frac{N e^{2}}{m c V} \boldsymbol{A}(\boldsymbol{q}) . \tag{3.49}
\end{equation*}
$$

To obtain the diagonal components of $\chi$ we must find the average value of that component of $\boldsymbol{p}_{\boldsymbol{q}}$ parallel to $\boldsymbol{A}(\boldsymbol{q})$ to the lowest order in the vector potential. If $\hat{\boldsymbol{n}}$ is a unit vector parallel to $\boldsymbol{A}(\boldsymbol{q})$, then we must compute $\left\langle\boldsymbol{p}_{\boldsymbol{q}} \cdot \hat{\boldsymbol{n}}\right\rangle$. This we shall do by perturbation theory.
In the presence of the field the Hamiltonian is

$$
\begin{equation*}
\mathcal{H}=\sum_{i} \frac{1}{2 m}\left[\boldsymbol{p}_{i}-\frac{e}{c} \boldsymbol{A}\left(\boldsymbol{r}_{i}\right)\right]^{2} \tag{3.50}
\end{equation*}
$$

Since the kinetic-energy part gives rise to our unperturbed Fermi sphere, the perturbation, to lowest order, is

$$
\begin{equation*}
\mathcal{H}_{1}=-\frac{e}{m c} \sum_{i} \boldsymbol{A}\left(\boldsymbol{r}_{i}\right) \cdot \boldsymbol{p}_{i} \tag{3.51}
\end{equation*}
$$

Expanding $\boldsymbol{A}\left(\boldsymbol{r}_{i}\right)$ in a Fourier series and making use of (3.48), we obtain

$$
\begin{equation*}
\mathcal{H}_{1}=-\frac{e}{m c V} \sum_{k} \boldsymbol{A}(\boldsymbol{k}) \cdot \boldsymbol{p}_{\boldsymbol{k}} \tag{3.52}
\end{equation*}
$$

Writing the eigenstate of the perturbed system as $|n\rangle$ and that of the unperturbed system as $\mid n)$, we have

$$
\begin{equation*}
\left.|0\rangle=\mid 0) \left.+\sum_{n \neq 0} \frac{\left(n\left|\mathcal{H}_{1}\right| 0\right)}{E_{0}-E_{n}} \right\rvert\, n\right) \tag{3.53}
\end{equation*}
$$

Therefore

$$
\begin{equation*}
\left\langle\boldsymbol{p}_{\boldsymbol{q}} \cdot \hat{\boldsymbol{n}}\right\rangle \hat{\boldsymbol{n}}=\frac{2 e}{m c V} \sum_{n \neq 0} \frac{\left|\left(n\left|\boldsymbol{p}_{\boldsymbol{q}} \cdot \hat{\boldsymbol{n}}\right| 0\right)\right|^{2}}{E_{n}-E_{0}} \boldsymbol{A}(\boldsymbol{q}) . \tag{3.54}
\end{equation*}
$$

Since the states $\mid n)$ are many-electron states and the operator $\boldsymbol{p}_{\boldsymbol{q}}$ is a manyelectron operator, it is convenient to second quantize $\boldsymbol{p}_{\boldsymbol{q}}$ :

$$
\begin{equation*}
\boldsymbol{p}_{\boldsymbol{q}} \cdot \hat{\boldsymbol{n}}=\sum_{k} \hbar \boldsymbol{k} \cdot \hat{\boldsymbol{n}} c_{\boldsymbol{k}+\boldsymbol{q}}^{\dagger} c_{\boldsymbol{k}} \tag{3.55}
\end{equation*}
$$

Therefore the state $\mid n$ ) corresponds to the one in which we have taken an electron in state $\boldsymbol{k}$ inside the Fermi surface and moved it to the state $\boldsymbol{k}+\boldsymbol{q}$ outside the Fermi surface. Equation (3.54) becomes

$$
\begin{gather*}
\left\langle\boldsymbol{p}_{\boldsymbol{q}} \cdot \hat{\boldsymbol{n}}\right\rangle \hat{\boldsymbol{n}}=\frac{2 e}{c V} \sum_{k<k_{F}} \frac{(\boldsymbol{k} \cdot \hat{\boldsymbol{n}})^{2}}{\boldsymbol{k} \cdot \boldsymbol{q}+q^{2} / 2} \boldsymbol{A}(\boldsymbol{q}) .  \tag{3.56}\\
|\boldsymbol{k}+\boldsymbol{q}|>k_{F}
\end{gather*}
$$



Fig. 3.3. Wave-vector dependence of the Landau and Pauli susceptibilities. The sum is shown by the solid curve

Converting the sum to an integral in (3.56) leads to the susceptibility

$$
\begin{equation*}
\chi_{L}(\boldsymbol{q})=\chi_{L} \frac{3 k_{F}^{2}}{2 q^{2}}\left[1+\frac{q^{2}}{4 k_{F}^{2}}-\frac{k_{F}}{q}\left(1-\frac{q^{2}}{4 k_{F}^{2}}\right)^{2} \ln \left|\frac{2 k_{F}+q}{2 k_{F}-q}\right|\right] \tag{3.57}
\end{equation*}
$$

where

$$
\begin{equation*}
\chi_{L}=-\frac{(N / V) e^{2}}{4 m c^{2} k_{F}^{2}}=-\frac{e^{2} k_{F}}{12 \pi^{2} m c^{2}} \tag{3.58}
\end{equation*}
$$

The second expression was arrived at by using $N / V=k_{F}^{3} / 3 \pi^{2}$, which assumes that each point in $k$ space has a twofold spin degeneracy. This result for $q=0$ was first obtained by Landau, and as we shall see in the next section, it is $-\frac{1}{3}$ the Pauli susceptibility. The $q$ dependence of $\chi_{L}(\boldsymbol{q})$ is shown in Fig. 3.3.

As we mentioned above, Peierls considered the effect of a periodic potential upon the orbital susceptibility. His result, which neglects interband effects, takes the form [41].

$$
\begin{equation*}
\chi_{L P}=-\frac{e^{2}}{48 \pi^{3} \hbar^{2} c^{2}} \int\left[\frac{\partial^{2} \epsilon}{\partial k_{x}^{2}} \frac{\partial^{2} \epsilon}{\partial k_{y}^{2}}-\left(\frac{\partial^{2} \epsilon}{\partial k_{x} \partial k_{y}}\right)^{2}\right] \frac{d S}{\left|\nabla_{k} \epsilon\right|} . \tag{3.59}
\end{equation*}
$$

If $\epsilon(\boldsymbol{k})=\hbar^{2} k^{2} / 2 m^{*}$ we obtain the factor $m / m^{*}$ mentioned above.
The general form of the orbital susceptibility of noninteracting Bloch electrons was established in the early 1960s. However, the formulas were quite complicated. In 1970 Fukayama [45] reformulated these results in a way which allows calculations to be carried out for realistic energy bands. The susceptibility is found to be a sensitive function of the position of the Fermi level relative to critical points in the Brillouin zone. This is illustrated by Fig. 3.4 which shows the susceptibility, in units of the Landau susceptibility, for a simple model which is periodic in the $x$ direction and free-electron-like in the other directions. The large diamagnetism of bismuth is due to such an interband effect and has the same physical interpretation of large interatomic circulating currents that give rise to large $g$ values (see p. 79).

In dealing with electrons in bands other than $s$ bands the possibility arises of a paramagnetic orbital contribution. Such a contribution was first pointed

(a)

(b)

Fig. 3.4. Orbital susceptibility (b) as a function of the Fermi level for the band structure shown in (a)
out by Kubo and Obata [46] and has the same origin as the Van Vleck susceptibility in the case of localized electrons. That is, it is a second-order effect involving the orbital part of the Zeeman interaction. In a metal this takes the form

$$
\begin{equation*}
\left.\chi_{\text {orb }}=\frac{2 \mu_{B}^{2}}{(2 \pi)^{3}} \int d \boldsymbol{k} \sum_{m^{\prime} \neq m} \frac{f\left(\epsilon_{m k}\right)-f\left(\epsilon_{m^{\prime} k}\right)}{\epsilon_{m^{\prime} k}-\epsilon_{m k}}\left|\left\langle m^{\prime} \boldsymbol{k}\right| \boldsymbol{L}\right| m \boldsymbol{k}\right\rangle\left.\right|^{2}, \tag{3.60}
\end{equation*}
$$

where $\epsilon_{m k}$ is the energy of an electron in the band $m$ with wave vector $\boldsymbol{k}$. The factor 2 in the numerator arises from the two spin states.

Finally, it is worth mentioning that in a superconductor the presence of a gap in the energy spectrum leads to the result that $\left\langle\boldsymbol{p}_{\boldsymbol{q}} \cdot \hat{\boldsymbol{n}}\right\rangle=0$. Therefore

$$
\begin{equation*}
\chi(\boldsymbol{q})_{\text {super }}=-\frac{1}{4 \pi} \frac{\omega_{p}^{2} / c^{2}}{q^{2}+\omega_{p}^{2} / c^{2}} \tag{3.61}
\end{equation*}
$$

where $\omega_{p}^{2}=4 \pi n e^{2} / m$ is the plasma frequency. The corresponding screening length is the London penetration length $\left(m c^{2} / 4 \pi n e^{2}\right)^{1 / 2}$. As $q \rightarrow 0$ this reduces to the susceptibility of a perfect diamagnet, $-1 / 4 \pi$.

### 3.2.2 The de Haas-van Alphen Effect

Just as in the ionic case, when the temperature becomes very low or the field very large, such that $\mu_{B} H>k_{B} T$, nonlinear effects begin to appear. In the case of metallic diamagnetism this nonlinearity manifests itself as a periodic variation of the induced moment as a function of $1 / H$. Such behavior was
suspected by Landau [40], worked out in detail by Peierls [41], and observed by de Haas and van Alphen [47]. This de Haas-van Alphen effect, as it is now known, has become important in determining the nature of Fermi surfaces.

The perturbation approach used to compute the Landau susceptibility is not sufficient to describe the de Haas-van Alphen effect. Therefore, we shall compute the susceptibility from the free energy which is, in turn, obtained from an explicit knowledge of the energy levels. It should be mentioned that Sondheimer and Wilson [43] have shown that for a degenerate electron system the free energy is given by the inverse Laplace transform of the classical partition function $Z(\beta)$ where $\beta=1 / k_{B} T$ is regarded as a complex variable. The interesting feature of this approach is that $Z(\beta)$ contains a branch point at the origin which is responsible for the Landau diamagnetism and a row of poles on the imaginary axis that lead to the de Haas-van Alphen oscillations.

The Schrödinger equation for an electron in a uniform magnetic field is

$$
\begin{equation*}
\frac{1}{2 m}\left(\boldsymbol{p}-\frac{e}{c} \boldsymbol{A}\right)^{2} \psi=E \psi \tag{3.62}
\end{equation*}
$$

Landau noticed that it is particularly convenient to choose the gauge $\boldsymbol{A}=$ $\boldsymbol{H} \times \hat{\boldsymbol{y}}$. Equation (3.62) then becomes

$$
\begin{equation*}
\frac{\partial^{2} \psi}{\partial x^{2}}+\left(\frac{\partial}{\partial y}-i \frac{e H}{\hbar c} x\right)^{2} \psi+\frac{\partial^{2} \psi}{\partial z^{2}}+\frac{2 m E}{\hbar^{2}} \psi=0 \tag{3.63}
\end{equation*}
$$

If we assume a solution of the form

$$
\begin{equation*}
\psi=\exp \left[i\left(k_{y} y+k_{z} z\right)\right] \varphi(x) \tag{3.64}
\end{equation*}
$$

then $\varphi(x)$ must satisfy

$$
\begin{equation*}
\frac{\partial^{2} \varphi}{\partial x^{2}}+\left[\frac{2 m E}{\hbar^{2}}-k_{z}^{2}-\left(k_{y}-\frac{e H}{\hbar c} x\right)^{2}\right] \varphi=0 \tag{3.65}
\end{equation*}
$$

But this is just the Schrödinger equation for a one-dimensional harmonc oscillator centered at $x_{0}=\hbar c k_{y} / e H$. Therefore we may immediately write the total eigenfunction as

$$
\begin{equation*}
\psi_{n, k_{y}, k_{z}}=\frac{N_{n}}{\sqrt{L_{y} L_{z}}} \exp \left[i\left(k_{y} y+k_{z} z\right)\right] \exp \left[-\left(\alpha^{2} / 2\right)\left(x-x_{0}\right)^{2}\right] H_{n}\left[\alpha\left(x-x_{0}\right)\right] \tag{3.66}
\end{equation*}
$$

where $N_{n}$ is a normalization factor, $H_{n}$ is a Hermite polynomial, and $\alpha=$ $\left(m \omega_{c} / \hbar\right)^{1 / 2}, \omega_{c}$ being the cyclotron frequency $|e| H / m c$. This has the eigenvalue

$$
\begin{equation*}
E_{n, k_{y}, k_{z}}=\left(n+\frac{1}{2}\right) \hbar \omega_{c}+\frac{\hbar^{2} k_{z}^{2}}{2 m} \tag{3.67}
\end{equation*}
$$

We could now proceed to compute the moment by means of the partition function (3.7). However, in computing the trace we must be careful to preserve
the total number of electrons. This was not a problem with insulators, since each of the ions or electrons was distinguishable. In a metal, however, we have no ionic cores on which to "trap" electrons and thereby identify them. Thus we are left with a system of $N$ truly identical particles. In such a situation it is convenient to sum over all possible states, irrespective of the number of particles involved, but to include in the distribution function a factor that ensures that the total number of particles is conserved. In mathematics such a factor is called a Lagrange multiplier. In our particular application it is referred to as the chemical potential. Thus we shall take as the equilibrium density matrix [36]

$$
\begin{equation*}
\rho=\exp [\beta(\Omega-\mathcal{H}+\lambda \mathcal{N})] \tag{3.68}
\end{equation*}
$$

where $\Omega$ is the thermodynamic potential

$$
\begin{equation*}
\Omega=-k_{B} T \ln \mathcal{Q} \tag{3.69}
\end{equation*}
$$

and $\mathcal{Q}$ is the grand partition function

$$
\begin{equation*}
\mathcal{Q}=\operatorname{Tr}\{\exp [-\beta \mathcal{H}-\lambda \mathcal{N}]\} \tag{3.70}
\end{equation*}
$$

Here $\mathcal{N}$ is the total number operator and $\lambda$ is the chemical potential, which is to be determined by the condition

$$
\begin{equation*}
\langle\mathcal{N}\rangle=N . \tag{3.71}
\end{equation*}
$$

The trace in (3.70) is taken without any restriction on the total number of particles. Equation (3.68) is referred to as the grand canonical distribution.

Since the total number of particles is not dependent on the magnetic field, we generalize (1.22) to

$$
\begin{equation*}
M=\frac{k_{B} T}{V} \frac{\partial}{\partial H} \ln \Omega \tag{3.72}
\end{equation*}
$$

In computing the trace indicated in (3.70) we shall take as our basis states those of the form (1.106). Since there is no restriction on the total number of particles, there will be a state with no particles, $\left|0_{1}, 0_{2}, \ldots, 0_{i}, \ldots, 0_{\infty}\right\rangle$; infinitely many with one particle, $\left|1_{1}, 0_{2}, \ldots, 0_{i} \ldots\right\rangle$; etc. Here $i$ stands for the set of quantum numbers $\left\{n, k_{y}, k_{z}\right\}$. Thus $\mathcal{Q}$ takes the form

$$
\begin{equation*}
\mathcal{Q}=1+\sum_{i} \exp \left[-\beta\left(E_{i}-\lambda\right)\right]+\sum_{i \neq j} \exp \left[-\beta\left(E_{i}-\lambda\right)\right] \exp \left[-\beta\left(E_{j}-\lambda\right)\right]+\ldots \tag{3.73}
\end{equation*}
$$

This may be rewritten as

$$
\begin{equation*}
\mathcal{Q}=\Pi_{i}\left(1+\exp \left[-\beta\left(E_{i}-\lambda\right)\right]\right) \tag{3.74}
\end{equation*}
$$



Fig. 3.5. Oscillatory component of the diamagnetic moment in iron (a) with its frequency spectrum (b) (courtesy of G.G. Lonzarich)

Therefore the thermodynamic potential becomes

$$
\begin{equation*}
\Omega=-k_{B} T \sum_{i} \ln \left(1+\exp \left[-\beta\left(E_{i}-\lambda\right)\right]\right) . \tag{3.75}
\end{equation*}
$$

In the absence of a magnetic field the states would be characterized by their wave vector $\boldsymbol{k}$, and the sum in (3.75) would be converted to an integral over $\boldsymbol{k}$ space. In the presence of the field, however, we find that the states are characterized by $n, k_{y}$, and $k_{z}$. What has happened is that the original distribution of points in the $k_{x} k_{y}$ plane has condensed onto "tubes" parallel to the $k_{z}$ axis labeled by the quantum number $n$. Since this total number of states must remain the same, we find that the number of states along a length $d k_{z}$ of such a tube is $\left(e H V / 2 \pi^{2} \hbar c\right) d k_{z}$. Therefore the sum over $i$ in (3.75) may be replaced by a sum over $n$ plus an integral along $k_{z}$ [48],

$$
\begin{equation*}
\Omega=k_{B} T\left(\frac{e H V}{2 \pi^{2} \hbar c}\right) \int_{-\infty}^{\infty} d k_{z} \sum_{n=0}^{\infty} \ln \left(1+\exp \left\{-\beta\left[E\left(n, k_{z}\right)-\lambda\right]\right\}\right) \tag{3.76}
\end{equation*}
$$

The resulting thermodynamic potential leads to two contributions to the susceptibility. The first is just the Landau result we have already obtained. The second contribution to the thermodynamic potential has the oscillatory form

$$
\begin{equation*}
\Omega^{(2)} \simeq k_{B} T \sum_{s=1}^{\infty}(-1)^{s}\left(\frac{e H}{2 \pi s c \hbar}\right)^{3 / 2} \frac{\left|A_{0}^{\prime \prime}\right|^{-1 / 2}}{\sinh \left(2 \pi^{2} s k_{B} T / \hbar \omega_{c}\right)} \cos \left(\frac{s c \hbar}{e H} A_{0} \pm \frac{\pi}{4}\right) . \tag{3.77}
\end{equation*}
$$

In this expression $A_{0}$ is the extremal cross-sectional area of the Fermi surface at some height $k_{z}=k_{0}$. The expansion of the cross-sectional area about this point has the form

$$
\begin{equation*}
A=A_{0} \pm \frac{1}{2}\left(k_{z}-k_{0}\right)^{2} A_{0}^{\prime \prime}+\ldots, \tag{3.78}
\end{equation*}
$$

which defines $A_{0}^{\prime \prime}$. Equation (3.77) implies that the magnetic susceptibility has a contribution which oscillates as a function of $1 / H$. Furthermore, the period of this oscillation directly measures the extremal area of the Fermi surface perpendicular to the direction of the magnetic field.

In Fig. 3.5a we show the oscillatory component of the magnetization in iron. Since both the "up" and "down" spins have their own Fermi surfaces, and since both have a complex topology, there are numerous areas contributing to the de Haas-van Alphen effect. These are identified by frequency analyzing the magnetization spectrum as shown in Fig. 3.5b. The cross-sectional area in atomic units is related to the frequency in megagauss by $A=2.673 \cdot 10^{-3} \mathrm{~F}$. Combining such data with band calculations enables one to construct the Fermi surface.

### 3.2.3 Quantized Hall Conductance

With the development of thin film growth techniques it is possible to fabricate devices capable of confining electrons to a region in which one of the dimensions is small compared with the de Broglie wavelength. Under these conditions the electrons behave like a two-dimensional electron gas. If a magnetic field is applied perpendicular to this two-dimensional gas the energy spectrum analogous to (3.67) consists of a ladder of discrete Landau levels with energy gaps between them. This has dramatic consequences that are not found in $3-\mathrm{D}$, or even 1-D, systems. The equation of motion for an electron in electric and magnetic fields is

$$
\begin{equation*}
m^{*} \frac{d \boldsymbol{v}}{d t}=e\left(\mathcal{E}+\frac{1}{c} \boldsymbol{v} \times \boldsymbol{H}\right)-m^{*} \frac{\boldsymbol{v}}{\tau} \tag{3.79}
\end{equation*}
$$

In steady state $(d \boldsymbol{v} / d t=0)$ and in high magnetic fields $\left(\omega_{c} \tau \gg 1\right)$, this equation reduces to

$$
\begin{equation*}
0=e \mathcal{E}_{x}+\frac{e H}{c} v_{y} . \tag{3.80}
\end{equation*}
$$



Fig. 3.6. Longitudinal and Hall voltages of a silicon MOSFET with a source drain current of $1 \mu \mathrm{~A}$ as a function of gate voltage in a magnetic field of 18 T . The index $n$ refers to the Landau level occupied. Structure within a given level is due to spin and band structure degeneracies [49]

The current density in the $y$ direction is $N e v_{y}$ where $N$ is the density of electrons. Consequently, the Hall conductivity is

$$
\begin{equation*}
\sigma_{x y}=\frac{j_{y}}{\mathcal{E}_{x}}=-\frac{N e c}{H} . \tag{3.81}
\end{equation*}
$$

If we assume that all the electrons are describable by the conducting Landau states and that the Fermi level is somehow pinned between the $n$ and $n+1$ Landau levels then the density $N$ is simply the product of the number of filled Landau levels, $n$, times the degeneracy of each level, $e H / h c$, per unit area. Thus the Hall conductivity becomes

$$
\begin{equation*}
-\sigma_{x y}=n \frac{e^{2}}{h} \tag{3.82}
\end{equation*}
$$

that is, it is quantized in multiples of $e^{2} / h$. Furthermore, as long as the Fermi level lies between the Landau levels, the density of states is zero and $\sigma_{x x}=0$. The fact that $\sigma_{x x}=0$ while $\sigma_{x y} \neq 0$ means that the diagonal resistivity

$$
\begin{equation*}
\rho_{x x}=\frac{\sigma_{x x}}{\sigma_{x x}^{2}+\sigma_{y y}^{2}} \tag{3.83}
\end{equation*}
$$



Fig. 3.7. Density of states showing broadened Landau levels and localized states (shaded)
also vanishes and the two-dimensional system is in a zero-resistance state!
This two-dimensional behavior has, in fact, been observed by von Klitzing et al. [49] in the inversion layer of a silicon MOSFET (metal-oxidesemiconductor field-effect transistor). As one changes the gate voltage on such a device, the Fermi level is swept through the Landau levels. Figure 3.6 shows the longitudinal voltage $V$ associated with a constant current as well as the Hall voltage $V_{\text {Hall }}$ as functions of the gate voltage. The plateaus in the Hall voltage correspond to a Hall resistance $R_{H}=h / e^{2} n$ to an accuracy of better than one part in $10^{5}$. Tsui and Gossard [50] have also observed this effect in gallium arsenide heterojunctions as a function of an applied magnetic field.

What is puzzling about these observations is the extraordinary accuracy with which the plateaus in $\sigma_{x y}$ give $e^{2} / h$. The fact that the plateaus exist suggests that there are localized states between the Landau levels through which the Fermi level can be moved, as illustrated in Fig. 3.7. However, since such states do not carry current, we might have expected $\sigma_{x y}$ to be reduced from its ideal value. Prange [51] as well as Tsui and Allen [52], have shown that even if localized states exist, the remaining nonlocalized states carry an extra Hall current which exactly compensates for that not carried by the localized states. Then there are also interaction effects and edge effects to worry about. Laughlin [53] pointed out that the quantization is more fundamental than


Fig. 3.8. Electron wavefunction associated with a metal loop in a radial magnetic field
that suggested above, being the consequence of gauge invariance. Consider a conducting strip connected in a ring of circumference $L$, as shown in Fig. 3.8. Let us assume there is a magnetic field normal to the strip. The electron wave functions are then plane waves in the $x$ direction, with a harmonic oscillator envelope in the $y$ direction centered at $y_{0}$. If we now change the flux $\Delta \phi$ which threads the ring, this corresponds to a change in the vector potential in the direction around the ring; i.e., $\boldsymbol{A} \rightarrow \boldsymbol{A}+\Delta \boldsymbol{A}=\boldsymbol{A}+(\Delta \phi / L) \hat{\boldsymbol{x}}$. This gauge change shifts the center of the wave function by an amount $\Delta A / H_{0}$. In particular, if the flux change is a quantum of flux, $h c / e$, then the shift moves each state precisely to an adjacent center. The net effect is to move one state per Landau level from one edge to the other. Assuming there is a voltage $V$ across the strip, this corresponds to a total increase in energy of ne $V$, where $n$ is the number of filled Landau levels. This change in energy $\Delta U$ is related to the current flowing around the strip by the general relation

$$
\begin{equation*}
I=\frac{c \Delta U}{\Delta \phi}=\frac{\operatorname{nec} V}{(h c / e)}=\frac{n e^{2} V}{h} \tag{3.84}
\end{equation*}
$$

Thus the Hall conductance $I / V$ has the quantized form found above. Any localized states present will have their phase shifted by the gauge transformation but their energy will be unchanged. Thus they will not contribute to the Hall currents. Furthermore, since the voltage $V$ is by definition the difference in the Fermi levels at the edge, any edge effects are automatically incorporated.

If one plots the Hall resistance as a function of magnetic field the 2-D resistance follows the linear relation, $R_{H}=B / N e$, while the quantum Hall resistance consists of steps along this line with the values $\left(h / e^{2}\right)(1 / n)$. At a
field of approximately 10 T in a $\mathrm{GaAs} / \mathrm{GaAl}$ As heterostructure the level with $n=1$ is reached. This corresponds to all the electrons being in the lowest Landau level. One might think that the Hall resistance would simply remain at the value $h / e^{2}$ for higher fields. Surprisingly, however, the Hall resistance continues to exhibit plateaus given by

$$
\begin{equation*}
R_{H}=\left(h / e^{2}\right)(p / q) \tag{3.85}
\end{equation*}
$$

where $p$ and $q$ are integers [54]. While the "integer" quantum Hall effect, where $p / q$ is an integer, depends upon the localized states between the Landau levels as described above, the "fractional" quantum Hall effect (FQHE) is quite different. To understand the fractional quantum Hall effect we recall that a magnetic field consists of discrete flux quanta. The magnitude of the flux quantum is $\phi_{0}=h / e$. The plateaus of the FQHE correspond to the system being in a correlated, many-body state in which flux quanta are bound to electrons. In the state $p / q=1 / 3$, for example, three flux quanta are bound to each electron. For more details we refer the reader to [55].

### 3.2.4 Pauli Paramagnetism

Let us now turn our attention to the spin response of a free-electron system. As mentioned at the beginning of this chapter, we can construct the response to an arbitrary static field if we know the response to a single Fourier component. Therefore, let us apply an external field of the form $\boldsymbol{H} \cos (\boldsymbol{q} \cdot \boldsymbol{r})$. The interaction with the electron spins is

$$
\begin{equation*}
\mathcal{H}=\sum_{i} g \mu_{B} \boldsymbol{s}_{i} \cdot \boldsymbol{H} \cos \left(\boldsymbol{q} \cdot \boldsymbol{r}_{i}\right) . \tag{3.86}
\end{equation*}
$$

According to (1.22), the moment induced by the field may be obtained by computing the change in the energy of the system that is proportional to the field. This we shall do by perturbation theory. Notice that if the quantization axis of our system is chosen to lie along the direction of $\boldsymbol{H}$, then when $\boldsymbol{q}=$ 0 , (3.86) has first-order diagonal matrix elements. Therefore a perturbation calculation would have to distinguish between $\boldsymbol{q}=0$ and $\boldsymbol{q} \neq 0$. In order to avoid this difficulty we shall assume that the field lies in the $x$ direction, $\boldsymbol{H}=H \hat{\boldsymbol{x}}$. Then

$$
\begin{equation*}
\mathcal{H}=\frac{g \mu_{B} H}{4} \sum_{i}\left(s_{i}^{+}+s_{i}^{-}\right)\left[\exp \left(i \boldsymbol{q} \cdot \boldsymbol{r}_{i}\right)+\exp \left(-i \boldsymbol{q} \cdot \boldsymbol{r}_{i}\right)\right] . \tag{3.87}
\end{equation*}
$$

Second quantizing this interaction by the prescription given in Chap. 1 gives

$$
\begin{equation*}
\mathcal{H}=\frac{g \mu_{B} H}{4} \sum_{\boldsymbol{k}}\left(a_{\boldsymbol{k}+\boldsymbol{q}, \uparrow}^{\dagger} a_{\boldsymbol{k} \downarrow}+a_{\boldsymbol{k}+\boldsymbol{q}, \downarrow}^{\dagger} a_{\boldsymbol{k} \uparrow}+a_{\boldsymbol{k}-\boldsymbol{q}, \uparrow}^{\dagger} a_{\boldsymbol{k}, \downarrow}+a_{\boldsymbol{k}-\boldsymbol{q}, \downarrow}^{\dagger} a_{\boldsymbol{k} \uparrow}\right) . \tag{3.88}
\end{equation*}
$$

We see immediately that there are no first-order diagonal matrix elements. The second-order correction to the energy is

$$
\begin{equation*}
\left.\Delta E=\left(\frac{g \mu_{B} H}{4}\right)^{2} \sum_{\boldsymbol{k}, \sigma} \frac{\left|\left\langle a_{k+\boldsymbol{q},-\sigma}^{\dagger} a_{\boldsymbol{k}}\right\rangle\right|^{2}}{\epsilon_{\boldsymbol{k} \sigma}-\epsilon_{\boldsymbol{k}+\boldsymbol{q},-\sigma}}+\text { (terms involving }-\boldsymbol{q}\right) . \tag{3.89}
\end{equation*}
$$

The sum over $\boldsymbol{k}$ is restricted to those values of $\boldsymbol{k}$ inside the Fermi sphere such that $\boldsymbol{k}+\boldsymbol{q}$ lies outside the Fermi sphere. Since the unperturbed energies are independent of spin, (3.89) reduces to

$$
\begin{equation*}
\Delta E=-\frac{g^{2} \mu_{B}^{2} H^{2}}{8} \sum_{k}\left[\frac{f_{k}\left(1-f_{k+q}\right)}{\epsilon_{k+q}+\epsilon_{k}}+\frac{f_{k}\left(1-f_{k-q}\right)}{\epsilon_{k-q}-\epsilon_{k}}\right], \tag{3.90}
\end{equation*}
$$

when the sum now runs over all $\boldsymbol{k}$ and $f_{\boldsymbol{k}}$ is the Fermi function

$$
\begin{equation*}
f_{k}=\frac{1}{\exp \left[\left(\epsilon_{\boldsymbol{k}}-\epsilon_{F}\right) / k_{B} T\right]+1} \tag{3.91}
\end{equation*}
$$

Since the sum does run over all $\boldsymbol{k}$, we may write $\boldsymbol{k} \rightarrow \boldsymbol{k}+\boldsymbol{q}$ in the second term. The two terms then combine to give

$$
\sum_{k} \frac{f_{k}-f_{k+q}}{\epsilon_{k+q}-\epsilon_{k}} .
$$

Since

$$
\begin{equation*}
\Delta E=-\frac{1}{2} \int d \boldsymbol{r} \boldsymbol{M}(\boldsymbol{r}) \cdot \boldsymbol{H}(\boldsymbol{r})=-\frac{H}{2} \int d \boldsymbol{r} \boldsymbol{M}(\boldsymbol{r}) \cos (\boldsymbol{q} \cdot \boldsymbol{r}) \tag{3.92}
\end{equation*}
$$

the derivative of $-\Delta E$ with respect to $H$ gives $\boldsymbol{M}(\boldsymbol{q})$ directly. Therefore, with $H(\boldsymbol{q})=H V / 2$, the susceptibility becomes

$$
\begin{equation*}
\chi(\boldsymbol{q})=\frac{g^{2} \mu_{B}^{2}}{V} \sum_{k} \frac{f_{k}-f_{k+\boldsymbol{q}}}{\epsilon_{\boldsymbol{k}+\boldsymbol{q}}-\epsilon_{\boldsymbol{k}}} . \tag{3.93}
\end{equation*}
$$

The sum in (3.93) may be evaluated by converting it into an integral. At $T=0 \mathrm{~K}$ we obtain

$$
\begin{equation*}
\chi(\boldsymbol{q})=\frac{3 g^{2} \mu_{B}^{2}(N / V)}{8 \epsilon_{F}} F\left(\frac{q}{2 k_{F}}\right) \tag{3.94}
\end{equation*}
$$

where

$$
\begin{equation*}
F\left(\frac{q}{2 k_{F}}\right)=\frac{1}{2}+\frac{k_{F}}{2 q}\left(1-\frac{q^{2}}{4 k_{F}^{2}}\right) \ln \left|\frac{2 k_{F}+q}{2 k_{F}-q}\right| \tag{3.95}
\end{equation*}
$$

and $N$ is the total number of electrons in the system. Notice that

$$
\begin{equation*}
\lim _{q \rightarrow 0} F\left(\frac{q}{2 k_{F}}\right)=1 \tag{3.96}
\end{equation*}
$$



Fig. 3.9. Wave-vector dependence of the spin susceptibility in a superconductor


Fig. 3.10. Relative splitting of a $d$ band in the presence of an external field

With $g=2$ and $\mu_{B}=e \hbar / 2 m c$, (3.85) may be rewritten as

$$
\begin{equation*}
\chi(q)=\chi_{\text {Pauli }} F\left(\frac{q}{2 k_{F}}\right) \tag{3.97}
\end{equation*}
$$

where

$$
\begin{equation*}
\chi_{\text {Pauli }}=\frac{3(N / V) e^{2}}{2 k_{F}} \tag{3.98}
\end{equation*}
$$

The Pauli susceptibility, given by (3.98), describes the spin response of an electron system to a uniform field. To see this, note that for a uniform field $\boldsymbol{H}(\boldsymbol{q})=\boldsymbol{H} \Delta(\boldsymbol{q})$. Therefore

$$
\begin{equation*}
\boldsymbol{M}(\boldsymbol{r})=\sum_{\boldsymbol{q}} e^{i \boldsymbol{q} \cdot \boldsymbol{r}} \chi(\boldsymbol{q}) \boldsymbol{H}(\boldsymbol{q})=\chi_{\mathrm{Pauli}} \boldsymbol{H} \tag{3.99}
\end{equation*}
$$

The wave-vector dependence of $\chi(\boldsymbol{q})$ is sketched in Fig. 3.3. Notice that this function has an infinite derivative when $q=2 k_{F}$. The susceptibility (3.97) was derived under the assumption that the temperature was small in comparison with the Fermi temperature. Since Fermi temperatures are typically of the


Fig. 3.11. The susceptibility of the transition metals at room temperature [56]
order of $10,000 \mathrm{~K}$, this is generally a good approximation. However, there are situations, as in metals like palladium and in nondegenerate semiconductors, where the effective Fermi temperature is much lower. It is then possible to reach temperatures where the electrons behave like Boltzman particles and exhibit a Curie-like susceptibility.

It is also interesting to consider how the spin susceptibility is changed if the metal becomes superconducting. In a superconductor electrons with opposite spin are correlated over a distance $\xi_{0}$ called the coherence length. This suppresses the magnetic response of such pairs at wave vectors below $\xi_{0}^{-1}$. When this effect is combined with the decreasing response beyond $2 k_{F}$ we obtain a maximum in the susceptibility at $q_{0}=\left(2 \pi k_{F}^{2} / \xi_{0}\right)^{1 / 3}$ as shown in Fig. 3.9.

As with the orbital susceptibility, the periodicity of the lattice also modifies the spin susceptibility. However, in the limit of weak spin-orbit coupling one can talk about spin-up and spin-down bands and the Pauli susceptibility takes a particularly simple and useful form. Let us consider a metal whose band structure gives rise to a density of states, i.e., number of states per unit energy per unit volume, as illustrated in Fig. 3.10. To lowest order, the effect of the applied field is to shift the relative energy distributions of the up and down spins. Since the electrons do, in fact, interact with one another, the up- and down-spin distributions will reach equilibrium in such a manner that their Fermi levels are the same. Therefore, as we see from Fig. 3.10 there will be more spins pointing anti-parallel to the field than parallel to it. Since the


Fig. 3.12. The temperature dependence of the specific susceptibility of selected transition metals [57]. The structure in the data for Ti and Zr near 1200 K is associated with structural phase transitions
gyromagnetic ratio of an electron is negative, this leads to a net moment in the direction of the field. To find this moment we need only compute the difference in the number of up- and down-spin electrons,

$$
\begin{equation*}
M=\frac{1}{2} g \mu_{B} \int_{-\infty}^{\infty}\left[\mathcal{D}(\epsilon) f\left(\epsilon-\frac{1}{2} g \mu_{B} H\right)-\mathcal{D}(\epsilon) f\left(\epsilon+\frac{1}{2} g \mu_{B} H\right)\right] d \epsilon . \tag{3.100}
\end{equation*}
$$

We expand the Fermi functions about $H=0$ to yield

$$
\begin{equation*}
M \simeq \frac{1}{2} g^{2} \mu_{B}^{2} H \int_{0}^{\infty}\left(-\frac{\partial f}{\partial \epsilon}\right) \mathcal{D}(\epsilon) d \epsilon . \tag{3.101}
\end{equation*}
$$

At low temperatures the Fermi function is essentially a step function at the Fermi level. Therefore its derivative is a delta function. Thus (3.101) leads to the susceptibility

$$
\begin{equation*}
\chi_{\text {Pauli }}=\frac{1}{2} g^{2} \mu_{B}^{2} \mathcal{D}\left(\epsilon_{F}\right) \tag{3.102}
\end{equation*}
$$

For a free-electron system

$$
\begin{equation*}
\mathcal{D}\left(\epsilon_{F}\right)=\frac{m k_{F}}{2 \pi^{2} \hbar^{2}}, \tag{3.103}
\end{equation*}
$$

and (3.102) reduces to our previous result (3.98).
From (3.102) we would expect the Pauli susceptibility to be roughly ten times larger when the Fermi surface lies within a $d$ band than when it lies


Fig. 3.13. Temperature dependence of the reciprocal susceptibility of $\mathrm{Fe}[56]$


Fig. 3.14. Temperature dependence of the reciprocal susceptibility of $\mathrm{Ni}[56]$
within an $s$ band since $d$ bands are generally narrower with a higher density of states. We might also expect this $d$-band contribution to exhibit a temperature dependence. The reason for this is that at a temperature $T$ the susceptibility essentially involves an average of $\mathcal{D}\left(\epsilon_{F}\right)$ over a region of the order of $k_{B} T$. Therefore, if the width of the structure in the $d$-band density states is of this order, it will be reflected in the susceptibility. Interactions between the electrons can also lead to a temperature dependence.

Susceptibilities for the various transition metals are shown in Fig. 3.11. First, note that the susceptibility of those metals with unfilled $d$ bands is much larger than for the $s$-band metals $\mathrm{Cu}, \mathrm{Ag}$, and Au . Second, note the variation in the susceptibility across the periodic table. This might be associated with variations in $d$-band density of states. This rigid-band explanation is consistent with the temperature dependence of these susceptibilities. As shown in Fig. 3.12, the susceptibility of metals such as $\mathrm{Ti}, \mathrm{Zr}$, and Hf, which
have a relative minimum in Fig. 3.11, increases with temperature, while for those with a maximum it decreases. Those metals with $d^{1}$ and $d^{9}$ configurations are further complicated by interaction effects which we shall discuss in the next chapter.

In Mn, Fe , Co, and Ni interactions among the electrons are sufficient to produce an ordered magnetic state. Above their ordering temperature these metals exhibit a relatively strong temperature dependence as shown in Figs. 3.13 and 3.14. This behavior is indicative of some sort of local-moment formation. It is not simply Curie-Weiss, however, for $d\left(\chi^{-1}\right) / d T$ is not temperature independent.
If band effects may be represented by an effective mass, then

$$
\begin{equation*}
\chi_{\text {Pauli }}=g^{2} \mu_{B}^{2} \frac{m^{*} k_{F}}{4 \pi^{2} \hbar^{2}} \tag{3.104}
\end{equation*}
$$

Notice that the mass entering the Bohr magneton is unaffected. However, the Landau-Peierls susceptibility (3.59) becomes

$$
\begin{equation*}
\chi_{\mathrm{LP}}=-\frac{e^{2} k_{F}}{12 \pi^{2} m^{*} c^{2}}=-\frac{1}{3}\left(\frac{m}{m^{*}}\right)^{2} \frac{e^{2} \hbar^{2} m^{*} k_{F}}{m^{2} c^{2} 4 \pi^{2} \hbar^{2}} \tag{3.105}
\end{equation*}
$$

Therefore

$$
\begin{equation*}
\chi_{\mathrm{LP}}=-\frac{1}{3}\left(\frac{m}{m^{*}}\right)^{2} \chi_{\text {Pauli }} \tag{3.106}
\end{equation*}
$$

Collecting all our results, we may express the total susceptibility of a nonmagnetic metal as

$$
\begin{equation*}
\chi(T)=\chi_{\text {core }}+\chi_{\mathrm{LP}}+\chi_{\text {orb }}+\chi(T)_{\text {Pauli }} \tag{3.107}
\end{equation*}
$$

The temperature dependence arises primarily from the $d$-band contribution to the Pauli susceptibility.

### 3.3 Measurement of the Susceptibility

At this point it is appropriate to say a little about measuring the susceptibility. A broad class of techniques use the fact that when a sample with a susceptibility $\chi_{g}$ per gram is placed in a magnetic field gradient it experiences a force. In particular, if the field is in the $x$ direction with a gradient in the $z$ direction, this force is

$$
\begin{equation*}
\Delta F_{z}=\left(H_{x} \frac{d H_{z}}{d z}\right) \chi_{g} \cdot m(g r) \tag{3.108}
\end{equation*}
$$

If the sample is mounted at the end of a pendulum and suspended at a right angle to the field gradient, there will be a torque tending to displace the pendulum. This is the pendulum galvanometer [58]. The torque due to the sample


Fig. 3.15. Simplified illustrations of (a) a vibrating-sample magnetometer and (b) a Faraday susceptibility balance
can be balanced by an opposing torque due to current flowing in a solenoid surrounding the sample. The measurement of the susceptibility is thus reduced to measuring the current flow at zero displacement and consequently has a large dynamic range well suited for ferromagnets and strong paramagnets.

For strongly magnetic materials Foner's vibrating-sample magnetometer is particularly convenient (Fig. 3.15a) [59]. In this arrangement the sample is placed at the end of a rod which vibrates up and down inside a pickup coil. If the whole assembly is placed between the pole faces of a magnet, a moment is induced in the sample which, by virtue of its vibration, induces a signal in the pickup coil that is proportional to the magnetization of the sample.

For weakly magnetic materials it is convenient to measure the force directly with an electrobalance. The most popular balance technique today is the Faraday balance (Fig. 3.15b). For this method the pole pieces of the magnet are carefully machined to produce a fairly large region over which $\boldsymbol{H}_{x} d \boldsymbol{H}_{x} / d z$ is constant. Samples small with respect to this region are suspended in the region and the force measured. The quantity $\boldsymbol{H}_{x} d \boldsymbol{H}_{x} / d z$ is determined by calibrating the system with a standard such as platinum. A typical microbalance can resolve 5 micrograms. In a related technique, known as the Gouy method, one employes a long uniform sample, frequently a liquid, which extends over the entire field region. Thus the force is the integral of (3.108).

Another way of measuring the susceptibility of small or magnetically weak samples is by a mutual-inductance technique [60]. The sample is mounted inside a pair of secondary coils on top of which is wound a primary coil. Measurement of the mutual inductance of this coil system with and without the sample yields an absolute determination of the susceptibility of the sample.

A very different method for obtaining the static susceptibility makes use of the KramersKronig relation

$$
\begin{equation*}
\chi(0)=\frac{2}{\pi} \int_{0}^{\infty} \frac{\chi^{\prime \prime}(\omega) d \omega}{\omega} \tag{3.109}
\end{equation*}
$$

where $\chi(0)$ is measured in relation to $\chi(\infty)$. If the imaginary part of the susceptibility is strongly peaked around a particular frequency $\omega_{0}$, then

$$
\begin{equation*}
\chi(0) \simeq \frac{2}{\pi \omega_{0}} \int_{0}^{\infty} \chi^{\prime \prime}(\omega) d \omega \tag{3.110}
\end{equation*}
$$

If, as in most cases, the experiment entails varying the magnetic field at a fixed frequency, this becomes

$$
\begin{equation*}
\chi(0)=\frac{g \mu_{B}}{\pi \hbar \omega} \int_{0}^{\infty} \chi^{\prime \prime}(H) d H \tag{3.111}
\end{equation*}
$$

Therefore the static susceptibility is simply given by the area under the magnetic resonance. Since this entails an absolute intensity measurement, it is rather difficult. However, Schumacher and Slichter [61], in determining the spin susceptibility of lithium and sodium, neatly solved this problem by comparing spin resonances with the nuclear resonance in the same sample. The nuclear susceptibility $\chi_{n}$ may be computed from the Langevin susceptibility (3.27). The spin susceptibility is determined by measuring the area under the conduction-electron spin resonance $A_{e}$ and the area under the nuclear resonance $A_{n}$ and using the relation

$$
\begin{equation*}
\chi_{e}=\chi_{n} \frac{\mu_{B} A_{e}}{\mu_{n} A_{n}} \tag{3.112}
\end{equation*}
$$

There is another technique involving nuclear magnetic resonance which is very helpful in determining the various contributions to the total susceptibility in a metal. As we saw in Sect. 2.2, s-like conduction electrons produce a contact hyperfine field at the nuclei of a metal. Thus, if the conduction electrons are polarized by an external field, they will, in turn, shift the nuclear magnetic resonance frequency from what it would be in a diamagnetic environment. This is known as the Knight shift. Since the ability of the conduction electrons to be polarized is determined by their Pauli susceptibility, the resulting Knight shift $K$ will be proportional to this susceptibility. In particular,

$$
\begin{equation*}
\left.K=\left.\left(\frac{8 \pi}{3}\right) \chi_{P} \Omega\langle | \psi_{S}(0)\right|^{2}\right\rangle_{F}, \tag{3.113}
\end{equation*}
$$

where $\chi_{P}$ is the Pauli susceptibility per unit volume, $\Omega$ is the volume of the unit cell, and $\langle | \psi_{S}(0)^{2}| \rangle_{F}$ is the average value of the $s$-electron probability density at the nucleus for electrons near the Fermi surface.

As was also pointed out in Sect.2.2, $d$-like electrons do not contribute to the contact hyperfine field. However, their presence can lead to a slight polarization of the otherwise paired core $s$ electrons. This core polarization depends on the $d$-band polarization and will therefore contribute a term to


Fig. 3.16. Windings of a Bitter magnet
the Knight shift that is proportional to the $d$-band susceptibility. It turns out that the core polarization generally leads to a negative Knight shift. Furthermore, since $\chi_{P}$ is temperature dependent, the resulting Knight shift will also be temperature dependent. Thus the Knight shift, together with direct susceptibility measurements, enables us to unravel the various contributions to the total susceptibility given by (3.98). A beautiful example of this is the work of Clogston et al. on metallic platinum [62].

In some cases, we are interested in the magnetic response of a system at very high fields, such as in de Haas-van Alphen studies or studies of magnetic impurity levels in semiconductors. The production of such high fields has become a specialty practiced only within the world's few high-field laboratories, such as the National High Magnetic Field Laboratory in Tallahassee or the joint German-French high-field laboratory in Grenoble.

The classical approach to generating large continuous magnetic fields is to use water-cooled coils. In the late 1930s, Francis Bitter pioneered the design of such high-field magnets. A typical Bitter magnet is illustrated in Fig. 3.16. In order to produce 15 T in a $5-\mathrm{cm}$ bore, five megawatts of power are required. If the coil is not stress limited, the central field is proportional to the square root of the power dissipated. As a result, the practical limit for such resistive magnets is about 20 T . If one tries to increase the field by reducing the inner diameter, the Lorentz force on the conductor may exceed its tensile strength.

### 3.4 Local Moments in Metals

When a potentially magnetic atom such as iron is dissolved in a nonmetallic host, the electronic states are localized at the impurity site. The magnetic character of this state is then determined by the intraatomic Coulomb interaction (Hund's rules). If the crystalline fields become large, the magnetic state
may be affected. $\mathrm{Fe}^{2+}$, for example, in an octahedral environment can have either a high-spin ${ }^{5} F_{2}\left(t_{2 g}{ }^{4} e_{g}^{2}\right)$ state or a low-spin ${ }^{1} A_{a}\left(t_{2 g}^{6}\right)$ state. But the lowtemperature susceptibility is readily calculated by the formalism described in the earlier sections of this chapter.

In a metallic host, the situation is much more complex because the electronic states associated with the impurity are often not localized. Even when the impurity appears to contain an integral number of electrons, the fact that they are coupled to a Fermi sea, no matter how weak the coupling, can lead to a correlated nonmagnetic ground state.

### 3.4.1 Virtual Bound States

If we consider the conduction electrons as plane waves, then a convenient formalism for describing the effect of a single impurity is scattering theory. If the impurity is represented by a real spherical potential (i.e., we neglect inelastic scattering), then the problem has symmetry about the axis defined by the incident wave vector $\boldsymbol{k}$, so the wave function, call it $u_{k}(r, \theta)$, may be expanded as a sum of products of radial functions and Legendre polynomials,

$$
\begin{equation*}
u_{k}(r, \theta)=\sum_{l=0}^{\infty}(2 l+1) i^{l} R_{l}(k, r) P_{l}(\cos \theta) . \tag{3.114}
\end{equation*}
$$

The Legendre polynomials are related to the spherical harmonics of Table 2.1 by

$$
P_{l}(\cos \theta)=\sqrt{\frac{4 \pi}{2 l+1}} Y_{l}^{0}(\theta, \varphi)
$$

The coefficient $R_{l}(k, r)$ is called the partial wave amplitude. This is an important quantity for, when the energy variable $k$ is regarded as a complex number, the poles of $R_{l}(k, r)$ along the positive imaginary axis correspond to bound states. Far from the impurity, this wave function has the form

$$
\begin{equation*}
\lim _{r \rightarrow \infty} u_{k}(r, \theta)=e^{i k \cdot r}+f(k, \theta)\left(e^{i k r} / r\right) \tag{3.115}
\end{equation*}
$$

where $f(k, \theta)$ is called the scattering amplitude and is a function of the scattering phase shift $\delta_{l}$,

$$
\begin{equation*}
f(k, \theta)=(1 / k) \sum_{l}[4 \pi(2 l+1)]^{1 / 2} \exp \left(i \delta_{l}\right)\left(\sin \delta_{l}\right) Y_{l}^{0}(\theta) . \tag{3.116}
\end{equation*}
$$

Substituting (3.116) into (3.115) shows that $R_{l}(k r)$ has the asymptotic form

$$
\begin{equation*}
R_{l}(k r) \underset{r \rightarrow \infty}{\longrightarrow} \frac{1}{k r} \exp \left(i \delta_{l}\right) \sin \left(k r-\frac{1}{2} l \pi+\delta_{l}\right) \tag{3.117}
\end{equation*}
$$

The phase shift, $\delta_{l}$ depends upon the energy of the scattering particle and on the details of the impurity potential. If the potential is a delta function of strength $V_{0}$, then there is only $s$-wave scattering and

$$
\begin{equation*}
\delta_{0}(E)=\tan ^{-1}\left\{\pi V_{0} N(E) /\left[1-V_{0} I(E)\right]\right\} \tag{3.118}
\end{equation*}
$$

where $N(E)$ is the host density of states and

$$
\begin{equation*}
I(E)=\mathcal{P} \int d E^{\prime} N\left(E^{\prime}\right) /\left(E^{\prime}-E\right) \tag{3.119}
\end{equation*}
$$

where $\mathcal{P}$ means that we take the principal part of the integral. If we define $E_{0}$ as the value of $E$ where $V_{0} I\left(E_{0}\right)=1$ and expand $V_{0} I(E)$ about $E=E_{0}$, then

$$
\begin{equation*}
\delta_{0}(E)=\tan ^{-1} \frac{\Delta}{E-E_{0}} \tag{3.120}
\end{equation*}
$$

where $\Delta$ is proportional to $N\left(E_{0}\right)$. Notice that when the phase shift goes through $\pi / 2$, the scattering amplitude goes through a maximum. This is referred to as a resonance or virtual bound state.

Suppose we surround the impurity by a sphere of radius $R$. If we require that the wavefunction go to zero on the boundary, then, from (3.117)

$$
\begin{equation*}
k R-\frac{1}{2} l \pi+\delta_{l}=n \pi \tag{3.121}
\end{equation*}
$$

where $n$ is an integer. In the absence of scattering $\delta_{l}=0$ As the scattering potential is "turned on" $\delta_{l}$ becomes nonzero. If the potential is attractive $\delta_{l}$ is positive and $\delta_{l} / \pi$ is the number of extra nodes introduced within the sphere. Each of these nodes corresponds to a state that can accomodate $2(2 l+1)$ electrons. Therefore, if $z$ is the charge differential between the impurity and the host

$$
\begin{equation*}
\sum_{l} 2(2 l+1) \frac{\delta_{l}}{\pi}=z \tag{3.122}
\end{equation*}
$$

This is known as the Friedel sum rule. The density of states associated with these extra states is

$$
\begin{equation*}
\eta(E)=\frac{d z}{d E}=\sum_{l} \frac{2(2 l+1)}{\pi} \frac{d \delta_{l}}{d E} \tag{3.123}
\end{equation*}
$$



Fig. 3.17. Residual resistivities of transitional impurities in aluminum

For the phase shift given by (3.122) this virtual bound state is characterized by the Lorentzian form

$$
\begin{equation*}
\eta(E)=\frac{1}{\pi} \frac{\Delta}{\left(E-E_{0}\right)^{2}+\Delta^{2}} . \tag{3.124}
\end{equation*}
$$

The differential scattering cross section $\sigma(\theta)$ is given by the square of the scattering amplitude, i.e., $\sigma(\theta)=|f(\theta)|^{2}$. The effective average cross section $\sigma$ (not to be confused with conductivity) that governs the resistivity is the angular average of $\sigma(\theta)$ weighted by $(1-\cos \theta)$, which measures the relative change in the component of the electron's velocity along its initial direction of motion:

$$
\begin{equation*}
\sigma=2 \pi \int_{-\pi}^{\pi} d \theta \sin \theta \sigma(\theta)(1-\cos \theta) . \tag{3.125}
\end{equation*}
$$

The mean free path is $\Lambda=1 / x \sigma$, where $x$ is the atomic concentration of impurities. The integral over the $\cos \theta$ term in (3.125) is facilitated by the relation

$$
Y_{l}^{0} \cos \theta=\frac{l+1}{\sqrt{(2 l+1)(2 l+3)}} Y_{l+1}^{0}+\frac{l}{\sqrt{(2 l+1)(2 l-1)}} Y_{l-1}^{0}
$$

and then using the orthogonality of the spherical harmonics. The resistivity associated with the impurities is then

$$
\begin{equation*}
\Delta \rho=\frac{4 \pi x}{n e^{2} k_{F}} \sum_{l=0}^{\infty}(l+1) \sin ^{2}\left[\delta_{l}\left(E_{F}\right)-\delta_{l+1}\left(E_{F}\right)\right], \tag{3.126}
\end{equation*}
$$

where $n$ is the density of conduction electrons. Thus, again if we only consider $s$-wave scattering $(l=0)$, the resistivity will show a peak when the Fermi level and the center of the virtual bound state coincide. There is evidence for such behavior in aluminum as shown in Fig. 3.17. This phase shift description has been successfully applied to many alloys, particularly by Friedel [63] and his collaborators. The problem arises when one begins to consider magnetic properties. Figure 3.18, for example, shows that iron may or may not exhibit a


Fig. 3.18. Magnetic moment in Bohr magnetons of an iron atom dissolved in various second-row transition metals (except Re which is a 5 d element) and alloys as a function of electron concentration [64]
magnetic moment when it is dissolved in 4d transition metals and alloys. This behavior attracted the attention of Anderson, who considered how a virtual bound state develops a moment.

### 3.4.2 Anderson's Theory of Moment Formation

The presence of an impurity in a metallic host leads to additional terms in the Hamiltonian of the system. Since the size or the charge of the impurity may differ from that of the host, there will be a change $V(\boldsymbol{r})$ in the crystal potential. Since this potential is screened by the conduction electrons, it is essentially confined to the impurity cell. In addition, the Coulomb interaction between electrons within the impurity cell, $v$, will be different from that between electrons within host cells. Most of the hosts we shall consider do not exhibit a significant exchange enhancement, and so we shall neglect the Coulomb interactions within the host cells, retaining it only for the impurity cell. Assuming that these are the major effects of the impurity, we write the total Hamiltonian as

$$
\begin{equation*}
\mathcal{H}=\mathcal{H}_{0}+\sum_{i} e V\left(\boldsymbol{r}_{i}\right)+\sum_{\substack{i, j \\ \text { (within } \\ \text { impurity cell) }}} v\left(\boldsymbol{r}_{i}-\boldsymbol{r}_{j}\right) \tag{3.127}
\end{equation*}
$$

Here $\mathcal{H}_{0}$ is the Hamiltonian for the pure host.


Fig. 3.19. Schematic density of states of copper containing an impurity mode

The next step is to write this Hamiltonian in its second-quantized form. The actual form will depend on the states we use to expand the field operator. For example, suppose we dissolve a transition metal such as manganese into copper. Since $\mathrm{Mn}^{2+}$ has four fewer electrons than $\mathrm{Cu}^{2+}$, it constitutes a strong perturbation. Therefore we might expect the localized state to be pushed out of the $d$ band of the copper host, as shown in Fig. 3.19. Since the $d$ band is filled, it will not contribute to the properties of the dilute alloy. Therefore we expand our field operator in terms of the $s$-band states and a localized nondegenerate $d$-like state. The one-electron terms in (3.127) then becomes

$$
\begin{equation*}
\sum_{k, \sigma} \epsilon_{k} c_{k \sigma}^{\dagger} c_{k \sigma}+\sum_{\sigma} \epsilon_{0} c_{0 \sigma}^{\dagger} c_{0 \sigma}+\sum_{k, \sigma}\left(V_{0 k} c_{k \sigma}^{\dagger} c_{0 \sigma}+V_{0 k}^{*} c_{0 \sigma}^{\dagger} c_{k \sigma}\right) . \tag{3.128}
\end{equation*}
$$

The first term is the $s$-band energy, the second term is the contribution from the impurity state, and the last term is the so-called sd mixing term. Notice that this mixing is a one-electron effect. It corresponds to the hopping of an electron from the localized $d$ orbital into the conduction band, or vice versa. The interaction part of (3.127) becomes

$$
\begin{equation*}
U n_{0 \uparrow} n_{0 \downarrow}, \tag{3.129}
\end{equation*}
$$

where $U$ is the intraatomic Coulomb repulsion between opposite spins in the localized orbital. Equations (3.128), (3.129) constitute what is known as the Anderson Hamiltonian [65].

To study the implications of this model, Anderson employed the so-called Hartree-Fock approximation which is a mean field approximation. Namely, the interaction term $U n_{0 \uparrow} n_{0 \downarrow}$ is replaced by $U\left(\left\langle n_{0 \uparrow}\right\rangle n_{0 \downarrow}+\left\langle n_{0 \downarrow}\right\rangle n_{0 \uparrow}-\left\langle n_{0 \uparrow}\right\rangle\left\langle n_{0 \downarrow}\right\rangle\right)$. Thus, in the Hartree-Fock approximation the Anderson Hamiltonian for a spin $\sigma$ becomes

$$
\begin{equation*}
\mathcal{H}_{\mathrm{HF}}^{\sigma}=\sum_{\boldsymbol{k}} \epsilon_{\boldsymbol{k}} c_{\boldsymbol{k} \sigma}^{\dagger} c_{\boldsymbol{k} \sigma}+\sum_{\sigma} \epsilon_{0 \sigma} c_{0 \sigma}^{\dagger} c_{0 \sigma}+\sum_{\boldsymbol{k}} V_{0 \boldsymbol{k}}\left(c_{\boldsymbol{k} \sigma}^{\dagger} c_{0 \sigma}+c_{0 \sigma}^{\dagger} c_{k \sigma}\right), \tag{3.130}
\end{equation*}
$$

where

$$
\begin{equation*}
\epsilon_{0 \sigma}=\epsilon_{0}+U\left\langle n_{0,-\sigma}\right\rangle \tag{3.131}
\end{equation*}
$$

Solving the Schrodinger equation is equivalent to finding the so-called Green's function, defined by

$$
\begin{equation*}
G^{\sigma}(\mathcal{E})=\lim _{s \rightarrow 0} \frac{1}{\mathcal{E}-\mathcal{H}^{\sigma}+i s} \tag{3.132}
\end{equation*}
$$

The usefulness of this function lies in its relation to the density of states. In particular, since the density of states may be represented by a sum of delta functions at energies given by the exact eigenvalues, i.e.,

$$
\begin{equation*}
\eta(E)=\sum_{n} \delta\left(E-E_{n}\right) \tag{3.133}
\end{equation*}
$$

then

$$
\begin{equation*}
\eta(E)=-\frac{1}{\pi} \operatorname{Im}[\operatorname{Tr} G(E)] \tag{3.134}
\end{equation*}
$$

Multiplying both sides (3.132) by ( $\epsilon-\mathcal{H}^{\sigma}+\mathrm{i} s$ ) and computing the matrix elements of the resulting equation between the states $|\boldsymbol{k}\rangle$ and $|0\rangle$ gives the following four relations:

$$
\begin{gather*}
\left(\epsilon-\epsilon_{0 \sigma}+\mathrm{i} s\right) G_{00}^{\sigma}(\epsilon)-\sum_{\boldsymbol{k}} V_{0 \boldsymbol{k}} G_{\boldsymbol{k} 0}^{\sigma}(\epsilon)=1  \tag{3.135}\\
\left(\epsilon-\epsilon_{\boldsymbol{k}}+\mathrm{i} s\right) G_{\boldsymbol{k} \boldsymbol{k}^{\prime}}^{\sigma}(\epsilon)-V_{\boldsymbol{k} 0} G_{0 \boldsymbol{k}^{\prime}}^{\sigma}(\epsilon)=\delta_{\boldsymbol{k} \boldsymbol{k}^{\prime}}  \tag{3.136}\\
\left(\epsilon-\epsilon_{\boldsymbol{k}}+\mathrm{i} s\right) G_{\boldsymbol{k} 0}^{\sigma}(\epsilon)-V_{\boldsymbol{k} 0} G_{00}^{\sigma}(\epsilon)=0  \tag{3.137}\\
\left(\epsilon-\epsilon_{0 \sigma}+\mathrm{i} s\right) G_{0 \boldsymbol{k}}^{\sigma}(\epsilon)-\sum_{\boldsymbol{k}^{\prime}} V_{0 \boldsymbol{k}^{\prime}} G_{\boldsymbol{k}^{\prime} \boldsymbol{k}}^{\sigma}(\epsilon)=0 \tag{3.138}
\end{gather*}
$$

By solving these equations we obtain the various matrix elements of the Green's function. We then use (3.134) to compute the local density of states $\eta_{0 \sigma}(\epsilon)$. This has the Lorentzian form

$$
\begin{equation*}
\eta_{0 \sigma}(\epsilon)=\frac{1}{\pi} \frac{\Delta}{\left(\epsilon-\epsilon_{0}-U\left\langle n_{0-\sigma}\right\rangle-\delta \epsilon\right)^{2}+\Delta^{2}} \tag{3.139}
\end{equation*}
$$

where

$$
\begin{equation*}
\Delta=\pi \sum_{\boldsymbol{k}}\left|V_{0 \boldsymbol{k}}\right|^{2} \delta\left(\epsilon-\epsilon_{\boldsymbol{k}}\right) \tag{3.140}
\end{equation*}
$$

and

$$
\begin{equation*}
\delta \epsilon=\mathcal{P} \sum_{\boldsymbol{k}} \frac{\left|V_{0 \boldsymbol{k}}\right|^{2}}{\epsilon-\epsilon_{\boldsymbol{k}}} \tag{3.141}
\end{equation*}
$$

From this density of states we can compute the occupation number of the localized state:

$$
\begin{equation*}
\left\langle n_{0 \sigma}\right\rangle=\int_{-\infty}^{\epsilon_{F}} \eta_{0 \sigma}(\epsilon) d \epsilon \tag{3.142}
\end{equation*}
$$



Fig. 3.20. "Phase diagram" corresponding to the Hartree-Fock solution of the Anderson Hamiltonian

Since $\eta_{0 \sigma}$ is a function of $\left\langle n_{0-\sigma}\right\rangle$, we have a set of coupled equations. These may have the single nonmagnetic solution $\left\langle n_{0 \sigma}\right\rangle=\left\langle n_{0-\sigma}\right\rangle$, or the two symmetrical magnetic solutions $\left\langle n_{0 \sigma}\right\rangle \neq\left\langle n_{0-\sigma}\right\rangle$, depending upon the relative values of the parameters $\epsilon_{0}, U$, and $\Delta$. These regimes are indicated in Fig. 3.20. Notice that integrating (3.123) and comparing it with (3.142) gives $\delta_{\sigma}\left(\epsilon_{F}\right)=\pi\left\langle n_{0 \sigma}\right\rangle$. If $Z$ is the total number of localized electrons, then $\delta_{\sigma}+\delta_{-\sigma}=\pi Z$, which is a special case of the Friedel sum rule, (3.122).

To determine the boundary between the magnetic and nonmagnetic regions let us introduce the number of localized electrons $n_{0}$ and the localized moment $m_{0}$ by

$$
\begin{align*}
& n_{0}=\frac{1}{2}\left(\left\langle n_{0 \uparrow}\right\rangle+\left\langle n_{0 \downarrow}\right\rangle\right),  \tag{3.143}\\
& m_{0}=\frac{1}{2}\left(\left\langle n_{0 \uparrow}\right\rangle-\left\langle n_{0 \downarrow}\right\rangle\right) . \tag{3.144}
\end{align*}
$$

Then

$$
\begin{equation*}
m_{0}=\frac{1}{2} f\left(\epsilon_{F} ; \epsilon_{0}+U n_{0}-U m_{0}\right)-\frac{1}{2} f\left(\epsilon_{F} ; \epsilon_{0}+U n_{0}+U m_{0}\right), \tag{3.145}
\end{equation*}
$$

where $f$ is the $\cot ^{-1}$ function obtained from integrating the Lorentzian density of states.

In the limit of large $m_{0}$ the right-hand side goes to 0 . Therefore, if there is a nonzero solution, the right-hand side must have a slope greater than 1 at $m_{0}=0$. Since

$$
\begin{equation*}
\left.\frac{\partial f\left(\epsilon_{F} ; \epsilon_{0}+U n_{0} \mp U m_{0}\right)}{\partial m_{0}}\right|_{m_{0}=0}=\mp U \frac{\partial f\left(\epsilon_{F} ; \epsilon_{0}+U n_{0}\right)}{\partial\left(\epsilon_{0}+U n_{0}\right)} \tag{3.146}
\end{equation*}
$$

the condition for the appearance of the localized moment is

$$
\begin{equation*}
-U \frac{\partial f\left(\epsilon_{F} ; \epsilon_{0}+U n_{0}\right)}{\partial\left(\epsilon_{0}+U n_{0}\right)}>1 \tag{3.147}
\end{equation*}
$$

If the localized state lies close to the Fermi surface, then $\Delta$ and $\delta \epsilon$ may be approximated by their values at the Fermi surface. Then

$$
\begin{equation*}
\frac{\partial f\left(\epsilon_{F} ; \epsilon_{0}+U n_{0}\right)}{\partial\left(\epsilon_{0}+U n_{0}\right)}=\int_{-\infty}^{\epsilon_{F}} d \epsilon \frac{\partial \eta_{0 \sigma}(\epsilon)}{\partial\left(\epsilon_{0}+U n_{0}\right)}=-\eta_{0 \sigma}\left(\epsilon_{F}\right) \tag{3.148}
\end{equation*}
$$

The condition (3.147) then becomes

$$
\begin{equation*}
U \eta_{0 \sigma}\left(\epsilon_{F}\right)>1 \tag{3.149}
\end{equation*}
$$

From (3.139) we see that a localized spin moment appears when $U$ is sufficiently large in comparison with the width $\Delta$ of the resonant level. Since $\Delta=\pi V^{2} \eta\left(\epsilon_{F}\right)$ a small density of states for the conduction band and a small covalent admixture favor the formation of a moment. Thus we expect to find moments when $3 d$ atoms are dissolved in noble metals but not in aluminum, as is the case.

One of the consequences of Anderson's Hartree-Fock solution is that in the magnetic regime the density of states is characterized by two Lorentzians separated by an energy $U\left(\left\langle n_{0 \uparrow}\right\rangle-\left\langle n_{0 \downarrow}\right\rangle\right)$. If we again look to the residual resistivity for evidence of such behavior, we do indeed find two peaks for transition-metal impurities dissolved in Cu as shown in Fig. 3.21. More microscopic probes, however, indicate that these solutes behave more atomically than the itinerant Anderson model would suggest. An extensive study of the moments of Fe in various hosts have been carried out by Riegel et al. [66] using timedifferential perturbed angular $\gamma$-ray distribution. In this technique a scandium $\left({ }^{45} \mathrm{Sc}\right)$ target is bombarded by carbon ions which produce ${ }^{54} \mathrm{Fe}$ ions


Fig. 3.21. Residual resistivities of transitional impurities in copper
(together with a proton and two neutrons) which recoil and imbed themselves in an adjacent film of the host to be studied. The ${ }^{54} \mathrm{Fe}$ then decays with the emission of two $\gamma$-rays. The second $\gamma$-ray emitted has an asymmetric distribution with respect to the first. If a field $H_{0}$ is applied perpendicular to the plane of the two $\gamma$-rays the asymmetric distribution rotates in space with a Larmour frequency $\omega_{L}(T)=\hbar^{-1} \mu_{N} g_{N}\left(H_{0}+H_{i}\right)$ where $H_{i}$ is the hyperfine field (2.47). According to the Wigner-Eckart theorem the electronic matrix element of (2.47) is proportional to $\left\langle J_{z}\right\rangle$. In the high-temperature limit $\left\langle J_{z}\right\rangle=g_{J} \mu_{B} J(J+1) H_{0} / 3 k_{B} T$. Therefore $H_{0}+H_{i}$ may be written as $\beta(T) H_{0}$ where $\beta-1$ may be thought of as a "local" susceptibility. These studies show that the behavior of Fe in the third-row transition metals has the same form as that shown in Fig. 3.18, i.e., Fe is nonmagnetic in Ta, Re, and Os, while it is magnetic in Mo, Ir, Pt, and Au with non-half-integral moments. However, in non-d-state hosts such as $\mathrm{K}, \mathrm{Rb}$, and Cs iron shows an ionic moment appropriate to a $3 d^{6}$ configuration. This suggests that moment formation in the noble- and transition-metal hosts involves the d-states of the host. This is particularly true in Pd and Pt where iron polarizes its host to produce a "giant" moment. Wolff [67] has developed a theory of local moments similar to Anderson's but obtains the local moment as a virtual bound state thereby explicitly involving the host.

### 3.4.3 The Kondo Effect

Much more dramatic is the behavior associated with the breakdown of the Hartree-Fock approximation itself, as manifest in the Kondo effect. Figure 3.22 shows the general behavior observed in "local-moment" systems such as those illustrated in Fig. 3.21 with decreasing temperature. The resistivity increases logarithmically and eventually saturates. When this increasing impurity contribution is combined with the decreasing phonon contribution, one obtains a minimum in the resistivity, a phenomenon that was known but not understood for many years. At the same time, the magnetic moment, as measured by the susceptibility, decreases, and the specific heat shows a peak corresponding to an entropy change of approximately $k_{B} \ln 2$. Although this transition is gradual, it is possible to assign a temperature, called the Kondo temperature, below which these anomalous properties appear. Figure 3.23 shows how this Kondo temperature varies for $3 d$ transition metals dissolved in copper.

It is now known that these properties, which are collectively referred to as the "Kondo effect", are associated with the behavior of a single localized electron spin interacting with a degenerate electron system. This seemingly simple problem has required an enormous effort to bring us to the point where we think that we understand what is going on. We shall not cover all this development (see for example [68a] or the reviews [68b]), but merely indicate a few aspects that will give the reader a "feel" for the Kondo effect.


Fig. 3.22. Schematic behavior characteristic of a typical Kondo alloy


Fig. 3.23. Variation of the Kondo temperature for the $3 d$ transition metals in copper
Let us begin by assuming we are in the magnetic regime of the Anderson model, that is $U \gg \Delta$. In this case Schrieffer and Wolff showed that one could perform a canonical transformation which eliminates $V_{0 k}$ to first order [69].

They found that the resulting Hamiltonian contains a contribution of the form

$$
\begin{equation*}
\mathcal{H}_{s d}=\sum_{\boldsymbol{k}, \boldsymbol{k}^{\prime}} J_{\boldsymbol{k}^{\prime} \boldsymbol{k}} \psi_{\boldsymbol{k}^{\prime}}^{\dagger} s \psi_{\boldsymbol{k}} \cdot \psi_{0}^{\dagger} \boldsymbol{S} \psi_{0}, \tag{3.150}
\end{equation*}
$$

where

$$
\psi_{\boldsymbol{k}}=\left[\begin{array}{l}
c_{\boldsymbol{k} \uparrow}  \tag{3.151}\\
c_{\boldsymbol{k} \downarrow}
\end{array}\right] \quad \text { and } \quad \psi_{0}=\left[\begin{array}{l}
c_{0 \uparrow} \\
c_{0 \downarrow}
\end{array}\right] .
$$

This has the form of an $s d$ exchange interaction. For wave vectors near the Fermi surface the exchange parameter becomes

$$
\begin{equation*}
J_{\boldsymbol{k}_{F} \boldsymbol{k}_{F}}=2\left|V_{0 \boldsymbol{k}_{F}}\right|^{2} \frac{U}{\epsilon_{0}\left(\epsilon_{0}+U\right)} . \tag{3.152}
\end{equation*}
$$

In this expression $\epsilon_{0}$ is measured in relation to the Fermi surface, which makes $J_{\boldsymbol{k}_{F} \boldsymbol{k}_{F}}$ negative, corresponding to antiferromagnetic coupling.

As we mentioned above, those alloys possessing local moments are also the ones which show a minimum in their resistivity as a function of temperature. This motivated Kondo [70] to calculate the spin-flip scattering amplitude of a conduction electron using the $s-d$ interaction (3.150). Let us outline this calculation. We shall characterize the impurity spin by its spin-projection quantum numbers $M_{S}$ and add an extra electron in the state $(\boldsymbol{k}, \sigma)$ to the Fermi sea. The state of the system at time $t=-\infty$ may then be written $c_{\boldsymbol{k} \sigma}^{\dagger}\left|F S ; M_{S}^{\prime}\right\rangle$. In the absence of an external field the unperturbed Hamiltonian is just

$$
\mathcal{H}_{0}=\sum \epsilon_{\boldsymbol{k}} c_{\boldsymbol{k} \sigma}^{\dagger} c_{\boldsymbol{k} \sigma}
$$

We now adiabetically turn on the interaction $\mathcal{H}_{1}$ and examine the amplitude for scattering into the state $c_{\boldsymbol{k}^{\prime} \sigma^{\prime}}^{\dagger}\left|F S ; \boldsymbol{M}_{S}\right\rangle$. This amplitude is

$$
\begin{align*}
\left\langle\boldsymbol{k}^{\prime} \sigma^{\prime} ; \boldsymbol{M}_{S}^{\prime} \mid \phi(\infty)\right\rangle= & \delta\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \delta_{\sigma, \sigma^{\prime}} \delta_{M_{S} \cdot M_{S}^{\prime}} \\
& -2 \pi i\left\langle\boldsymbol{k}^{\prime} \sigma^{\prime} ; \boldsymbol{M}_{S}^{\prime}\right| \mathcal{H}_{1}+\mathcal{H}_{1} \frac{1}{\epsilon_{k}-\mathcal{H}_{0}} \mathcal{H}_{1}+\ldots\left|\boldsymbol{k}, \sigma ; \boldsymbol{M}_{S}\right\rangle \\
& \times \delta\left(\epsilon_{\boldsymbol{k}}-\epsilon_{\boldsymbol{k}^{\prime}}\right) . \tag{3.153}
\end{align*}
$$

Suppose $\mathcal{H}_{1}$ corresponded to ordinary potential scattering; then it would have the form $\sum c_{l^{\prime} \sigma}^{\dagger} V_{l^{\prime} l} c_{l \sigma}$. The interesting term in (3.153) is the one involving $\mathcal{H}_{1}$ twice. There are two distinct ways in which the scattering $\boldsymbol{k}-\boldsymbol{k}^{\prime}$ can occur through this term. These are illustrated in Fig. 3.24. The matrix element for process (a) is

$$
\begin{equation*}
\langle F S| c_{\boldsymbol{k}^{\prime}} c_{\boldsymbol{k}^{\prime}}^{\dagger} V_{\boldsymbol{k}^{\prime} l} c_{l} \frac{1}{\epsilon_{\boldsymbol{k}}-\mathcal{H}_{0}} c_{l}^{\dagger} V_{l \boldsymbol{k}} c_{\boldsymbol{k}} c_{\boldsymbol{k}}^{\dagger}|F S\rangle \tag{3.154}
\end{equation*}
$$



Fig. 3.24. Contributions to the second-order scattering amplitude associated with a spin-independent potential
which reduces to

$$
\begin{equation*}
V_{\boldsymbol{k}^{\prime} l} \frac{1-f\left(\epsilon_{l}\right)}{\epsilon_{\boldsymbol{k}}-\epsilon_{l}} V_{l \boldsymbol{k}} . \tag{3.155}
\end{equation*}
$$

Process (b) becomes

$$
\begin{equation*}
\langle F S| c_{\boldsymbol{k}^{\prime}} V_{l \boldsymbol{k}} c_{\boldsymbol{k}} \frac{1}{\epsilon_{\boldsymbol{k}}-\mathcal{H}_{0}} c_{\boldsymbol{k}^{\prime}}^{\dagger} V_{\boldsymbol{k}^{\prime} l} c_{l} c_{\boldsymbol{k}}^{\dagger}|F S\rangle, \tag{3.156}
\end{equation*}
$$

which contracts to

$$
\begin{equation*}
-V_{l \boldsymbol{k}} \frac{f\left(\epsilon_{l}\right)}{\epsilon_{\boldsymbol{k}}-\left(\epsilon_{\boldsymbol{k}}-\epsilon_{l}+\epsilon_{\boldsymbol{k}^{\prime}}\right)} V_{\boldsymbol{k}^{\prime} l}=V_{l \boldsymbol{k}} \frac{f\left(\epsilon_{l}\right)}{\epsilon_{\boldsymbol{k}^{\prime}}-\epsilon_{l}} V_{\boldsymbol{k}^{\prime} l} . \tag{3.157}
\end{equation*}
$$

When these two processes are added together, the Fermi function cancels out. Thus, the exclusion principle does not enter into ordinary potential scattering. This is not the case, however, for a spin-dependent potential. The Hamiltonian (3.150) becomes

$$
\begin{equation*}
\mathcal{H}_{1}=-J \boldsymbol{S} \cdot \sum_{l, l^{\prime}} \sum_{\sigma, \sigma^{\prime}} c_{l \sigma}^{\dagger} s_{\sigma \sigma^{\prime}} c_{l^{\prime} \sigma^{\prime}} . \tag{3.158}
\end{equation*}
$$

The two second-order processes arising from this interaction are illustrated in Fig. 3.25. Process (a) gives

$$
\begin{equation*}
J^{2}\left\langle F S ; \boldsymbol{M}_{S}^{\prime}\right| S_{\nu} S_{\mu} c_{\boldsymbol{k}^{\prime} \sigma^{\prime}} c_{\boldsymbol{k}^{\prime} \sigma^{\prime}}^{\dagger} s_{\sigma^{\prime} \sigma^{\prime \prime}}^{\nu} c_{l \sigma^{\prime \prime}} \frac{1}{\epsilon_{\boldsymbol{k}}-\mathcal{H}_{0}} c_{l \sigma^{\prime \prime}}^{\dagger} s_{\sigma^{\prime \prime} \sigma}^{\mu} c_{\boldsymbol{k} \sigma} c_{\boldsymbol{k} \sigma}^{\dagger}\left|F S ; \boldsymbol{M}_{S}\right\rangle \tag{3.159}
\end{equation*}
$$

which reduces to

$$
\begin{equation*}
J^{2} \frac{1-f\left(\epsilon_{l}\right)}{\epsilon_{\boldsymbol{k}}-\epsilon_{l}}\left\langle\boldsymbol{M}_{S}^{\prime}\right| S_{\nu} S_{\mu} s_{\sigma^{\prime} \sigma^{\prime \prime}}^{\nu} s_{\sigma^{\prime \prime} \sigma}^{\mu} c_{\boldsymbol{k} \sigma} c_{\boldsymbol{k} \sigma}^{\dagger}\left|\boldsymbol{M}_{S}\right\rangle \tag{3.160}
\end{equation*}
$$



Fig. 3.25. Contributions to the second-order scattering amplitude associated with the $s-d$ interaction

Process (b) gives

$$
\begin{equation*}
J^{2} \frac{f\left(\epsilon_{l}\right)}{\epsilon_{\boldsymbol{k}}-\epsilon_{l}}\left\langle\boldsymbol{M}_{S}^{\prime}\right| S_{\nu} S_{\mu} s_{\sigma^{\prime \prime} \sigma^{\prime}}^{\nu} s_{\sigma^{\prime} \sigma^{\prime \prime}}^{\mu}\left|M_{S}\right\rangle \tag{3.161}
\end{equation*}
$$

When these are added together, we obtain

$$
\begin{equation*}
\frac{J^{2}}{\epsilon_{\boldsymbol{k}}-\epsilon_{l}}\left[\frac{1}{4} S(S+1)-\left\langle M_{S}^{\prime}, \sigma^{\prime}\right| \boldsymbol{S} \cdot \boldsymbol{s}\left|M_{S}, \sigma\right\rangle\right]+\frac{J^{2} f\left(\epsilon_{l}\right)}{\epsilon_{\boldsymbol{k}}-\epsilon_{l}}\left\langle M_{S}^{\prime}, \sigma^{\prime}\right| \boldsymbol{S} \cdot \boldsymbol{s}\left|M_{S}, \sigma\right\rangle \tag{3.162}
\end{equation*}
$$

The second term in (3.162) arises from the fact that the spin operators may not be interchanged. Therefore we obtain a contribution to the scattering which does depend on the exclusion principle. Summing over the intermediate states introduces the factor

$$
\sum_{l} \frac{f\left(\epsilon_{l}\right)}{\epsilon_{\boldsymbol{k}}-\epsilon_{l}}
$$

Introducing the conduction-electron density states of $N(\epsilon)$, this sum may be written

$$
\begin{equation*}
\int N\left(\epsilon^{\prime}\right) \frac{f\left(\epsilon^{\prime}\right)}{\epsilon-\epsilon^{\prime}} d \epsilon^{\prime} \tag{3.163}
\end{equation*}
$$

Assuming a simple rectangular band,

$$
N(\epsilon)= \begin{cases}N(0) & -D<\epsilon<D  \tag{3.164}\\ 0 & \text { otherwise }\end{cases}
$$

the integral for $\epsilon=0$ gives

$$
\begin{equation*}
-N(0) \ln \frac{k_{B} T}{D}+\text { const. } \tag{3.165}
\end{equation*}
$$

Since the resistivity involves the square of the scattering amplitude, the cross term between the first-order term and this second-order term gives a contribution proportional to $J^{3} \ln T$.

For antiferromagnetic exchange $(J<0)$ the resistivity increases with decreasing temperature as shown in Fig. 3.22. The divergence as $T \rightarrow 0$, however, indicates that the perturbation theory is not valid in this regime. This remarkable result initiated intense activity. Experimental studies established the systematics of this phenomenon while theoretical work explored the properties of the $s-d$ Hamiltonian as well as the Anderson Hamiltonian.

The first attempts to improve on Kondo's calculation led to a scattering amplitude that diverged at a finite temperature

$$
\begin{equation*}
T_{K}=D \exp \left[1 / 2 J N\left(E_{F}\right)\right] \tag{3.166}
\end{equation*}
$$

which provides a quantitative expression for the Kondo temperature. Although the divergence indicated that the problem was still not being treated properly, it did indicate the formation of a resonance in the scattering amplitude at the Fermi level. That is, the Kondo effect is basically an impurity-induced Fermi surface instability. A great deal of effort has gone into identifying the nature of the ground state. From the very beginning it was suspected that it must be a singlet. However, it was only the exact diagonalization of the $s-d$ Hamiltonian by Andrei [71] and Wiegmann [72] that this singlet nature was confirmed. Yosida and collaborators [73] have shown that if one assumes a singlet wave function of the form

$$
\begin{equation*}
\psi_{\text {Kondo }}=\frac{1}{\sqrt{2}}\left(\chi_{\uparrow} \psi_{\uparrow}-\chi_{\downarrow} \psi_{\downarrow}\right) \tag{3.167}
\end{equation*}
$$

where $\chi_{\sigma}$ is the wave function of the impurity spin, then the conductionelectron component $\psi_{\uparrow}$ consists of half an electron with down spin and half a hole with up spin bound, to the impurity. This is illustrated schematically in Fig. 3.26.

Anderson [74] also considered the implications of a singlet ground state on the conduction-electron phase shifts. In the Hartree-Fock approximation discussed above, in the case of a well-localized moment $\delta_{\uparrow}=\pi$ and $\delta_{\downarrow}=0$. However, if we do have a singlet ground state there is rotational invariance and the phase shift must be independent of $\sigma$. Anderson postulated that in the vicinity of the Fermi level the phase shifts readjust as indicated in Fig. 3.26. The appearance of $\pi / 2$ phase shifts at the Fermi level implies a resonance at the Fermi level. This "Abrikosov-Suhl" resonance, as it is sometimes called, is also shown in Fig. 3.26. Such a peak in the density of states has also been derived [75] directly from the Anderson Hamiltonian. This result shows that the peak has a width $k_{B} T_{K}$ and disappears at the Kondo temperature. If only electrons within a characteristic energy $k_{B} T_{K}$ of the Fermi level are involved, this implies a spatial extent of

$$
\begin{equation*}
\xi_{K}=\frac{v_{F}}{k_{B} T_{K}} \tag{3.168}
\end{equation*}
$$





Fig. 3.26. (a) Schematic illustration of how the Hartree-Fock solution is augmented by the appearance of a resonance at the Fermi level consisting of half a spin-down electron and half a spin-up hole. (b) Variation of the phase shift with energy. (c) Variation in the local density of states

## Problems

3.1. Show that the sum of $\chi_{\text {diamag }}$ defined by (3.23) and $\chi_{V V}$ defined by (3.28) is invariant under a change in origin.

Hint: Use the relation

$$
\langle\alpha| p_{\mu}|\beta\rangle=\frac{i E_{\alpha \beta}}{\hbar}\langle\alpha| \mu|\beta\rangle,
$$

where $\mu=x, y$, or $z$.
3.2.
(a) Compute the partition function, $Z$, for a collection of $N$ spin- $J$ particles in a field $H$.
(b) Using the thermodynamic relation for the entropy,

$$
S=-\frac{\partial\left(k_{B} T \ln Z\right)}{\partial T}
$$

compute the entropy for the collection of spin- $J$ particles.
(c) Let us assume that the sample can be thermally insulated so that the entropy remains constant. Then if we reduce the field from some initial value, $H_{i}$, to some final value $H_{f}$, the temperature will change from its initial value, $T_{i}$, to a new final value, $T_{f}$. Calculate $T_{f}$. This is the principle of magnetic cooling.
3.3. Assume that the saturation magnetization (magnetic moment per unit volume) for iron arises only from the ionic moments associated with the electronic configuration $\mathrm{Fe}^{2+}\left(3 \mathrm{~d}^{6}\right)$. Calculate the saturation magnetization for a body-centered cubic structure with a lattice parameter $a=2.87 \AA$. How does this compare with the experimental value for iron?
3.4. Calculate the de Haas-van Alphen period $\Delta(1 / H)$ expected for copper assuming a free electron model with a Fermi wave vector of $k_{F}=1.36 \times$ $10^{8} \mathrm{~cm}^{-1}$.
3.5. Consider a two-dimensional electron gas (2 DEG) of density $n$ (electrons/ $\mathrm{cm}^{2}$ ) in which the electrons have an effective $g$-factor $g^{*}$ and an effective mass $m^{*}$.
(a) Show that the spin susceptibility is proportional to $g^{*} m^{*}$.
(b) Calculate the field, $B_{p}$, at which the system would exhibit total spin polarization.
3.6. Consider a dimer consisting of two $\mathrm{Cu}^{2+}\left(3 d^{9}\right)$ ions. Assume that the 3 d holes interact through an antiferromagnetic exchange, $\mathcal{H}=J s_{1} . s_{2}$. Using (3.19) derive the susceptibility of this isolated dimer.

## The Static Susceptibility of Interacting Systems: Local Moments

In this chapter we shall turn our attention to the static response of systems in which interactions among localized moments may lead to long-range order. A thorough treatment of such interactions and the resulting phase transition is an extremely complicated subject. Although very sophisticated techniques have been developed to treat these problems, there are still gaps in our understanding. However, except for the region very close to the critical point, an effective field theory works quite well. Therefore we shall employ this approximation throughout most of this chapter.

In Sect. 2.2 we found that the Coulomb interaction between the valence electrons on different ions could be expressed as an effective interaction between the individual electron spins. We also found that under certain conditions this interaction could be expressed in terms of the total ionic spin or, in some cases, the effective spin of the ground-state multiplet. Let us consider a system whose interactions may, in fact, be described by the Heisenberg exchange Hamiltonian

$$
\begin{equation*}
\mathcal{H}_{\mathrm{ex}}=-\sum_{i} \sum_{j \neq i} J_{i j} S_{i} \cdot S_{j}, \tag{4.1}
\end{equation*}
$$

where $J_{i j}$ is a function of the relative separation $\boldsymbol{R}_{i}-\boldsymbol{R}_{j}$.
Although many systems do not satisfy our conditions for writing the interaction in this form, it is often found that such systems may, nevertheless, be described surprisingly well by it. However, as we shall see, the treatment of this interaction entails certain approximations. Hence our success may result more from our methods than from the interaction with which we start. Since the exchange interaction is often large in comparison with other interactions, such as the magnetic-dipole-dipole interaction, the gross features of such a system may be described by (4.1) alone.

Let us now see how such a system responds to a static applied field. Since (4.1) is rotationally invariant, the direction of this applied field may be taken to define the $z$-axis. Just as in the preceding chapter, we apply a field of the form

$$
\begin{equation*}
\boldsymbol{H}(\boldsymbol{r})=\boldsymbol{H} \hat{\boldsymbol{z}} \cos (\boldsymbol{q} \cdot \boldsymbol{r}), \tag{4.2}
\end{equation*}
$$

where $\boldsymbol{q}$ corresponds to some point within the first Brillouin zone of the lattice. If the $g$ value associated with the effective spin is $g$, then the total Hamiltonian becomes

$$
\begin{equation*}
\mathcal{H}=-\sum_{i} \sum_{j \neq i} J_{i j} S_{i} \cdot S_{j}+g \mu_{B} H \sum_{i} S_{i}^{z} \cos \left(\boldsymbol{q} \cdot \boldsymbol{R}_{i}\right) . \tag{4.3}
\end{equation*}
$$

As in most cases involving coupling between lattice sites, it is convenient to express the Hamiltonian in Fourier components. Since

$$
\begin{equation*}
S\left(\boldsymbol{q}^{\prime}\right)=\int d \boldsymbol{r} e^{i \boldsymbol{q}^{\prime} \cdot \boldsymbol{r}} S(\boldsymbol{r})=\sum_{i} \int d \boldsymbol{r} e^{i \boldsymbol{q}^{\prime} \cdot \boldsymbol{r}} S_{i} \delta\left(\boldsymbol{r}-\boldsymbol{R}_{i}\right)=\sum_{i} e^{i \boldsymbol{q}^{\prime} \cdot \boldsymbol{r}_{i}} S_{i} \tag{4.4}
\end{equation*}
$$

we may write (4.3) as

$$
\begin{equation*}
\mathcal{H}=-\sum_{\boldsymbol{q}^{\prime}} J\left(-\boldsymbol{q}^{\prime}\right) S\left(\boldsymbol{q}^{\prime}\right) \cdot S\left(-\boldsymbol{q}^{\prime}\right)+\frac{1}{2} g \mu_{B} H\left[S_{z}(\boldsymbol{q})+S_{z}(-\boldsymbol{q})\right], \tag{4.5}
\end{equation*}
$$

where

$$
\begin{equation*}
J\left(-\boldsymbol{q}^{\prime}\right) \equiv \frac{1}{N} \sum_{i \neq j} J\left(\boldsymbol{R}_{i}-\boldsymbol{R}_{j}\right) e^{i \boldsymbol{q}^{\prime} \cdot\left(\boldsymbol{r}_{i}-\boldsymbol{r}_{j}\right)} \tag{4.6}
\end{equation*}
$$

Notice that if the crystal has inversion symmetry, $J(-\boldsymbol{q})=J(\boldsymbol{q})$. The analysis of the Hamiltonian (4.5) is very difficult and has been the subject of much work. The simplest approach is to consider one of the spins in (4.1) and replace its interaction with the other spins by an effective field [76]. This is referred to as the mean-field approximation. The concept appears to have first been applied by van der Waals in 1873 to develop the liquid-gas equation of state. Its application to ferromagnetism was made by P. Weiss in 1907. The same approximation was employed by Bragg and Williams in 1934 to describe orderdisorder transitions such as occur in $\beta$-brass when the copper and zinc atoms, through diffusion, order themselves with the copper at the center and the zinc at the corners of the body-centered-cubic lattice. The physics of such orderdisorder transitions is identical to that of an Ising magnet. In 1937 Landau developed a generalized mean-field theory applicable to all second-order phase transitions. We shall return to Landau's theory later in this chapter.

Since we have been emphasizing the usefullness of working with Fourier components it is appropriate to apply a variation of the mean-field approximation in which each of the Fourier components in (4.5) is assumed to be independent. This if referred to as the random-phase approximation. In this approximation the exchange interaction becomes

$$
\begin{equation*}
\mathcal{H}_{\mathrm{ex}}=-\sum_{\boldsymbol{q}^{\prime}} J\left(-\boldsymbol{q}^{\prime}\right) S\left(\boldsymbol{q}^{\prime}\right) \cdot\left\langle S\left(-\boldsymbol{q}^{\prime}\right)\right\rangle . \tag{4.7}
\end{equation*}
$$

### 4.1 High Temperatures

If the temperature is higher than that at which long-range order sets in, we may assume that the only components with nonzero average values are those driven by the applied field. Thus $\left\langle S\left(-\boldsymbol{q}^{\prime}\right)\right\rangle$ is replaced by $\left\langle S_{z}\left(-\boldsymbol{q}^{\prime}\right)\right\rangle \hat{\boldsymbol{z}} \Delta\left(\boldsymbol{q}-\boldsymbol{q}^{\prime}\right)$. The total Hamiltonian in the random-phase approximations becomes

$$
\begin{align*}
\mathcal{H}_{\mathrm{RPA}}= & -\left[J(\boldsymbol{q})\left\langle S_{z}(-\boldsymbol{q})\right\rangle S_{z}(\boldsymbol{q})+J(\boldsymbol{q})\left\langle S_{z}(\boldsymbol{q})\right\rangle S_{z}(-\boldsymbol{q})\right] \\
& +\frac{1}{2} g \mu_{B} H\left[S_{z}(\boldsymbol{q})+S_{z}(-\boldsymbol{q})\right] \tag{4.8}
\end{align*}
$$

which defines the total effective field seen by the $\boldsymbol{q}$ th component as

$$
\begin{equation*}
\boldsymbol{H}(-\boldsymbol{q})_{\mathrm{eff}}=\frac{J(-\boldsymbol{q}) V}{g \mu_{B}}\left\langle S_{z}(-\boldsymbol{q})\right\rangle \hat{\boldsymbol{z}}+\frac{1}{2} H V \hat{\boldsymbol{z}} . \tag{4.9}
\end{equation*}
$$

In discussing noninteracting systems we found that the response of the $\boldsymbol{q}$ th component of the spin at high temperatures was determined by

$$
\begin{equation*}
\chi_{0}(\boldsymbol{q})=\frac{C}{T} \equiv \chi_{0}, \tag{4.10}
\end{equation*}
$$

where

$$
C=\frac{N}{V} g^{2} \mu_{B}^{2} \frac{S(S+1)}{3 k_{B}} .
$$

Therefore, employing our definition of the susceptibility, we have

$$
\begin{align*}
M_{z}(\boldsymbol{q}) & =-g \mu_{B}\left\langle S_{z}(\boldsymbol{q})\right\rangle=\chi_{0}(\boldsymbol{q}) H_{z}(\boldsymbol{q})_{\mathrm{eff}} \\
& =-\frac{J(\boldsymbol{q}) \chi_{0}(\boldsymbol{q}) V}{g \mu_{B}}\left\langle S_{z}(\boldsymbol{q})\right\rangle+\frac{1}{2} H V \chi_{0}(\boldsymbol{q}) . \tag{4.11}
\end{align*}
$$

Solving for $\left\langle S_{z}(\boldsymbol{q})\right\rangle$ and using (4.10) gives us the susceptibility of the interacting system at high temperatures,

$$
\begin{equation*}
\chi(\boldsymbol{q})=\frac{\chi_{0}}{1-\chi_{0} \frac{J(\boldsymbol{q}) V}{g^{2} \mu_{B}^{2}}}=\frac{C / T_{c}}{\left(T-T_{c}\right) / T_{c}+[1-J(\boldsymbol{q}) / J(\boldsymbol{q})]} \tag{4.12}
\end{equation*}
$$

We notice immediately that as the temperature decreases a divergence appears at a critical temperature

$$
\begin{equation*}
T_{c}=\frac{J(\boldsymbol{q}) C V}{g^{2} \mu_{B}^{2}} \tag{4.13}
\end{equation*}
$$

where $\boldsymbol{q}$ is the wave vector for which $J(\boldsymbol{q})$ is a maximum. The fact that the susceptibility diverges for this particular wave vector means that the component of the magnetization with that wave vector would remain nonzero even if the probing field were to go to 0 . Thus we have a spontaneous magnetization. The wave vector $\boldsymbol{q}$ for which this transition occurs depends on the nature of $J(\boldsymbol{q})$. Let us consider four possible cases.

Ferromagnetism. Suppose that the exchange $J_{i j}$ is positive and extends only to nearest neighbors. Then

$$
\begin{equation*}
J(\boldsymbol{q})=\frac{J}{N} \sum_{\delta} \exp (-i \boldsymbol{q} \cdot \boldsymbol{\delta}) \tag{4.14}
\end{equation*}
$$

where $\boldsymbol{\delta}$ is a vector to the nearest neighbor. In particular, if we have a simple cubic lattice with a lattice parameter $a$, then

$$
\begin{equation*}
J(\boldsymbol{q})=\frac{2 J}{N}\left(\cos q_{x} a+\cos q_{y} a+\cos q_{z} a\right) \tag{4.15}
\end{equation*}
$$

Figure 4.1 shows $1 / \chi(\boldsymbol{q})$ plotted as a function of temperature for various values of $\boldsymbol{q}$. We see immediately that as the temperature decreases the first divergence appears at $\boldsymbol{q}=0$.

This instability results in a uniformly magnetized system, a ferromagnet. The temperature associated with this transition is the Curie temperature, which, for our simple cubic example, is

$$
\begin{equation*}
T_{c}=\frac{J(0) C V}{g^{2} \mu_{B}^{2}}=\frac{6 J S(S+1)}{3 k_{B}} . \tag{4.16}
\end{equation*}
$$

The uniform susceptibility is

$$
\begin{equation*}
\chi(0)_{\mathrm{ferro}}=\frac{C}{T-T_{c}} . \tag{4.17}
\end{equation*}
$$

In fact, ferromagnetism is not compatible with cubic symmetry. This has to do with time reversal. In the ferromagnetically ordered state time reversal by itself is not a symmetry operation, but only occurs in conjunction with some other symmetry operator. Consider, for example, a body-centered-cubic (bcc) system. In the paramagnetic state the symmetry operations which transform this structure into itself constitute the octahedral group denoted $O_{h}$ or m3m. If, in the ordered state, the spins at each site all point in the $z$-direction then those operations of $O_{h}$ which involve rotations about the $x$ - or $y$-axes must be combined with time reversal to preserve the direction of the spins. The resulting allowed operations constitute the so-called magnetic point group, which, in this case, is denoted $4 / \mathrm{mm} \underline{m}$. The important feature of this group is that it is tetragonal. When a material develops a spontaneous magnetization, it also generally develops a strain proportional to the magnetization. This magnetostrictive effect, as it is known, reflects the symmetry of the system. Thus, iron, which is bcc above its Curie temperature, develops a tetragonal distortion in the ferromagnetic state. However, since this distortion is very small one often finds ferromagnetic iron characterized as bcc.

Another general result which is obscured by the above mean field approximation has to do with the dimensionality of the system. Landau and


Fig. 4.1. Temperature dependence of the inverse susceptibility $1 / \chi(\boldsymbol{q})$ of a ferromagnet for various values of $\boldsymbol{q}$

Lifshitz [77a] pointed out that one cannot have long-range order in one dimension at a finite temperature. Consider, for example, a chain of spins. The long-range order is destroyed by simply "flipping" one spin. Although this costs exchange energy, the entropy gained is proportional to the logarithm of the number of ways this can be done. For an infinitely long chain this entropy term will always dominate the free energy, resulting in disorder. Lieb and Mattis have shown [77b] that at $T=0$ the ground state of a system of $N$ electrons in 1-dimension subject to an arbitrary symmetric potential is unmagnetized. While it is not possible to realize a truely 1-dimensional system, it is possible to fabricate GaAs-AlGaAs heterojunctions that behave as quantum wires. The quantization of conductance in integer multiples of $2 e^{2} / \hbar$ is the signature of 1-D transport. Recent results suggest that under such conditions the transport electrons are spin polarized [77c]. This is a subject of current interest.

In two dimensions the situation depends upon the details of the interaction - a Heisenberg system, for example, does not exhibit ferromagnetism, while an Ising system does.

Antiferromagnetism. From Fig. 4.1 it is obvious that if the exchange constant between nearest neighbors is negative, then the first divergence appears for $\boldsymbol{q}=(\pi / a)(\hat{\boldsymbol{x}}+\hat{\boldsymbol{y}}+\hat{\boldsymbol{z}})$ or one of the other similar wave vectors in a bodydiagonal direction. This means that the phase of the magnetization changes by $\pi$ from one plane of atoms to the next as we proceed along the direction of $\boldsymbol{q}$. Thus we have an antiferromagnetic system. The temperature at which $\chi(\boldsymbol{q})$ diverges is the Néel temperature,

$$
\begin{equation*}
T_{N}=\frac{6|J| S(S+1)}{3 k_{B}} . \tag{4.18}
\end{equation*}
$$



Fig. 4.2. Possible types of antiferromagnetic order in body-centered and facecentered cubic lattices. The symbols $\oplus$ and $\ominus$ refer to "up" and "down" magnetic moments, respectively

The uniform susceptibility is given by

$$
\begin{equation*}
\chi(0)_{\mathrm{antiferro}}=\frac{C}{T+T_{N}}, \tag{4.19}
\end{equation*}
$$

which is well behaved at the Néel temperature.
In general the exchange interaction will extend beyond just the nearest neighbors. This can lead to a variety of antiferromagnetic configurations. Antiferromagnetism is compatible with cubic symmetry, and several "types" of antiferromagnetic orderings in cubic lattices are illustrated in Fig. 4.2. The oxides $\mathrm{MnO}, \mathrm{FeO}$, and NiO are examples of the fcc type II order.
Helimagnetism. In Chap. 9 we shall discuss the RKKY exchange interaction, an indirect exchange between localized moments which arises through the presence of conduction electrons. For our present purposes it is sufficient to note that this interaction is long range and oscillatory. To see what effect such an exchange may have on our spin configuration, let us consider our simple cubic lattice and take

$$
J_{i j}= \begin{cases}J_{1} & \text { for the six nearest neighbors. } \\ -J_{2} & \text { for the twelve next-nearest neighbors. }\end{cases}
$$



Fig. 4.3. Magnetic properties of the rare-earth metals. Data assembled from [78]

Then

$$
\begin{align*}
J(\boldsymbol{q})= & \frac{2 J_{1}}{N}\left(\cos q_{x} a+\cos q_{y} a+\cos q_{z} a\right)  \tag{4.20}\\
& -\frac{4 J_{2}}{N}\left[\left(\cos q_{x} a\right)\left(\cos q_{y} a\right)+\left(\cos q_{y} a\right)\left(\cos q_{z} a\right)+\left(\cos q_{z} a\right)\left(\cos q_{x} a\right)\right]
\end{align*}
$$

This exchange has an extremum when $a \boldsymbol{q}=\cos ^{-1}\left(J_{1} / 4 J_{2}\right)(\hat{\boldsymbol{x}}+\hat{\boldsymbol{y}}+\hat{\boldsymbol{z}})$. If $J_{1}<4 J_{2}$, it will lead to a spin configuration whose wavelength is incommensurate with the lattice spacing. An example of such a system is the rareearth metal thulium (Tm) at temperatures between 40 and 56 K . The spin configuration of Tm in this region is illustrated in Fig. 4.3. This particular configuration is sometimes referred to as a longitudinal wave.

The general situation is actually more complicated. So far our probing field has had a sinusoidally varying amplitude but has been fixed in direction. In principle, we could also imagine a field whose direction also varies in space. Should the response to such a peculiar field diverge, a correspondingly peculiar spin configuration would occur. Such spin configurations are, in fact, found in the heavy rare-earth metals as indicated in Fig. 4.3. The insert illustrates various spin configurations. Such systems are referred to as helimagnets. Dealing with the generalized susceptibility is not a very practical way of determining the existence of such spin configurations. A better method is to minimize the exchange energy. This is, in fact, the way these configurations were first obtained [79]. For our longitudinal-wave helimagnet, $J(\boldsymbol{q})=3 J_{1}^{2} / 4 N J_{2}$ and

$$
\begin{equation*}
T_{c}=\frac{S(S+1) J_{1}^{2}}{4 k_{B} J_{2}} . \tag{4.21}
\end{equation*}
$$

Therefore the uniform susceptibility is

$$
\begin{equation*}
\chi(0)_{\text {heli }}=\frac{C}{T-\left[8 J_{2}\left(J_{1}-2 J_{2}\right) / J_{1}^{2}\right] T_{c}} . \tag{4.22}
\end{equation*}
$$

Since $J_{1}<4 J_{2}$, the coefficient of $T_{c}$ in the denominator is always less than 1 . Thus the uniform susceptibility will be finite at the transition temperature. However, its high-temperature behavior will resemble that of a ferromagnet if $J_{1}>2 J_{2}$ and that of an antiferromagnet if $J_{1}<2 J_{2}$.
Ferrimagnetism. In the preceding three cases we have assumed that the spins and their environments were all identical. If some spins or some environments are different, then we have an impurity or alloy problem. However, if there are two different sites, each of which is translationally equivalent, i.e., two sublattices, then we can have what Néel called a ferrimagnet. As an example of such a system, let us consider an NaCl -like structure with spins $S_{1}$, say, at the Na-like sites and $S_{2}$ at the Cl-like sites. Thus we have a basis of two spins, just as NaCl has a basis of two ions. The Bravais lattice is face-centered cubic.

If we denote the spin in the $i$ th cell with the basis vector $\boldsymbol{b}$ as $S_{i b}$ and assume a nearest-neighbor exchange interaction, then the exchange Hamiltonian is

$$
\begin{equation*}
\mathcal{H}_{\mathrm{ex}}=-J \sum_{i, j} \sum_{b, b^{\prime}} S_{i \boldsymbol{b}} \cdot S_{j \boldsymbol{b}^{\prime}} \tag{4.23}
\end{equation*}
$$

where the sums involve only nearest-neighbor spins. The reciprocal lattice associated with our system is that appropriate to the face-centered-cubic Bravais lattice. Therefore the Fourier expansion of the spins will involve wave vectors whose components are multiples of $2 \pi / L$ up to $\pi / 2 a$, where $L$ is the crystal dimension and $a$ is the ionic spacing. Applying an external field with a spatial variation characterized by one of these wave vectors gives a Zeeman Hamiltonian of the form

$$
\begin{equation*}
\mathcal{H}_{Z}=g \mu_{B} H \sum_{i, \boldsymbol{b}} S_{i \boldsymbol{b}}^{z} \cos \left(\boldsymbol{q} \cdot \boldsymbol{R}_{i}+\boldsymbol{q} \cdot \boldsymbol{b}\right) \tag{4.24}
\end{equation*}
$$

In Fourier components, the total Hamiltonian is

$$
\begin{align*}
\mathcal{H}= & -\sum_{\boldsymbol{q}^{\prime}} \sum_{\boldsymbol{b} \neq \boldsymbol{b}^{\prime}} J\left(-\boldsymbol{q}^{\prime}\right) S_{\boldsymbol{b}}\left(\boldsymbol{q}^{\prime}\right) \cdot S_{\boldsymbol{b}^{\prime}}\left(-\boldsymbol{q}^{\prime}\right)+\frac{1}{2} g \mu_{B} H \\
& \times \sum_{\boldsymbol{b}}\left[S_{\boldsymbol{b}}^{z}(\boldsymbol{q}) e^{-i \boldsymbol{q} \cdot \boldsymbol{b}}+S_{\boldsymbol{b}}^{z}(-\boldsymbol{q}) e^{i \boldsymbol{q} \cdot \boldsymbol{b}}\right] \tag{4.25}
\end{align*}
$$

where

$$
\begin{equation*}
J(-\boldsymbol{q})=\frac{J}{N} \sum_{\delta}^{\prime} e^{-i \boldsymbol{q} \cdot \boldsymbol{\delta}} \tag{4.26}
\end{equation*}
$$

The prime indicates that $\boldsymbol{\delta}$ is restricted to 0 and five vectors to nearest neighbors, which depend on the definition of the basis. If we take $\boldsymbol{b}=a \hat{\boldsymbol{x}}$, then

$$
\begin{equation*}
J(-\boldsymbol{q})=\frac{2 J}{N}\left(\cos \boldsymbol{q}_{x} a+\cos \boldsymbol{q}_{y} a+\cos \boldsymbol{q}_{z} a\right) \exp \left(-i \boldsymbol{q}_{x} a\right) \tag{4.27}
\end{equation*}
$$

The effective field seen by the spin $S_{b}$ is

$$
\begin{equation*}
\boldsymbol{H}_{\boldsymbol{b}}(-\boldsymbol{q})_{\mathrm{eff}}=-\frac{J(-\boldsymbol{q}) V}{g \mu_{B}}\left\langle S_{\boldsymbol{b}^{\prime}}^{z}(-\boldsymbol{q})\right\rangle \hat{\boldsymbol{z}}+\frac{1}{2} H V e^{-i \boldsymbol{q} \cdot \boldsymbol{b}} \hat{\boldsymbol{z}} . \tag{4.28}
\end{equation*}
$$

Making use of (4.10), we have

$$
\begin{equation*}
\left\langle S_{\boldsymbol{b}}^{z}(\boldsymbol{q})\right\rangle=-\frac{\chi_{0}(\boldsymbol{q})}{g \mu_{B}} H_{\boldsymbol{b}}(\boldsymbol{q})_{\mathrm{eff}}=\frac{C_{\boldsymbol{b}} J(\boldsymbol{q}) V}{g^{2} \mu_{B}^{2} T}\left\langle S_{\boldsymbol{q}^{\prime}}^{z}(\boldsymbol{q})\right\rangle-\frac{C_{\boldsymbol{b}} H V}{2 g \mu_{B} T} e^{-i \boldsymbol{q} \cdot \boldsymbol{b}} \tag{4.29}
\end{equation*}
$$

with a similar equation for $\left\langle S_{b^{\prime}}^{z}(\boldsymbol{q})\right\rangle$. Solving these two equations gives

$$
\begin{equation*}
\left\langle S_{\boldsymbol{b}}^{z}(\boldsymbol{q})\right\rangle=-\frac{H V}{2 g \mu_{B} T} \frac{C_{\boldsymbol{b}} e^{i \boldsymbol{q} \cdot \boldsymbol{b}}+\left[C_{\boldsymbol{b}} C_{\boldsymbol{b}^{\prime}} J(\boldsymbol{q}) V / g^{2} \mu_{B}^{2} T\right] e^{i \boldsymbol{q} \cdot \boldsymbol{b}^{\prime}}}{1-C_{\boldsymbol{b}} C_{\boldsymbol{b}^{\prime}} J(\boldsymbol{q})^{2} V^{2} / g^{4} \mu_{B}^{4} T^{2}} \tag{4.30}
\end{equation*}
$$

Since

$$
\begin{align*}
M_{z}(\boldsymbol{q}) & =-g \mu_{B} \int d \boldsymbol{r} e^{i \boldsymbol{q} \cdot \boldsymbol{r}} \sum_{i, \boldsymbol{b}}\left\langle S_{i \boldsymbol{b}}^{z}\right\rangle \delta\left(\boldsymbol{r}-\boldsymbol{R}_{i}-\boldsymbol{b}\right), \\
& =-g \mu_{B} \sum_{\boldsymbol{b}}\left\langle S_{\boldsymbol{b}}(\boldsymbol{q})\right\rangle e^{-i \boldsymbol{q} \cdot \boldsymbol{b}}, \tag{4.31}
\end{align*}
$$

we obtain for the susceptibility of our ferrimagnetic system,

$$
\begin{equation*}
\chi(\boldsymbol{q})=\frac{\left(C_{1}+C_{2}\right) T+2 C_{1} C_{2} J(\boldsymbol{q}) \cos \left(q_{x} a\right) V / g^{2} \mu_{B}^{2}}{T^{2}-C_{1} C_{2} J(\boldsymbol{q})^{2} V^{2} / g^{4} \mu_{B}^{4}} \tag{4.32}
\end{equation*}
$$



Fig. 4.4. Two possible basis configurations for a ferrimagnet


Fig. 4.5. General behavior of the high-temperature inverse susceptibility associated with various systems

From the nature of $J(\boldsymbol{q})$, this susceptibility diverges for $\boldsymbol{q}=0$. Furthermore, this divergence is independent of whether $J$ is positive or negative. If it is positive, the two spins within the basis are parallel; if it is negative, they are antiparallel. These two possible configurations are shown in Fig. 4.4. The uniform susceptibility of this ferrimagnetic system is

$$
\begin{equation*}
\chi(0)_{\text {ferri }}=\frac{\left(C_{1}+C_{2}\right) T+2 \sqrt{C_{1} C_{2}} T_{c}}{T^{2}-T_{c}^{2}} \tag{4.33}
\end{equation*}
$$

where the transition temperature is

$$
\begin{equation*}
T_{c}=\frac{6 J \sqrt{S_{1} S_{2}\left(S_{1}+1\right)\left(S_{2}+1\right)}}{3 k_{B}} . \tag{4.34}
\end{equation*}
$$

The high-temperature susceptibilities associated with the various types of magnetic order are shown in Fig. 4.5. The rare-earth iron garnets, $\mathrm{RE}_{3} \mathrm{Fe}_{5} \mathrm{O}_{12}$, are typical examples of ferrimagnets.

Although our preceeding discussion has focused on lattices, the existence of such atomic long-range order is not required for magnetic long-range order. There are a large number of materials that can be prepared in the amorphous state which show magnetic order. In particular, amorphous films of rare-earth and transition metals, such as Gd-Co and Tb-Fe, are ferrimagnetic.

Below the ferromagnetic transistion temperature the system is characterized by a spontaneous uniform magnetization. In most ferromagnets the magnetization develops smoothly from zero, identifying such transitions as second order. A typical magnetization curve is shown in Fig. 4.6.


Fig. 4.6. Magnetization of europium oxide as a function of temperature [80]


Fig. 4.7. Magnetization of gadolinium iron garnet as a function of temperature (a). The garnets have three inequivalent magnetic sublattices. The " $a$ " ions are arranged on a bcc lattice in octahedral sites; the " $c$ " and " $d$ " ions sit in dodecahedral and tetrahedral sites, respectively. The dominant exchange interaction is an antiferromagnetic coupling between the $a$ and $d$ sites. The calculated contributions to the magnetization from these sublattices is shown in (b) [81]

The magnetization curve for a ferrimagnet is more complex. Figure 4.7 shows the net magnetization associated with a two-component, antiferromagnetically coupled ferrimagnet. Because the temperature dependences of the individual components are different, the net magnetization may go to zero at a point called the compensation temperature. This temperature is very important in certain applications involving the switching of the magnetization.

Spin Glasses. In a metal the exchange between local moments can be positive (ferromagnetic) or negative (antiferromagnetic) (see Sect.9.2.1). This means


Fig. 4.8. Simple example of frustration. The signs refer to the exchange. Thus, if the three spins are aligned as indicated, the fourth will be frustrated
that some spins may find themselves in configurations where it is not possible to satisfy all the exchange interactions. Such a situation is illustrated in Fig. 4.8 and is referred to as "frustration". The first model of a spin system incorporating frustration was suggested by Edwards and Anderson [82]. Their model consists of spins on every site of a regular lattice interacting with $z$ neighbors through an exchange $J_{i j}$, which is random and governed by a probability distribution $P\left(J_{i j}\right)$. To see the qualitative implications of this model, consider the mean-field equation (4.35) for the thermal average of a spin $\frac{1}{2}$,

$$
\begin{equation*}
\left\langle S_{i}\right\rangle=\tanh \left(\sum_{j} J_{i j}\left\langle S_{j}\right\rangle / k_{B} T\right) \tag{4.35}
\end{equation*}
$$

Linearizing gives

$$
\begin{equation*}
\left\langle S_{i}\right\rangle=\sum_{j} J_{i j}\left\langle S_{j}\right\rangle / k_{B} T \tag{4.36}
\end{equation*}
$$

Averaging over $J_{i j}=0$ leads to the result that $\overline{\left\langle S_{i}\right\rangle}=0$. However, if we square (4.36) and again average over the exchange values, we obtain

$$
\begin{equation*}
\overline{\left\langle S_{i}\right\rangle^{2}}=\frac{z}{\left(k_{B} T\right)^{2}} \overline{J_{i j}^{2}} \overline{\left\langle S_{j}\right\rangle^{2}} . \tag{4.37}
\end{equation*}
$$

This means that $\overline{\left\langle S_{i}\right\rangle^{2}}$ becomes nonzero at a critical temperature $T_{f}=$ $z \overline{J_{i j}^{2}} / k_{B}$ and is identified as the order parameter $q$. The fact that $\overline{\left\langle S_{i}\right\rangle^{2}} \neq 0$, while $\overline{\left\langle S_{i}\right\rangle}=0$, implies a spin configuration in which each spin is frozen in some specific direction, but this direction varies randomly throughout the alloy. This is generally what is meant by a "spin glass". The mean-field solution to the Edwards-Anderson model gives a cusp in the low-field ac susceptibility as observed experimentally (Fig. 4.9). However, the theory also predicts a cusp in the specific heat at $T_{f}$ which is not observed.

A difficulty in comparing experimental results with random exchange models is that the data seem to suggest that the actual systems may be more complex. The ac susceptibility, for example, is slightly frequency dependent,


Fig. 4.9. ac susceptibility as a function of temperature for $\mathbf{C u}: \mathrm{Mn}$ [83]


Fig. 4.10. dc susceptibility of $\mathbf{A g}: \mathrm{Mn}[84]$
as shown in the insert in Fig. 4.9. The dc susceptibility is also marked by timedependent and irreversible behavior. Figure 4.10 shows the dc susceptibility of Mn in Ag . If the sample is cooled in zero magnetic field (which involves cancellation of the earth's field) and then the susceptibility measured with increasing temperature, one obtains the solid curve. On the other hand, if one cools the sample in the presence of the field which is used to measure susceptibility, then one obtains the larger values indicated by the dashed lines. These field-cooled susceptibilities are reversible whereas the zero-field-cooled curve is not. Furthermore, if one sits at a given temperature $T<T_{f}$ on the zero-field-cooled curve, the magnetization increases logarithmically with time, eventually approaching the field-cooled value. This behavior is believed to be associated with the existence of a large number of low-lying states connected by energy barriers. These barriers restrict the phase space available to the system and the low temperature magnetic properties are governed by the shape of these wells.

### 4.2 Low Temperatures

Let us now turn briefly to the question of how the systems we have just discussed respond to a static field when they are below their ordering temperature. In the treatment above we considered only an isotropic exchange interaction. If this were the only contribution to the Hamiltonian, then the Hamiltonian, as well as its eigenstates, would be invariant under rotations. This would mean that the isotropic exchange interaction itself could not lead to a macroscopically ordered state. There are, in fact, additional interactions which favor certain crystallographic directions. Nickel, for example, prefers to magnetize along its $\left[\begin{array}{lll}1 & 1 & 1\end{array}\right]$ direction while iron prefers the $\left[\begin{array}{lll}1 & 0 & 0\end{array}\right]$ direction. Such magnetic anisotropy has its origin in the spin-orbit interaction as we discussed in Sect. 2.3.1. In metals this interaction leads to shifts in the energy bands as the magnetization direction is varied. Such shifts are accompanied by an electron redistribution among the bands with a corresponding change in the total electronic energy.

Macroscopically, the magnetic anisotropy is characterized by an energy which is a function of the direction cosines of the magnetization relative to the crystallographic axes. A uniaxial anistropy, for example, would be represented by $K_{1} \sin ^{2} \theta$. Microscopically, at least for an ionic solid, the anisotropy appears as terms in the Hamiltonian involving products of the components of the spin. In particular, for a uniaxial system,

$$
\begin{equation*}
\mathcal{H}_{\text {aniso }}=-D \sum_{i}\left(S_{i}^{z}\right)^{2} \tag{4.38}
\end{equation*}
$$

where $D$ is the anisotropy constant. The total effective field acting on the $i$ th spin in the molecular field approximation is therefore

$$
\begin{equation*}
\boldsymbol{H}_{i, \mathrm{eff}}=-\frac{1}{g \mu_{B}} \sum_{j \neq i} J_{i j}\left\langle S_{j}\right\rangle-\frac{D}{g \mu_{B}}\left\langle S_{i}^{z}\right\rangle \hat{\boldsymbol{z}}+\boldsymbol{H} \cos \left(\boldsymbol{q} \cdot \boldsymbol{R}_{i}\right) \tag{4.39}
\end{equation*}
$$

Because there is now an inherent direction in the system, the response to an applied field will depend upon the direction of such a field. Let us first consider the case in which the applied field is parallel to the anisotropy axis. Then

$$
\begin{equation*}
\left\langle S_{j}\right\rangle=\left\langle S_{i}^{z}\right\rangle_{0} \cos \left[\boldsymbol{Q} \cdot\left(\boldsymbol{R}_{j}-\boldsymbol{R}_{i}\right)\right] \hat{\boldsymbol{z}}+\delta S_{j}^{z} \hat{\boldsymbol{z}}, \tag{4.40}
\end{equation*}
$$

where $\left\langle S_{i}^{z}\right\rangle_{0}$ is the average value of $S_{i}^{z}$ in the absence of the applied field and $Q$ characterizes the order. Since the exchange energy exceeds the thermal energy in the ordered state, this is given by the Brillouin function as

$$
\begin{equation*}
\left\langle S_{i}^{z}\right\rangle_{0}=-S B_{S}\left(-\frac{[N S J(\boldsymbol{Q})+D S]\left\langle S_{i}^{z}\right\rangle_{0}}{k_{B} T}\right) \tag{4.41}
\end{equation*}
$$

The term $\delta S_{j}^{z}$ in (4.40) is that part of $\left\langle S_{j}^{z}\right\rangle$ which is induced by the applied field. This response is what defines the susceptibility. The average value of $S_{i}^{z}$
in the presence of the field is given by an expression similar to (4.41), with the applied field added to the argument of the Brillouin function as well as terms involving $\delta S_{i}^{z}$. However, if all these additional terms are small, we may expand the Brillouin function in powers of these terms. To lowest order, we obtain

$$
\begin{align*}
\left\langle S_{i}^{z}\right\rangle= & \left\langle S_{i}^{z}\right\rangle_{0}+\frac{N S^{2} B_{S}^{\prime}}{k_{B} T} \frac{1}{N} \sum_{j \neq i} J_{i j} \delta S_{j}^{z} \\
& +\frac{D S^{2} B_{S}^{\prime}}{k_{B} T} \delta S_{i}^{z}-\frac{g \mu_{B} S^{2} H B_{S}^{\prime}}{k_{B} T} \cos \left(\boldsymbol{Q} \cdot \boldsymbol{R}_{i}\right) \tag{4.42}
\end{align*}
$$

where $B_{S}^{\prime}$ is the derivative of the Brillouin function with respect to its argument, evaluated at zero field. If we take the Fourier transform of (4.39), the susceptibility is found to be

$$
\begin{equation*}
\chi_{\|}(\boldsymbol{q})=\frac{3 S C B_{S}^{\prime} /(S+1)}{T-\left[3 S B_{S}^{\prime} /(S+1)\right][N J(\boldsymbol{q})+D] S(S+1) / 3 k_{B}} . \tag{4.43}
\end{equation*}
$$

By similar arguments, the response to a field applied perpendicular to the $z$-axis is characterized by

$$
\begin{equation*}
\chi_{\perp}(\boldsymbol{q})=\frac{g^{2} \mu_{B}^{2} N / V}{N[J(\boldsymbol{Q})-J(\boldsymbol{q})]+D} \tag{4.44}
\end{equation*}
$$

From these expressions we find that the perpendicular susceptibility is independent of temperature, while the parallel susceptibility decreases to 0 as the temperature does. This leads to a rather interesting phenomenon in antiferromagnets. At zero temperature the application of a parallel field produces no polarization. Thus there is no Zeeman energy associated with this state. A perpendicular field, however, produces a small canting of the spins which does lead to a polarization. The Zeeman energy associated with this state is essentially $-\boldsymbol{M} \cdot \boldsymbol{H}$. Thus, if there were no anisotropy energy, the spins in a parallel field would all "flop" over into the lower-energy perpendicular configuration. Because of the anisotropy energy there is a minimum field at which this "spin-flop" transition occurs. By equating the energies in the two states we find, for nearest-neighbor interactions,

$$
\begin{equation*}
H_{\mathrm{crit}}=\frac{S}{g \mu_{B}} \sqrt{4 z D|J|} \tag{4.45}
\end{equation*}
$$

which is the geometrical mean of the exchange field and the anistropy field. This will not happen in a ferromagnet, even though the parallel response function does go to 0 , because of the large dipolar energy associated with the aligned state. Figure 4.11 shows the phase diagram for an antiferromagnet.


Fig. 4.11. Phase diagram for an antiferromagnet ( $H_{i}$ is the internal field)


Fig. 4.12. Phase diagram for a metamagnet in terms of the internal field, $H_{i}$ (a) and the applied field, $H_{0}(\mathbf{b})$

Metamagnetism. In a material with strong anistropy the spin-flop state is suppressed and below a certain temperature the system goes directly into the paramagnetic state via a first-order transition. Such systems are called metamagnets. Classic examples are $\mathrm{FeCl}_{2}$ and $\mathrm{DyPO}_{4}$. A schematic phase diagram is shown in Fig. 4.12a. The point at which the line of second-order transitions changes into a line of first-order transitions is called the tricritical point. In an antiferromagnet the field conjugate to the staggered magnetization is the staggered field $H(\boldsymbol{q}) \equiv H_{s}$. Griffiths [85] has pointed out that in the $H_{i}-$ $H_{s}-T$ phase diagram for a metamagnet there exist two first-order surfaces extending like wings out into the $H_{s} \neq 0$ region as shown in Fig. 4.12a. Notice that these wings are bounded by two lines of second-order transitions. Thus the tricritical point is also the meeting of three critical lines. In finite samples the internal field $H_{i}$ and the applied field $H_{0}$ differ due to demagnetizing effects. For an elliptical sample characterized by a demagnetizing factor $N$, the internal field is given by $H_{i}=H_{0}-4 \pi N M$. Since the magnetization increases discontinuously as we cross the line of first-order transitions, the internal field is discontinuously reduced to a value below that required for the transition. The material resolves this contradiction by breaking into domains of two phases. This mixed phase is analogous to the so-called intermediate state in superconductivity.

### 4.3 Temperatures Near $\boldsymbol{T}_{\boldsymbol{c}}$

Let us now turn to the interesting region of the critical point itself. The object of any critical-point theory is to predict accurately the behavior of various physical quantities as the temperature or some other variable approaches its critical-point value. Generally this approach is represented by a power law such as $\left(T-T_{c}\right)^{\lambda}$. Figure 4.6, for example, shows that the magnetization of EuO vanishes as $\left(T-T_{c}\right)^{0.37}$. A successful theory must correctly predict the value of $\lambda$, as well as any relationship, if it exists, between the exponents associated with different physical quantities.

There are two basic steps in this problem. First a model must be selected that adequately represents the actual system but isstill mathematically tractable. Our discussions so far have been based on the Heisenberg Hamiltonian, $-\sum J_{i j} S_{i} \cdot S_{j}$. We have also mentioned the Ising model, $-\sum J_{i j} S_{i}^{z} S_{j}^{z}$. Although some materials, such as dysprosium aluminum garnet, may actually be described by this model, its main attraction is that it is much easier to deal with than the Heisenberg model. In fact, the thermodynamic quantities associated with a two-dimensional Ising model may be computed exactly [86].

Since even the relatively simple Ising model has not yet been solved exactly in three dimensions, we are forced to make certain approximations. Therefore the second step in the critical-point problem is the development of mathematical techniques that enable us to calculate physical properties near the phase transition of our model system. In Sect.4.1, we employed the meanfield approximation for low temperatures where each spin was assumed to be statistically independent; that is, $\left\langle S_{i}^{z} S_{j}^{z}\right\rangle_{0}=\left\langle S_{i}^{z}\right\rangle_{0}\left\langle S_{j}^{z}\right\rangle_{0}$, where the subscript indicates that this average is to be taken in zero field. In the hightemperature region we employed the random-phase approximation, in which only the Fourier components were assumed independent. Notice that use of the molecular field approximation in this region would have implied that the energy of the system, which involves $\left\langle S_{i}^{z} S_{j}^{z}\right\rangle_{0}$, was 0 above $T_{c}$. Thus the specific heat would also have been 0 . In actual fact, however, as $T_{c}$ is approached from above the spins begin to correlate with one another. That is, $\left\langle S_{i}^{z} S_{j}^{z}\right\rangle$ is not 0 for spins that are relatively close together. We speak of this as the appearance of short-range order. Owing to the existence of this short-range order, the energy, and consequently the specific heat, are not 0 above the point where the spontaneous magnetization vanishes.

The determinations of the correlation function $\left\langle S_{i}^{z} S_{j}^{z}\right\rangle_{0}$ provides us with a nice application of the fluctuation-dissipation theorem. Introducing Fourier components and requiring that this correlation function depend only upon the relative coordinates of the spins gives

$$
\begin{equation*}
\left\langle S_{i}^{z} S_{j}^{z}\right\rangle_{0}=\frac{1}{N^{2}} \sum_{\boldsymbol{q}}\left\langle S(\boldsymbol{q})_{z} S(-\boldsymbol{q})_{z}\right\rangle_{0} \exp \left[i \boldsymbol{q} \cdot\left(\boldsymbol{R}_{i}-\boldsymbol{R}_{j}\right)\right] \tag{4.46}
\end{equation*}
$$

Since $\mathcal{M}_{\eta}(\boldsymbol{q})=-g \mu_{B} S_{\eta}(\boldsymbol{q})$, the fluctuation-dissipation theorem (1.88) gives

$$
\begin{equation*}
\left\langle S(\boldsymbol{q}, t)_{z} S(-\boldsymbol{q})_{z}\right\rangle_{0}=\int \frac{d \omega}{2 \pi} \frac{\hbar V}{g^{2} \mu_{B}^{2}} \operatorname{coth}(\beta \hbar \omega / 2) \chi_{z z}^{\prime \prime}(\boldsymbol{q} \omega) e^{-i \omega t} . \tag{4.47}
\end{equation*}
$$

Setting $t=0$ and assuming that $k_{B} T / \hbar$ is larger than any relevant frequencies (we shall discuss the validity of this assumption in Chap. 6), we find

$$
\begin{equation*}
\left\langle S(\boldsymbol{q})_{z} S(-\boldsymbol{q})_{z}\right\rangle_{0}=\frac{k_{B} T V}{\pi g^{2} \mu_{B}^{2}} \int \frac{\chi_{z z}^{\prime \prime}(\boldsymbol{q}, \omega)_{s}}{\omega} d \omega . \tag{4.48}
\end{equation*}
$$

By the Kramers-Kronig relation (1.64), the frequency integral is just $\pi$ times the static susceptibility $\chi_{z z}(\boldsymbol{q}, 0)$. Therefore we obtain

$$
\begin{equation*}
\left\langle S_{i}^{z} S_{j}^{z}\right\rangle_{0}=\frac{k_{B} T V}{N^{2} g^{2} \mu_{B}^{2}} \sum_{q} \chi_{z z}(\boldsymbol{q}) \exp \left[i \boldsymbol{q} \cdot\left(\boldsymbol{R}_{i}-\boldsymbol{R}_{j}\right)\right] \tag{4.49}
\end{equation*}
$$

Notice that since $\left\langle\left(S_{i}^{z}\right)^{2}\right\rangle=S(S+1) / 3$, (4.49) leads to what we refer to as a sum rule

$$
\begin{equation*}
\frac{1}{N} \sum_{\boldsymbol{q}} \chi(\boldsymbol{q})=\chi_{0} \tag{4.50}
\end{equation*}
$$

where $\chi_{0}$ was defined in (4.10).
If we use the random-phase result for $\chi_{z z}(\boldsymbol{q})$ (4.12) and assume a simple cubic lattice, then in the long-wavelength limit (4.49) becomes

$$
\begin{equation*}
\left\langle S_{i}^{z} S_{j}^{z}\right\rangle_{0}=\frac{6 S(S+1)}{3 N a^{2}} \frac{T}{T_{c}} \sum_{q} \frac{\exp \left[i \boldsymbol{q} \cdot\left(\boldsymbol{R}_{i}-\boldsymbol{R}_{j}\right)\right]}{\kappa^{2}+q^{2}} \tag{4.51}
\end{equation*}
$$

where

$$
\begin{equation*}
\kappa^{-1}=a \sqrt{\frac{T_{c}}{6\left(T-T_{c}\right)}} \tag{4.52}
\end{equation*}
$$

is referred to as the correlation length. Notice that as $T$ becomes very large in comparison with $T_{c}$, the correlation length becomes very small and

$$
\begin{equation*}
\left\langle S_{i}^{z} S_{j}^{z}\right\rangle_{0} \underset{T>T_{c}}{\longrightarrow} \frac{1}{3} S(S+1) \Delta\left(\boldsymbol{R}_{i}-\boldsymbol{R}_{j}\right) . \tag{4.53}
\end{equation*}
$$

As $T$ approaches $T_{c}$ the correlation function takes the so-called Yukawa-like form

$$
\begin{equation*}
\left\langle S_{i}^{z} S_{j}^{z}\right\rangle_{0}=\frac{S(S+1)}{16 \pi^{4}(N / V) a^{2}} \frac{T}{T_{c}} \frac{\exp \left(-\kappa\left|\boldsymbol{R}_{i}-\boldsymbol{R}_{j}\right|\right)}{\left|\boldsymbol{R}_{i}-\boldsymbol{R}_{j}\right|} . \tag{4.54}
\end{equation*}
$$



Fig. 4.13. The effect of various approximations on the susceptibility and the specific heat of a Heisenberg ferromagnet: (a) molecular field, (b) random phase, and (c) typical experimental behavior

Thus as $T$ approaches $T_{c}$ each spin exerts a polarizing influence on those spins within a sphere of radius $\kappa^{-1}$. At $T=T_{c}$ this sphere encompasses the whole sample, and we say that long-range order has set in.

The specific heat associated with this ordering may also be computed from (4.49). The behavior of the susceptibility and the specific heat in the mean-field and random phase approximations are compared schematically with typical experimental data in Fig. 4.13. The most notable discrepancy is the fact that the actual transition occurs below the value predicted by these theories. This is the consequence of an inadequate treatment of short-range order.

We can obtain a better approximation for $\chi(\boldsymbol{q})$ by explicitly taking shortrange order in account. The basic idea is that the spins surrounding any given spin will be correlated to the motion of that spin and will, therefore, not contribute to the mean field seen by that spin. This is incorporated into the theory by subtracting a term from the mean field which is proportional to $\left\langle S_{i}^{z}\right\rangle$ itself,

$$
\begin{equation*}
H_{i}^{\mathrm{eff}}=-\sum_{j} \frac{J_{i j}}{g \mu_{B}}\left\langle S_{j}^{z}\right\rangle+\sum_{j} \frac{\lambda_{i j} J_{i j}}{g \mu_{B}}\left\langle S_{i}^{z}\right\rangle . \tag{4.55}
\end{equation*}
$$

The parameters $\lambda_{i j}$ are assumed to be temperature dependent and characterize this so-called Onsager reaction field. Proceeding as in the derivation of (4.12) we obtain

$$
\begin{equation*}
\chi(\boldsymbol{q})=\frac{\chi_{0}}{1-\frac{\chi_{0} V}{g^{2} \mu_{B}^{2}}[J(\boldsymbol{q})-\lambda]}, \tag{4.56}
\end{equation*}
$$

where $\lambda=(1 / N) \sum_{j} \lambda_{i j} J_{i j}$. This parameter is obtained by requiring that the susceptibility (4.53) satisfies the sum rule (4.50). The result is

$$
\begin{equation*}
\lambda_{i j}=\frac{\left\langle S_{i}^{z} S_{j}^{z}\right\rangle_{0}}{S(S+1) / 3} \tag{4.57}
\end{equation*}
$$

Thus, (4.46) now becomes a self-consistent equation for the correlation function $\left\langle S_{i}^{z} S_{j}^{z}\right\rangle_{0}$.

This improved treatment of short-range order also renormalizes the transition temperature relative to the mean-field value $T_{c}$. If we sum (4.53) over $q$ and again use the sum rule we obtain the relation

$$
\begin{equation*}
G(S)=T_{c} / T \tag{4.58}
\end{equation*}
$$

where $S=T / T_{c}+\lambda / J(\boldsymbol{q})$ and the sum

$$
\begin{equation*}
G(S)=\frac{1}{N} \sum_{\boldsymbol{q}} \frac{1}{S-J(\boldsymbol{q}) / J(\boldsymbol{q})} \tag{4.59}
\end{equation*}
$$

is called the lattice Green's function. From (4.53) we see that $\chi(\boldsymbol{q})$ diverges at a temperature which corresponds to $S=1$. Therefore,

$$
\begin{equation*}
T_{c}^{*}=T_{c} / G(1) \tag{4.60}
\end{equation*}
$$

For simple cubic, body-centered-cubic, and face-centered-cubic lattices the values of $G(1)$ are $1.517,1.393$, and 1.345 , respectively. Thus we see that incorporating the Onsager reaction field predicts a lower transition temperature as we observed in Fig. 4.13.

Just below $T_{c}$ the quantity of thermodynamic interest is the spontaneous magnetization. As $T_{c}$ is approached from below, $\left\langle S_{i}^{z}\right\rangle_{0}$ becomes very small, which enables us to expand the Brillouin function in (4.41). The resulting magnetization in this molecular field approximation is found to vanish as $\left(T_{c}-T\right)^{1 / 2}$.

At very low temperatures the molecular field expression (4.41) predicts that the magnetization decreases with increasing temperature as $e^{-2 T_{c} /(S+1) T}$. The decrease is found experimentally to be much less rapid. The reason for this has to do with the existence of spin-wave modes, which we shall discuss in Chap. 8.

### 4.4 Landau Theory of Second-Order Transitions

This idea of treating the magnetization as an expansion parameter is a fundamental aspect of Landau's theory of second-order phase transitions. Landau associated second-order phase transitions with transitions in which there is a "broken symmetry". That is, the new ground state of the sytem does not possess the total symmetry of the Hamiltonian. In the case of ferromagnetism the rotational invariance of the Heisenberg Hamiltonian is broken by the appearance of the spontaneous magnetization $\boldsymbol{M}$. Landau identified the parameter whose value becomes nonzero in the unsymmetrical state as the order parameter. In this case it is obviously the magnetization. The order parameter represents an additional variable that must now be used to specify the state of the system. For the Heisenberg model the order parameter is a vector. We therefore speak of it having the dimensionality $n=3$. Since an Ising model involves only the $z$-component of the spin, the order parameter has the dimensionality $n=1$.

If the order parameter, call it $M$, is to grow from zero above $T_{c}$ to a finite value below $T_{c}$ then the Landau theory argues that near $T_{c}$ the free energy has the form

$$
\begin{equation*}
F=a\left(T-T_{c}\right) M^{2}+B M^{4} \tag{4.61}
\end{equation*}
$$

where $a$ and $B$ are constants. Minimizing this energy with respect to $M$ tells us that $M \sim\left(T_{c}-T\right)^{1 / 2}$ as we found above. If we add an applied field term, $-M H$, then it can be shown that the susceptibility diverges as $\chi \sim\left(T-T_{c}\right)^{-1}$. Similarly, if we assume that the magnetization varies slowly in space, then there will be an additional term in the free energy. Since it costs virtually no energy to rotate the magnetization uniformly, we expect that the energy associated with a gradual variation may be expressed in terms of derivatives of $\boldsymbol{M}$. In order to satisfy time reversal, this must be a quadratic expression. There are several such possibilities. In an isotropic medium, for example, there are three: $|\nabla \boldsymbol{M}|^{2}=\left|\nabla M_{x}\right|^{2}+\left|\nabla M_{y}\right|^{2}+\left|\nabla M_{z}\right|^{2},(\nabla \cdot \boldsymbol{M})^{2}$, and $|\nabla \times \boldsymbol{M}|^{2}$. If we assume that all those terms reflecting the spatial symmetry are taken into account through an anisotropy energy, then the exchange energy must be invariant with respect to rotations in spin space. For example, a rotation of $\pi$ about the $z$-axis in spin space takes $M_{x} \rightarrow-M_{x}$ and $M_{y} \rightarrow-M_{y}$, but leaves $x$ and $y$ unchanged. Thus, the exchange energy in a cubic crystal must have the form

$$
\begin{equation*}
\frac{\delta E}{V}=\frac{A}{M_{0}^{2}}|\nabla \boldsymbol{M}|^{2}, \tag{4.62}
\end{equation*}
$$

where $A$ is referred to as the exchange stiffness. This contribution introduces a characteristic length, the correlation length, which varies as $\xi \sim\left(T_{c}-T\right)^{-1 / 2}$, as we have already found. These critical exponents,

$$
\begin{aligned}
& \beta=\frac{1}{2} \quad \text { for the magnetization, } \\
& \lambda=1 \quad \text { for the susceptibility, and } \\
& \eta=\frac{1}{2} \quad \text { for the correlation length, }
\end{aligned}
$$

do not agree with those observed experimentally. This is not too surprising for the theory itself predicts that as $T \rightarrow T_{c}$ fluctuations in the order parameter become larger than the order parameter itself. Careful measurements of these and other critical exponents in the 1960s stimulated much theoretical activity. It was particularly intriguing that particular critical exponents in different systems seemed to have nearly the same values. Furthermore, certain combinations of exponents seemed to be related.

### 4.5 Critical Phenomena

The first major assault on this problem was Widom's hypothesis that the critical part of free energy, $G$, was a homogeneous function of its independent variables. We say that a function $G(\epsilon, H)$ is homogeneous if it can be written in the form

$$
\begin{equation*}
G\left(\lambda^{x} \varepsilon, \lambda^{y} H\right)=\lambda G(\varepsilon, H), \tag{4.63}
\end{equation*}
$$

where $\epsilon=\left(T-T_{c}\right) / T_{c}, x$ and $y$ are two critical indices, and $\lambda$ was subsequently shown by Kadanoff to correspond to a scaling length. With this "scaling" hypothesis all the critical exponents now become combinations of $x$ and $y$. In 1971 K . Wilson introduced the renormalization group which clarified the nonanalytic nature of the phase transition and provided the basis for scaling. Various methods have been developed for performing renormalization-group calculations for the critical exponents themselves. Such calculations show that the critical exponents are only functions of the dimensionality of space and the dimensionality of the order parameter, a situation referred to as universality (see [87]).

It is difficult to make accurate comparisons with experiment. First of all, impurities and strains tend to smear out the transition, making it difficult to measure close to the transition. And also, weak anisotropies become important near the transition and can lead to "crossover" from one universality class to another. These difficulties are illustrated in Fig. 4.14, where we have plotted the critical exponent $\beta$ for four representative materials among the constant $\beta$ contours in the $n, d$-plane obtained from a renormalization-group calculation [88]. Dysprosium aluminum garnet (DAG) is considered to be a three-dimensional Ising system, $\mathrm{K}_{2} \mathrm{NiF}_{4}$ a two-dimensional Heisenberg system, and $\mathrm{GdCl}_{3}$ a three-dimensional Heisenberg system but one in which long-range dipolar interactions are important.

Table 4.1. The critical exponent $\beta$ for selected materials

| Material | $\beta$ | $\frac{T_{c}-T}{T_{c}}$ | Refs. |
| :--- | :---: | :---: | :---: |
| $\mathrm{GdCl}_{3}$ | $\beta=0.43$ | $0.002 \leq \epsilon \leq 0.07$ | $[90]$ |
| DAG | $\beta=0.26$ | $0.001 \leq \epsilon \leq-.056$ | $[91]$ |
| $\mathrm{K}_{2} \mathrm{NiF}_{4}$ | $\beta=0.138$ | $0.0003 \leq \epsilon \leq 0.2$ | $[92]$ |
| $\mathrm{MnF}_{2}$ | $\beta=0.333$ | $0.00006 \leq \epsilon \leq 0.08$ | $[93]$ |

### 4.5.1 Order in 2D

Notice that the theoretical curves shown in Fig. 4.14 do not extend to $d=2$. In two dimensions, the nature of the long-range order depends critically on the dimensionality of the order parameter. Mermin and Wagner [89] have shown that two-dimensional systems with a continuous suymmetry, such as a Heisenberg system, will not exhibit conventional long-range order as characterized, for example, by a spontaneous magnetization or a sublattice magnetization.

A good example of 2-dimensional behavior is found in the undoped hightemperature superconductor $\mathrm{La}_{2} \mathrm{CuO}_{4}$ [94]. This compound has the layered perovskite structure shown in Fig. 4.15. Since La has the oxidation state +3 and oxygen is -2 , this suggests that the copper is in a +2 oxidation state corresponding to a $3 \mathrm{~d}^{9}$ electronic configuration. With one hole per copper atom one would expect $\mathrm{La}_{2} \mathrm{CuO}_{4}$ to be a metal. However, it is an antiferromagnetic insulator. This is presumably the result of electron-electron correlations as originally suggested by Mott.


Fig. 4.14. Variation of the critical exponent $\beta$ (associated with the magnetization) with the dimensionality of space (d) and order parameter ( $n$ ). The experimental values for several materials are indicated (see Table 4.1 for references)


Fig. 4.15. Layered perovskite structure (Figure to right shows spin configuration of $\mathrm{La}_{2} \mathrm{CuO}_{4}$ )

The spin $1 / 2$ holes in the copper layers describe a spin $1 / 2$ 2D square lattice quantum Heisenberg system. Chakravarty et al. [95] have shown that the correlation length of such a system varies as

$$
\frac{\xi}{a}=0.493 e^{1.15 J / k_{B} T}
$$

which implies that ordering only occurs at $T=0 \mathrm{~K}$. The fact that $\mathrm{La}_{2} \mathrm{CuO}_{4}$ has a relatively high Neél temperature at $T_{N}=325 \mathrm{~K}$ is due to anisotropy in the exchange as well as interlayer exchange. The Hamiltonian for $\mathrm{La}_{2} \mathrm{CuO}_{4}$ has been found [94] to have the form

$$
\begin{aligned}
=\mathcal{H}= & J\left[\sum_{i, \boldsymbol{\delta}_{\|}} S_{i} \cdot S_{i+\boldsymbol{\delta}_{\|}}+\alpha_{x y} \sum_{i, \boldsymbol{\delta}_{\|}} S_{i}^{c} S_{i+\delta_{\|}}^{c}\right. \\
& \left.+\sum_{i, \delta_{\perp j}} \alpha_{\perp j} S_{i} \cdot S_{i+\delta_{\perp j}}+\alpha_{D M} \sum_{i, \boldsymbol{\delta}_{\|}}(-1)^{i} \hat{\boldsymbol{b}} \cdot S_{i} \times S_{i+\boldsymbol{\delta}_{\|}}\right]
\end{aligned}
$$

where $\alpha_{x y}, \alpha_{\perp j}$, and $\alpha_{D M}$ represent the $x-y$ anisotropy, the interlayer coupling, and the Dzyaloshinski-Moriya interaction, respectively. The index $j$ refers to the two different out-of-plane neighbors, and the notation " $c$ " indicates the component of the spin in the $c$-direction. Including the anisotropy term and the interlayer term, the Neél temperature is given by

$$
k_{B} T_{N}=\left(\frac{\xi}{a}\right)^{2} J\left(z_{\|} \alpha_{x y}+z_{\perp} \alpha_{\perp}\right)
$$

where $z_{\|}$and $z_{\perp}$ are the in-plane and out-of-plane coordination numbers, respectively. The magnetic order is shown in the insert in Fig. 4.15. The


Fig. 4.16. Phase diagram for $\mathrm{La}_{2-x} \mathrm{Sr}_{x} \mathrm{CuO}_{4}$ summarizing structural, magnetic, and transport properties. The narrow dashed line $(d R / d T=0)$ separates the region of metallic linear resistance from that of logarithmically increasing resistance. The conductance in the Néel state is strongly localized. From Keimer, Belk et al. [96]

Dzyaloshinski-Moriya term causes the spins to cant out of the plane by about $0.17^{\circ}$. The interlayer coupling in turn causes these small moments to orient ferromagnetically from layer to layer.

When $\mathrm{La}_{2} \mathrm{CuO}_{4}$ is doped with Sr or Ba one obtains many different phases, including the phase exhibiting superconductivity. The phase diagram is shown in Fig. 4.16. Notice the precipitous drop in the Neel temperature with Sr doping. This is due to the fact that the Sr doping introduces holes in the oxygen which reduces the superexchange.

The Mermin-Wagner Theorem mentioned above does not exclude the possibility of a phase transition associated with more complex spin dynamics. The two-dimensional $X Y$ model is the classic example. Berezinskii [97] has calculated the spin-spin correlation function $\left\langle S_{i} S_{j}\right\rangle$ for this model using a low-temperature expansion, and found a power-law behavior

$$
\left\langle S_{i} S_{j}\right\rangle \sim\left(\frac{\left|R_{i}-R_{j}\right|}{R_{0}}\right)^{-k_{B} T / 4 \pi J} .
$$



Fig. 4.17. Spin Vortex

This implies that the susceptibility is infinite, i.e., that the system is undergoing large fluctuations which destroy any long-range order. Kosterlitz and Thouless [98], however, have pointed out that, in addition to the longwavelength spin fluctuations responsible for this power-law behavior, there also exist local "topological defects" in the order parameters which, in this case, correspond to vortices as illustrated in Fig. 4.17. Other examples of "defects" in order parameters include dislocations in crystalling solids and vortices in superfluid helium. To calculate the energy of an isolated vortex, we write the $X Y$ Hamiltonian as

$$
\begin{equation*}
\mathcal{H}_{X Y}=-2 J \sum_{i>j}\left(S_{i}^{x} S_{j}^{x}+S_{i}^{y} S_{j}^{y}\right)=-2 J \sum_{i>j} \cos \left(\varphi_{i}-\varphi_{j}\right), \tag{4.64}
\end{equation*}
$$

where $\varphi_{i}$ is the angle the $i$ th spin makes with some arbitrary axis. Expanding the cosine,

$$
\begin{equation*}
E-E_{o} \approx J \sum_{r}[\Delta \varphi(r)]^{2}, \tag{4.65}
\end{equation*}
$$

where $\Delta$ denotes the first difference operator. For a vortex as shown in Fig. 4.17, $\Delta \varphi(r)=2 \pi / 2 \pi r$. Therefore,

$$
\begin{equation*}
E-E_{0}=2 \pi J \ln (R / a), \tag{4.66}
\end{equation*}
$$

where $R$ is the radius of the system and $a$ the nearest-neighbor distance. Since this vortex could be centered on any one of the $\pi R^{2} / a^{2}$ sites, the entropy is

$$
\begin{equation*}
S=2 k_{B} \ln (R / a) . \tag{4.67}
\end{equation*}
$$

The free energy is $E-E_{0}-T S$. Since both the energy and entropy depend upon the size of the system in the same logarithmic way, the energy term will dominate the free energy at low temperatures, and the probability of a vortex appearing is vanishingly small. However, when the temperature exceeds $\pi J / k_{B}$, the entropy dominates and free vortices are likely to appear. If one now includes interactions between vortices, the critical temperature is given by the solution of [98]

$$
\begin{equation*}
\frac{\pi J}{k_{B} T_{K T}}-1=2 \pi \exp \left(-\pi^{2} J / k_{B} T_{K T}\right) . \tag{4.68}
\end{equation*}
$$

Below the Kosterlitz-Thouless temperature, $T_{K T}$, the vortices are bound in pairs of zero total vorticity. This is referred to as topological long-range order. The spin-spin correlation function still has a power-law behavior indicating an infinite susceptibility. However, above $T_{K T}$, the vortices give the correlation function an exponential form with a susceptibility given by

$$
\begin{equation*}
\chi(T) \sim \exp \left(2.625 t^{-1 / 2}\right) \tag{4.69}
\end{equation*}
$$

where $t=\left(T-T_{K T}\right) / T_{K T}$.

### 4.6 Stoner-Wohlfarth Model

The usefulness of magnetic materials generally depends upon the existence of a net magnetization at room temperature. That is, magnetic materials of practical interest are either ferromagnets or ferrimagnets with Curie temperatures above room temperature. Their electrical conductivity ranges from metallic to insulating.

The susceptibilities given by (4.17) or (4.33) are the "small signal" responses of these systems. If one applies a large enough field opposite to the direction of the magnetization it is possible to reverse the magnetization. As one cycles the magnetic field, positive and negative, the magnetization follows a "hysteresis loop" as shown in Fig. 4.18.

The shapes of hysteresis loops depend upon many extrinsic factors such as crystallographic microstructure and the role of magnetic domains. The magnetic response characterized by a hyperesis loop is refered to as the "technical" magnetization. This subject is beyond the scope of this text. However, there is a very simple model that provides a connection between the hysteresis loop and our microscopic concepts.

This model, due to Stoner and Wohlfarth [99], considers the response of an array of noninteracting magnetic particles. Let us assume these particles are ellipsoidal in shape and are uniformly magnetized as shown in Fig. 4.19. To determine the direction of the magnetization in the presence of an applied field, $\mathrm{H}_{0}$, we must minimize the energy of the system. Let us consider a single particle. In addition to the Zeeman energy density, $\boldsymbol{-} \boldsymbol{M} \cdot \boldsymbol{H}_{0}$, there is a magnetostatic energy density associated with the magnetization itself given by $-\frac{1}{2} \boldsymbol{M} \cdot \boldsymbol{H}_{D}$, where $\boldsymbol{H}_{D}$ is the "demagnetization" field. To solve for $\boldsymbol{H}_{D}$ we combine the Maxwell equation $\nabla \cdot \boldsymbol{B}=0$ with the definition $\boldsymbol{B}=\boldsymbol{H}+4 \pi \boldsymbol{M}$ to obtain

$$
\begin{equation*}
\nabla \cdot \boldsymbol{H}_{D}=-4 \pi \nabla \cdot \boldsymbol{M} \tag{4.70}
\end{equation*}
$$

Since there are no "free" currents in this problem, $\nabla \times \boldsymbol{H}_{D}=0$. Therefore $\boldsymbol{H}_{D}$ may be expressed in terms of a magnetic scalar potential, $\varphi$, as $\boldsymbol{H}_{D}=-\nabla \varphi$. Therefore (4.70) becomes


Fig. 4.18. Typical "hysteresis loop" of a ferromagnet


Fig. 4.19. Coordinate system used to describe an ellipsoidal particle

$$
\begin{equation*}
\nabla^{2} \varphi=4 \pi \nabla \cdot M \tag{4.71}
\end{equation*}
$$

This has the solution

$$
\begin{equation*}
H_{D}(\boldsymbol{r})=-\int \frac{\nabla^{\prime} \cdot \boldsymbol{M}^{\prime}\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}\right)}{\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|^{3}} d^{3} \boldsymbol{r}^{\prime} \tag{4.72}
\end{equation*}
$$

If the magnetization is assumed to remain uniform, $\nabla \cdot \boldsymbol{M}$ is nonzero only at the surface of the particle. This "magnetic charge" produces a "demagnetization" field inside given by

$$
\begin{equation*}
\boldsymbol{H}_{D}=-\underset{\sim}{\boldsymbol{N}} \cdot \boldsymbol{M}, \tag{4.73}
\end{equation*}
$$

where

$$
\underset{\sim}{\boldsymbol{N}}=\left(\begin{array}{ccc}
N_{a} & 0 & 0  \tag{4.74}\\
0 & N_{b} & 0 \\
0 & 0 & N_{c}
\end{array}\right)
$$



Fig. 4.20. Hysteresis loop for fields parallel (a) and perpendicular (b) to the axis of an ellipsoidal particle

It can be shown that the demagnetization factors $N_{i}$ satisfy

$$
\begin{equation*}
\sum_{i=1}^{3} N_{i}=4 \pi \tag{4.75}
\end{equation*}
$$

The fact that the demagnetization field is uniform inside the particle is due to its ellipsoidal shape. The demagnetization field inside a uniformly magnetized bar, for example, is not uniform.

Since the particle has axial symmetry we may assume that the magnetization and the applied field lie in the $a-b$-plane. If the magnetization makes an angle $\theta$ with the $b$-axis then the total energy density of the system is

$$
\begin{align*}
\mathcal{E} & =-\boldsymbol{M} \cdot \boldsymbol{H}_{0}-\frac{1}{2} \boldsymbol{M} \cdot \boldsymbol{H}_{D}  \tag{4.76}\\
& =-M H_{a} \sin \theta-M H_{b} \cos \theta+\frac{1}{2}\left(N_{a}-N_{b}\right) M^{2} \sin ^{2} \theta+\frac{1}{2} N_{b} M^{2} .
\end{align*}
$$

In the absence of the applied field the direction of $\boldsymbol{M}$ depends upon the demagnetization factors. Let us assume $N_{a}>N_{b}$. The magnetization will then point along the $b$-direction. Suppose we now apply a field along the $b$-direction opposite to $\boldsymbol{M}$. The energy density is then given by (ignoring the constant term)

$$
\begin{equation*}
\mathcal{E}=M\left|H_{b}\right| \cos \theta+\frac{1}{2}\left(N_{a}-N_{b}\right) M^{2} \sin ^{2} \theta . \tag{4.77}
\end{equation*}
$$

For small $H_{b}$ this energy density has minima at $\theta=0$ and $\theta=\pi$. When $H_{b}$ exceeds $H_{K} \equiv 2 K_{u} / M$, where $K_{u} \equiv \frac{1}{2}\left(N_{a}-N_{b}\right) M^{2}$, the minimum at $\theta=0$ vanishes leaving only the minimum at $\theta=\pi$. At this point $\boldsymbol{M}$ switches to the negative $b$-direction (Fig. 4.20a).

If the field is applied along the $a$-direction then the energy density becomes

$$
\begin{equation*}
\mathcal{E}=-M H_{a} \sin \theta+\frac{1}{2}\left(N_{a}-N_{b}\right) M^{2} \sin ^{2} \theta . \tag{4.78}
\end{equation*}
$$

In this case the minimum shifts continuously from $\theta=0$ to $\theta=\pi / 2$ and the magnetization rotates smoothly into the $a$-direction (Fig. 4.20b).

If we now assume that we have an array of identical particles, but that they are randomly oriented with respect to the applied field, and if we neglect the dipolar fields among the particles, then Stoner and Wohlfarth [99] showed that the magnetization of the array has a form similar to Fig. 4.18 with a coercivity $H_{c}=H_{K} / 2$ and a remanence $M_{r}=M / 2$. In this case the coercivity is governed by the shape anisotropy of the particles. If the particles also possess crystalline anisotropy arising from the spin-orbit interaction described in Sect. 2.3.1, this energy must be added to (4.74). Cobalt, for example, has an electronic structure that generally produces a large crystalling anisotropy. Consequently, one often finds cobalt as the main constituent in high coercivity materials.

Coercitivities can range from a fraction of an oersted, such as in permalloy, an alloy of iron and nickel, to tens of thousands of oersteds, as in transition metal-rare earth alloys. Materials having low coercivities are referred to as magnetically "soft", while those with large coercivities are "hard".

### 4.7 Dynamic Coercivity

Let us now consider the consequences of incorporating temperature in the Stoner-Wohlfarth model. Suppose we start in the fully saturated state and suddenly reverse the applied field to the point A on the hysteresis loop shown below. The sum of the anisotropy energy and the Zeeman energy as a function

of the angle the magnetization makes with the easy axis is shown in Fig. 4.21. Until $H$ reaches $-H_{K}$ there is still a local energy minimum at $\theta=0$. The energy difference between this minimum and the maximum between $\theta=0$ and $\theta=\pi$ is

$$
\begin{equation*}
\Delta E=K_{u} V\left(1-H / H_{K}\right)^{2}, \tag{4.79}
\end{equation*}
$$



Fig. 4.21. Energy of a magnetic particle as a function of the direction that an applied field makes with the axis of the particle


Fig. 4.22. Phonon-assisted magnetization reversal
where $V$ is the "switching volume" which might be a magnetic particle or a grain in a film or just a semi-isolated spin cluster. If temperature is included then there is a probability that this volume may be excited over the barrier into the local minimum at $\theta=\pi$. Physically this reversal occurs through coupling between the spins of the magnetic system and the thermal vibrations of the lattice. As the lattice vibrates it modulates the exchange (exchangestriction) and the magnetostatic energy (magnetostriction). To lowest order these coupling energies are proportional to the amplitude of the lattice displacement, $\Delta x$. The displacement $\Delta x$ may be expanded in terms of quantized lattice vibration, or phonon, amplitudes $b_{q}, b_{q}^{\dagger}$. The coupling energy then has the form $g S_{\mu} S_{\nu}\left(b_{q}+b_{q}^{\dagger}\right)$ where $g$ characterizes the strength of the coupling. Second order perturbation theory gives the rate at which a phonon is absorbed by the magnetic system, exciting it to an energy $\Delta E$, and then reemitting a phonon and dropping into the lower minimum as illustrated in Fig. 4.22,

$$
\begin{equation*}
\frac{1}{\tau}=\frac{2 \pi}{\hbar^{2}} \sum_{\boldsymbol{q}, \boldsymbol{q}^{\prime}}|g|^{2} n_{\boldsymbol{q}}\left(n_{\boldsymbol{q}}+1\right) \delta\left(\Delta E-\hbar \omega_{q}\right), \tag{4.80}
\end{equation*}
$$



Fig. 4.23. Dynamic coercivity as a function of the time taken to do the measurement. The very short times are measurements taken with a pulsed field. The cluster of longer times are magnetometer measurements [101]
where

$$
\begin{equation*}
n_{q}=\left\langle b_{q}^{\dagger} b_{q}\right\rangle=\frac{1}{e^{\hbar \omega q / k_{B} T}-1} \tag{4.81}
\end{equation*}
$$

Since $\hbar \omega_{q}=\Delta E$ which is, in general, larger than $k_{B} T$,

$$
\begin{equation*}
\frac{1}{\tau}=f_{0} e^{-\Delta E / k_{B} T} \tag{4.82}
\end{equation*}
$$

$f_{0}$ is often referred to as an "attempt" frequency. In this model it is proportional to the spin-phonon coupling. This process corresponds to "thermally assisted" reversal of the magnetization, or superparamagnetism.

Equation (4.82) implies that the probability that a cluster of spins reverses by hopping over the barrier is $1-e^{-t / \tau}$. Then the magnetization will reverse according to

$$
\begin{equation*}
M(t)=M_{s}\left(2 e^{-t / \tau}-1\right) \tag{4.83}
\end{equation*}
$$

The magnetization will pass through zero at a time $t_{0}=-\left(\ln \frac{1}{2}\right) \tau$. If we define the field at which this occurs as the coercivity $H_{c}\left(t_{0}\right)$, then

$$
\begin{equation*}
H_{c}\left(t_{o}\right)=H_{K}\left[1-\frac{k_{B} T}{K_{u} V} \ln \left(\frac{f_{0} t_{0}}{0.693}\right)\right] \tag{4.84}
\end{equation*}
$$

where $t_{0}$ is identified as the "measurement time". Thus, (4.85) says that the coercivity depends upon the measurement time. Equation (4.85) is called Sharrock's law after M. Sharrock who applied it to particulate media [100]. The coercivity is plotted as a function of the measurement time in Fig. 4.23. The dashed line is (4.85). We see that this does not describe the data at very short times. We shall see what is happening at short times in Chap. 6.

### 4.8 Magnetic Viscosity

Since the barrier discussed in the previous section is proportional to the volume of the spin cluster, we expect, in general, to have a distribution of barrier heights. Let us define $N(E)$ as the density of spin clusters with barrier height $E$. As a result of thermal activation the rate of change of the number of clusters, $N(E) d E$, with barriers between $E$ and $E+d E$, is given by

$$
\begin{equation*}
\frac{d}{d t} N(E) d E=-f_{0} e^{-E / k_{B} T} N(E) d E . \tag{4.85}
\end{equation*}
$$

This has the solution

$$
\begin{equation*}
N(E)=N_{0}(E) e^{-t f_{0} \exp \left(-E / k_{B} T\right)}, \tag{4.86}
\end{equation*}
$$

where $N_{0}(E)$ is the initial density distribution. Suppose, for example, that the initial distribution has a square shape with the value $N_{0}$ up to $E_{\max }$, i.e.,

$$
N_{0}(E)=N_{0}, \quad 0 \leq E \leq E_{\max }
$$

As time evolves after application of a reversing field those clusters with small barriers will reverse, depleting the low energy end of the distribution as shown in Fig. 4.24. The reverse magnetization is given by the area of this "hole". Since this is an exponential process the curve will sweep out equal areas in equal logarithmic increases in time. That is, the two shaded areas in the figure are the same. This means that the magnetization decays logarithmically with time,

$$
\begin{equation*}
M(t)=M(0)-S \ln t . \tag{4.87}
\end{equation*}
$$

The coefficient $S$ is known as the viscosity parameter [102].
Since the thermal fluctuations lead to a change in the magnetization characterized by the viscosity $S$, one may describe this by an effective fluctuation field $H_{f}$ which is related to $S$ by an "irreversible" susceptibility,

$$
S=\chi_{\mathrm{irr}} H_{f}
$$



Fig. 4.24. Distribution of barrier heights for different times after a reversal field has been applied


Fig. 4.25. Remanence curves for $\mathrm{CrO}_{2}$ with data for different values of pulse length shown on an expanded scale [103]

This susceptibility may be obtained from the reverse remanence curve. That is, we initially saturate the sample and then apply a reverse field for some time $\tau$. At the end of this time the remanent moment is measured enabling us to construct a remanence curve as shown in Fig. 4.25. The irreversible susceptibility $\chi_{\text {irr }}$ is defined as the maximum slope, which occurs at the remanent coercivity.

## Problems

4.1. Consider an impurity spin $S^{\prime}$ which couples to its nearest neighbors through an exchange interaction $J^{\prime}$. In the molecular field approximationg this impurity represents an effective field $H_{\text {eff }}^{z}=2\left(J^{\prime} S^{\prime}-J S\right) / g \mu_{B}$. Using the concept of the generalized susceptibility calculate the moment induced around the impurity as the temperature approaches $T_{c}$ from above.
4.2. Add an anisotropy energy of the form $-D \sum_{i}\left(S_{i}^{z}\right)^{2}$ to a ferromagnet and
(a) determine how this affects $T_{c}$;
(b) calculate $\chi_{\perp}(0)$.
4.3. Entropy is given by the temperature derivative of the free energy, $S=-\partial F / \partial T$.
(a) How does the entropy vary below the transition according to Landau Theory.
(b) What does Landau Theory predict for the specific heat at $T_{c}$.
4.4. Differentiate (4.63) with respect to $H$ and use the definition

$$
\partial G(\epsilon, H) / \partial H=-M
$$

to derive a relation between $x, y$, and $\beta$, where $\beta$ is defined by $M(\epsilon, 0) \sim$ $(-\epsilon)^{\beta}$. Similarly, derive a relation between $x, y$, and $\delta$, where $\delta$ is defined by $M(0, H) \sim H^{1 / \delta}$. Now differentiate twice with respect to $H$ and use the definition of the isothermal susceptibility, $\chi_{T}=-\left(\partial^{2} G / \partial H^{2}\right)_{T}$ and, $\chi_{T}(\epsilon, 0) \sim(-\epsilon)^{-\gamma^{\prime}}$ to derive a relation between $\gamma^{\prime}, \beta$, and $\delta$. This is know as the Widom equality.
4.5. Compute $\chi_{\perp}(0)$ for the Stoner-Wohlfarth model and thereby obtain a relationship between the microscopic anisotropy constant, $D$ in Problem 4.2, and the macroscopic anisotropy constant, $K_{1}$.

# The Static Susceptibility of Interacting Systems: Metals 

The long-range magnetic order in metals is very similar to that observed in insulators as illustrated by the magnetization curve of nickel shown in Fig. 5.1. However, the electrons participating in this magnetic state are itinerant as determined by the existence of a Fermi surface; that is, they also have translational degrees of freedom. How such a system of interacting electrons responds to a magnetic field is a many-body problem with all its attendant difficulties.

The many-body corrections to the Landau susceptibility and the Pauli susceptibility must be treated separately. Kanazawa and Matsudaira [104] found that the many-body corrections to the Landau susceptibility are small (less than one per cent) for high electron densities.

We shall approach the effect of electron-electron interactions on the spin susceptibility in two ways. The first, Fermi liquid theory, is a phenomenological approach. It involves parameters completely analogous to the parameters entering the spin Hamiltonian. These parameters may be determined experimentally or they may be obtained from the second approach which is to assume a specific microscopic model from which various physical properties can be calculated.

### 5.1 Fermi Liquid Theory

The phenomenological theory of an interacting fermion system was developed by Landau in 1956 [106]. Although Landau was mainly interested in the properties of liquid $\mathrm{He}^{3}$, his theory may also be applied to metals. Modifications of this theory in terms of the introduction of a magnetic field have been made by Silin [107].

Let us begin by considering the ground state of a system of $N$ electrons. For a noninteracting system the ground state corresponds to a well-defined Fermi sphere. Landau assumed that as the interaction between the electrons is gradually "turned on" the new ground state evolves smoothly out of the


Fig. 5.1. Magnetization of nickel as a function of temperature. The original data of Weiss and Forrer [105] taken at constant pressure has been corrected to constant volume to eliminate the effects of thermal expansion
original Fermi sphere; if $|0\rangle$ is this new ground state, it is related to the original Fermi sphere $|F S\rangle$ by a unitary transformation,

$$
\begin{equation*}
|0\rangle=U|F S\rangle . \tag{5.1}
\end{equation*}
$$

Let us denote the energy associated with $|0\rangle$ as $E_{0}$.
Landau also applied this assumption to the excitations of the interacting system. For example, suppose we add one electron, with momentum $\hbar \boldsymbol{k}$, to the non-interacting system. This state has the form $a_{\boldsymbol{k} \sigma}^{\dagger}|F S\rangle$, where $a_{\boldsymbol{k} \sigma}^{\dagger}$ is the creation operator for an electron. If the interactions are gradually turned on, let us approximate the new state as

$$
\begin{equation*}
|\boldsymbol{k} \sigma\rangle=U a_{\boldsymbol{k} \sigma}^{\dagger}|F S\rangle \tag{5.2}
\end{equation*}
$$

Because the electron possesses spin, this wave function is a spinor.
Let us define the difference between the energy of $|\boldsymbol{k} \sigma\rangle$ and $|0\rangle$ as $\epsilon^{0}(\boldsymbol{k}, \boldsymbol{\sigma})$. Since the wave function is a spinor, this energy will be a $2 \times 2$ matrix. If the system is isotropic, and in particular if there is no external magnetic field, then this energy is independent of the spin,

$$
\epsilon^{0}(\boldsymbol{k}, \boldsymbol{\sigma})_{\alpha \beta}=\epsilon^{0}(\boldsymbol{k}) \delta_{\alpha \beta} .
$$

Because the whole Fermi sphere has readjusted itself as a result of the interactions, the energy $\epsilon^{0}(\boldsymbol{k})$ will be quite different from the energy of a free particle. As we do not know this energy, we shall assume that $\boldsymbol{k}$ is close to $k_{F}$ and expand in powers of $k-k_{F}$. Thus we obtain

$$
\begin{equation*}
\epsilon^{0}(\boldsymbol{k})=\mu+\frac{\hbar^{2} k_{F}}{m^{*}}\left(k-k_{F}\right)+\ldots, \tag{5.3}
\end{equation*}
$$

where

$$
\begin{equation*}
\left.\frac{\hbar^{2} k_{F}}{m^{*}} \equiv \frac{\partial \epsilon^{0}(\boldsymbol{k})}{\partial k}\right|_{k=k_{F}} \tag{5.4}
\end{equation*}
$$

This electron, "dressed" by all the other electrons, is called a quasiparticle. Notice that the energy required to create a quasiparticle at the Fermi surface is $\mu$, the chemical potential. Its increase in energy as it moves away from the Fermi surface is characterized by its effective mass $m^{*}$. We restrict ourselves to the region close to the Fermi surface because it is only in this region that quasiparticle lifetimes are long enough to make their description meaningful.

We could just as well have removed an electron from some point within the Fermi sphere. This would have created a "hole", which the interactions would convert into a quasi-hole. The energy associated with a hole is the energy required to remove an electron at the Fermi surface, $-\mu$, plus the energy it takes to move the electron at $\boldsymbol{k}$ up to the surface, $\left(\hbar^{2} k_{F} / m^{*}\right)\left(k_{F}-k\right)$. However, if we define the total energy of the system containing a quasi-hole as $E_{0}-\epsilon^{0}(\boldsymbol{k})$, then

$$
\epsilon^{0}(\boldsymbol{k})=\mu+\frac{\hbar^{2} k_{F}}{m^{*}}\left|k-k_{F}\right|
$$

Thus the excitation spectrum associated with our Fermi liquid has the form shown in Fig. 5.2.

Suppose that other quasiparticles are now introduced into the system. This could occur, for example, as a result of an external field producing electronhole pairs. Since the energy of a quasiparticle depends on the distribution of all the other quasiparticles, any change in distribution will lead to a change in the quasiparticle energy. Let us denote the change in the distribution by $\delta n(\boldsymbol{k}, \boldsymbol{\sigma})$.

The quasiparticle distribution is essentially the density matrix associated with the quasiparticle. In particular, it is a $2 \times 2$ matrix. For example, $\delta n(\boldsymbol{k}, \boldsymbol{\sigma})_{11}$ gives the probability of finding an electron of momentum $\hbar \boldsymbol{k}$ with


Fig. 5.2. Single-particle excitation spectrum of a Fermi liquid
spin up. Therefore the quasiparticle energy may be written in phenomenological terms as

$$
\begin{equation*}
\epsilon(\boldsymbol{k}, \boldsymbol{\sigma})=\epsilon^{0}(\boldsymbol{k}, \boldsymbol{\sigma})+\frac{1}{V} \operatorname{Tr}_{\sigma^{\prime}}\left\{\sum_{\boldsymbol{k}^{\prime}} f\left(\boldsymbol{k}, \boldsymbol{\sigma} ; \boldsymbol{k}^{\prime}, \boldsymbol{\sigma}^{\prime}\right) \delta n\left(\boldsymbol{k}^{\prime}, \boldsymbol{\sigma}^{\prime}\right)\right\} . \tag{5.5}
\end{equation*}
$$

The quantity $f\left(\boldsymbol{k}, \boldsymbol{\sigma} ; \boldsymbol{k}^{\prime}, \boldsymbol{\sigma}^{\prime}\right)$ is a product of $2 \times 2$ matrices analogous to a dyadic vector product. Again, if the system is isotropic, the most general form this quantity can have is

$$
\begin{equation*}
f\left(\boldsymbol{k}, \boldsymbol{\sigma} ; \boldsymbol{k}^{\prime}, \boldsymbol{\sigma}^{\prime}\right)=\varphi\left(\boldsymbol{k}, \boldsymbol{k}^{\prime}\right) \mathbf{1 1 ^ { \prime }}+\psi\left(\boldsymbol{k}, \boldsymbol{k}^{\prime}\right) \boldsymbol{\sigma} \cdot \boldsymbol{\sigma}^{\prime} \tag{5.6}
\end{equation*}
$$

where 1 is the $2 \times 2$ unit matrix. Furthermore, since this theory is valid only near the Fermi surface, we may take $\left|\boldsymbol{k}^{\prime}\right| \simeq|\boldsymbol{k}|=k_{F}$. Then $\varphi$ and $\psi$ depend only upon the angle $\theta$ between $\boldsymbol{k}^{\prime}$ and $\boldsymbol{k}$, and we may expand $\varphi$ and $\psi$ in Legendre polynomials:

$$
\begin{align*}
& \varphi\left(\boldsymbol{k}, \boldsymbol{k}^{\prime}\right)=\frac{\pi^{2} \hbar^{2}}{m^{*} k_{F}} A\left(\hat{\boldsymbol{k}} \cdot \hat{\boldsymbol{k}}^{\prime}\right)=\frac{\pi^{2} \hbar^{2}}{m^{*} k_{F}}\left[A_{0}+A_{1} P_{1}(\cos \theta)+\ldots\right]  \tag{5.7}\\
& \psi\left(\boldsymbol{k}, \boldsymbol{k}^{\prime}\right)=\frac{\pi^{2} \hbar^{2}}{m^{*} k_{F}} B\left(\hat{\boldsymbol{k}} \cdot \hat{\boldsymbol{k}}^{\prime}\right)=\frac{\pi^{2} \hbar^{2}}{m^{*} k_{F}}\left[B_{0}+B_{1} P_{1}(\cos \theta)+\ldots\right] \tag{5.8}
\end{align*}
$$

If we know the quasiparticle distribution function, then we can compute, just as for the electron gas, all the relevant physical quantities. These will involve the parameters $A_{n}$ and $B_{n}$. The beauty of this theory is that some of the same parameters enter different physical quantities. Therefore by measuring certain quantities we can predict others. The difficulty, of course, is in determining the distribution function $\delta n(\boldsymbol{k}, \boldsymbol{\sigma})$. For static situations this is relatively easy. However, for dynamic situations, as we shall see in the following chapters, we have to solve a Boltzmann-like equation.

Since the $\boldsymbol{k}$ dependence of the quasiparticle energy is a result of interactions, there should be a relation between $m^{*}$ and the parameters $A_{n}$ and $B_{n}$. To obtain this relation let us consider the situation at $T=0$ in which we have one quasiparticle at $\boldsymbol{k}$ with spin up, as illustrated in Fig. 5.3a. Now, suppose the momentum of this system is increased by $\hbar \boldsymbol{q}$, giving us the situation in


Fig. 5.3. Effect of a uniform translation in momentum space on a state containing one extra particle

Fig. 5.3b. This corresponds to placing the whole system on a train moving with a velocity $\hbar \boldsymbol{q} / m$. To an observer at rest with respect to the train it will appear that the quasiparticle has acquired an additional energy

$$
\begin{equation*}
\delta \epsilon(\boldsymbol{k}, \boldsymbol{\sigma})_{11}=\hbar^{2} \boldsymbol{k} \cdot \boldsymbol{q} / m \tag{5.9}
\end{equation*}
$$

for small $\boldsymbol{q}$. However, the quasiparticle itself experiences a change in energy associated with its own motion in momentum space, which, from (5.3), is just $\hbar^{2} \boldsymbol{k} \cdot \boldsymbol{q} / m^{*}$. In addition, it sees the redistribution of quasiparticles indicated in Fig. 5.3b. Since this momentum displacement does not produce any spin flipping, $\delta n(\boldsymbol{k}, \boldsymbol{\sigma})_{\alpha \beta}$ will have the form $\delta n(\boldsymbol{k}) \delta_{\alpha \beta}$, where $\delta n(\boldsymbol{k})$ is +1 for the quasiparticles and -1 for the quasi-holes. This gives a contribution of

$$
\frac{2}{V} \sum_{\boldsymbol{k}^{\prime}} \varphi\left(\boldsymbol{k}, \boldsymbol{k}^{\prime}\right) \delta n\left(\boldsymbol{k}^{\prime}\right)
$$

to the 1,1 component of the energy, where the factor 2 arises from the spin trace. Equating these two changes in energy, which is what is meant by Galilean invariance, and converting the sum over $\boldsymbol{k}^{\prime}$ to an integral leads to our desired relation,

$$
\begin{equation*}
m^{*}=m\left(1+\frac{A_{1}}{3}\right) \tag{5.10}
\end{equation*}
$$

It can be shown that the specific heat of a Fermi liquid has the same form as that for an ideal Fermi gas, with $m$ replaced by $m^{*}$. Thus by measuring the specific heat we can determine the Fermi liquid parameter $A_{1}$.

Exchange Enhancement of the Pauli Susceptibility. We are now ready to consider our original question of the response of a Fermi liquid to a magnetic field. In the presence of a magnetic field the noninteracting quasiparticle energy $\epsilon^{0}(\boldsymbol{k}, \boldsymbol{\sigma})$ is no longer independent of the spin, but contains a Zeeman contribution,

$$
\begin{equation*}
\epsilon^{0}(\boldsymbol{k}, \boldsymbol{\sigma})=\epsilon^{0}(\boldsymbol{k}) \mathbf{1}+\mu_{B} H \sigma_{z} . \tag{5.11}
\end{equation*}
$$

We shall assume that any field-induced contributions to the interaction term are small. Therefore the total quasiparticle energy is

$$
\begin{equation*}
\epsilon(\boldsymbol{k}, \boldsymbol{\sigma})=\epsilon^{0}(\boldsymbol{k}) \mathbf{1}+\mu_{B} H \sigma_{z}+\frac{1}{V} \operatorname{Tr}_{\sigma^{\prime}}\left\{\sum_{\boldsymbol{k}^{\prime}} f\left(\boldsymbol{k}, \boldsymbol{\sigma} ; \boldsymbol{k}^{\prime}, \boldsymbol{\sigma}^{\prime}\right) \delta n\left(\boldsymbol{k}^{\prime} \boldsymbol{\sigma}^{\prime}\right)\right\} \tag{5.12}
\end{equation*}
$$

It is energetically more favorable for the quasiparticles to align themselves opposite to the field, since their gyromagnetic ratio is negative. However, each time a quasiparticle flips over it changes the distribution, thereby bringing in contributions from the last term in (5.12). Thus, if we start with two equal spin


Fig. 5.4. Effect of a dc magnetic field on the spin-up and the spin-down Fermi spheres
distributions, as shown in Fig. 5.4a, an equilibrium situation will eventually be reached, as illustrated in Fig. 5.4b, in which the energy of a quasiparticle on the up-spin Fermi surface is equal to that of a quasiparticle on the down-spin surface; that is,

$$
\begin{equation*}
\epsilon\left(k_{F}+\delta k_{F}, \boldsymbol{\sigma}\right)_{22}=\epsilon\left(k_{F}-\delta k_{F}, \boldsymbol{\sigma}\right)_{11} . \tag{5.13}
\end{equation*}
$$

From (5.3), (5.12) this condition becomes

$$
\begin{align*}
& \frac{\hbar^{2} k_{F}}{m^{*}} \delta k_{F}-\mu_{B} H+\frac{1}{V} \operatorname{Tr}_{\sigma^{\prime}}\left\{\sum_{\boldsymbol{k}^{\prime}}\left[\varphi\left(\hat{\boldsymbol{k}} \cdot \hat{\boldsymbol{k}}^{\prime}\right) \mathbf{1}^{\prime}-\psi\left(\hat{\boldsymbol{k}} \cdot \hat{\boldsymbol{k}}^{\prime}\right) \sigma_{z}^{\prime}\right] \delta n\left(\boldsymbol{k}^{\prime}, \boldsymbol{\sigma}^{\prime}\right)\right\} \\
=- & \frac{\hbar^{2} k_{F}}{m^{*}} \delta k_{F}+\mu_{B} H+\frac{1}{V} \operatorname{Tr}_{\sigma^{\prime}}\left\{\sum_{\boldsymbol{k}^{\prime}}\left[\varphi\left(\hat{\boldsymbol{k}} \cdot \hat{\boldsymbol{k}}^{\prime}\right) \mathbf{1}^{\prime}+\psi\left(\hat{\boldsymbol{k}} \cdot \hat{\boldsymbol{k}}^{\prime}\right) \sigma_{z}^{\prime}\right] \delta n\left(\boldsymbol{k}^{\prime}, \boldsymbol{\sigma}^{\prime}\right)\right\} \tag{5.14}
\end{align*}
$$

The change in quasiparticle distribution shown in Fig. 5.4b is characterized by

$$
\delta n(\boldsymbol{k}, \boldsymbol{\sigma})=\left\{\begin{array}{l}
{\left[\begin{array}{ll}
0 & 0 \\
0 & 1
\end{array}\right] \quad k_{F}<|\boldsymbol{k}|<k_{F}+\delta k_{F}}  \tag{5.15}\\
{\left[\begin{array}{rr}
-1 & 0 \\
0 & 0
\end{array}\right] k_{F}-\delta k_{F}<|\boldsymbol{k}|<k_{F}}
\end{array}\right.
$$

Therefore

$$
\begin{equation*}
\operatorname{Tr}_{\sigma^{\prime}}\left\{\sum_{\boldsymbol{k}^{\prime}} \varphi\left(\hat{\boldsymbol{k}} \cdot \hat{\boldsymbol{k}}^{\prime}\right) \mathbf{1} \delta n\left(\boldsymbol{k}^{\prime}, \sigma^{\prime}\right)\right\}=0 \tag{5.16}
\end{equation*}
$$

while

$$
\begin{equation*}
\operatorname{Tr}_{\sigma^{\prime}}\left\{\sum_{k^{\prime}} \psi\left(\hat{\boldsymbol{k}} \cdot \hat{\boldsymbol{k}}^{\prime}\right) \sigma_{z}^{\prime} \delta n\left(\boldsymbol{k}^{\prime}, \boldsymbol{\sigma}\right)\right\}=-\frac{4 \pi V}{(2 \pi)^{3}} k_{F}^{2} \delta k_{F} \int_{-1}^{+1} d(\cos \theta) \psi\left(\hat{\boldsymbol{k}} \cdot \hat{\boldsymbol{k}}^{\prime}\right) . \tag{5.17}
\end{equation*}
$$

Equation (5.14) then reduces to

$$
\begin{equation*}
\frac{2 \hbar^{2} k_{F}}{m^{*}} \delta k_{F}-2 \mu_{B} H+\frac{2 \hbar^{2} k_{F} \delta k_{F}}{m^{*}} B_{0}=0 . \tag{5.18}
\end{equation*}
$$

Since the magnetization is

$$
\begin{equation*}
M_{z}=-\frac{\mu_{B}}{V} \operatorname{Tr}_{\sigma}\left\{\sum_{\boldsymbol{k}} \sigma_{z} \delta n(\boldsymbol{k}, \boldsymbol{\sigma})\right\}=2 \mu_{B} \frac{\pi k_{F}^{2} \delta k_{F}}{(2 \pi)^{3}} \tag{5.19}
\end{equation*}
$$

the uniform susceptibility of a Fermi liquid at $T=0$ is

$$
\begin{equation*}
\chi(0)=\frac{1+\frac{1}{3} A_{1}}{1+B_{0}} \chi_{\text {Pauli }} \tag{5.20}
\end{equation*}
$$

Thus we find that in addition to the appearance of the effective mass in place of the bare mass, the susceptibility is also modified by the factor $\left(1+B_{0}\right)^{-1}$. In the Hartree-Fock approximation

$$
\begin{equation*}
B_{0}=-\frac{m e^{2}}{\pi \hbar^{2} k_{F}}=-0.166 r_{s} \tag{5.21}
\end{equation*}
$$

and we speak of the susceptibility as being exchange enhanced. As the electron density decreases and $r_{s} \rightarrow 6.03$ the susceptibility diverges. This is usually taken to imply that such a material will be ferrogmagnetic. There has been a great deal of discussion [108] about the magnetic state of an interacting electron system, and it is generally agreed that such a system will not become ferromagnetic at any electron density. That is, the Hartree-Fock approximation favors ferromagnetism. The reason is that in this approximation parallel spins are kept apart by the exclusion principle while antiparallel spins are spatially uncorrelated. Thus the antiparallel spins have a relatively large Coulomb energy to gain by becoming parallel. In an exact treatment one would expect the antiparallel spins to be somewhat correlated, thereby reducing the Coulomb difference. The differences between the exact properties of an interacting electron system and those obtained in the Hartree-Fock approximation are referred to as correlation effects. Estimates of these correlation corrections indicate that the nonmagnetic ground state of the electron gas has a lower energy than the ferromagnetic one.

The predictions of Fermi-liquid theory, namely that the low temperature heat capcity varies as $\gamma T$ and that the resistivity varies as $T^{2}$ are found to describe most metals. During the last decade, however, non-Fermi-liquid behavior has been observed in a number of systems. One of the most studied is the high-temperature superconductor, $\mathrm{La}_{z-x} \mathrm{Sr}_{x} \mathrm{CuO}_{4}$. The phase diagram for this system is shown in Fig. 4.16. The "normal" region above the superconducting region shows anamolous features. Anderson, for example, argues that the absence of a residual resistivity in the $a b$ plane invalidates a Fermiliquid description. It is known that a Fermi-liquid approach certainly fails in one dimension, for in one dimension the Fermi "surface" consists of only two points at $k= \pm k_{F}$. Any interaction with momentum transfer $q=2 k_{F}$ leads to an instability that produces a gap in the energy spectrum. In 1963

Luttinger introduced a model of 1D interacting Fermions. His solution does not give quasiparticles, but rather spin and charge excitations that propagate independently. Whether the $2 \mathrm{D} \mathrm{CuO}_{2}$ planes in $\mathrm{La}_{2-x} \mathrm{Sr}_{x} \mathrm{CuO}_{4}$ can be described by such a "Luttinger liquid" is a subject of debate. Other materials exhibiting non-Fermi-liquid behavior are the so-called heavy Fermions.

### 5.2 Heavy Fermion Systems

At low temperatures the electrons in a "normal" metal contribute a term to the specific heat that is linear in the temperature, i.e., $C=\gamma T$ as we mentioned above. Simple theoretical considerations give $\gamma=\frac{2}{3} \pi^{2} k_{B}^{2} N\left(E_{F}\right)$. In particular, for a free electron metal the density of states is given by $N\left(E_{F}\right)=\left(2 m / \hbar^{2}\right)^{3 / 2} E_{F}^{1 / 2}$ which gives a value of $\gamma$ of the order of one $m J / K^{-2} \mathrm{~mol}^{-1}$. There exist, however, metallic systems with low temperature heat capacity coefficients of the order of $1000 \mathrm{~mJ} / \mathrm{K}^{-2} \mathrm{~mol}^{-1}$. Examples include $\mathrm{CeCu}_{2} \mathrm{Si}_{2}$, $\mathrm{UBe}_{13}$, and $\mathrm{UPt}_{3}$. Almost all the examples involve rare earths, such as Ce, or actinides, such as U . These elements have their $f^{n}$ and $f^{n \pm 1}$ electronic configurations close enough in energy to allow valence fluctuations with hybridization. This can lead to Kondo behavior (see Sect. 3.4.3) and is why some refer to heavy Fermion systems as "Kondo lattices". In this description the large electronic mass is associated with a large density of states at the Fermi level that derives from the many-body resonance we found in our treatment of the Kondo impurity. When $d$-electron ions are used to create a Kondo lattice their large spatial extent results in too strong a hybridization to show heavy Fermion behavior. $\mathrm{LiV}_{2} \mathrm{O}_{4}$ appears to be an exception.

Once one has a heavy Fermion system it is subject to the same sorts of Fermi surface instabilities found in more normal metals. In particular, $\mathrm{CeCu}_{2} \mathrm{Si}_{2}$ shows both a spin density wave and superconductivity as one changes the 4f-conduction electron coupling by substituting Ge for the Si.

The Kondo lattice is not the only mechanism that may lead to heavy Fermions. When $\mathrm{Nd}_{2} \mathrm{CuO}_{4}$ is doped with electrons by introducing Ce for Nd , i.e., $\mathrm{Nd}_{2-x} \mathrm{Ce}_{x} \mathrm{CuO}_{4}$, the linear specific heat coefficient is $\gamma=4 \mathrm{~J} / \mathrm{K}^{-2} \mathrm{~mol}^{-1}$. The conduction occurs through hopping among the Cu sites. As a result of the double exchange we described in Sect. 2.2.10, these hopping electrons see an effective antiferromagnetic field. The conduction electron Hamiltonian is therefore taken to be

$$
-t \sum_{i, j, \sigma}\left(a_{i \sigma}^{\dagger} a_{j \sigma}+h . c .\right)+h \sum_{i \sigma} \sigma e^{i \boldsymbol{Q} \cdot \boldsymbol{R}_{i}} a_{i \sigma}^{\dagger} a_{i \sigma},
$$

where $\boldsymbol{Q}$ is a reciprocal lattice vector $(\pi / a, \pi / a)$ and $h$ is the effective field that accounts for the antiferromagnetic correlations. The 4f electrons are described by the term

$$
\epsilon_{f} \sum_{i \sigma} f_{i \sigma}^{\dagger} f_{i \sigma} .
$$



Fig. 5.5. Schematic plot of the quasiparticle bands of $\mathrm{Nd}_{z-x} C e_{x} \mathrm{CuO}_{4}$ for $x \neq 0$. The Fermi energy is indicated by a dotted line. Solid lines: $f$-like excitations, and dashed lines: $d$-like excitations [109]

Finally, we add a hybridization

$$
V \sum_{i \sigma}\left(a_{i \sigma}^{\dagger} f_{i \sigma}+h . c .\right) .
$$

This is a very simplified model since it only considers one 4 f orbital instead of seven. Nevertheless, when this Hamiltonian is diagonalized [109] one obtains the four bands shown in Fig. 5.5. The Fermi level in the doped case sits in the narrow $f$-band giving rise to a large electronic mass.

### 5.3 Itinerant Magnetism

The appearance of ferromagnetism in real metals is related to the presence of the ionic cores which tend to localize the intinerant electrons and introduce structure in the electronic density of states. We shall now consider two models that incorporate these features.

### 5.3.1 The Stoner Model

In the 1930s both Slater [110] and Stoner [111] combined Fermi statistics with the molecular field concept to explain itinerant ferromagnetism. This one-electron approach is now generally referred to as the Stoner model. It bears similarities to Landau's Fermi liquid theory in that the effect of the electron-electron interactions is to produce a spin-dependent potential that simply shifts the original Bloch states.

Stoner's result is contained within the generalized susceptibility $\chi(\boldsymbol{q})$ of an interacting electron system. As a model Hamiltonian we take a form similar to (1.139) where $\epsilon_{k}$ now refers to the Bloch band energy. Since the Coulomb interaction in a metal is screened, let us take a delta-function interaction of
the form $I \delta\left(\boldsymbol{r}_{i}-\boldsymbol{r}_{j}\right)$. In this case one need not add a compensating background charge density and (1.139) becomes

$$
\begin{equation*}
\mathcal{H}_{0}=\sum_{\boldsymbol{k} \sigma} \epsilon_{k} a_{k \sigma}^{\dagger} a_{k \sigma}+\frac{I}{V} \sum_{\boldsymbol{k}} \sum_{\boldsymbol{k}} \sum_{\boldsymbol{k}^{\prime}} \sum_{\boldsymbol{q}} \sum_{\sigma} a_{k-\boldsymbol{q}, \sigma}^{\dagger} a_{\boldsymbol{k}^{\prime}+\boldsymbol{q},-\sigma}^{\dagger} a_{\boldsymbol{k}, \sigma} a_{\boldsymbol{k}^{\prime} \sigma^{\prime}} \tag{5.22}
\end{equation*}
$$

If we now add a spatially varying field $H \hat{\boldsymbol{z}} \cos (\boldsymbol{q} \cdot \boldsymbol{r})$, the Zeeman Hamiltonian becomes

$$
\begin{equation*}
\mathcal{H}_{Z}=-\frac{H}{2}\left[\mathcal{M}_{z}(\boldsymbol{q})+\mathcal{M}_{z}(-\boldsymbol{q})\right], \tag{5.23}
\end{equation*}
$$

where

$$
\begin{equation*}
\mathcal{M}_{z}(\boldsymbol{q})=\frac{1}{2} g \mu_{B} \sum_{\boldsymbol{k}}\left(a_{\boldsymbol{k}-\boldsymbol{q}, \uparrow}^{\dagger} a_{k \uparrow}-a_{\boldsymbol{k}-\boldsymbol{q}, \downarrow}^{\dagger} a_{k \downarrow}\right) . \tag{5.24}
\end{equation*}
$$

Susceptibility. The susceptibility is obtained by calculating the average value of $\mathcal{M}_{z}(\boldsymbol{q})$ to lowest order in H. In particular, we must calculate the average of

$$
m_{\boldsymbol{k}, \boldsymbol{q}} \equiv a_{k-\boldsymbol{q}, \uparrow}^{\dagger} a_{k, \uparrow}-a_{k-\boldsymbol{q}, \downarrow}^{\dagger} a_{k, \downarrow} .
$$

Following Wolff [112] we shall do this by writing the equation of motion for $m_{\boldsymbol{k}, \boldsymbol{q}}$ and using the fact that in equilibrium $\partial\left\langle m_{\boldsymbol{k}, \boldsymbol{q}}\right\rangle \partial t=0$. Thus,

$$
\begin{equation*}
\left\langle\left[m_{\boldsymbol{k}, \boldsymbol{q}}, \mathcal{H}_{0}+\mathcal{H}_{z}\right]\right\rangle=0 \tag{5.25}
\end{equation*}
$$

This commutator involves a variety of twofold and fourfold products of electron operators. These are simplified by making a random-phase approximation in which we retain only those pairs which are diagonal or have the forms appearing in $m_{\boldsymbol{k}, \boldsymbol{q}}$ itself. Furthermore, the diagonal pairs are replaced by their average in the noninteracting ground state. This is equivalent to a HartreeFock approximation. The result is

$$
\begin{equation*}
\left(\epsilon_{\boldsymbol{k}}-\epsilon_{\boldsymbol{k}+\boldsymbol{q}}\right)\left\langle m_{\boldsymbol{k}, \boldsymbol{q}}\right\rangle-\frac{2 I}{V}\left(n_{\boldsymbol{k}+\boldsymbol{q}}-n_{\boldsymbol{k}}\right) \sum_{\boldsymbol{k}^{\prime}}\left\langle m_{\boldsymbol{k}^{\prime}, \boldsymbol{q}}\right\rangle-g \mu_{B} H\left(n_{\boldsymbol{k}+\boldsymbol{q}}-n_{\boldsymbol{k}}\right)=0 \tag{5.26}
\end{equation*}
$$

Dividing by $\left(\epsilon_{\boldsymbol{k}+\boldsymbol{q}}-\epsilon_{\boldsymbol{k}}\right)$ and summing over $\boldsymbol{k}$ gives

$$
\begin{equation*}
\sum_{k}\left\langle m_{\boldsymbol{k}, \boldsymbol{q}}\right\rangle=\frac{g \mu_{B} H \sum_{\boldsymbol{k}} \frac{n_{\boldsymbol{k}}-n_{\boldsymbol{k}+\boldsymbol{q}}}{\epsilon_{\boldsymbol{k}+\boldsymbol{q}}-\epsilon_{\boldsymbol{k}}}}{1-\frac{2 I}{V} \sum_{\boldsymbol{k}} \frac{n_{\boldsymbol{k}}-n_{\boldsymbol{k}+\boldsymbol{q}}}{\epsilon_{\boldsymbol{k}+\boldsymbol{q}}-\epsilon_{\boldsymbol{k}}}} \tag{5.27}
\end{equation*}
$$

Since the equilibrium occupation number $n_{\boldsymbol{k}}$ is just the Fermi function $f_{k}$, we recognize the sum appearing in this expression as the same as that which appears in the noninteracting susceptibility (3.93), which we shall denote as $\chi_{0}(\boldsymbol{q})$. Thus,

$$
\begin{equation*}
\chi(\boldsymbol{q})=\frac{\chi_{0}(\boldsymbol{q})}{1-\frac{2 I}{g^{2} \mu_{B}^{2}} \chi_{0}(\boldsymbol{q})} \tag{5.28}
\end{equation*}
$$

We could also have calculated $\left\langle m_{\boldsymbol{k}, \boldsymbol{q}}\right\rangle$ directly by the formulation indicated in (1.81). However, the appearance of the interaction term in the exponentials which enter $m_{\boldsymbol{k}, \boldsymbol{q}}(t)$ requires many-body perturbation techniques which are beyond the scope of this monograph. We shall use the diagrams introduced in Chap. 1 to make the results of such a treatment plausible. The interaction term in (5.22) has the diagramatic form


In calculating average values such as the energy or the magnetization the electron and hole lines must be closed.

There are two ways one can close the electron and hole lines:

(a)

(b)

In (a) the vertices indicated by the small squares involve a momentum change $\boldsymbol{q}$ but no spin flip. This longitudinal spin fluctuation represents the first-order correction to $\chi_{z z}$. The susceptibility (5.28) corresponds to the summation of all such diagrams:

$$
x_{n}(q)=1 \cdot 1 \cdots+1+1+\cdots
$$

In diagram (b) the vertices also involve a spin flip. This diagram is the firstorder correction to the transverse susceptibility $\chi_{-+}(\boldsymbol{q})$ whose noninteracting form is given by (3.97). Summing all such transverse spin fluctuations gives the transverse susceptibility.


In the paramagnetic state rotational invariance requires $\chi_{-+}(\boldsymbol{q})=2 \chi_{z z}(\boldsymbol{q})$.
Returning to (5.28), since $\lim _{\boldsymbol{q} \rightarrow 0} \chi_{0}(\boldsymbol{q})=\frac{1}{3} g^{2} \mu_{B}^{2} \mathcal{D}\left(\epsilon_{F}\right)$, we see that

$$
\begin{equation*}
\chi(0)=\frac{\chi_{0}(0)}{1-I \mathcal{D}\left(\epsilon_{F}\right)} . \tag{5.29}
\end{equation*}
$$

This has the same form as our Fermi liquid result (5.20). Thus we have an expression, at least in the random-phase approximation, for the Fermi liquid parameter $B_{0}$ in terms of the intraatomic exchange integral $I$ and the density of states.

Notice that the criterion for the appearance of ferromagnetism is that $I \mathcal{D}\left(\epsilon_{F}\right) \geq 1$. This is referred to as the Stoner criterion.

One might wonder how ferromagnetism can occur with only an intraatomic Coulomb interaction. To see the physical origin of this, suppose we have a spin up at some site $\alpha$. If the spin on a neighboring site $\alpha^{\prime}$ is also up, it is forbidden by the exclusion principle from hopping onto site $\alpha$. Therefore the two electrons do not interact, and we might define the energy of such a configuration as 0 . However, if the spin of site $\alpha^{\prime}$ is down, it has a nonzero probability of hopping onto site $\alpha$. Thus the energy of this configuration is higher than that of the "ferromagnetic" one. However, hopping around can lower the kinetic energy of the electrons. This is reflected in the appearance of the density of states in the Stoner criterion. The occurrence of ferromagnetism depends, therefore, on the relative values of the Coulomb interaction and the kinetic energy.

Equation (5.29) has interesting consequences for metals which are paramagnetic but have a large enhancement factor. For example, an impurity spin placed in such a host produces a large polarization of the conduction electrons in its vicinity. Such giant moments have been observed in palladium and certain of its alloys. This seems reasonable, since palladium falls just below nickel in the periodic table and has similar electronic properties. Thus we might suspect that although palladium is not ferromagnetic like nickel, it at least possesses a large exchange enhancement.

Spin-Density Waves. Just as in the case of localized moments, a divergence of $\chi(\boldsymbol{q})$ for $\boldsymbol{q} \neq 0$ would imply a transition to a state of nonuniform magnetization. In fact, Overhauser [113] has shown that the $\chi(\boldsymbol{q})$ associated with an unscreened Coulomb interaction in the Hartree-Fock approximation does diverge as $q \rightarrow 2 k_{F}$, as shown in Fig. 5.6. This would lead to a ground state characterized by a period spin density, called a spin-density wave. The effects of screening and electron correlations, however, tend to suppress this divergence. Consequently, a spin-density wave can form only under rather special conditions. We get some feeling for these conditions by considering the behavior of the non-interacting susceptibility $\chi_{0}(\boldsymbol{q})$ in one and two dimensions


Fig. 5.6. Effect of electron-electron interactions on the susceptibility (3 dimensions)


Fig. 5.7. Effect of dimensionality on the free electron susceptibility
as shown in Fig. 5.7. We see that lower dimensional systems are more likely to become unstable with respect to spin-density wave formation.

The reason for this has to do with the fact that in a state characterized by a wave vector $\boldsymbol{q}$ electrons with wave vectors which differ by $\boldsymbol{q}$ become correlated. This effectively removes them from the Fermi sea. This is often described as a "nesting" of the corresponding states. In one and two dimensions Fermi surfaces are geometrically simpler, which means that nesting will have more dramatic effects. These same considerations, however, also apply
to charge-density instabilities. And, in fact, most of the materials which do show such Fermi-surfaced-related instabilities show charge-density waves.

To date, chromium and its alloys are the best examples of materials possessing a spin-density-wave ground state. The reason for this has to do with the band structure of chromium.

If the susceptibility does not actually diverge at some nonzero wave vector, but nevertheless becomes very large, the system may be said to exhibit antiferromagnetic exchange enhancement. Experiments on dilute alloys of Sc:Gd indicate that scandium metal may be an example of such a type [114].

Exchange Splitting. If the system is ferromagnetic, then $\left\langle m_{\boldsymbol{k}, \boldsymbol{q}=0}\right\rangle=\left(n_{\boldsymbol{k} \uparrow}-\right.$ $\left.n_{\boldsymbol{k} \downarrow}\right) \neq 0$ even in the absence of an applied field. In this case the Hamiltonian may be written in a particularly revealing form by considering only the diagonal terms in (5.22):

$$
\begin{equation*}
\frac{1}{2} n_{k^{\prime} \downarrow} a_{k \uparrow}^{\dagger} a_{k \uparrow}+\frac{1}{2} n_{k^{\prime} \uparrow} a_{k \downarrow}^{\dagger} a_{k \downarrow} . \tag{5.30}
\end{equation*}
$$

Since

$$
\begin{equation*}
M=\frac{g \mu_{B}}{2 V} \sum_{k}\left(n_{k \uparrow}-n_{k \downarrow}\right), \tag{5.31}
\end{equation*}
$$

the Hamiltonian becomes

$$
\begin{equation*}
\mathcal{H}_{0}^{\prime}=E_{0}+\sum_{k, \sigma} \epsilon_{k \sigma} a_{k \sigma}^{\dagger} a_{k \sigma}, \tag{5.32}
\end{equation*}
$$

where

$$
\begin{equation*}
\epsilon_{k \sigma}=\epsilon_{k}+\frac{N I}{4 V}-\frac{I M}{2 g \mu_{B}} \sigma . \tag{5.33}
\end{equation*}
$$

Thus the spin-up and spin-down energy bands are split by an amount proportional to the magnetization. This was the basic idea in Stoner's original theory of ferromagnetism. More generally, this splitting arises from the difference between the spin-up and spin-down exchange-correlation potentials seen by the electrons. Since the Stoner model was first proposed there has been a great deal of progress in specifying these potentials.

In 1951 Slater [115] suggested that we approximate the effect of exchange by the potential

$$
V_{x}(\boldsymbol{r})=-6[(3 / 8 \pi) \rho(\boldsymbol{r})]^{1 / 3} .
$$

This approximation form has been used extensively both in atomic and solidstate calculations. Physically, this density to the one-third power arises from the fact that in the Hartree-Fock approximation parallel spins are kept farther apart than antiparallel spins. Therefore, there is an "exchange hole" around any particular spin associated with a deficiency of similar spins. The radius of this hole must be such that $\left(\frac{3}{4}\right) \pi r^{3} \rho=1$. Since the potential associated with this deficiency is proportional to $1 / r$, we obtain an exchange potential proportional to $\rho^{1 / 3}$.

In 1965 Kohn and Sham [116] rederived the exchange potential by a different method and obtained a value two thirds that of Slater's. This led workers to multiply $V_{x}(\boldsymbol{r})$ by an adjustable constant, $\alpha$, which can be determined for each atom by requiring that the so-called $X \alpha$ energy be equal to the HartreeFock energy for that atom. An interesting application of the $X \alpha$ method has been made by Hattox et al. [117]. They calculated the magnetic moment of bcc vanadium as a function of lattice spacing. The result is shown in Fig. 5.8. We see that the moment falls suddenly to zero at a spacing $20 \%$ larger than the actual observed spacing. This decrease is due to the broadening of the 3d band as the lattice spacing decreases. This is consistent with the fact that bcc vanadium, where the vanadium-vanadium distance is $\sqrt{3} a_{0} / 2=2.49 \AA$, is observed to be nonmagnetic. In $\mathrm{Au}_{4} \mathrm{~V}$, however, the vanadium-vanadium distance has increased to $3.78 \AA$ and the vanadium has a moment near one Bohr magneton.

If one uses this approach to find $\alpha$ for the magnetic transition metals one finds that the resulting magnetic moments are not in agreement with those observed.

This is not surprising when we consider that we have replaced a nonlocal potential (the Hartree-Fock potential) by a local potential (the Slater $\rho^{1 / 3}$ ). Furthermore, the fact that these are different means that the Slater potential must, by definition, include some correlation. However, we do not know if it is in the right direction.

The arbitrariness inherent in the $X \alpha$ method may be avoided by using the "spin-density functional" formalism. This essentially enables one to utilize the results of many-body calculations for the homogeneous electron gas in determining the exchange and correlation potentials in transition metals. This


Fig. 5.8. Calculated magnetic moment of vanadium metal as a function of lattice parameter. The two points for $a=3.5 \AA$ correspond to two distinct self-consistent solutions associated with different starting potentials. These two solutions are the result of a double minimum in the total energy versus magnetization curve. At $4.25 \AA$ and $3.15 \AA$ the calculations converged to unique values [117]
approach is based on a theorem by Hohenberg and Kohn [118] which states that the ground-state energy of an inhomogeneous electron gas is a functional of the electron density $\rho(\boldsymbol{r})$ and the spin density $m(\boldsymbol{r})$. The effective potential, for example, is given by

$$
\begin{equation*}
V_{\mathrm{eff}}=v(\boldsymbol{r})+e^{2} \int \frac{\rho\left(\boldsymbol{r}^{\prime}\right) d \boldsymbol{r}^{\prime}}{\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|}+\frac{\delta E_{x c}\{\rho\}}{\delta \rho(\boldsymbol{r})}, \tag{5.34}
\end{equation*}
$$

where $v(\boldsymbol{r})$ is the one-electron potential, the second term is the Hartree term, and $E_{x c}\{\rho\}$ is the exchange and correlation energy. The importance of this theorem is that it reduces the many-body problem to a set of one-body problems for the one-electron wave functions $\phi_{k \sigma}(\boldsymbol{r})$ which make up the density,

$$
\begin{equation*}
\rho(\boldsymbol{r})=\sum_{\boldsymbol{k}, \sigma} \phi_{\boldsymbol{k} \sigma}^{*}(\boldsymbol{r}) \phi_{\boldsymbol{k} \sigma}(\boldsymbol{r}) . \tag{5.35}
\end{equation*}
$$

The local density approximation consists of replacing the unknown functional $E_{x c}\{\rho\}$ by $\int d^{3} r \rho(\boldsymbol{r}) \epsilon_{x c}^{h}[\rho(\boldsymbol{r})]$ where $\epsilon_{x c}^{h}[\rho(\boldsymbol{r})]$ is the exchange and correlation contribution to the energy of a homogeneous interacting electron gas of density $\rho(\boldsymbol{r})$. Although one might question the use of such an approximation in transition metals where there are rapid variations in the charge density, the fact that it is only the spherical average of the exchange-correlation hole which enters the calculation makes $E_{x c}\{\rho\}$ fairly insensitive to the details of this hole.

The density functional approach leads to a set of self-consistent Hartree equations. It is tempting to identify the eigenvalues as effective single particle energies. However, detailed studies of the energy bands indicate that this identification may not be appropriate in certain cases. Photoemission has become a powerful technique for probing the electronic states of solids. In this technique, light (actually ultraviolet or X-rays) is absorbed by a solid. Those electrons excited above the vacuum level leave the solid and are collected. Initially, all the electrons emitted were collected and analyzed. However, with the availability of high-intensity synchrotron X-ray sources, it became possible to resolve the direction of the emitted electrons. This enables one to reconstruct the energymomentum relation of the electrons in the solid. Figure 5.9a compares the results of such an experiment on copper [119] with the calculated band structure. The agreement is remarkable. This technique has now been extended to determine the spin polarization of the photoemitted electrons. This extension was pioneered by H.C. Siegmann in Zürich. The photoemitted electrons are accelerated to relativistic velocities and then scattered from a gold foil. Any initial spin polarization is reflected in asymmetric, or Mott, scattering. Figure 5.9b shows the results of such measurements on Ni [120]. Although the overall features are described by the theory, the detailed fit is not nearly as good as in Cu .

Despite this problem with the identification of single-particle energies, one can calculate ground-state properties such as the bulk modulus and the magnetic moment. The results are in very good agreement with the experimental values. What makes this agreement all the more impressive is that the only input to such calculations are the atomic numbers and the crystal structures.


Fig. 5.9. Comparison of angle-resolved photoemission data with calculated band structures for (a) copper and (b) nickel (open data points correspond to spin up, solid points to spin down). The triangles are de Haas van Alphen data


Fig. 5.10. Saturation magnetization as a function of electron concentration

Alloys. A band description also works well for alloys. Fig. 5.10 shows the magnetic moments for various transition metal alloys. This curve is known as the Slater-Pauling curve. Slater [121] noted that the magnetic properties of 3d solid solutions, particularly their moments, could be averaged over the periodic table and plotted as a function of the filling of the $d$-band. If the pairs of atoms have too much charge contrast, then the electronic states tend to become localized and the simple averaging fails as indicated by the lines branching off the main trend. The Slater-Pauling curve may be understood by considering
the $d$-electron bands to be exchange split as shown for Ni in Fig. 5.9b. In the "rigid-band" approximation, one assumes that the only effect of alloying is to shift the Fermi level. The majority spin band in nickel is completely full (in recognition of which it is sometimes referred to as "strong" meaning further splitting cannot increase the magnetism). The maximum moment between cobalt and iron in the Slater-Pauling curve reflects the composition where the majority band is just completely full. Further removal of electrons as one moves across the compositional axis towards iron results in depletion of both majority and minority bands. Pauling [122] offered an alternative explanation based on the idea that $2.56 d$-orbitals hybridize with $s$ - and $p$-orbitals to form nonmagnetic bonding orbitals. The remaining $2.44 d$-orbitals fill according to Hund's rule to give the magnetic moments.

There is no doubt that the magnetic electrons partake in the transport properties of the transition metal ferromagnets, i.e., that they are itinerant. Nevertheless, there are some physical properties where a localized model is a reasonable and tractable approximation. The situation that pertains is, of course, somewhere between completely localized and free. Using neutron diffraction, which is discussed in Chap. 10, Mook [123] has apportioned the moment, in $\mu_{B}$, in nickel as follows:

$$
\begin{array}{ll}
3 \mathrm{~d} \operatorname{spin}\left(n_{\uparrow}-n_{\downarrow}\right) & =+0.656 \\
\text { 3d orbital } & =+0.055 \\
\text { 4s polarization } & =-0.105 \\
\hline & +0.606
\end{array}
$$

The moment density is quite asymmetric about the lattice sites. About $80 \%$ of the 3d magnetic electrons occupy $\mathrm{t}_{2 g}$ orbitals. For hexagonal cobalt Moon [124] finds:

$$
\begin{array}{ll}
3 \mathrm{~d} \operatorname{spin}\left(n_{\uparrow}-n_{\downarrow}\right)= & +1.86 \\
3 \mathrm{~d} \text { orbital }= & +0.13 \\
\text { 4s polarization }= & -0.28 \\
\hline & +1.71
\end{array}
$$

In this case, the magnetic moment looks like an almost spherical distribution of positive moment localized around each atomic site decreasing to a negative level in the region between atoms.

Although the Stoner theory works reasonably well for magnetic properties at $T=0$, it fails when applied to finite temperature properties. For example, the only place that temperature enters the susceptibility (5.28) is in the arguments of the Fermi functions. The Curie temperature is calculated from the relation

$$
\begin{equation*}
M=\frac{g \mu_{B}}{2 V} \sum_{k}\left(f_{k \uparrow}-f_{k \downarrow}\right), \tag{5.36}
\end{equation*}
$$

where $f_{k \sigma}$ is the Fermi function with $\epsilon_{k \sigma}=\epsilon_{k}+N I / 4 V-\left(I M / 2 g \mu_{B}\right) \sigma$. Since at $T_{c} M$ is very small, the Fermi functions may be expanded about $M=0$. The condition for $T_{c}$ then becomes


Fig. 5.11. Pictorial comparison of the exchange fields seen by an electron in the Stoner model and what is more likely the case

$$
\begin{equation*}
I \int d \epsilon \frac{\partial f\left(T_{c}\right)}{\partial \epsilon} \mathcal{D}(\epsilon)+1=0 \tag{5.37}
\end{equation*}
$$

Using the values of $I$ that give the correct moments at $T=0$ for $\mathrm{Fe}, \mathrm{Co}$, and Ni , we obtain $T_{c}$ 's from (5.37) that are about 5 times larger than the observed values.

The problem with this application of the Stoner model is that the introduction of "up" and "down" spin directions destroys the rotational symmetry. That is, at nonzero temperatures the direction of the effective field arising from the electron-electron interactions as well as its magnitude will vary from site to site as illustrated in Fig. 5.11. Independent calculations by Hubbard [125] and Heine and collaborators [126] show that the energy associated with such local changes in the direction of the magnetization is much less than that associated with changes in the magnitude of the magnetization. That is, the exchange stiffness which characterizes the directional variation is less than the Stoner parameter $I$. The problem remains, however, to relate this observation to the thermodynamic properties.

### 5.3.2 The Hubbard Model

The one-electron Stoner model described above is expected to apply to systems with fairly broad bands. As the bands become narrower intraionic correlation effects become more important. In this case it is convenient to work in the Wannier representation which emphasizes the atomic aspect of the problem. In this representation the one-electron terms becomes

$$
\begin{equation*}
\sum_{\alpha \alpha^{\prime} \sigma} t_{\alpha \alpha^{\prime}} a_{\alpha^{\prime} \sigma}^{\dagger} a_{\alpha \sigma} \tag{5.38}
\end{equation*}
$$

where

$$
\begin{equation*}
t_{\alpha \alpha^{\prime}}=\frac{1}{V} \sum_{\boldsymbol{k}} \epsilon_{\boldsymbol{k}} \exp \left[i \boldsymbol{k} \cdot\left(\boldsymbol{R}_{\alpha}-\boldsymbol{R}_{\alpha^{\prime}}\right)\right] \tag{5.39}
\end{equation*}
$$

describes the hopping of an electron from site $\alpha$ to site $\alpha^{\prime}$. The interaction terms are given by (2.89). Since we are now dealing with an itinerant situation, we shall assume that screening effects restrict the interaction to one site. If there is a single nondegenerate orbital $\varphi_{0}\left(\boldsymbol{r}-\boldsymbol{R}_{\alpha}\right)$ associated with each site, then the interaction becomes

$$
\begin{equation*}
\sum_{\alpha, \sigma} U_{0} n_{\alpha \sigma} n_{\alpha,-\sigma} \tag{5.40}
\end{equation*}
$$

where

$$
\begin{align*}
U_{0}= & \langle 00| V|00\rangle=\iint d \boldsymbol{r} d \boldsymbol{r}^{\prime} \varphi_{0}^{*}\left(\boldsymbol{r}-\boldsymbol{R}_{\alpha}\right) \varphi_{0}^{*}\left(\boldsymbol{r}^{\prime}-\boldsymbol{R}_{\alpha}\right) V\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}\right) \\
& \times \varphi_{0}\left(\boldsymbol{r}^{\prime}-\boldsymbol{R}_{\alpha}\right) \varphi_{0}\left(\boldsymbol{r}-\boldsymbol{R}_{\alpha}\right) . \tag{5.41}
\end{align*}
$$

Because of the screening, which we can think of as $s-d$ correlation effects, the value of $U_{0}$ is of the order of several eV .

Equations (5.38), (5.40) constitute the Hubbard Hamiltonian. It contains the same physics as the Stoner model. In fact, it gives the same susceptibility (5.28) in the mean-field approximation with $U_{0}$ in place of $I$. In a series of papers Hubbard [127] investigated the effects of correlation within this model. He found, for example, that for large correlation the electronic band is split into two subbands separated by $U_{0}$. The transition-metal oxides such as NiO and CoO are generally cited as examples of materials where such correlation effects are responsible for their insulating properties.

In order to understand the variation in magnetic properties as one moves across the transition-metal series, it is necessary to generalize the model above to include orbital degeneracy. This obviously introduces many more Coulomb and exchange integrals. The first simplification is to neglect interactions involving more than two orbitals. One then assumes that all the off-diagonal Coulomb and exchange integrals are the same, i.e.,

$$
\left.\begin{array}{l}
\left\langle m m^{\prime}\right| V\left|m m^{\prime}\right\rangle=U  \tag{5.42}\\
\left\langle m m^{\prime}\right| V\left|m^{\prime} m\right\rangle=J
\end{array}\right\} m^{\prime} \neq m
$$

The exchange integral $J$ is smaller than $U$. We also take all the diagonal integrals to have the same value. If we require that our model Hamiltonian preserve the rotational invariance of the original Hamiltonian, then the diagonal integral is related to the off-diagonal integrals by

$$
\begin{equation*}
\langle m m| V|m m\rangle=U+J . \tag{5.43}
\end{equation*}
$$

The resulting generalized Hubbard Hamiltonian becomes

$$
\begin{align*}
\mathcal{H}^{\prime}= & \frac{1}{2}(U+J) \sum_{\alpha, m, \sigma} n_{\alpha m \sigma} n_{\alpha m,-\sigma}+\frac{1}{2} \sum_{\alpha, m, m^{\prime} \sigma}\left(1-\delta_{m m^{\prime}}\right)  \tag{5.44}\\
& \times\left[U n_{\alpha m \sigma} n_{\alpha m^{\prime},-\sigma}+(U-J) n_{\alpha m \sigma} n_{\alpha m^{\prime} \sigma}-J a_{\alpha m \sigma}^{\dagger} a_{\alpha m-\sigma} a_{\alpha m^{\prime}-\sigma}^{\dagger} a_{\alpha m^{\prime} \sigma}\right] .
\end{align*}
$$

By making use of the spin representation (2.85)-(2.87) the last term may be written

$$
\begin{equation*}
\left(U-\frac{1}{2} J\right) \sum_{\alpha, m<m^{\prime}, \sigma, \sigma^{\prime}} n_{\alpha m \sigma} n_{\alpha m^{\prime} \sigma^{\prime}}-2 J \sum_{\alpha, m<m^{\prime}} \boldsymbol{S}_{\alpha m} \cdot \boldsymbol{S}_{\alpha m^{\prime}} \tag{5.45}
\end{equation*}
$$

which clearly reveals the Hund's rule exchange coupling. Let us now consider how these exchange interactions modify the generalized susceptibility. As in the derivation (5.28) we shall employ the Hartree-Fock approximation. This amounts to writing

$$
\begin{equation*}
n_{\alpha m \sigma}=\left\langle n_{\alpha m \sigma}\right\rangle+\left(n_{\alpha m \sigma}-\left\langle n_{\alpha m \sigma}\right\rangle\right) \tag{5.46}
\end{equation*}
$$

and assuming the term in parentheses is small. Thus,

$$
\begin{equation*}
n_{\alpha m \sigma} n_{\alpha m^{\prime} \sigma^{\prime}}=\left\langle n_{\alpha m \sigma}\right\rangle n_{\alpha m^{\prime} \sigma^{\prime}}+\left\langle n_{\alpha m^{\prime} \sigma^{\prime}}\right\rangle n_{\alpha m \sigma}-\left\langle n_{\alpha m \sigma}\right\rangle\left\langle n_{\alpha m^{\prime} \sigma^{\prime}}\right\rangle, \tag{5.47}
\end{equation*}
$$

and the Hartree-Fock Hamiltonian becomes

$$
\begin{align*}
\mathcal{H}_{H F}= & \sum_{\alpha, \alpha^{\prime} m, \sigma} t_{\alpha \alpha^{\prime}} a_{\alpha m \sigma}^{\dagger} a_{\alpha^{\prime} m \sigma}+(U+J) \sum_{\alpha, m \sigma}\left\langle n_{\alpha m \sigma}\right\rangle n_{\alpha m,-\sigma} \\
& +U \sum_{\alpha, \alpha^{\prime} m, \sigma}\left(\left\langle n_{\alpha m \sigma}\right\rangle n_{\alpha m \sigma,-\sigma}+\left\langle n_{\alpha m^{\prime},-\sigma}\right\rangle n_{\alpha m \sigma}\right) \\
& +(U-J) \sum_{\alpha, m<m^{\prime}, \sigma}\left(\left\langle n_{\alpha m \sigma}\right\rangle n_{\alpha m^{\prime} \sigma}+\left\langle n_{\alpha m^{\prime} \sigma}\right\rangle n_{\alpha m \sigma}\right) . \tag{5.48}
\end{align*}
$$

The magnetic moment per ion is

$$
\begin{equation*}
m_{\alpha}=-\frac{g \mu_{B}}{2} \sum_{m}\left(\left\langle n_{\alpha m \uparrow}\right\rangle-\left\langle n_{\alpha m \downarrow}\right\rangle\right) . \tag{5.49}
\end{equation*}
$$

If the average number of electrons per ion is $n$, then

$$
\begin{equation*}
n=\sum_{m}\left(\left\langle n_{\alpha m \uparrow}\right\rangle+\left\langle n_{\alpha m \downarrow}\right\rangle\right) . \tag{5.50}
\end{equation*}
$$

If we take the case of a transition metal where $m=1, \ldots 5$, then

$$
\begin{align*}
& \left\langle n_{\alpha m \uparrow}\right\rangle=\frac{1}{10}\left(n-\frac{2 m_{\alpha}}{g \mu_{B}}\right), \\
& \left\langle n_{\alpha m \downarrow}\right\rangle=\frac{1}{10}\left(n+\frac{2 m_{\alpha}}{g \mu_{B}}\right), \tag{5.51}
\end{align*}
$$

and the Hartree-Fock Hamiltonian becomes

$$
\begin{align*}
\mathcal{H}_{H F}= & \sum_{\alpha, \alpha^{\prime} m, \sigma} t_{\alpha \alpha^{\prime}} a_{\alpha m \sigma}^{\dagger} a_{\alpha^{\prime} m \sigma}+\frac{1}{10} N(9 U-3 J) n^{2} \\
& +\frac{U+5 J}{g \mu_{B}} \sum_{\alpha, m} m_{\alpha}\left(n_{\alpha m \uparrow}-n_{\alpha m \downarrow}\right) . \tag{5.52}
\end{align*}
$$

In the presence of an external field $H \cos (\boldsymbol{q} \cdot \boldsymbol{r}) \hat{\boldsymbol{z}}$ the Zeeman interaction has the form

$$
\begin{equation*}
\mathcal{H}_{Z}=\frac{g \mu_{B} H}{2} \sum_{\alpha, m}\left(n_{\alpha m \uparrow}-n_{\alpha m \downarrow}\right) \cos \boldsymbol{q} \cdot \boldsymbol{R}_{\alpha} \tag{5.53}
\end{equation*}
$$

If we assume that the induced moments $m_{\alpha}$ have the same spatial variation as the applied field, i.e.,

$$
m_{\alpha}=m \cos \left(\boldsymbol{q} \cdot \boldsymbol{R}_{\alpha}\right),
$$

then by comparing the last term in (5.52) with (5.53) we see that the effect of the interactions is to give an effective field

$$
\begin{equation*}
H(\boldsymbol{r})_{\mathrm{eff}}=\frac{2 m}{g \mu_{B}}(U+5 J) \cos (\boldsymbol{q} \cdot \boldsymbol{r}) \tag{5.54}
\end{equation*}
$$

Taking the Fourier transform of the total effective field and using the fact that

$$
\begin{equation*}
M(\boldsymbol{q})=\chi_{0}(\boldsymbol{q}) H(\boldsymbol{q})_{\mathrm{eff}}, \tag{5.55}
\end{equation*}
$$

where $\chi_{0}(\boldsymbol{q})$ is the susceptibility of the noninteracting electron system, we find for the susceptibility of this Hubbard model

$$
\begin{equation*}
\chi(\boldsymbol{q})=\frac{\chi_{0}(\boldsymbol{q})}{1-\frac{2(U+5 J)}{g^{2} \mu_{B}^{2}} \chi_{0}(\boldsymbol{q})} . \tag{5.56}
\end{equation*}
$$

This has the same form as the Stoner susceptibility with an effective Stoner parameter $I_{\text {eff }}=U+5 J$. The corresponding Stoner criterion becomes $I_{\text {eff }} \mathcal{D}\left(\epsilon_{F}\right)>1$. Thus the presence of intraatomic exchange favors ferromagnetism. However, again, we expect correlation effects to be very important. There have been many calculations of correlation effects within the Hubbard model but their description is beyond the scope of the monograph. The general result of including correlation is to reduce the region of parameter space where ferromagnetism, or antiferromagnetism, is expected.

## Problems

5.1. To obtain some familiarity with the Fermi liquid formalism, this problem asks you to determine the particle current associated with a quasiparticle of momentum $k$. From the definition of the particle current,

$$
j_{k}=v_{\boldsymbol{k}}-\sum_{\boldsymbol{k}^{\prime}} f_{k k^{\prime}} \frac{\partial n_{k}}{\partial \epsilon_{k}^{\prime}} v_{F} .
$$

show that

$$
j_{k}=v_{k}+\left(\frac{m^{*}}{m}-1\right) v_{F}
$$

The last term on the right is a "drag" term associated with the flow of the other quasiparticles.
5.2. Evaluate (5.28) for 1 -dimension at $T=0 K$.
5.3. Considering the exchange split bands having the form


$$
N_{\uparrow}(\varepsilon)=\frac{15}{4 \varepsilon_{0}}\left[1-\left(\frac{\varepsilon-\varepsilon_{0}}{\varepsilon_{0}}\right)^{2}\right]
$$

Compute the magnetic moment as a function of $\varepsilon_{F}$ for $\varepsilon_{0}<\varepsilon_{F}<4 \varepsilon_{0}$ for the two exchange splittings $\Delta=\varepsilon_{0}$ and $\Delta=3 \varepsilon_{0} / 2$.
5.4. For the band structure shown in Problem 5.3, calculate the total energy as a function of the number of electrons per atom, $n$. Find the value of $\Delta$ which minimizes the total energy and plot $\Delta(n)$.

## The Dynamic Susceptibility of Weakly Interacting Systems:

## Local Moments

We now turn to the response of magnetic systems to time-dependent excitations. In this chapter we shall restrict our consideration to systems in which the interactions among the constituents are not strong enough to produce a spontaneous magnetization. The study of the frequency response of such systems is essentially the study of paramagnetic resonance and relaxation phenomena. This is obviously an enormous subject, and we shall not be able to go into it in great detail. However, we shall examine some of the basic ideas within the framework of our generalized susceptibility.

### 6.1 Equation of Motion

Let us begin by considering a system of identical localized spins characterized by a noninteracting Hamiltonian $\mathcal{H}_{0}$. In Sect. 3.1 we found that in the presence of a uniform static field $H_{0} \hat{\boldsymbol{z}}$ such a system develops a magnetization, which we shall denote by $M_{0} \hat{\boldsymbol{z}}$. Let us now apply an additional time-dependent field $\boldsymbol{H}_{1} \cos \omega t$ and investigate the response to this field.

Since the applied field is uniform, we shall drop explicit reference to spatial considerations. Thus we may write the magnetization as

$$
\begin{equation*}
\boldsymbol{M}=\frac{1}{V} \operatorname{Tr}\{\rho \mathcal{M}\} \tag{6.1}
\end{equation*}
$$

The presence of the volume in this relation and not in (1.49) is due to our definition of the space-dependent operator in (1.48). Because the Zeeman Hamiltonian is time dependent, the density matrix, and hence the magnetization, will be time dependent. Differentiating (6.1) with respect to time and making use of (1.47), which implies $d \rho / d t=0$, we obtain

$$
\begin{equation*}
\frac{d \boldsymbol{M}}{d t}=-\frac{i}{\hbar V} \operatorname{Tr}\{\rho[\mathcal{M}, \mathcal{H}]\} \tag{6.2}
\end{equation*}
$$

For the present let us assume that the Hamiltonian consists of a part which commutes with $\boldsymbol{\mathcal { M }}$ plus a Zeeman part

$$
\begin{equation*}
\mathcal{H}_{Z}=-\mathcal{M} \cdot \boldsymbol{H} . \tag{6.3}
\end{equation*}
$$

Equation (6.2) then becomes

$$
\begin{equation*}
\frac{d \boldsymbol{M}}{d t}=-\gamma \boldsymbol{M} \times \boldsymbol{H} \tag{6.4}
\end{equation*}
$$

where $\gamma \hbar=g \mu_{B}$. The minus sign arises because we are explicitly dealing with electrons which have a negative gyromagnetic ratio.

If the dynamic field $\boldsymbol{H}_{1}(t)=\boldsymbol{H}_{1} \cos \omega t$ is applied in the $z$ direction, then, according to (6.4), it exerts no torque on the equilibrium magnetization $M_{0} \hat{\boldsymbol{z}}$. Therefore the response to such a field is 0 . This raises an interesting point. If the frequency $\omega$ goes to 0 , (6.4) tells us that there is no response to such a static field. But in Chap. 3 we found that the magnetization does respond to a static field, with the resulting magnetization given by Curie's law. The answer to this paradox lies in the fact that in Chap. 3 we assumed that the spin system was always in equilibrium. This implies that there is a coupling between the individual spins and their environment which enables them to reach equilibrium. The time it might take the spin system to do this is not important in the static case, since we can always keep the field on until equilibrium has been achieved. In the dynamic case, however, this assumption is not valid, since we may want the response at a frequency that is much faster than this relaxation frequency. In fact, this is generally the experimental situation. In the dynamic case we must actually solve for the nonequilibrium density matrix. We shall see later that the only way to get a response in the $z$ direction is to introduce a relaxation mechanism (see Problem 6.1).

Let us now consider a system which has come to equilibrium in an applied $d c$-field, $H_{0}$, and ask what the response will be to a time-varying transverse field $\boldsymbol{H}_{1}$. In particular, let $\boldsymbol{H}_{1}(t)=H_{1}(t) \hat{\boldsymbol{x}}$. If we write the magnetization as

$$
\begin{equation*}
\boldsymbol{M}=m_{x} \hat{\boldsymbol{x}}+m_{y} \hat{\boldsymbol{y}}+\left(M_{0}-m_{z}\right) \hat{\boldsymbol{z}} . \tag{6.5}
\end{equation*}
$$

(6.4) becomes, in component form,

$$
\begin{align*}
\frac{d m_{x}}{d t} & =-\gamma H_{0} m_{y}  \tag{6.6a}\\
\frac{d m_{y}}{d t} & =-\gamma H_{1}(t)\left(M_{0}-m_{z}\right)+\gamma H_{0} m_{x}  \tag{6.6b}\\
\frac{d m_{z}}{d t} & =-\gamma H_{1}(t) m_{y} \tag{6.6c}
\end{align*}
$$

These equations are nonlinear. As a consequence, magnetic systems exhibit a number of interesting features, such as "spin echoes", which we shall discuss
later. For the present, let us linearize (6.6) by neglecting terms which are quadratic in $H_{1}$ or the components of $\boldsymbol{m}$. The result is

$$
\begin{align*}
\frac{d m_{x}}{d t} & =-\omega_{0} m_{y}  \tag{6.7a}\\
\frac{d m_{y}}{d t} & =-\gamma H_{1}(t) M_{0}+\omega_{0} m_{x}  \tag{6.7b}\\
\frac{d m_{z}}{d t} & =0 \tag{6.7c}
\end{align*}
$$

where $\omega_{0} \equiv \gamma H_{0}$.
We see from (6.7c) than $m_{z}$ is a constant. Since $[\mathcal{M} \cdot \boldsymbol{\mathcal { M }}, \boldsymbol{\mathcal { M }} \cdot \boldsymbol{H}]=0$, this means that the magnitude of the magnetization is a conserved quantity. Therefore once $m_{x}$ and $m_{y}$ are known, $m_{z}$ may be obtained from the condition that

$$
\begin{equation*}
\mathcal{M} \cdot \mathcal{M}=M_{0}^{2} \tag{6.8}
\end{equation*}
$$

The components $m_{x}$ and $m_{y}$ may be determined from (6.7a,b). Differentiating (6.7a) with respect to time and using (6.7b), we obtain the equation for $m_{x}$,

$$
\begin{equation*}
\frac{d^{2} m_{x}}{d t^{2}}+\omega_{0}^{2} m_{x}=\gamma H_{1} \omega_{0} M_{0} \cos \omega t \tag{6.9}
\end{equation*}
$$

To find the susceptibility we must solve this differential equation. We may write it in a more general form as

$$
\begin{equation*}
\mathcal{L} m_{x}(t)=F(t) \tag{6.10}
\end{equation*}
$$

where $\mathcal{L}$ is the differential operator, in this case $d^{2} / d t^{2}+\omega_{0}^{2}$. The solution is then given symbolically by

$$
\begin{equation*}
m_{x}(t)=\mathcal{L}^{-1} F(t) \tag{6.11}
\end{equation*}
$$

where $\mathcal{L}^{-1}$ is the operator inverse of $\mathcal{L}$, provided that is exists. It is customary to rewrite this as

$$
\begin{equation*}
m_{x}(t)=\int_{-\infty}^{\infty} d t^{\prime} \mathcal{L}^{-1} F\left(t^{\prime}\right) \delta\left(t-t^{\prime}\right)=\int_{-\infty}^{\infty} d t^{\prime} \mathcal{G}\left(t, t^{\prime}\right) F\left(t^{\prime}\right) \tag{6.12}
\end{equation*}
$$

where $\mathcal{G}\left(t, t^{\prime}\right)$ is the Green's function of the differential operator $\mathcal{L}$, defined as $\mathcal{L}^{-1}$ operating on the delta function.

A very important relationship between the Green's function and the susceptibility is easily obtained from (6.12). Taking the Fourier transform, we have

$$
\begin{equation*}
m_{x}(\omega)=\int_{-\infty}^{\infty} d t \int_{-\infty}^{\infty} d t^{\prime} \mathcal{G}\left(t, t^{\prime}\right) F\left(t^{\prime}\right) e^{i \omega t} \tag{6.13}
\end{equation*}
$$

If the medium is stationary, it can be shown that the Green's function depends only on the relative time $t-t^{\prime}$. Inserting the factor $\exp \left(-i \omega t^{\prime}\right) \exp \left(i \omega t^{\prime}\right)$ in (6.13), we obtain

$$
\begin{equation*}
m_{x}(\omega)=\int_{-\infty}^{\infty} d t \int_{-\infty}^{\infty} d t^{\prime} \mathcal{G}\left(t-t^{\prime}\right) e^{i \omega\left(t-t^{\prime}\right)} F\left(t^{\prime}\right) e^{i \omega t^{\prime}} . \tag{6.14}
\end{equation*}
$$

Converting the integral over $t$ into the integral over $\tau \equiv t-t^{\prime}$ and recalling our definition of the susceptibility (1.58), we obtain

$$
\begin{equation*}
\chi_{x x}(\omega)=\gamma M_{0} \omega_{0} \mathcal{G}(\omega) \tag{6.15}
\end{equation*}
$$

The factor $\gamma M_{0} \omega_{0}$ arises because the forcing function $F(t)$ differs from the applied field by this quantity. The important result is that the Fourier transform of the Green's function is, essentially, the frequency-dependent susceptibility. Notice that if the so-called double-time Green's function defined on page 18 is introduced into equation (1.81), we obtain (6.15) directly, aside from the proportionality factor. This should not be surprising, for both Green's functions represent the linear response to a time-dependent magnetic field.

Let us now evaluate the Green's function. This is easily done by using the integral representation for the delta function.

$$
\delta\left(t-t^{\prime}\right)=\frac{1}{2 \pi} \int_{-\infty}^{\infty} d \omega e^{-i \omega\left(t-t^{\prime}\right)}
$$

Thus

$$
\begin{equation*}
\mathcal{G}\left(t-t^{\prime}\right)=\mathcal{L}^{-1} \delta\left(t-t^{\prime}\right)=\frac{1}{2 \pi} \int_{-\infty}^{\infty} d \omega \frac{e^{i \omega\left(t-t^{\prime}\right)}}{-\omega^{2}+\omega_{0}^{2}} \tag{6.16}
\end{equation*}
$$

This integral is not defined until we specify how to treat the singularity at $\omega=$ $\omega_{0}$. To resolve this difficulty we invoke causality and require that $\mathcal{G}\left(t-t^{\prime}\right)=0$ for $t<t^{\prime}$. This enables us to evaluate (6.16) unambiguously. The result is

$$
\begin{equation*}
\mathcal{G}\left(t-t^{\prime}\right)=\frac{\sin \omega_{0}\left(t-t^{\prime}\right)}{\omega_{0}} \theta\left(t-t^{\prime}\right) \tag{6.17}
\end{equation*}
$$

where $\theta\left(t-t^{\prime}\right)$ is 0 for $t<t^{\prime}$ and 1 for $t>t^{\prime}$. Taking the Fourier transform of (6.17) and multiplying the result by $\gamma M_{0} \omega_{0}$, we finally obtain

$$
\begin{equation*}
\chi_{x x}(\omega)=\frac{\gamma M_{0} \omega_{0}}{\omega_{0}^{2}-\omega^{2}}+i \frac{\pi \gamma M_{0}}{2}\left[\delta\left(\omega-\omega_{0}\right)-\delta\left(\omega+\omega_{0}\right)\right] \tag{6.18}
\end{equation*}
$$

It is interesting to note that the real part of this susceptibility comes from the particular solution to (6.9), while the imaginary part, which is necessary to satisfy causality, comes from the solutions of the homogeneous version of (6.9). It is easily demonstrated that (6.18) satisfies the Kramers-Kronig relations (1.64), (1.65).


Fig. 6.1. The excitation spectrum of a system of uncoupled spins

The power absorbed by the magnetic system from this time-varying source is given by

$$
\begin{equation*}
P=\overline{-\boldsymbol{M} \cdot \frac{d \boldsymbol{H}_{1}(t)}{d t}}, \tag{6.19}
\end{equation*}
$$

where the bar indicates a time average. From (1.55),

$$
\begin{equation*}
M_{x}(t)=H_{1}\left[\chi_{x x}^{\prime}(\omega) \cos \omega t+\chi_{x x}^{\prime \prime}(\omega) \sin \omega t\right] \tag{6.20}
\end{equation*}
$$

and so (6.19) becomes

$$
\begin{equation*}
P=\frac{1}{2} \omega H_{1}^{2} \chi_{x x}^{\prime \prime}(\omega) . \tag{6.21}
\end{equation*}
$$

From (6.18) we see that the power absorption of our noninteracting magnetic system occurs only at the frequency $\omega_{0}=\gamma H_{0}$. Furthermore, this response will be infinite. In reality, of course, interactions within the system make this response finite and spread it over a distribution of frequencies. It is the determination of this response function to which we now address ourselves.

The poles in the complex response function define the excitation spectrum associated with the system. The real part of the pole gives the frequency of the excitation, and the imaginary part gives its damping. If the poles move too far from the real axis, the concept of an excitation is less well defined. Since we are dealing here with noninteracting localized moments, these poles are independent of wave vector. Therefore the excitation spectrum is as indicated in Fig. 6.1.

### 6.2 The Bloch Equations

If the magnetization is excited to a nonequilibrium value under the influence of an external field, when the field is suddenly removed the magnetization will relax back to its equilibrium value. The details of the relaxation depend on the nature of the interactions in the system. However, if we assume that this
relaxation, whatever its origin, has an exponential form, then we can develop a phenomenological description of the response function. In general, the longitudinal and transverse components of the magnetization may relax with different rates. The equations of motion, called the Bloch equations, are [128]

$$
\begin{align*}
\frac{d m_{z}}{d t} & =-\gamma(\boldsymbol{M} \times \boldsymbol{H})_{z}-\frac{m_{z}}{T_{1}}  \tag{6.22a}\\
\frac{d m_{x, y}}{d t} & =-\gamma(\boldsymbol{M} \times \boldsymbol{H})_{x, y}-\frac{m_{x, y}}{T_{2}} \tag{6.22b}
\end{align*}
$$

If we again assume a driving field of the form $\boldsymbol{H}_{1}(t)=H_{1} \cos (\omega t) \hat{\boldsymbol{x}}$, the linearized equation for $m_{x}$ is

$$
\begin{equation*}
\frac{d^{2} m_{x}}{d t^{2}}+\frac{2}{T_{2}} \frac{d m_{x}}{d t}+\left(\omega_{0}^{2}+\frac{1}{T_{2}^{2}}\right) m_{x}=\gamma H_{1} \omega_{0} M_{0} \cos \omega t \tag{6.23}
\end{equation*}
$$

By assuming that $m_{\nu}$ relaxes to 0 we have essentially incorporated causality into our solution, for the poles which enter the expression for the Green's function associated with this system, analogous to (6.16), are now displaced off the real axis, as shown in Fig. 6.2. Thus we speak of the susceptibility as being analytic in the upper half of the complex plane. The Green's function is then

$$
\begin{equation*}
\mathcal{G}\left(t-t^{\prime}\right)=\frac{\sin \omega_{0}\left(t-t^{\prime}\right)}{\omega_{0}} e^{-\left(t-t^{\prime}\right) / T_{2}} \theta\left(t-t^{\prime}\right) \tag{6.24}
\end{equation*}
$$

Taking the Fourier transform leads us to

$$
\begin{equation*}
\chi_{x x}(\omega)=\chi_{x x}^{\prime}(\omega)+i \chi_{x x}^{\prime \prime}(\omega) \tag{6.25}
\end{equation*}
$$

where

$$
\begin{equation*}
\chi_{x x}^{\prime}(\omega)=\frac{1}{2} \gamma M_{0}\left[\frac{\omega_{0}-\omega}{\left(\omega_{0}-\omega\right)^{2}+\left(1 / T_{2}\right)^{2}}+\frac{\omega+\omega_{0}}{\left(\omega+\omega_{0}\right)^{2}+\left(1 / T_{2}\right)^{2}}\right] \tag{6.26}
\end{equation*}
$$

and

$$
\begin{equation*}
\chi_{x x}^{\prime \prime}(\omega)=\frac{\gamma M_{0}}{2 T_{2}}\left[\frac{1}{\left(\omega_{0}-\omega\right)^{2}+\left(1 / T_{2}\right)^{2}}-\frac{1}{\left(\omega_{0}+\omega\right)^{2}+\left(1 / T_{2}\right)^{2}}\right] . \tag{6.27}
\end{equation*}
$$

As $1 / T_{2}$ becomes very small the functions in (6.27) become higher and narrower in such a way as to maintain their area. Therefore, in the limit $1 / T_{2} \rightarrow 0$, they may be considered as representations of delta functions; that is,

$$
\begin{equation*}
\lim _{\epsilon \rightarrow 0} \frac{\epsilon}{x^{2}+\epsilon^{2}}=\pi \delta(x) \tag{6.28}
\end{equation*}
$$



Fig. 6.2. Location of the poles in the imaginary part of the susceptibility


Fig. 6.3. Plot of the real and imaginary parts of the susceptibility, $\chi_{x x}(\omega)$
and (6.26), (6.27) reduce to our previous result (6.18). The real and imaginary part of the susceptibility are shown in Fig. 6.3.

Let us keep in mind that we are dealing with the response to a linearly polarized driving field. Some experiments employ a circularly polarized field. In such cases the response involves the other components of the susceptibility. For example, consider the circularly polarized field

$$
\boldsymbol{H}_{1}(t)=H_{1} \cos (\omega t) \hat{\boldsymbol{x}}+H_{1} \sin (\omega t) \hat{\boldsymbol{y}} .
$$

When $\omega$ is positive this corresponds to counter-clockwise rotation. This is the direction $\boldsymbol{M}$ precesses in the presence of the dc field $H_{0} \hat{\boldsymbol{z}}$. From (1.55), the responses in the $x$ and $y$ directions to such a field may be written as

$$
\begin{aligned}
& m_{x}(t)=2 \pi H_{1}\left[\left(\chi_{x x}^{\prime}(\omega)-\chi_{x y}^{\prime \prime}(\omega)\right) \cos \omega t+\left(\chi_{x x}^{\prime \prime}(\omega)+\chi_{x y}^{\prime}(\omega)\right) \sin \omega t\right] \\
& m_{y}(t)=2 \pi H_{1}\left[\left(\chi_{y x}^{\prime}(\omega)-\chi_{y y}^{\prime \prime}(\omega)\right) \cos \omega t+\left(\chi_{y x}^{\prime \prime}(\omega)+\chi_{y y}^{\prime}(\omega)\right) \sin \omega t\right]
\end{aligned}
$$

Solving (6.22a,b) for $m_{y}$ leads to the results

$$
\begin{aligned}
& \chi_{y x}^{\prime}(\omega)=-\frac{\gamma M_{0}}{2 T_{2}}\left[\frac{1}{\left(\omega_{0}-\omega\right)^{2}+\left(1 / T_{2}\right)^{2}}+\frac{1}{\left(\omega+\omega_{0}\right)^{2}+\left(1 / T_{2}\right)^{2}}\right] \\
& \chi_{y x}^{\prime \prime}(\omega)=\frac{\gamma M_{0}}{2}\left[\frac{\omega_{0}-\omega}{\left(\omega_{0}-\omega\right)^{2}+\left(1 / T_{2}\right)^{2}}-\frac{\omega_{0}+\omega}{\left(\omega+\omega_{0}\right)^{2}+\left(1 / T_{2}\right)^{2}}\right]
\end{aligned}
$$

If a field is applied in the $y$ direction, the equation for $m_{y}$ is identical to (6.23). Therefore $\chi_{y y}=\chi_{x x}$. However, $\chi_{x y}=-\chi_{y x}$. Combining these results, we find that the rotational component $m_{+}=m_{x}+i m_{y}$ has the solution

$$
m_{+}(t)=\left(\chi_{+}^{\prime}(\omega)+i \chi_{+}^{\prime \prime}(\omega)\right) H_{1} e^{i \omega t}
$$

where

$$
\begin{align*}
\chi_{+}^{\prime}(\omega) & =\gamma M_{0} \frac{\omega_{0}-\omega}{\left(\omega-\omega_{0}\right)^{2}+\left(1 / T_{2}\right)^{2}} \quad \text { and }  \tag{6.29a}\\
\chi_{+}^{\prime \prime}(\omega) & =-\frac{\gamma M_{0}}{T_{2}} \frac{1}{\left(\omega-\omega_{0}\right)^{2}+\left(1 / T_{2}\right)^{2}} \equiv-\pi \gamma M_{0} f_{L}(\omega) . \tag{6.29b}
\end{align*}
$$

Figure 6.4 shows the power absorbed as predicted by the Bloch equation for a circularly polarized field. While the Bloch equations offer a nice description of resonance the form given in $(6.22 \mathrm{a}, \mathrm{b})$ has an interesting unphysical consequence. Namely, if we drive the system in the clockwise (anti-Larmor) direction the power absorption becomes negative! The reason for this is that in $(6.22 \mathrm{a}, \mathrm{b})$ the magnetization relaxes to the $z$-direction, i.e., the transverse components relax to zero. But, in reality, the magnetization should relax to the direction of the instantaneous field $\boldsymbol{H}_{0}+\boldsymbol{H}_{1}(t)$.

The line shape $f_{L}(\omega)$ defined by (6.29b) is the familiar Lorentzian curve. This shape reflects the fact that it is the lifetime of the quantum states participating in the transition, in this case the Zeeman levels, that govern the profile. It is often found experimentally that the shape of the absorption more nearly resembles the Gaussian function

$$
\begin{equation*}
f_{G}(\omega)=\frac{1}{\Delta \sqrt{2 \pi}} e^{-\left(\omega-\omega_{0}\right)^{2} / 2 \Delta^{2}} \tag{6.30}
\end{equation*}
$$



Fig. 6.4. Frequency response to a circularly polarized field ( $H_{1}=0.0141 \omega_{0} / \gamma$ ) (Courtesy of Jian-gang Zhu)


Fig. 6.5. Coordinate system rotating at a rate $\omega$ showing that the $d c$ field is reduced by $\omega / \gamma$
where $\Delta$ characterizes the width of the Gaussian. The appearance of such a shape is the result of inhomogeneous broadening. That is, the moments find themselves in different fields which give rise to a distribution of resonant frequencies. In general, the absorption may have some arbitrary shape $f(\omega)$. This shape tells us a great deal about the dynamics of the magnetic system. Adiabatic Rapid Passage. This discussion of susceptibility has been based on linearized equations which result in $m_{z}$ being constant. The Bloch equations $(6.22 \mathrm{a}, \mathrm{b})$, however, contain a rich variety of solutions. For example, in the expressions above we have assumed that the frequency of the driving field is fixed. Experimentally, however, one generally studies the resonance in a magnetic system by sweeping the value of the frequency or, equivalently, the $d c$ field $\boldsymbol{H}_{0}$. This raises the question as to the relationship between the sweep rate and the relaxation times in the Bloch equations. Suppose, for example, we wish to reverse the magnetization by using resonance. We apply a circularlypolarized field and sweep through the resonance. This is most conveniently described by using the rotating coordinate system shown in Fig. 6.5. In this frame the total field is

$$
\boldsymbol{H}_{t}=\left(\boldsymbol{H}_{0}-\frac{\omega}{\gamma}\right)+\boldsymbol{H}_{1} .
$$

Suppose we start at a frequency $\omega \ll \gamma H_{0}$. Then $\boldsymbol{H}_{t}$ is largely aligned with $\boldsymbol{H}_{0}$. As we increase $\omega, \boldsymbol{H}_{t}$ rotates out away from $\boldsymbol{H}_{0}$. The magnetization $\boldsymbol{M}$ will process around $\boldsymbol{H}_{t}$ at a rate $\gamma H_{t}$. If we want $\boldsymbol{M}$ to follow $\boldsymbol{H}_{t}$ in a tight spiral, then the sweep rate, $d \theta / d t$, must be slow compared to $\gamma \boldsymbol{H}_{t}$. The smallest value of $\gamma \boldsymbol{H}_{t}$ occurs at resonance (i.e., $\boldsymbol{H}_{t}=\boldsymbol{H}_{1}$ ). Therefore this condition becomes

$$
\frac{1}{\boldsymbol{H}_{1}} \frac{d \boldsymbol{H}_{0}}{d t} \ll \gamma \boldsymbol{H}_{1} .
$$

When this condition holds we say that the motion is adiabatic. On the other hand, the sweep rate must be faster than the time it takes for the magnetization to relax back to its equilibrium direction along $\boldsymbol{H}_{0}, T_{1}$, i.e.

$$
\frac{1}{\boldsymbol{H}_{1}} \frac{d \boldsymbol{H}_{0}}{d t} \gg \frac{1}{T_{1}}
$$

These conditions define "adiabatic rapid passage", the technique used by Bloch, Hansen, and Packard [129a] in their historic demonstration of nuclear induction.

Precessional Switching. The value of $T_{1}$ for the nuclear spins associated with the protons in water is approximately 3 seconds. Therefore it is relatively easy to reverse the nuclear magnetization by sweeping the field $\boldsymbol{H}_{0}$ in the presence of an rf field. Bloembergen [129b] pointed out that Bloch's equations, which Bloch developed with nuclear moments in mind, apply equally well to electronic moments, particularly those in a ferromagnet where they are exchange-coupled together to form a macroscopic magnetization, M. For electron spins, however, $T_{1}$ is very short, making it much more difficult to satisfy the adiabatic rapid passage conditions. It is, nevertheless, possible to exploit the gyromagnetic nature of the Bloch equations to reverse the magnetization of a ferromagnet. This is done by applying a dc field, $H_{\text {pulse }}$, at right angles to the magnetization for a time equal to half a precessional cycle. Consider a thin magnetic film initially magnetized in the plane of the film. The field $H_{\text {pulse }}$ applied in the plane of the film at a right angle to the magnetization causes the magnetization to tip up out of the plane. This produces a relatively large demagnetization field which causes the magnetization to precess in a conical path. Such a "quasiballistic" magnetization reversal has been observed in a film of $\mathrm{CoFe}(4 \pi \mathrm{M}=10,800 \mathrm{oe})$ with a pulse having an amplitude of 81 oe and a duration of 175 psec [129c].

### 6.3 Resonance Line Shape

The shape of the resonance contains information about the interactions which govern the time dependence of the system. There are two approaches that have been very fruitful in understanding the nature of the magnetic-resonance line shape. One is the method of moments, which was employed so successfully by Van Vleck [130]. The other is what we might call the relaxation-function method, developed by Kubo and Tomito [131]. These approaches enable us to relate the phenomenological description given in the previous section to the microscopic physics.

### 6.3.1 The Method of Moments

If the resonance curve is described by a normalized shape function $f(\omega)$ centered at $\omega_{0}$, then the $n$th moment with respect to $\omega_{0}$ is defined by

$$
\begin{equation*}
M_{n}=\int_{-\infty}^{\infty}\left(\omega-\omega_{0}\right)^{n} f(\omega) d \omega . \tag{6.31}
\end{equation*}
$$

If the function $f(\omega)$ is symmetric about $\omega_{0}$, it is convenient to introduce the function $F(\Omega)=f\left(\omega_{0}+\Omega\right)$. In terms of this function, the $n$th moment is

$$
\begin{equation*}
M_{n}=\int_{-\infty}^{\infty}(\Omega)^{n} F(\Omega) d \Omega . \tag{6.32}
\end{equation*}
$$

If $\Gamma(t)$ is the Fourier transform of $F(\Omega)$,

$$
\begin{equation*}
\Gamma(t)=\int_{-\infty}^{\infty} F(\Omega) e^{-i \Omega t} d \Omega=2 \int_{0}^{\infty} F(\Omega) \cos (\Omega t) d \Omega, \tag{6.33}
\end{equation*}
$$

then the $2 n$th moment may be written as

$$
\begin{equation*}
M_{2 n}=\left.(-1)^{n} \frac{d^{2 n} \Gamma(t)}{d t^{2 n}}\right|_{t=0} \tag{6.34}
\end{equation*}
$$

In order to obtain an explicit expression for the $2 n$th moment let us assume that the width of the absorption at $\omega_{0}$ is much less than $\omega_{0}$ itself. We may then approximate the shape function by $\chi^{\prime \prime}(\omega) / \omega$. Let us also make the high-temperature approximation $g \mu_{B} H \ll k_{B} T$. With this approximation the correlation function introduced in Sect. 1.3.2 becomes [132]

$$
\begin{equation*}
\left\langle\mathcal{M}_{x}(t) \mathcal{M}_{x}\right\rangle \rightarrow \frac{\operatorname{Tr}\left\{\mathcal{M}_{x}(t) \mathcal{M}_{x}\right\}}{\operatorname{Tr}\{1\}} \equiv G(t) . \tag{6.35}
\end{equation*}
$$

Under these conditions the fluctuation-dissipation theorem (1.87) reduces to

$$
\begin{equation*}
\left\langle\mathcal{M}_{x}(t) \mathcal{M}_{x}\right\rangle=\frac{k_{B} T}{\pi} \int_{-\infty}^{\infty} d \omega \frac{\chi_{x x}^{\prime \prime}(\omega)}{\omega} e^{-i \omega t} \tag{6.36}
\end{equation*}
$$

Therefore, since $\chi^{\prime \prime}(\omega) / \omega$ is proportioned to the lineshape $f(\omega)$,

$$
\begin{equation*}
G(t)=C \int_{0}^{\infty} d \omega f(\omega) \cos \omega t \tag{6.37}
\end{equation*}
$$

where $C$ is the coefficient of proportionality. This may be rewritten as

$$
\begin{equation*}
G(t)=C \int_{-\omega_{0}}^{\infty} d \Omega F(\Omega) \cos \left(\omega_{0}+\Omega\right) t \tag{6.38}
\end{equation*}
$$

If $F(\Omega)$ falls to 0 by the time $\Omega$ reaches $-\omega_{0}$, so that the lower limit may be extended to $-\infty$, then

$$
\begin{equation*}
G(t)=\left[2 C \int_{0}^{\infty} d \Omega F(\Omega) \cos \Omega t\right] \cos \omega_{0} t=G_{1}(t) \cos \omega_{0} t \tag{6.39}
\end{equation*}
$$

Therefore

$$
\begin{equation*}
M_{2 n}=\left.\frac{(-1)^{n}}{G_{1}(0)} \frac{d^{2 n} G_{1}(t)}{d t^{2 n}}\right|_{t=0} \tag{6.40}
\end{equation*}
$$

Differentiating (6.35), (6.39), we obtain the explicit expressions for the second and fourth moments,

$$
\begin{align*}
& M_{2}=-\frac{\operatorname{Tr}\left\{\left[\mathcal{H}, \mathcal{M}_{x}\right]^{2}\right\}}{\hbar^{2} \operatorname{Tr}\left\{\mathcal{M}_{x}^{2}\right\}},  \tag{6.41}\\
& M_{4}=\frac{\operatorname{Tr}\left\{\left[\mathcal{H},\left[\mathcal{H}, \mathcal{M}_{x}\right]^{2}\right\}\right.}{\hbar^{4} \operatorname{Tr}\left\{\mathcal{M}_{x}^{2}\right\}}-6 \omega_{0}^{2} M_{2}-\omega_{0}^{4} \tag{6.42}
\end{align*}
$$

Let us consider what these moments would be for Lorentizian and Gaussian lines. Consider first the normalized Gaussian given by (6.30). From definition (6.31) we find

$$
\begin{equation*}
M_{2}=\Delta^{2} \quad \text { and } \quad M_{4}=3 \Delta^{4} \tag{6.43}
\end{equation*}
$$

The halfwidth $\Delta \omega$, as defined by $f_{G}\left(\omega_{0}+\Delta \omega\right)=\frac{1}{2} f_{G}\left(\omega_{0}\right)$, is

$$
\begin{equation*}
\Delta \omega=\sqrt{2 \ln 2} \Delta=1.18 \Delta \tag{6.44}
\end{equation*}
$$

Therefore the square root of the second moment gives a good approximation to the width of a Gaussian line.

Now consider the normalized Lorentzian,

$$
\begin{equation*}
f_{L}(\omega)=\frac{1}{\pi T_{2}} \frac{1}{\left(\omega-\omega_{0}\right)^{2}+\left(1 / T_{2}\right)^{2}} \tag{6.45}
\end{equation*}
$$

The integrals for the second and higher moments diverge for this function. Therefore a cutoff is usually introduced at $\left|\omega-\omega_{0}\right|=\omega_{m}$. The moments are then given by

$$
\begin{equation*}
M_{2}=\frac{2 \omega_{m}}{\pi T_{2}} \quad \text { and } \quad M_{4}=\frac{2 \omega_{m}^{3}}{3 \pi T_{2}} \tag{6.46}
\end{equation*}
$$

Notice that

$$
\frac{M_{4}}{M_{2}^{2}}=\left\{\begin{array}{c}
3 \text { for a Gaussian }  \tag{6.47}\\
\frac{\pi \omega_{m} T_{2}}{6} \text { for a cutoff Lorentzian }
\end{array}\right.
$$

If we compute this ratio using (6.41) and (6.42) for some relaxation process defined by $\mathcal{H}$ and find that the result is very large, we suspect the line shape will be Lorentzian, whereas if the result is near 3, the line shape will be closer to a Gaussian.

The problem to which Van Vleck addressed himself was that of a system of magnetic moments located in an external field and interacting weakly through
both the dipole-dipole interaction (2.50) and the exchange interaction (2.89). Thus the system is characterized by the Hamiltonian

$$
\begin{equation*}
\mathcal{H}=\mathcal{H}_{Z}+\mathcal{H}_{\mathrm{dip}}+\mathcal{H}_{\mathrm{ex}} \tag{6.48}
\end{equation*}
$$

Notice that the last three terms in (2.50) have matrix elements between states of the system in which the total magnetic quantum number is changed by $\pm 1$ and $\pm 2$. These terms lead to transitions which are separated from the main resonance by multiples of $g \mu_{B} H_{0}$ and appear as sidebands on the main Zeeman line at $g \mu_{B} H_{0}$. As long as the sidebands do not overlap our main line, we may neglect the last three terms in (2.50), in so far as we are concerned only with the main line. The truncated Hamiltonian is thus

$$
\begin{equation*}
\mathcal{H}=\mathcal{H}_{Z}+\mathcal{H}_{\mathrm{dip}}^{\prime}+\mathcal{H}_{\mathrm{ex}} \tag{6.49}
\end{equation*}
$$

where

$$
\begin{equation*}
\mathcal{H}_{\mathrm{dip}}^{\prime}=g^{2} \mu_{B}^{2} \sum_{i, j \neq i}\left[-\frac{3 \cos ^{2} \theta_{i j}-1}{r_{i j}^{3}} S_{i}^{z} S_{j}^{z}+\frac{3 \cos ^{2} \theta_{i j}-1}{4 r_{i j}^{3}}\left(S_{i}^{+} S_{j}^{-}+S_{i}^{-} S_{j}^{+}\right)\right] \tag{6.50}
\end{equation*}
$$

Since

$$
\mathcal{M}_{x}=-g \mu_{B} \sum_{i} S_{i}^{x} \quad \text { and } \quad \mathcal{H}_{Z}=g \mu_{B} H \sum_{i} S_{i}^{z}
$$

we find that

$$
\begin{equation*}
\left[\mathcal{H}_{Z}, \mathcal{M}_{x}\right]=i \hbar \omega_{0} \mathcal{M}_{y} \tag{6.51}
\end{equation*}
$$

It is also easy to show that $\left[\mathcal{H}_{\mathrm{ex}}, \mathcal{M}_{x}\right]=0$. Therefore the second moment reduces to

$$
\begin{equation*}
M_{2}=-\frac{\operatorname{Tr}\left\{\left[\mathcal{H}_{\mathrm{dip}}^{\prime}, \mathcal{M}_{x}\right]^{2}\right\}}{\hbar^{2} \operatorname{Tr}\left\{\mathcal{M}_{x}^{2}\right\}} \tag{6.52}
\end{equation*}
$$

To evaluate the traces Van Vleck used the fact that the trace is independent of the basis. Therefore, even though this is truly a many-body system, we may use a basis consisting of products of individual spin states, $\left|M_{S_{1}}, M_{S_{2}}, \ldots\right\rangle$. We can then readily carry out the traces and find that

$$
\begin{equation*}
M_{2}=\frac{3}{4} \frac{g^{4} \mu_{B}^{4}}{\hbar^{2}} S(S+1) \sum_{i} \frac{\left(1-3 \cos ^{2} \theta_{i j}\right)^{2}}{r_{i j}^{6}} . \tag{6.53}
\end{equation*}
$$

If the sample consists of randomly oriented crystallites, then the angular part of (6.53) averages to $\frac{4}{5}$. Furthermore, if we have a moment at every site in a simple cubic lattice with a lattice parameter $a$, then

$$
\sum_{i} \frac{1}{r_{i j}^{6}}=\frac{8.32}{a^{6}} \quad \text { and } \quad M_{2}=\frac{5 \mu^{4} S(S+1)}{\hbar^{2} a^{6}}
$$

For nuclear moments separated by, say $3 \AA$, the corresponding line width $\Delta H=\sqrt{M_{2}} \gamma_{N}$ is about 6 gauss, which is in reasonable agreement with observations in nuclear magnetic-resonance experiments. For electronic moments, however, this line width is about 5 kG . This is enormous. But when we have electronic moments as close as $3^{\circ} \AA$, the exchange interaction becomes very important, and the second moment, which does not contain exchange effects, is not sufficient to describe the situation. In particular, for a Lorentzian line (6.46) gives

$$
\begin{equation*}
\frac{1}{T_{2}}=\frac{\pi M_{2}}{2} \sqrt{\frac{M_{2}}{3 M_{4}}} . \tag{6.54}
\end{equation*}
$$

To study the effects of exchange Van Vleck also computed the fourth moment. What he found was that when the exchange interaction exceeds the dipoledipole interaction, the fourth moment exceeds the square of the second moment. Equation (6.47) then tells us that as the exchange interaction increases, the shape of the absorption line changes from Gaussian to Lorentzian. Furthermore, if the fourth moment increases while the second moment remains unchanged, the intensity in the wings of the absorption curve increases. If the total integrated intensity is to remain the same, there must be a decrease in intensity closer to the center of the line. This results in what is called exchange narrowing, illustrated in Fig. 6.6. The origin of this narrowing may be better understood by considering the effective field acting on a particular spin. In the absence of any exchange, this spin experiences not only the applied field $\boldsymbol{H}_{0}$, but also a dipolar field arising from the other spins in its environment. Since each spin experiences a slightly different environment, this leads to a distribution of resonant frequencies which manifests itself as an inhomogeneously broadened absorption. The effect of the exchange interaction is to modulate the dipolar field. As this modulation increases the average dipolar field decreases, with the result that the distribution of resonant frequencies peaks more strongly near $\omega_{0}$.

### 6.3.2 The Relaxation-Function Method

Guided by this interpretation of the results of the moment calculations, let us now outline the relaxation-function approach to obtain the detailed shape of the resonance curve. Our discussion follows that of Abragam [133]. Since we are assuming that the absorption spectrum is proportional to $\chi^{\prime \prime}(\omega) / \omega$, we must compute the high-temperature correlation function introduced in (6.35),

$$
\begin{equation*}
G(t)=\frac{\operatorname{Tr}\left\{\mathcal{M}_{x}(t) \mathcal{M}_{x}\right\}}{\operatorname{Tr}\{1\}} . \tag{6.55}
\end{equation*}
$$



Fig. 6.6. Schematic represenation of exchange narrowing. The arrows indicate the transfer of intensity

We shall not include the exchange interaction explicitly, but shall merely assume that it leads to a time-dependent dipolar interaction. The total Hamiltonian is then $\mathcal{H}=\mathcal{H}_{Z}+\mathcal{H}_{\text {dip }}$. The dipole-dipole interaction is assumed to be small in comparison with the Zeeman interaction. Therefore we look for a solution to $\mathcal{M}_{x}(t)$ which is an expansion in powers of the dipoledipole interaction. This is very much different from the method of moments, which is essentially an expansion of $G(t)$ in powers of $t$.

In order to develop an expansion of $\mathcal{M}_{x}(t)$ in the dipole interaction it is convenient to remove the Zeeman interaction by the transformation

$$
\begin{equation*}
\tilde{\mathcal{M}}_{x} \equiv \exp \left(\frac{-i \mathcal{H}_{Z} t}{\hbar}\right) \mathcal{M}_{x}(t) \exp \left(\frac{i \mathcal{H}_{Z} t}{\hbar}\right) \tag{6.56}
\end{equation*}
$$

The equation of motion for this operator is

$$
\begin{equation*}
-i \hbar \frac{d \tilde{\mathcal{M}}_{x}}{d t}=\left[\exp \left(\frac{-\mathcal{H}_{Z} t}{\hbar}\right) \mathcal{H}_{\mathrm{dip}} \exp \left(\frac{i \mathcal{H}_{Z} t}{\hbar}\right), \tilde{\mathcal{M}}_{x}\right] \tag{6.57}
\end{equation*}
$$

The corresponding equation for the matrix element of $\tilde{\mathcal{M}}_{x}$ between eigenstates of $\mathcal{H}_{Z}$ is

$$
\begin{align*}
-i \hbar \frac{d}{d t}\left(\tilde{\mathcal{M}}_{x}\right)_{n n^{\prime}}= & \sum_{n^{\prime \prime}}\left\{\left(\mathcal{H}_{\text {dip }}\right)_{n n^{\prime \prime}}\left(\tilde{\mathcal{M}}_{x}\right)_{n^{\prime \prime} n^{\prime}} \exp \left[i\left(E_{n^{\prime \prime}}-E_{n}\right) t / \hbar\right]\right. \\
& \left.-\left(\tilde{\mathcal{M}}_{x}\right)_{n n^{\prime \prime}}\left(\mathcal{H}_{\mathrm{dip}}\right)_{n^{\prime \prime} n^{\prime}} \exp \left[-i\left(E_{n^{\prime \prime}}-E_{n^{\prime}}\right) t / \hbar\right]\right\} \tag{6.58}
\end{align*}
$$

Since the transformation (6.56) has removed the rapid Zeeman precession from $\tilde{\mathcal{M}}_{x}$, we may assume that remaining time dependence is relatively slow. Then, since $E_{n^{\prime \prime}}-E_{n}$ and $E_{n^{\prime \prime}}-E_{n^{\prime}}$ are multiples of $\hbar \omega_{0}$, those terms in (6.58) for which these differences are not 0 oscillate rapidly, giving a very small contribution which we shall neglect. This leaves us with matrix elements
of the form $\left(\mathcal{H}_{\text {dip }}\right)_{n n^{\prime \prime}}$ between degenerate states. We shall assume that these states are chosen such that these matrix elements vanish unless $n^{\prime \prime}=n$. Thus (6.58) reduces to

$$
\begin{equation*}
-i \hbar \frac{d}{d t}\left(\tilde{\mathcal{M}}_{x}\right)_{n n^{\prime}}=\hbar \Delta \omega(t)_{n n^{\prime}}\left(\tilde{\mathcal{M}}_{x}\right)_{n n^{\prime}} \tag{6.59}
\end{equation*}
$$

where

$$
\begin{equation*}
\hbar \Delta \omega(t)_{n n^{\prime}} \equiv\left(\mathcal{H}_{\mathrm{dip}}\right)_{n n}-\left(\mathcal{H}_{\mathrm{dip}}\right)_{n^{\prime} n^{\prime}} \tag{6.60}
\end{equation*}
$$

The time dependence of this quantity reflects the exchange modulation. That is, the exchange interaction causes the spin system to fluctuate among the degenerate states within $|n\rangle$ giving rise to different values of $\left(\mathcal{H}_{\text {dip }}\right)_{n n}$. Equation (6.59) has the solution

$$
\begin{equation*}
\left(\tilde{\mathcal{M}}_{x}\right)_{n n^{\prime}}=\left(\tilde{\mathcal{M}}_{x}\right)_{n n^{\prime}}^{0} \exp \left[i \int_{0}^{t} \Delta \omega\left(t^{\prime}\right)_{n n^{\prime}} d t^{\prime}\right] \tag{6.61}
\end{equation*}
$$

If we invert (6.56) and use the solution (6.61), the correlation function becomes

$$
\begin{equation*}
\left.G(t)=\sum_{n, n^{\prime}} \exp \left[i\left(E_{n}-E_{n^{\prime}}\right) t / \hbar\right]\left|\langle n| \mathcal{M}_{x}\right| n^{\prime}\right\rangle\left.\right|^{2} \exp \left[i \int_{0}^{t} \Delta \omega\left(t^{\prime}\right)_{n n^{\prime}} d t^{\prime}\right] \tag{6.62}
\end{equation*}
$$

Let us consider only the main absorption line, for which $E_{n}-E_{n^{\prime}}=\hbar \omega_{0}$. This restricts the sum over $n$ and $n^{\prime}$ to those pairs whose eigenvalues differ by $\hbar \omega_{0}$. If we define

$$
\begin{equation*}
\int_{0}^{t} \Delta \omega\left(t^{\prime}\right)_{n n^{\prime}} d t^{\prime} \equiv x(t) \tag{6.63}
\end{equation*}
$$

then for those states $n$ and $n^{\prime}$ which give a particular $x(t)$ we also have a corresponding value for $\left.\left|\langle n| \mathcal{M}_{x}\right| n^{\prime}\right\rangle\left.\right|^{2}$, which we write as $P[x(t)]$. Thus the correlation function may be thought of as the average of $\exp [i x(t)]$ using the probability distribution $P[x(t)]$; that is,

$$
\begin{equation*}
G(t)=e^{i \omega_{0} t} \int_{-\infty}^{\infty} d x P(x) e^{i x}=e^{i \omega_{0} t}\left\langle e^{i x}\right\rangle \tag{6.64}
\end{equation*}
$$

where $P(x)$ includes a normalizing factor as well as the matrix element appearing in (6.62).

The assumption is now made that $\Delta \omega\left(t^{\prime}\right)_{n n^{\prime}}$ is a Gaussian function of time, with a mean value given by the second moment $M_{2}$, which we computed earlier. Thus we take

$$
\begin{equation*}
\left\langle\Delta \omega(t)_{n n^{\prime}} \Delta \omega(t+\tau)_{n n^{\prime}}\right\rangle=M_{2} \psi(\tau) \tag{6.65}
\end{equation*}
$$

where $\psi(\tau)$ characterizes the fluctuations in the local dipolar field as it is randomly modulated by the exchange interaction. There is a theorem, called the central-limit theorem, which says, in effect, that if $\Delta \omega\left(t^{\prime}\right)_{n n^{\prime}}$ is a Gaussian
function, then $x(t)$, as defined by (6.63), is also a Gaussian function. This means that $P[x(t)]$ has the Gaussian form

$$
\begin{equation*}
P[x(t)]=\frac{1}{\sqrt{2 \pi\left\langle x^{2}\right\rangle}} \exp \left(-x^{2} / 2\left\langle x^{2}\right\rangle\right) . \tag{6.66}
\end{equation*}
$$

Thus

$$
\left\langle e^{i x}\right\rangle=e^{-\left\langle x^{2}\right\rangle / 2}
$$

where

$$
\begin{equation*}
\left\langle x^{2}\right\rangle=\left\langle\int_{0}^{t} d t^{\prime} \int_{0}^{t} d t^{\prime \prime} \Delta \omega\left(t^{\prime}\right)_{n n^{\prime}} \Delta \omega\left(t^{\prime \prime}\right)_{n n^{\prime}}\right\rangle=2 M_{2} \int_{0} d \tau(t-\tau) \psi(\tau) . \tag{6.67}
\end{equation*}
$$

Therefore we finally obtain the result that the correlation function whose Fourier transform gives the lineshape is given by

$$
\begin{equation*}
G(t)=e^{i \omega_{0} t} \varphi(t), \tag{6.68}
\end{equation*}
$$

where the relaxation function, $\varphi(t)$, is

$$
\begin{equation*}
\varphi(t)=\exp \left[-M_{2} \int_{0}^{t}(t-\tau) \psi(\tau) d \tau\right] \tag{6.69}
\end{equation*}
$$

The narrowing process may be seen from this expression. If the correlation time that characterizes $\psi(\tau)$ is long, then $\psi(\tau) \simeq 1$ over the range of the integral in (6.69) and

$$
\begin{equation*}
\varphi(t) \rightarrow \exp \left(-M_{2} t^{2} / 2\right) \tag{6.70}
\end{equation*}
$$

This leads to a Gaussian line with the Van Vleck second moment. If, on the other hand, $\psi(\tau)$ decays before we reach the upper limit of the integral, then

$$
\begin{equation*}
M_{2} \int_{0}^{t}(t-\tau) \psi(\tau) d \tau \simeq M_{2} t \int_{0}^{\infty} \psi(\tau) d \tau \equiv M_{2} t / \omega_{\mathrm{ex}} \tag{6.71}
\end{equation*}
$$

and

$$
\begin{equation*}
\varphi(t) \rightarrow \exp \left(-M_{2} t / \omega_{\mathrm{ex}}\right) . \tag{6.72}
\end{equation*}
$$

This leads to a Lorentzian line with a halfwidth proportional of $M_{2} / \omega_{\text {ex }}$. Thus as the exchange increases, the dipolar broadened line changes from Gaussian to narrow Lorentzian.

An analytic form for $\psi(\tau)$ which contains both the Gaussian and Lorentzian limits is

$$
\begin{equation*}
\psi(\tau)=\exp \left(-\pi \omega_{\mathrm{ex}}^{2} \tau^{2} / 4\right) \tag{6.73}
\end{equation*}
$$

### 6.3.3 Spin Diffusion

Detailed comparison with measured correlation functions shows that $\psi(\tau)$ actually decays more slowly than a Gaussian. To obtain a better description of the relaxation at long times we recognize that if we perturb the spin system at some point $\boldsymbol{r}$ this perturbation will propagate away by means of the exchange interaction. At long times this process will involve many spins and may be described by a diffusion process. This means that the fluctuations described by $\psi(t)$ will also be spatially dependent, i.e., $\psi(\boldsymbol{r}, t)$ and will obey the diffusion equation,

$$
\begin{equation*}
\Lambda \nabla^{2} \psi=\frac{\partial \psi}{\partial t} \tag{6.74}
\end{equation*}
$$

where the diffusion coefficient $\Lambda$ is related to the correlation time $\omega_{\mathrm{ex}}^{-1}$. The difference between Gaussian behavior and diffusive behavior is illustrated in Fig. 6.7.

It is interesting to note from the diffusion equation that $\psi(\tau)$ must vary as $\tau^{-d / 2}$ where $d$ is the dimensionality. Thus, in one dimension the correlation time $\omega_{\text {ex }}^{-1}$ defined by (6.71) diverges and we expect an anomalous line shape. $\left(\mathrm{CH}_{3}\right)_{4} \mathrm{NMnCl}_{3}$, abbreviated TMMC, is a system in which the $\mathrm{Mn}^{2+}$ spins are exchange coupled only along chains approximating a one-dimensional spin system. Magnetic resonance studies indeed show [134] that the line shape is the Fourier transform of $\exp \left(-A t^{3 / 2}\right)$, intermediate between a Gaussian and a Lorentzian.

Although we have considered here the case of exchange-narrowed dipolarbroadened lines, the relaxation-function approach may also be applied in a variety of other situations, such as exchange-narrowed hyperfine-broadened nuclear magnetic resonance lines [135] or motionally narrowed, dipolarbroadened nuclear resonance lines [136].


Fig. 6.7. Comparison of the Gaussian and diffusion approximations to the correlation function $\psi(\tau)$. The time is in units of $\left(1 / \tau_{0}\right)^{2}=2 z(J / \hbar)^{2} S(S+1) / 3$ where $z$ is the number of of neighbors and $J$ is the exchange

### 6.4 Spin Echoes

### 6.4.1 Measurement of $T_{1}$

Notice that the longitudinal relaxation time $T_{1}$ does not enter the linear response function (6.27). Had we included the nonlinear contributions to this response function, the additional term $\gamma^{2} H_{1}^{2} T_{1} T_{2}$ would have appeared in the denominator. As a consequence, when the amplitude of the driving field becomes comparable to $\left(\gamma^{2} T_{1} T_{2}\right)^{-1 / 2}$ the resonance begins to saturate. The onset of this saturation provides a measure of $T_{1}$.

The same nonlinearity is also employed to produce spin echoes [137]. This phenomenon is easily understood with the help of Fig. 6.8. A circularily polarized field $H_{1}$ at frequency $\omega_{0}$ is applied transverse to the $d c$ field $H_{0}$. We know from the Bloch equations that in a coordinate system rotating about the $z$-axis, at a rate $\omega_{0}$, the magnetization will precess away from the $z$-axis as illustrated in Fig. 6.8a. If the driving field is turned off just as the magnetization reaches the $x y$-plane, a $90^{\circ}$ pulse is produced. Leaving the driving field on for twice as long results in a $180^{\circ}$ pulse, which just inverts the magnetization.

Suppose that at time $t=0$ we apply a $90^{\circ}$ pulse. After this pulse is turned off the spins process at their own resonant frequencies, which, because of the dipolar field, are distributed about $\omega_{0}$. After some dephasing time $T_{2}^{*}$ the spins produce a "pancake" in the rotating system, as shown in Fig. 6.8b. A $180^{\circ}$ pulse applied at some time $\tau$ to the system in this configuration will cause this pancake to rotate $180^{\circ}$ about the $x^{\prime}$ axis, as shown in Fig. 6.8c.


Fig. 6.8. Description of the origin of a spin echo in a coordinate frame rotating about the $z$ axis with the Zeeman frequency

Now, as the spins precess they begin to rephase and at a time $\tau$ after the $180^{\circ}$ pulse they again become coherent, producing an "echo". If we continue to apply $180^{\circ}$ pulses at times $3 \tau, 5 \tau$, etc., we shall observe echoes at times $4 \tau$, $6 \tau$, etc. If there were no transverse relaxation, these echoes would all have the same height. However, because of this relaxation the height of the $n$th echo decreases as $\exp \left(-2 n \tau / T_{2}\right)$, providing us with a measure of $T_{2}$. This scheme is shown in Fig. 6.9.

If $T_{1} \gg T_{2}$, then the longitudinal relaxation time $T_{1}$ may be obtained as follows. First we apply a $90^{\circ}$ pulse, which takes $M_{z}$ to zero. After a time $\tau$, $M_{z}$ has returned to $M_{0}\left[1-\exp \left(-\tau / T_{1}\right)\right]$. If we now apply a $90^{\circ}$ pulse followed by a $180^{\circ}$ pulse, the height of the resulting echo will be proportional to $M_{z}(\tau)$. By repeating this sequence we can follow $M_{z}$ back to $M_{0}$.

Let us consider briefly still another way of determining $T_{1}$. This consists of measuring the response of the system to a low-frequency longitudinal driving field. In general, the magnetization relaxes toward the instantaneous field. Therefore the Bloch equation (6.22a) for a field $\boldsymbol{H}=H_{0} \hat{\boldsymbol{z}}+H_{1} \cos \omega t \hat{\boldsymbol{z}}$ should be written as

$$
\begin{equation*}
\frac{d m_{z}}{d t}=\gamma(\boldsymbol{M} \times \boldsymbol{H})_{z}+\frac{\chi_{0} H_{1} \cos \omega t-m_{z}}{T_{1}} \tag{6.75}
\end{equation*}
$$

This is only an approximation, in the sense that we have used the static susceptibility $\chi_{0}$. Solving (6.75) leads directly to the response functions

$$
\begin{align*}
& \chi_{z z}^{\prime}(\omega)=\frac{\chi_{0}}{1+\omega^{2} T_{1}^{2}},  \tag{6.76a}\\
& \chi_{z z}^{\prime \prime}(\omega)=\frac{\chi_{0} \omega T_{1}}{1+\omega^{2} T_{1}^{2}} . \tag{6.76b}
\end{align*}
$$

These functions are plotted in Fig. 6.10. For electronic spins this broad longitudinal absorption is in the radio-frequency part of the spectrum. This is far below the transverse resonance, which is in the microwave region. Microwave sources were unavailable until World War II, and consequently the relaxation time $T_{1}$ was investigated much earlier than $T_{2}$. In fact, the response function (6.76b) was derived from thermodynamic considerations long before the development of Bloch's equations.


Fig. 6.9. Spin echo scheme for measuring $T_{2}$


Fig. 6.10. Longitudinal susceptibility of a weakly interacting spin system

### 6.4.2 Calculation of $T_{1}$

Let us now derive an expression for the phenomenological relaxation time $T_{1}$. According to the Bloch equation (6.22a), if the $z$ component of the magnetization is reduced from its equilibrium value $M_{0}$, it will return to this value according to

$$
\begin{equation*}
M_{z}=M_{0}\left(1-e^{t / T_{1}}\right) \tag{6.77}
\end{equation*}
$$

To obtain an explicit expression for $T_{1}$ let us compute $M_{z}$ for a simple twolevel spin system that has been displaced from equilibrium. If the number of spins in the state $\left|-\frac{1}{2}\right\rangle$ is $N_{-}$and the number in $\left|+\frac{1}{2}\right\rangle$ is $N_{+}$, then the total magnetization is

$$
\begin{equation*}
M_{z}=\frac{\frac{1}{2} g \mu_{B}\left(N_{-}-N_{+}\right)}{V}=\frac{1}{2} g \mu_{B} n . \tag{6.78}
\end{equation*}
$$

Thus, since the $z$ component of the magnetization depends on the relative population of the Zeeman states, any change in this population will result in a change in $M_{z}$.

Let us define $W(-\rightarrow+)$ as the probability per unit time that a spin in the state $\left|-\frac{1}{2}\right\rangle$ is "flipped" to the state $\left|+\frac{1}{2}\right\rangle$. Then the change in the populations may be described by the rate equations

$$
\begin{align*}
\frac{d N_{+}}{d t} & =N_{-} W(-\rightarrow+)-N_{+} W(+\rightarrow-),  \tag{6.79a}\\
\frac{d N_{-}}{d t} & =N_{+} W(+\rightarrow-)-N_{-} W(-\rightarrow+) . \tag{6.79b}
\end{align*}
$$

In equilibrium,

$$
\begin{equation*}
N_{-}^{0} W(-\rightarrow+)-N_{+}^{0} W(+\rightarrow-)=0 . \tag{6.80}
\end{equation*}
$$

Therefore, if the levels are separated by $g \mu_{B} H$ and we define $W(+\rightarrow-) \equiv W$, then

$$
\begin{equation*}
W(-\rightarrow+)=W \exp \left(-g \mu_{B} H / k_{B} T\right) . \tag{6.81}
\end{equation*}
$$

The equation for $n$ becomes

$$
\begin{equation*}
\frac{d n}{d t}=\frac{2 N_{+} W}{V}=\frac{2 N_{-} W \exp \left(-g \mu_{B} H / k_{B} T\right)}{V} \tag{6.82}
\end{equation*}
$$

In the high-temperature limit, valid for most experimental situations, the exponential in (6.82) may be expanded. If we replace the occupation numbers in (6.78) by their equilibrium values, we see that $n_{0}$ is approximately $\left(N_{-} / V\right)\left(g \mu_{B} H / k_{B} T\right)$ and

$$
\begin{equation*}
\frac{d n}{d t}=-2 W\left(n-n_{0}\right) \tag{6.83}
\end{equation*}
$$

Solving this equation and using (6.78), we obtain

$$
\begin{equation*}
M_{z}=M_{0}\left(1-e^{-2 W t}\right) . \tag{6.84}
\end{equation*}
$$

Comparing this with (6.77), we have the result

$$
\begin{equation*}
\frac{1}{T_{1}}=2 W \tag{6.85}
\end{equation*}
$$

There are various mechanisms that might contribute to the transition probability $W$. For example, in a paramagnet the spins may be coupled to the lattice vibrations. In this case the spin flips are accompanied by the emission or absorption of phonons. The resulting $T_{1}$ is called the spin-lattice relaxation time.

Another example is that of nuclear spins in a ferromagnet. In this case the nuclear spins are coupled to the electron spins by the hyperfine interaction. Fluctuations in the electron-spin system can then flip the nuclear spins, leading to a nuclear-spin relaxation time $T_{1}$. Let us consider this particular mechanism as an example of the calculation of $T_{1}$.

Suppose our unperturbed system is a single nuclear spin of $\frac{1}{2}$ plus the exchange-coupled electron system. Thus

$$
\begin{equation*}
\mathcal{H}_{0}=\mathcal{H}_{N}+\mathcal{H}_{\mathrm{el}}, \tag{6.86}
\end{equation*}
$$

where $\mathcal{H}_{N}=-g_{N} \mu_{N} H I_{z}$ and $\mathcal{H}_{\text {el }}$ is the electronic Hamiltonian. The eigenfunctions of $\mathcal{H}_{0}$ have the form $\left|m_{I}, n\right\rangle$, where $n$ characterizes the state of the electron system. The perturbing Hamiltonian is the hyperfine interaction

$$
\begin{equation*}
\mathcal{H}_{1}=A \boldsymbol{I} \cdot \boldsymbol{S} \tag{6.87}
\end{equation*}
$$

where $\boldsymbol{S}$ is the spin of the electron associated with the particular nucleus we are considering. If, at time $t=0$, the system is in the state $\left|m_{1}, n\right\rangle$, then we want to know the probability of finding the system in the state $\left|m_{I}^{\prime}, n^{\prime}\right\rangle$ at some later time $t$. To find this probability we must solve the Schrödinger equation

$$
\begin{equation*}
i \hbar \frac{\partial \psi}{\partial t}=\left(\mathcal{H}_{0}+\mathcal{H}_{1}\right) \psi \tag{6.88}
\end{equation*}
$$

We shall see in a moment that it is convenient to introduce

$$
\begin{equation*}
\psi=\exp \left(\frac{-i \mathcal{H}_{0} t}{\hbar}\right) \phi \tag{6.89}
\end{equation*}
$$

where $\phi$ satisfies

$$
\begin{equation*}
i \hbar \frac{\partial \phi}{\partial t}=\mathcal{H}_{1}(t) \phi \tag{6.90}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathcal{H}_{1}(t) \equiv \exp \left(\frac{i \mathcal{H}_{0} t}{\hbar}\right) \mathcal{H}_{1} \exp \left(\frac{-i \mathcal{H}_{0} t}{\hbar}\right) \tag{6.91}
\end{equation*}
$$

Integrating this equation with the condition that $\phi(t=0)=\left|m_{I}, n\right\rangle$, we obtain

$$
\begin{equation*}
\phi=\exp \left[-\frac{i}{\hbar} \int_{0}^{t} d t^{\prime} \mathcal{H}_{1}\left(t^{\prime}\right)\right]\left|m_{I}, n\right\rangle . \tag{6.92}
\end{equation*}
$$

The reason for introducing $\phi$ is that (6.92) may be expanded in powers of the perturbation $\mathcal{H}_{1}$,

$$
\begin{equation*}
\phi=\left|m_{I}, n\right\rangle-\frac{i}{\hbar} \int_{0}^{t} d t^{\prime} \mathcal{H}_{1}\left(t^{\prime}\right)\left|m_{I}, n\right\rangle+\ldots \tag{6.93}
\end{equation*}
$$

Therefore the probability of finding the system in the state $\left|m_{I}^{\prime}, n^{\prime}\right\rangle$ is

$$
\begin{align*}
\left|\left\langle m_{I}^{\prime}, n^{\prime} \mid \psi\right\rangle\right|^{2}= & \frac{1}{\hbar^{2}} \int_{0}^{t} d t^{\prime} \int_{0}^{t} d t^{\prime \prime}\left\langle m_{I}, n\right| \mathcal{H}_{1}\left(t^{\prime} \mid\right)\left|m_{1}^{\prime}, n^{\prime}\right\rangle \\
& \times\left\langle m_{1}^{\prime}, n^{\prime}\right| \mathcal{H}_{1}\left(t^{\prime \prime}\right)\left|m_{I}, n\right\rangle+\ldots \tag{6.94}
\end{align*}
$$

The total probability per unit time that the system will make a transition is obtained by dividing (6.94) by $t$ and letting $t \rightarrow \infty$. To find $W$ we set $m_{I}=-\frac{1}{2}$ and $m_{I}^{\prime}=+\frac{1}{2}$. We also average over all the electronic degrees of freedom. That is, we multiply (6.94) by the probability that the electronic system will be in the initial state $n$ and then we sum over $n$ as well as over all the final states $n^{\prime}$. The sum over $n^{\prime}$ gives unity by closure, leaving us with just the thermal average of $\mathcal{H}_{1}\left(t^{\prime}\right) \mathcal{H}_{1}\left(t^{\prime \prime}\right)$, which we denote by $\langle\ldots\rangle$. This is not to be confused with the bras and kets above. Thus

$$
\begin{equation*}
W=\lim _{t \rightarrow \infty} \frac{A^{2}}{4 \hbar^{2} t} \int_{0}^{t} d t^{\prime \prime} \exp \left[i \omega_{N}\left(t^{\prime}-t^{\prime \prime}\right)\right]\left\langle S^{-}\left(t^{\prime}\right) S^{+}\left(t^{\prime \prime}\right)\right\rangle \tag{6.95}
\end{equation*}
$$



Fig. 6.11. Variation of $T_{1}$ with the correlation time $\tau$ according to the BPP model
where $\omega_{N}=g_{N} \mu_{N} H$ is the nuclear magnetic resonance frequency. Changing variables leads to the result

$$
\begin{equation*}
\frac{1}{T_{1}}=\frac{A^{2}}{2 \hbar^{2}} \int_{-\infty}^{\infty} d t\left\langle S^{-}(t) S^{+}\right\rangle \exp \left(i \omega_{N} t\right) \tag{6.96}
\end{equation*}
$$

Thus we see that the longitudinal relaxation frequency in this case is the Fourier component at the nuclear magnetic resonance frequency of the electronspin correlation function. If the correlation function relaxes exponentially, i.e.,

$$
\left\langle S^{-}(t) S^{+}\right\rangle=\left\langle S_{\perp}^{2}\right\rangle e^{-t / \tau}
$$

then

$$
\begin{equation*}
\frac{1}{T_{1}}=\frac{A^{2}\left\langle S_{\perp}^{2}\right\rangle}{\hbar^{2}} \frac{\tau}{1+\omega_{N}^{2} \tau^{2}} \tag{6.97}
\end{equation*}
$$

The variation of $T_{1}$ with $\tau$ is shown in Fig. 6.11. Thus as $\tau$ varies, due to a variation in temperature for example, $T_{1}$ goes through a minimum when $\omega_{N} \tau \sim 1$. This characteristic behavior was first derived by Bloembergen, Purcell, and Pound [138] and is often simply referred to as the BPP result.

## Problems

6.1. Consider a moment $M$ initially pointing along the $+z$ direction. If we apply a dc field $H$ in the -z-direction describe the behavior of $M_{x}, M_{y}, M_{z}$ according to the Bloch equations.
6.2. Show that the real and imaginary parts of the susceptibility (6.26) and (6.3) satisfy the Kramers-Kronig relations (1.64) and (1.65).
6.3. Calculate the second and fourth moments (i.e., (6.43)) of the Gaussian function (6.30)
6.4. Show that $\left[\mathcal{H}_{\mathrm{ex}}, M_{x}\right]=0$. What does this imply about the torque on the magnetization from exchange?
6.5. Would a single-ion anisotropy of the form

$$
\mathcal{H}_{K}=\sum_{i} K\left(S_{i}^{z}\right)^{2}
$$

contribute to the broadening of the resonance?
6.6. Solve the linearized Bloch equations,

$$
\begin{aligned}
& \dot{m}_{x}=-\frac{1}{T_{2}} m_{x}-\gamma H_{y} m_{y}+\gamma h_{y}(t) \\
& \dot{m}_{y}=-\frac{1}{T_{2}} m_{y}+\gamma H_{x} m_{x}-\gamma h_{x}(t)
\end{aligned}
$$

where $H_{x, y}$ are called the Kittel "stiffness" fields, to obtain $\chi_{\alpha \beta}(\omega)$. Use the fluctuation-dissipation theorem to find the correlation functions $\left\langle m_{\alpha}(\tau) m_{\beta}(0)\right\rangle$ $(\alpha, \beta=x, y)$. The "noise power" is given by setting $\tau=0$. Use the result to calculate the energy $\langle\varepsilon\rangle=M_{s} V H_{x}\left\langle m_{x}^{2}\right\rangle$. What is the meaning of this result? [139]

# The Dynamic Susceptibility of Weakly Interacting Systems: Metals 

Let us now investigate the response of a metal to a time-dependent magnetic field. Experimentally, such investigations are very difficult because of problems associated with the fact that the driving field penetrates only a short distance into the metal. The first resonance experiments involving conductionelectron spins were carried out in the early 1950s. These experiments entailed measuring the surface impedance of samples located in a microwave cavity.

In 1964 electron spin resonance was observed in transmission. The analysis of both resonance techniques requires a knowledge of the nonlocal susceptibility function $\chi\left(z, z^{\prime}, \omega\right)$. This may be obtained from the generalized susceptibility $\chi(\boldsymbol{q}, \omega)$ along with a boundary condition on $\boldsymbol{M}$. If we assume that the boundaries do not relax the magnetization then the magnetization current $\boldsymbol{\nabla} \times \boldsymbol{M}$ must be conserved at the boundary. Let us now consider the generalized susceptibility. One approach that is particularly instructive makes use of the fluctuation-dissipation theorem. As we saw earlier, the presence of a time-dependent field leads to a coupling between the $x$ and $y$ components of the magnetization. Consequently, it is more convenient to work with the rotational components $M_{ \pm}(\boldsymbol{q}, \omega)$. In terms of these components, the susceptibility $\chi_{x x}^{\prime \prime}+\chi_{y y}^{\prime \prime}$ is proportional to the correlation function $\left\langle\mathcal{M}_{-}(\boldsymbol{q}, t) \mathcal{M}_{+}(-\boldsymbol{q})\right\rangle$. This is just the susceptibility $\chi_{-+}(\boldsymbol{q}, \omega)$ we have already encountered.

The magnetization operator associated with the spin of a system of itinerant electrons is

$$
\begin{equation*}
\mathcal{M}(\boldsymbol{r})=\sum_{i} \mu_{B} \boldsymbol{\sigma}_{i} \delta\left(\boldsymbol{r}-\boldsymbol{r}_{i}\right) \tag{7.1}
\end{equation*}
$$

Second quantizing this operator in terms of the plane-waves states (1.130) gives

$$
\begin{equation*}
\mathcal{M}(\boldsymbol{r})=\frac{\mu_{B}}{V} \sum_{\boldsymbol{k}, \boldsymbol{q}} \sum_{\alpha, \beta} \boldsymbol{\sigma}_{\alpha \beta} e^{i \boldsymbol{q} \cdot \boldsymbol{r}} a_{\boldsymbol{k}-\boldsymbol{q}, \alpha}^{\dagger} a_{\boldsymbol{k}, \beta} \tag{7.2}
\end{equation*}
$$

Therefore

$$
\begin{equation*}
\mathcal{M}_{+}(-\boldsymbol{q})=-2 \mu_{B} \sum_{\boldsymbol{k}} a_{\boldsymbol{k}+\boldsymbol{q}, \uparrow}^{\dagger} a_{\boldsymbol{k} \downarrow} \tag{7.3}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathcal{M}_{-}(\boldsymbol{q})=-2 \mu_{B} \sum_{\boldsymbol{k}} a_{\boldsymbol{k}-\boldsymbol{q}, \downarrow}^{\dagger} a_{\boldsymbol{k} \uparrow} \tag{7.4}
\end{equation*}
$$

The desired correlation function is then

$$
\begin{align*}
\left\langle\mathcal{M}_{-}(\boldsymbol{q}, t) \mathcal{M}_{+}(-\boldsymbol{q})\right\rangle= & 4 \mu_{B}^{2} \sum_{\boldsymbol{k}} \sum_{\boldsymbol{k}^{\prime}}  \tag{7.5}\\
& \times\left\langle\exp \left(\frac{i \mathcal{H} t}{\hbar}\right) a_{\boldsymbol{k}^{\prime}-\boldsymbol{q}, \downarrow}^{\dagger} a_{\boldsymbol{k}^{\prime} \uparrow} \exp \left(\frac{-i \mathcal{H} t}{\hbar}\right) a_{\boldsymbol{k}+\boldsymbol{q}, \uparrow}^{\dagger} a_{\boldsymbol{k} \downarrow}\right\rangle
\end{align*}
$$

where

$$
\begin{equation*}
\mathcal{H}=\sum_{\boldsymbol{k}} \sum_{\sigma} \epsilon_{\boldsymbol{k} \sigma} a_{\boldsymbol{k} \sigma}^{\dagger} a_{\boldsymbol{k} \sigma} . \tag{7.6}
\end{equation*}
$$

The eigenvalue $\epsilon_{\boldsymbol{k} \sigma}$ is $\hbar^{2} k^{2} / 2 m+m u_{B} H_{0} \sigma$, where $\sigma$ is +1 for an up spin and -1 for a down spin.

At $T=0 \mathrm{~K}$ the ground state consists of up- and down-spin Fermi spheres. As in our calculation of the static susceptibility in Chap. 3, the wave vector $\boldsymbol{k}$ is restricted to those values within the down-spin Fermi sphere such that $\boldsymbol{k}+\boldsymbol{q}$ lies outside the up-spin Fermi sphere. The correlation function at $T=0 \mathrm{~K}$ is then

$$
\begin{equation*}
\left\langle\mathcal{M}_{-}(\boldsymbol{q}, t) \mathcal{M}_{+}(-\boldsymbol{q})\right\rangle=4 \mu_{B}^{2} \sum_{\boldsymbol{k}} f_{\boldsymbol{k} \downarrow}\left(1-f_{\boldsymbol{k}+\boldsymbol{q}, \uparrow}\right) \exp \frac{-i\left(\epsilon_{\boldsymbol{k}+\boldsymbol{q}, \uparrow}-\epsilon_{\boldsymbol{k} \downarrow}\right) t}{\hbar} \tag{7.7}
\end{equation*}
$$

Taking the Fourier transform and applying (1.88) at $T=0 \mathrm{~K}$ leads to the susceptibility,

$$
\begin{equation*}
\chi_{-+}^{\prime \prime}(\boldsymbol{q}, \omega)_{s}=\frac{8 \pi \mu_{B}^{2}}{V} \sum_{\boldsymbol{k}} f_{\boldsymbol{k} \downarrow}\left(1-f_{\boldsymbol{k}+\boldsymbol{q}, \uparrow}\right) \delta\left(\hbar \omega-\epsilon_{\boldsymbol{k}+\boldsymbol{q}, \uparrow}+\epsilon_{\boldsymbol{k} \downarrow}\right) . \tag{7.8}
\end{equation*}
$$

The real part of the susceptibility is obtained from the Kramers-Kronig relation (1.65),

$$
\begin{equation*}
\chi_{-+}^{\prime}(\boldsymbol{q}, \omega)_{s}=\frac{8 \mu_{B}^{2}}{V} \sum_{\boldsymbol{k}} \frac{f_{\boldsymbol{k} \downarrow}\left(1-f_{\boldsymbol{k}+\boldsymbol{q}, \uparrow}\right)}{\epsilon_{\boldsymbol{k}+\boldsymbol{q}, \uparrow}-\epsilon_{\boldsymbol{k} \downarrow}-\hbar \omega} . \tag{7.9}
\end{equation*}
$$

Notice that $\chi_{-+}$involves different spin indices whereas $\chi_{z z}$, as given in (3.84), for example, involves the same spin indices. In zero field $\epsilon_{\boldsymbol{k} \uparrow}=\epsilon_{\boldsymbol{k} \downarrow}=\epsilon_{\boldsymbol{k}}$, and in the limit $\omega \rightarrow 0$ (7.9) correctly reduces to twice the static result.

The single-particle energies entering the delta function of (7.8) have the value

$$
\begin{equation*}
\epsilon_{\boldsymbol{k}+\boldsymbol{q}, \uparrow}-\epsilon_{\boldsymbol{k} \uparrow}=2 \mu_{B} H_{0}+\frac{\hbar^{2}}{m} \boldsymbol{k} \cdot \boldsymbol{q}+\frac{\hbar^{2}}{2 m} q^{2} \tag{7.10}
\end{equation*}
$$



Fig. 7.1. The magnetic-excitation spectrum of a noninteracting electron gas
Therefore the excitation spectrum has the form shown in Fig. 7.1. The $\boldsymbol{q}=0$ mode is the conduction-electron spin resonance at $\omega=\omega_{s}=g \mu_{B} H_{0}$.

### 7.1 Paramagnons

Let us now consider how the susceptibility is modified by the introduction of interactions among the electrons. The result for $\chi_{-+}(\boldsymbol{q}, \omega)$ in the presence of the delta-function interaction introduced in (4.81) is readily obtained by the equation-of-motion approach used in that section. In order to calculate $\chi_{-+}(\boldsymbol{q}, \omega)$, as opposed to $\chi_{z z}(\boldsymbol{q}, \omega)$, we must determine the response

$$
\begin{equation*}
M_{+}(\boldsymbol{q})=-2 \mu_{B} \sum_{\boldsymbol{k}}\left\langle a_{\boldsymbol{k}-\boldsymbol{q}, \uparrow}^{\dagger} a_{\boldsymbol{k} \downarrow}\right\rangle \tag{7.11}
\end{equation*}
$$

to a transverse field $H[\cos (\omega t) \hat{\boldsymbol{x}}+\sin (\omega t) \hat{\boldsymbol{y}}] \cos (\boldsymbol{q} \cdot \boldsymbol{r})$. The corresponding Zeeman interaction is

$$
\begin{equation*}
\mathcal{H}_{Z}=-\frac{1}{4} H\left\{\left[\mathcal{M}_{-}(\boldsymbol{q})+\mathcal{M}_{-}(-\boldsymbol{q})\right] e^{i \omega t}+\left[\mathcal{M}_{+}(\boldsymbol{q})+\mathcal{M}_{+}(-\boldsymbol{q})\right] e^{i \omega t}\right\} \tag{7.12}
\end{equation*}
$$

Adding this interaction to (4.81) the equation of motion for $\left\langle a_{\boldsymbol{k}-\boldsymbol{q}, \uparrow}^{\dagger} a_{\boldsymbol{k}_{\downarrow}}\right\rangle$ in the random-phase approximation becomes

$$
\begin{align*}
i \hbar \frac{d}{d t}\left\langle a_{\boldsymbol{k}-\boldsymbol{q}, \uparrow}^{\dagger} a_{\boldsymbol{k} \downarrow}\right\rangle= & \left(\epsilon_{\boldsymbol{k}}-\epsilon_{\boldsymbol{k}-\boldsymbol{q}}\right)\left\langle a_{\boldsymbol{k}-\boldsymbol{q}, \uparrow}^{\dagger} a_{\boldsymbol{k} \downarrow}\right\rangle \\
& +\frac{2 I}{V} \sum_{\boldsymbol{k}^{\prime}}\left(n_{\boldsymbol{k}^{\prime} \uparrow}-n_{\boldsymbol{k}^{\prime} \downarrow}\right)\left\langle a_{\boldsymbol{k}-\boldsymbol{q}, \uparrow}^{\dagger} a_{\boldsymbol{k} \downarrow}\right\rangle \\
& -\frac{2 I}{V}\left(n_{\boldsymbol{k}-\boldsymbol{q}, \uparrow}-n_{\boldsymbol{k} \downarrow}\right) \sum_{\boldsymbol{q}^{\prime}}\left\langle a_{\boldsymbol{k}-\boldsymbol{q}^{\prime}-\boldsymbol{q}, \uparrow}^{\dagger} a_{\boldsymbol{k}-\boldsymbol{q}^{\prime}, \downarrow}\right\rangle \\
& +\frac{1}{2} \mu_{B} H\left(n_{\boldsymbol{k}-\boldsymbol{q}, \uparrow}-n_{\boldsymbol{k} \downarrow}\right) e^{i \omega t} . \tag{7.13}
\end{align*}
$$

We see that the "spin fluctuation" $\left\langle a_{\boldsymbol{k}-\boldsymbol{q}, \uparrow}^{\dagger} a_{\boldsymbol{k} \downarrow}\right\rangle$ is coupled to many other fluctuations through the third term on the right-hand side. If we assume that these spin fluctuations all have a time dependence of the form $\exp (i \omega t)$, then

$$
\begin{align*}
\left\langle a_{\boldsymbol{k}-\boldsymbol{q}, \uparrow}^{\dagger} a_{\boldsymbol{k} \downarrow}\right\rangle= & \frac{(2 I / V)\left(n_{\boldsymbol{k}-\boldsymbol{q}, \uparrow}-n_{\boldsymbol{k} \downarrow}\right) \sum_{\boldsymbol{q}^{\prime}}\left\langle a_{\boldsymbol{k}-\boldsymbol{q}^{\prime}-\boldsymbol{q}, \uparrow}^{\dagger} a_{\boldsymbol{k}-\boldsymbol{q}^{\prime}, \downarrow}\right\rangle}{\hbar \omega-\left(\tilde{\epsilon}_{\boldsymbol{k}-\boldsymbol{q}, \uparrow}-\tilde{\epsilon}_{\boldsymbol{k} \downarrow}\right)} \\
& -\frac{\frac{1}{2} \mu_{B} H\left(n_{\boldsymbol{k}-\boldsymbol{q}, \uparrow}-n_{\boldsymbol{k} \downarrow}\right)}{\hbar \omega-\left(\tilde{\epsilon}_{\boldsymbol{k}-\boldsymbol{q}, \uparrow}-\tilde{\epsilon}_{\boldsymbol{k} \downarrow}\right)} \tag{7.14}
\end{align*}
$$

where

$$
\begin{equation*}
{\underset{\sim}{\tau}}_{\underset{\boldsymbol{k} \sigma}{ }}=\epsilon_{\boldsymbol{k}}+\frac{I}{2 V} \sum_{\boldsymbol{k}^{\prime}} n_{\boldsymbol{k}^{\prime} \sigma} . \tag{7.15}
\end{equation*}
$$

Since we're interested in the magnetization, (7.11), we must sum (7.14) over $\boldsymbol{k}$. The index $\boldsymbol{q}^{\prime}$ then becomes a dummy index, which enables us to solve for the magnetization. From definition (1.55) of the susceptibility we obtain for the real part

$$
\begin{equation*}
\chi_{-+}^{\prime}(\boldsymbol{q}, \omega)=\frac{\left(2 \mu_{B}^{2} / V\right) \Gamma(\boldsymbol{q}, \omega)}{1-(2 / V) \Gamma(\boldsymbol{q}, \omega)} \tag{7.16}
\end{equation*}
$$

where

$$
\begin{equation*}
\Gamma(\boldsymbol{q}, \omega)=\sum_{\boldsymbol{k}} \frac{n_{\boldsymbol{k}-\boldsymbol{q}, \uparrow}-n_{\boldsymbol{k} \downarrow}}{\hbar \omega-\left(\tilde{\epsilon}_{\boldsymbol{k}-\boldsymbol{q}, \uparrow}-\tilde{\epsilon}_{\boldsymbol{k} \downarrow}\right)} . \tag{7.17}
\end{equation*}
$$

In zero field and in the paramagnetic state $\epsilon_{\boldsymbol{k} \uparrow}=\epsilon_{\boldsymbol{k} \downarrow}$. In this case we can evaluate the real and imaginary parts of the susceptibility for simple parabolic bands. The imaginary part is shown in Fig. 7.2. When the interaction $I=0$, we obtain a broad response. However, as $I$ increases toward the Stoner critical value, the response develops a sharp peak at low frequency whose position varies linearly with the wave vector $\boldsymbol{q}$. The presence of this low-frequency peak, or paramagnon, enhances the effective mass $m^{*}$. In particular, it is found [141] that the mass contains a contribution which varies as the logarithm of the Stoner enhancement factor.

The above treatment does not include the interactions between the electrons and their host lattice. These interactions are primarily responsible for the resistivity and are characterized by a relaxation time $\tau$. If this relaxation time is much smaller than the inverse cyclotron frequency $\omega_{c}$, i.e., $\omega_{c} \tau \ll 1$, then the electron's flight between collisions is approximately a straight line. The electron's overall motion will then be that of a random walk with a diffusion constant $D=\frac{1}{3} v_{F}^{2} \tau$. We shall see below that this behavior, while not shifting the conduction-electron spin resonance frequency, has a


Fig. 7.2. Frequency response of the imaginary part of the susceptibility, showing the paramagnon peak [140]
dramatic effect on the line shape. It is possible to incorporate collision effects into the susceptibility (7.9) in analogy with Mermin's [142] treatment of the Lindhard dielectric function. We shall, however, do this within the framework of Fermi liquid theory.

### 7.2 Fermi Liquid Theory

As we saw in Sect.4.2, the important quantity in the Fermi liquid approach is the distribution of quasiparticles $n(\boldsymbol{k}, \boldsymbol{\sigma})$. Since we shall eventually be interested in the response to space-varying excitations, let us consider a region of space which is small in comparison with the wavelength of such excitations but large enough to contain many quasiparticles. Then $n(\boldsymbol{k}, \boldsymbol{\sigma})$ becomes a function of position $n(\boldsymbol{r}, \boldsymbol{k}, \boldsymbol{\sigma})$. In Chap. 4 we were able to guess correctly how the distribution function was changed by a constant velocity displacement or by the presence of a uniform magnetic field. In the case of a time-dependent perturbation, however, it is not obvious what the resulting change will be.

In the absence of any magnetic fields the quasiparticle energy is $\epsilon^{0}(\boldsymbol{k}) \mathbf{1}$. When magnetic fields are applied the energy changes for two reasons. First, there are orbital and spin Zeeman terms. Second, these Zeeman terms alter the distribution of quasiparticles, thereby bringing interaction terms into the energy. If we write the change in the quasiparticle distribution in the general form

$$
\begin{equation*}
\delta n(\boldsymbol{r}, \boldsymbol{k}, \boldsymbol{\sigma})=n_{1}(\boldsymbol{r}, \boldsymbol{k}) \mathbf{1}+\boldsymbol{n}_{2}(\boldsymbol{r}, \boldsymbol{k}) \cdot \boldsymbol{\sigma}, \tag{7.18}
\end{equation*}
$$

then the change in the quasiparticle energy may be written as

$$
\begin{equation*}
\delta \epsilon(\boldsymbol{r}, \boldsymbol{k}, \boldsymbol{\sigma})=\epsilon_{1}(\boldsymbol{r}, \boldsymbol{k}) \mathbf{1}+\boldsymbol{\epsilon}_{2}(\boldsymbol{r}, \boldsymbol{k}) \cdot \boldsymbol{\sigma}, \tag{7.19}
\end{equation*}
$$

where

$$
\begin{equation*}
\epsilon_{1}(\boldsymbol{r}, \boldsymbol{k})=-\frac{e \hbar}{2 m^{*} c} \boldsymbol{k} \times \boldsymbol{H}_{0} \cdot \boldsymbol{r}+\frac{2}{V} \sum_{\boldsymbol{k}^{\prime}} \varphi\left(\hat{\boldsymbol{k}} \cdot \hat{\boldsymbol{k}}^{\prime}\right) n_{1}\left(\boldsymbol{r}, \boldsymbol{k}^{\prime}\right) \tag{7.20}
\end{equation*}
$$

and

$$
\begin{equation*}
\boldsymbol{\epsilon}_{2}(\boldsymbol{r}, \boldsymbol{k})=\mu_{B} H_{0} \hat{\boldsymbol{z}}+\mu_{B} \boldsymbol{H}_{1}(\boldsymbol{r}, t)+\frac{2}{V} \sum_{\boldsymbol{k}^{\prime}} \psi\left(\hat{\boldsymbol{k}} \cdot \hat{\boldsymbol{k}}^{\prime}\right) \boldsymbol{n}_{2}\left(\boldsymbol{r}, \boldsymbol{k}^{\prime}\right), \tag{7.21}
\end{equation*}
$$

where $\boldsymbol{H}_{1}(\boldsymbol{r}, t)$ is the probing magnetic field and the quantities $\varphi$ and $\psi$ were defined in (4.66). The first term in $\epsilon_{1}(\boldsymbol{r}, \boldsymbol{k})$ is the orbital Zeeman contribution.

The magnetization at $\boldsymbol{r}$ arising from the quasiparticles in state $\boldsymbol{k}$ is

$$
\begin{equation*}
\boldsymbol{m}(\boldsymbol{r}, \boldsymbol{k})=-\frac{\mu_{B}}{V} \operatorname{Tr}_{\sigma}\{[n(\boldsymbol{r}, \boldsymbol{k}, \boldsymbol{\sigma}) \boldsymbol{\sigma}]\}=-\frac{2 \mu_{B}}{V} \boldsymbol{n}_{2}(\boldsymbol{r}, \boldsymbol{k}) \tag{7.22}
\end{equation*}
$$

To determine the magnetization we must therefore determine the spindependent part of the change in the quasiparticle distribution function. This may be found by solving the equation of motion associated with $n(\boldsymbol{r}, \boldsymbol{k}, \boldsymbol{\sigma})$.

To set up this equation we ask for the different ways in which $n(\boldsymbol{r}, \boldsymbol{k}, \boldsymbol{\sigma})$ may change with time. First of all, it might depend explicitly on time. This rate of change has the form $\partial n / \partial t$. Second, quasiparticles may drift into and out of the region in real space defined by $\boldsymbol{r}$. The rate of change of $n(\boldsymbol{r}, \boldsymbol{k}, \boldsymbol{\sigma})$ associated with this process is

$$
\begin{equation*}
\frac{1}{2 \hbar}\left(\frac{\partial n}{\partial \boldsymbol{r}} \frac{\partial \epsilon}{\partial \boldsymbol{k}}+\frac{\partial \epsilon}{\partial \boldsymbol{k}} \frac{\partial n}{\partial \boldsymbol{r}}\right) . \tag{7.23}
\end{equation*}
$$

Since $\epsilon(\boldsymbol{r}, \boldsymbol{k}, \boldsymbol{\sigma})$ and $n(\boldsymbol{r}, \boldsymbol{k}, \boldsymbol{\sigma})$ are matrices, this is written in the symmetrized form. A third way in which the quasiparticle distribution might change is for quasiparticles to change their momentum $\hbar \boldsymbol{k}$. Using Hamiltonian's equation $\partial \boldsymbol{p} / \partial t=-\partial \epsilon / \partial \boldsymbol{r}$, we have for this contribution

$$
\begin{equation*}
\frac{1}{2 \hbar}\left(\frac{\partial n}{\partial \boldsymbol{k}} \frac{\partial \epsilon}{\partial \boldsymbol{r}}+\frac{\partial \epsilon}{\partial \boldsymbol{r}} \frac{\partial n}{\partial \boldsymbol{k}}\right) \tag{7.24}
\end{equation*}
$$

Another way for $n(\boldsymbol{k}, \boldsymbol{r}, \boldsymbol{\sigma})$ to change is for the quasiparticle to change its spin state. This change is determined by the commutator $[\epsilon, n]$. Finally, the interaction with the lattice will also produce a change in the distribution. Therefore the total equation of motion becomes

$$
\begin{equation*}
\frac{\partial n}{\partial t}+\frac{1}{\hbar}\left\{\frac{\partial n}{\partial \boldsymbol{r}} \frac{\partial \epsilon}{\partial \boldsymbol{k}}\right\}+\frac{1}{\hbar}\left\{\frac{\partial n}{\partial \boldsymbol{k}} \frac{\partial \epsilon}{\partial \boldsymbol{r}}\right\}-\frac{i}{\hbar}[\epsilon, n]=\left.\frac{\partial n}{\partial t}\right|_{\text {collisions }}, \tag{7.25}
\end{equation*}
$$

where the braces indicate the symmetrized product. Notice that the second and third terms have been written as a symmetrized Poisson bracket.

The equation of motion for the magnetization is obtained by multiplying (7.25) by $-\left(\mu_{B} / V\right) \boldsymbol{\sigma}$ and taking the spin trace. Let us consider the second
term. Since the unperturbed distribution function is spatially independent, the spatial derivative becomes

$$
\begin{equation*}
\frac{\partial n}{\partial \boldsymbol{r}}=\frac{\partial n_{1}}{\partial \boldsymbol{r}}+\frac{\partial}{\partial \boldsymbol{r}}\left(\boldsymbol{n}_{2} \cdot \boldsymbol{\sigma}\right) \tag{7.26}
\end{equation*}
$$

The derivative of the energy with respect to the wave vector is

$$
\begin{equation*}
\frac{\partial \epsilon}{\partial \boldsymbol{k}}=\frac{\partial \epsilon^{0}}{\partial \boldsymbol{k}}+\frac{\partial \epsilon_{1}}{\partial \boldsymbol{k}}+\frac{\partial}{\partial \boldsymbol{k}}\left(\boldsymbol{\epsilon}_{2} \cdot \boldsymbol{\sigma}\right)=\hbar \boldsymbol{v}+\frac{\partial}{\partial \boldsymbol{k}}\left(\boldsymbol{\epsilon}_{2} \cdot \boldsymbol{\sigma}\right) \tag{7.27}
\end{equation*}
$$

Since $\operatorname{Tr}\{\boldsymbol{\sigma}\}=0, \operatorname{Tr}\{(\boldsymbol{A} \cdot \boldsymbol{\sigma}) \boldsymbol{\sigma}\}=2 A$, and $\operatorname{Tr}\{(\boldsymbol{A} \cdot \boldsymbol{\sigma})(\boldsymbol{B} \cdot \boldsymbol{\sigma}) \boldsymbol{\sigma}\}=2 i \boldsymbol{A} \times \boldsymbol{B}$, we obtain

$$
\begin{equation*}
-\frac{\mu_{B}}{V} \operatorname{Tr}\left\{\frac{\partial n}{\partial \boldsymbol{r}} \frac{\partial \epsilon}{\partial \boldsymbol{k}}\right\} \boldsymbol{\sigma}=-\frac{2 \mu_{B}}{V}\left(\frac{\partial n_{1}}{\partial \boldsymbol{r}} \frac{\partial}{\partial \boldsymbol{k}}\right) \boldsymbol{\epsilon}_{2}+\hbar(\boldsymbol{v} \cdot \boldsymbol{\nabla}) \boldsymbol{m} \tag{7.28}
\end{equation*}
$$

But

$$
\begin{equation*}
\frac{\partial n_{1}}{\partial \boldsymbol{r}}=\frac{\partial n_{0}}{\partial \epsilon^{0}} \frac{\partial \epsilon_{1}}{\partial \boldsymbol{r}}=-\frac{\partial n_{0}}{\partial \epsilon^{0}}\left(\frac{e \hbar}{2 m^{*} c}\right) \boldsymbol{k} \times \boldsymbol{H}_{0} \tag{7.29}
\end{equation*}
$$

Therefore

$$
\begin{equation*}
-\frac{\mu_{B}}{\hbar V} \operatorname{Tr}\left\{\frac{\partial n}{\partial \boldsymbol{r}} \frac{\partial \epsilon}{\partial \boldsymbol{k}}\right\} \boldsymbol{\sigma}=\frac{\mu_{B}}{V} \frac{\partial n_{0}}{\partial \epsilon^{0}} \frac{e}{m^{*} c}\left[\left(\boldsymbol{k} \times \boldsymbol{H}_{0}\right) \cdot \frac{\partial}{\partial \boldsymbol{k}}\right] \epsilon_{2}+\hbar(v \cdot \nabla) \boldsymbol{m} \tag{7.30}
\end{equation*}
$$

The third term in (7.25) is evaluated in the same manner, giving

$$
\begin{equation*}
\frac{\mu_{B}}{\hbar V} \operatorname{Tr}\left\{\frac{\partial n}{\partial \boldsymbol{k}} \frac{\partial \epsilon}{\partial \boldsymbol{r}}\right\} \boldsymbol{\sigma}=\frac{2 \mu_{B}}{V} \frac{\partial n_{0}}{\partial \epsilon^{0}}(v \cdot \boldsymbol{\nabla}) \epsilon_{2}+\frac{e}{2 m^{*} c}\left[\left(\boldsymbol{k} \times \boldsymbol{H}_{0}\right) \cdot \frac{\partial}{\partial \boldsymbol{k}}\right] \boldsymbol{m} \tag{7.31}
\end{equation*}
$$

Notice that the terms in $(7.30,7.31)$ which do not explicitly involve $\boldsymbol{m}$ contain the factor $\partial n_{0} / \partial \epsilon^{0}$. This implies that $\boldsymbol{m}$ is proportional to $\partial n_{0} / \partial \epsilon^{0}$. Since $\partial n_{0} / \partial \epsilon^{0}$ is essentially nonzero only at the Fermi surface, the magnetization arises only from those quasiparticles at the Fermi surface. This, together with the fact that we are interested in the transverse response of the system, suggests that we introduce the quantity $g(\boldsymbol{r}, \boldsymbol{k})$, defined by

$$
\begin{equation*}
m_{+}(\boldsymbol{r}, \boldsymbol{k})=m_{x}+i m_{y}=-\frac{\partial n_{0}}{\partial \epsilon^{0}} g(\boldsymbol{r}, \boldsymbol{k}) \tag{7.32}
\end{equation*}
$$

Since $\boldsymbol{k} \simeq k_{F} \hat{\boldsymbol{k}}$, the dependence of $g(\boldsymbol{r}, \boldsymbol{k})$ upon $\boldsymbol{k}$ involves only the polar angles of $\boldsymbol{k}$ with respect to the $z$-axis.

The contribution to the equation of motion for $m_{+}$from the fourth term involving the commutator is
$i \frac{\mu_{B}}{\hbar V} \operatorname{Tr}\left\{[\epsilon, n] \sigma_{+}\right\}=i\left[\left(\frac{\mu_{B} H_{0}}{\hbar}+\frac{V}{2 \hbar \mu_{B}} G_{z}\right) m_{+}+\frac{V}{2 \hbar \mu_{B}} m_{z} G-\frac{\mu_{B}}{\hbar} m_{z} H_{+}\right]$,
where

$$
\begin{equation*}
G(\boldsymbol{r}, \boldsymbol{k})=\frac{2}{V} \sum_{k^{\prime}} \psi\left(\hat{\boldsymbol{k}} \cdot \hat{\boldsymbol{k}}^{\prime}\right) m_{+}\left(\boldsymbol{r}, \boldsymbol{k}^{\prime}\right) \tag{7.34}
\end{equation*}
$$

and $G_{z}$ involves $m_{z}$ in place of $m_{+}$. To proceed further with this expression we must determine $m_{z}(\boldsymbol{r}, \boldsymbol{k})$. In Chap. 5 we found that the magnetization resulting from a uniform field arises from a spherically symmetric shell of states at the Fermi surface. Therefore we take

$$
\begin{equation*}
m_{z}(\boldsymbol{r}, \boldsymbol{k})=-\frac{\partial n_{0}}{\partial \epsilon_{0}} g(\boldsymbol{r})_{z} . \tag{7.35}
\end{equation*}
$$

To find $g(\boldsymbol{r})_{z}$ we note that the magnetization at $\boldsymbol{r}$, which is given by

$$
\begin{equation*}
m_{z}(\boldsymbol{r})=\sum_{k} m_{z}(\boldsymbol{r}, \boldsymbol{k}), \tag{7.36}
\end{equation*}
$$

is also related to the static susceptibility by

$$
\begin{equation*}
m_{z}(\boldsymbol{r})=\frac{1}{V} \sum_{\boldsymbol{q}} \chi(\boldsymbol{q}) H(\boldsymbol{q})=\chi(0) H_{0} . \tag{7.37}
\end{equation*}
$$

We use the fact that

$$
\begin{equation*}
\frac{\partial n_{0}}{\partial \epsilon_{0}}=-\delta\left(\mu-\epsilon^{0}(\boldsymbol{k})\right)=-\frac{m^{*}}{\hbar^{2} k_{F}} \delta\left(k-k_{F}\right) \tag{7.38}
\end{equation*}
$$

along with our result (4.80) for the static susceptibility, which may be written as

$$
\begin{equation*}
\chi(0)=\frac{\mu_{B}^{2} m^{*} k_{F}}{\pi^{2} \hbar^{2}\left(1+B_{0}\right)} . \tag{7.39}
\end{equation*}
$$

We then obtain

$$
\begin{equation*}
m_{z}(\boldsymbol{r}, \boldsymbol{k})=-\frac{\partial n_{0}}{\partial \epsilon^{0}} \frac{2 \mu_{B}^{2} H_{0}}{V\left(1+B_{0}\right)} \tag{7.40}
\end{equation*}
$$

The collision term on the right-hand side of (7.25) is handled by assuming that the distribution function $n(\boldsymbol{r}, \boldsymbol{k}, \boldsymbol{\sigma})$ relaxes to its local average value $\bar{n}(\boldsymbol{r}, \boldsymbol{\sigma})$, defined by

$$
\begin{equation*}
\bar{n}(\boldsymbol{r}, \boldsymbol{\sigma})=\frac{1}{\frac{4}{3} \pi k_{F}^{2}} \int d \boldsymbol{k} n(\boldsymbol{r}, \boldsymbol{k}, \boldsymbol{\sigma}) . \tag{7.41}
\end{equation*}
$$

If this relaxation is characterized by a time $\tau$, then

$$
\begin{equation*}
\left.\frac{\partial g}{\partial t}\right|_{\text {collisions }}=-\frac{1}{\tau}\left(g-\frac{1}{4 \pi} \int d \Omega g\right) . \tag{7.42}
\end{equation*}
$$

Combining all these results in the equation of motion for $g(\boldsymbol{r}, \boldsymbol{k})$ yields

$$
\begin{align*}
& \frac{\partial g}{\partial t}+\left[\boldsymbol{v} \cdot \boldsymbol{\nabla}+\frac{e}{m^{*} c}\left(\boldsymbol{k} \times \boldsymbol{H}_{0}\right) \cdot \frac{\partial}{\partial \boldsymbol{k}}+i \Omega_{0}\right](g+G) \\
& =-\frac{1}{\tau}\left(g-\frac{1}{4 \pi} \int d \Omega g\right)+\frac{2 \mu_{B}^{2}}{V}\left(\boldsymbol{v} \cdot \boldsymbol{\nabla}+i \Omega_{0}\right) H_{+} \tag{7.43}
\end{align*}
$$

where

$$
\begin{equation*}
\Omega_{0}=\frac{2 \mu_{B} H_{0}}{\hbar\left(1+B_{0}\right)} \tag{7.44}
\end{equation*}
$$

Equation (7.43) is a linear integral equation that is difficult to solve in general. Therefore certain simplifying approximations are made. For example, Silin has considered the spatially uniform normal modes of a collisionless system [143]. This corresponds to solving (7.43) without the $\boldsymbol{v} \cdot \boldsymbol{\nabla}$ term on the left and with the right side set to 0 . The resulting solutions for $g(\theta, \varphi)$ are spherical harmonics, $Y_{n}^{m}(\theta, \varphi)$, with the corresponding eigenfrequencies.

$$
\begin{equation*}
\omega_{n m}=\left(\Omega_{0}+m \omega_{c}\right)\left(1+\frac{B_{n}}{2 n+1}\right) \tag{7.45}
\end{equation*}
$$

where $\omega_{c}=e H_{0} / m^{*} c$ is the cyclotron frequency. The mode $\omega_{00} \equiv \omega_{s} \equiv$ $2 \mu_{B} H_{0} / \hbar$ is the conduction-electron spin resonance. We see that as a result of the interactions there are also modes involving combined spin and orbital excitations.

Platzman and Wolff have investigated the $\boldsymbol{q}$ dependence of the $\omega_{00}$ mode [144]. However, they also retained the collision term characterized by a relaxation time $\tau$. Their result for the susceptibility, including also a spin-relaxation term $T_{2}$ is ${ }^{1}$

$$
\begin{equation*}
\chi(\boldsymbol{q}, \omega)=\frac{m^{*}}{m} \frac{\chi_{\text {Pauli }}}{1+B_{0}} \frac{\omega_{s}}{\omega_{s}-\omega-i D^{*} q^{2}-i / \bar{T}_{2}} \tag{7.46}
\end{equation*}
$$

where

$$
\begin{align*}
i D^{*}= & \frac{1}{3} v_{F}^{2}\left(1+B_{0}\right)\left(1+B_{1}\right)\left(\bar{\omega}_{s}-\bar{\Omega}_{0}\right) \\
& \times\left[\frac{\sin ^{2} \Delta}{\bar{\omega}_{c}^{2}-\left(\bar{\omega}_{s}-\bar{\Omega}_{0}\right)^{2}}-\frac{\cos ^{2} \Delta}{\left(\bar{\omega}_{s}-\bar{\Omega}_{0}\right)^{2}}\right] \tag{7.47}
\end{align*}
$$

[^2]Here $\Delta$ is the angle that $\boldsymbol{q}$ makes with the $z$ axis, and

$$
\begin{align*}
\bar{\omega}_{s} & =\omega_{s}+\frac{i}{\tau}\left(1+B_{1}\right),  \tag{7.48}\\
\bar{\omega}_{c} & =\frac{e H_{0}}{m^{*} c}\left(1+B_{1}\right),  \tag{7.49}\\
\bar{\Omega}_{0} & =\Omega_{0}\left(1+B_{1}\right)  \tag{7.50}\\
\bar{T}_{2} & =T_{2}\left(1+B_{0}\right)^{-1}
\end{align*}
$$

Notice that as $\omega$ and $q \rightarrow 0$ and $\tau \rightarrow \infty$, (7.46) reduces to the result we obtained in Chap. 4.

### 7.3 Conduction-Electron Spin Resonance

An interesting limit is when there are no quasiparticle interactions, that is, $B_{0}=B_{1}=0$. In this case $\bar{\omega}_{s}-\bar{\Omega}_{0}=\frac{i}{\tau}$ and $D^{*}$ is a real number. The susceptibility (7.46) then contains a pole at the conduction-electron spin resonance (CESR) frequence $\omega_{s}$. The fact that the lifetime of this mode is partially governed by the diffusion term has an interesting consequence for the resonance spectrum. The point is that in a metal the electromagnetic field that excites the resonance is not uniform across the sample. To find the field distribution we must solve Maxwell's equations with the appropriate boundary conditions.

Let us consider the geometry shown in Fig. 7.3 where the electromagnetic wave is incident from the left on a metal with conductivity $\sigma$. Assuming the


Fig. 7.3. Geometry and field distributions associated with conduction-electron spin resonance
fields vary only along the $z$-direction, the two Maxwell equations, together with $\boldsymbol{j}=\sigma \boldsymbol{E}$, reduce to

$$
\begin{gather*}
\nabla \times \boldsymbol{E}=\frac{1}{c} \frac{\partial \boldsymbol{B}}{\partial t}\left\{\begin{array}{l}
\frac{\partial E_{x}}{\partial z}=-\frac{1}{c}\left(\frac{\partial H_{y}}{\partial t}+4 \pi \frac{\partial M_{y}}{\partial t}\right) \\
\frac{\partial E_{y}}{\partial z}=\frac{1}{c}\left(\frac{\partial H_{x}}{\partial t}+4 \pi \frac{\partial M_{z}}{\partial t}\right)
\end{array}\right.  \tag{7.51}\\
\nabla \times \boldsymbol{H}=\frac{4 \pi}{c} j\left\{\begin{array}{l}
\frac{\partial E_{x}}{\partial z}=\frac{4 \pi}{c} j_{y}=\frac{4 \pi}{c} \sigma E_{y} \\
\frac{\partial H_{y}}{\partial z}=-\frac{4 \pi}{c} j_{x}=-\frac{4 \pi}{c} \sigma E_{x}
\end{array}\right. \tag{7.52}
\end{gather*}
$$

Introducing the circular components $M_{+}=M_{x}+i M_{y}, H_{+}=H_{x}+i H_{y}$, and assuming solutions of the form

$$
\begin{align*}
M_{+} & =m e^{i \omega t-\kappa z} \\
H_{+} & =h e^{i \omega t-\kappa z} \tag{7.53}
\end{align*}
$$

we obtain

$$
\begin{equation*}
\frac{m}{h}=\chi=-\frac{1}{4 \pi}\left(1+\frac{1}{2} i \delta^{2} \kappa^{2}\right) \tag{7.54}
\end{equation*}
$$

where $\delta=c / \sqrt{2 \pi \sigma \omega}$ is the skin depth. Self-consistency between the susceptibility (7.46) derived from the equation of motion for the magnetization and that derived above from Maxwell's equations gives a quadratic equation for the parameter $\kappa$. This has two roots, one of the order of $\delta$, the other of the order of $\sqrt{D^{*} T_{2}}$. The latter characterizes how far a spin diffuses before relaxing. The amplitudes of the fields associated with these solutions are determined from the boundary conditions. The results are sketched in Fig. 7.3. The magnetic field falls off in a distance of the order of the skin depth. The magnetization, however, penetrates a distance $\sqrt{D^{*} T_{2}}$ which may be much larger than $\delta$.

In the standard reflection-type resonance experiment the metal is placed at one end of a microwave cavity. The power absorbed by the cavity, which is easily calculated from the above results, is shown in Fig. 7.4.

We immediately notice the asymmetric nature of the absorption. This is associated with the fact that although an electron may only spend a time of the order of $T_{D}=\delta^{2} / 2 D^{*}$ in the skin depth, it returns to the skin depth many times before its spin "memory" is destroyed. Thus it experiences a set of microwave pulses whose intervals are random but whose phases are coherent. This can lead to destructive as well as constructive interference with the result that the power absorbed at some values of the dc field may be less than that ordinarily absorbed in zero field. Since Dyson [145] was the first to derive this characteristic shape, such lines are referred to as Dysonian. The asymmetry may be quantified by the ratio $\mathrm{A} / \mathrm{B}$ which depends upon the ratio of $T_{D}$ to


Fig. 7.4. Power absorption (a) and its derivative (b) due to electron spin resonance in a metal for a ratio of $T_{D} / T_{2} \simeq 0.1$


Fig. 7.5. Dependence of the asymmetry ratio $A / B$ on the ratio of the spin diffusion time $T_{D}$ to the spin relaxation time $T_{2}$
$T_{2}$ as shown in Fig. 7.5. The fact that the width of the line is proporitional to $1 / T_{2}$ is also due to the fact that the electron returns to the skin depth many times.

The fact that the magnetization penetrates much farther into the metal than the driving magnetic field is the basis of the transmission technique. In this technique the sample takes the form of a thin film whose thickness is large compared with $\delta$ but smaller than $\sqrt{D^{*} T_{2}}$. This film is placed between two microwave cavities. Off resonance no power reaches the second cavity. At resonance, however, the precessing spins diffuse across the film and radiate into the second cavity. The intensity of the magnetization excited depends upon the susceptibility within the skin depth. Thus it has been found that the sensitivity of the transmission technique can be greatly enhanced by depositing a thin ferromagnetic film on the front surface of the film being studied.

### 7.4 Spin Waves

Let us now return to the susceptibility (7.46) and consider the effect of the electron-electron interactions. In particular, if

$$
\left|\frac{\left(B_{0}-B_{1}\right) \omega_{s} \tau}{1+B_{0}}\right| \gg 1
$$

then $\tilde{\omega}_{s}-\bar{\Omega}_{0}$ becomes real and $D^{*}$ becomes pure imaginary and modes appear at $\omega=\omega_{s}-D^{*} k^{2}$. Thus, the interactions convert the transport of the magnetization from diffusive to propagating. These modes are referred to as spin waves, although they bear only a qualitative resemblance to the spin waves we shall discuss in the next chapter. In a slab of thickness $L$ the wave vector takes on values which are multiples of $\pi / L$. The modes then appear as sidebands of the main conduction-spin resonance line. Such spinwave sidebands have been observed in various metals [146]. The transmission spectrum for sodium is shown in Fig. 7.6. From careful measurements of the angular dependence of the spin-wave positions the Fermi liquid parameters can be deduced. For sodium $B_{0}=-0.18$ and $B_{1}=0.05$.

Notice that $D^{*}$ may be positive or negative, depending on the direction of $\boldsymbol{q}$ with respect to the dc field. In the next chapter we shall find that the spinwave spectrum in a ferromagnetic insulator always curves upward. The fact that the spectrum may curve downward in the metal is due to the "repulsion" of these spin-wave modes by the higher-lying orbital modes, whose $\boldsymbol{q}=0$ frequencies we have derived in (7.45).

Since the Platzmann-Wolff solution (7.46) is valid only for small $\boldsymbol{q}$ near $\omega_{s}$, it does not include the single-particle excitations illustrated in Fig. 7.1. In the presence of interactions these modes are shifted upward by a self-energy that is proportional to $N_{\downarrow}-N_{\uparrow}$. Therefore the spectrum has the form shown in Fig. 7.7. When the spin waves enter the single-particle band, they can decay into single-particle excitations. In this region they become critically damped.

### 7.5 Local Moments in Metals

It is interesting to consider the case when a "potentially" magnetic ion is dissolved in a metal. We say "potentially" because in some cases the magnetic response of the impurity is destroyed by the conduction electrons, a situation referred to as the Kondo effect which was discussed in Chap. 3. For our present purposes we shall assume that the local moment exists and that its coupling to the conduction electrons may be described by the exchange interaction

$$
\begin{equation*}
\mathcal{H}=-J \boldsymbol{S} \cdot s \tag{7.55}
\end{equation*}
$$

As a result of this interaction the magnetization associated with the local impurity will relax with a rate

$$
\begin{equation*}
\frac{1}{T_{i e}}=\frac{\pi}{\hbar} J^{2} N\left(\epsilon_{F}\right)^{2} k_{B} T \tag{7.56}
\end{equation*}
$$

(This result is analogous to the relaxation of nuclear spins in a metal through their hyperfine coupling with conduction electrons. In that case $J$ is replaced


Fig. 7.6. Typical spin wave signals as a function of applied dc magnetic field ( $H_{0} \approx$ $3,250 G$ ). (a) The $n=0$ mode (usual conduction-electron spin resonance) and the $n=1$ mode are clearly shown. (b) The gain and field sweep have been increased to display the first four spinwave modes beyond the CESR. The theoretical points have been obtained from the susceptibility in (7.46) [146]
by the hyperfine constant $A$, and we refer to the result as the Korringa relaxation rate.) The impurity spins also relax the conduction-electron magnetization with the rate

$$
\begin{equation*}
\frac{1}{T_{e i}}=\frac{2 \pi}{\hbar} J^{2} N\left(\epsilon_{F}\right) \frac{S(S+1)}{3} c \tag{7.57}
\end{equation*}
$$



Fig. 7.7. Magnetic excitation spectrum of an interacting electron system


Fig. 7.8. Schematic representation of the energy resevoirs associated with a localized spin impurity in a metal
where $c$ is the impurity concentration. Notice that

$$
\begin{equation*}
\frac{T_{i e}}{T_{e i}}=\frac{\chi_{i}}{\chi_{e}}, \tag{7.58}
\end{equation*}
$$

where $\chi_{i}$ is the Curie susceptibility and $\chi_{e}$ the Pauli susceptibility. This relation is actually very general, being a consequence of the principle of detailed balance. Considering that both spin systems can also relax directly to the lattice we have the situation illustrated in Fig. 7.8. The magnetizations are described by a pair of coupled Bloch-like equations [147],

$$
\begin{align*}
\frac{d \boldsymbol{M}_{e}}{d t} & =\gamma_{e} \boldsymbol{M}_{e} \times\left(\boldsymbol{H}+\lambda \boldsymbol{M}_{i}\right)-\frac{\boldsymbol{M}_{e}}{T_{e i}}+\frac{\boldsymbol{M}_{i}}{T_{i e}}-\frac{\left(\boldsymbol{M}_{e}-\boldsymbol{M}_{e}^{0}\right)}{T_{e l}} \\
\frac{d \boldsymbol{M}_{i}}{d t} & =\gamma_{i} \boldsymbol{M}_{i} \times\left(\boldsymbol{H}+\lambda \boldsymbol{M}_{e}\right)-\frac{\boldsymbol{M}_{i}}{T_{i e}}+\frac{\boldsymbol{M}_{e}}{T_{e i}}-\frac{\left(\boldsymbol{M}_{i}-\boldsymbol{M}_{i}^{0}\right)}{T_{i l}} \tag{7.59}
\end{align*}
$$

Here $\lambda$ is an effective field parameter which is proportional to the exchange $J$. For transition-metal impurities, such as Mn in $C u$ the relaxation rates $1 / T_{e i}$ and $1 / T_{i e}$ are much larger than the relaxation rate to the lattice. This
corresponds to a "bottleneck" condition. If the coupling $J$ is strong, then the two magnetizations remain parallel to one another and the transverse components of (7.59) become

$$
\frac{d}{d t}\binom{M_{e}^{+}}{M_{i}^{+}}=\left(\begin{array}{cc}
-i \gamma_{e} H-\frac{1}{T_{e i}} & \frac{1}{T_{i e}}  \tag{7.60}\\
\frac{1}{T_{e i}} & -i \gamma_{i} H-\frac{1}{T_{i e}}
\end{array}\right)\binom{M_{e}^{+}}{M_{i}^{+}} .
$$

Diagonalizing this equation we find that the effective $g$ value for the strongly coupled case is

$$
\begin{equation*}
g_{\mathrm{eff}}=\frac{g_{i} \chi_{i}+g_{e} \chi_{e}}{\chi_{i}+\chi_{e}} \tag{7.61}
\end{equation*}
$$

At low impurity concentrations or high temperatures $\chi_{i}$ is small and the observed $g$ value should be closed to that of the pure metal. As one increases the impurity concentration or goes to lower temperatures, $g_{\text {eff }}$ should shift towards a value characteristic of the impurity. The transmission electron spin resonance data [148] on Cu Mn shown in Fig. 7.9 has these features.


Fig. 7.9. Plot of the $g$ value obtained from transmission resonance versus temperature for three Cu Mn samples. The theoretical curves were obtained from (7.61) using $g_{\mathrm{Cu}}=2.033$ and $g_{\mathrm{Mn}}=2.013$ and the susceptibility ratios shown. A susceptibility ratio of 3 corresponds to 13 ppm of Mn in Cu [148]

### 7.6 Faraday Effect

The Faraday effect refers to the rotation of the plane of polarization of a linearly polarized electromagnetic wave as it propagates through a magnetic or magnetized material. Assuming for the moment that the propagation through such a medium is adequately characterized by the susceptibility (or permeability) tensor, Maxwell's equations tell us that the rotation per unit length of the medium is given by

$$
\frac{\Delta \theta}{\Delta z}=\frac{2 \pi \omega}{\eta} \chi_{x y}^{\prime \prime}
$$

In the case of a Kramers ground state we found that when $\omega \gg \omega_{0}, \chi_{x y}^{\prime \prime}$ decreases as $1 / \omega$ and $\Delta \theta / \Delta z$ reduces to

$$
\frac{\Delta \theta}{\Delta z}=\frac{\omega_{M}}{2 c / n}
$$

where $n$ is the real part of the complex index of refraction in the absence of a static magnetization and $\omega_{M}=4 \pi \gamma M$. For a magnetic material with a saturation magnetization of $4 \pi M=2000 \mathrm{G}$ and a dielectric constant of 13 , this gives a rotation of approximately $140^{\circ} / \mathrm{cm}$. Such rotation forms the basis for various nonreciprocal microwave devices.

As one goes beyond microwave frequencies, one must also consider the time-varying electric field which accompanies the "probing" magnetic field and brings the dielectric, or conductivity, tensor into play. The Faraday rotation associated with this "polarization" response is

$$
\frac{\Delta \theta}{\Delta z}=-\frac{2 \pi}{c n} \sigma_{x y}^{\prime}=\frac{2 \pi \omega}{c n} \varepsilon_{x y}^{\prime \prime} .
$$

Symmetry arguments, similar to those used in deriving the Onsager relation (1.89), tell us that $\varepsilon_{x y}^{\prime \prime}$ is a linear function of $M_{z}$. Physically, this dependence of the dielectric function on the magnetization arises through the spin-orbit interaction. The important point, however, is that the polarization-induced rotation increases with frequency while the magnetic contribution is independent of frequency. Thus there will be a frequency beyond which the polarization contribution dominates. This typically occurs in the near infrared. For this reason, one generally finds magnetooptical phenomena described entirely in terms of the conductivity. Pershan [149], in fact, has argued that so long as the electromagnetic wavelength is less that the sample dimensions, one can always describe the wave properties in terms of an effective dielectric function, setting the magnetic susceptibility to zero. However, as Pershan has also noted, one must pay careful attention to the boundary conditions when applying such a decription. On the other hand, there may be situations in which the microscopic behavior of the Faraday rotation may be more conveniently understood, or calculated, in terms of magnetic dipole matrix elements.

## Problems

7.1. The transmission resonances described in this chapter offer a good example of the nonlocal susceptibility introduced in Sect. 1.3. Suppose we wish to calculate the magnetic field at the back face of a metal film excited by a field at the front face (see figure on page 236). It can be shown that the magnetic field just outside the back face is proportional to the magnetization at the back surface, i.e., $h^{+}\left(L^{+}\right) \sim m^{+}\left(L^{-}\right)$. The proportionality involves the surface impedance. Use (1.58) and (1.59) to determine $m_{+}\left(L^{-}, \omega\right)$. Assume $\chi(\boldsymbol{q}, \omega)$ has the form (7.46) in the noninteracting limit, i.e., $B_{n}=0$, and that $h^{+}\left(z^{\prime}, \omega\right)$ is a delta function i.e., $h^{+}\left(z^{\prime}, \omega\right) \sim \delta\left(z^{\prime}\right)$. Since $q_{z}=n \pi / L$ the sum in (1.59) can be written as a sum over $n$. Using the identity


$$
\sum_{n=-\infty}^{\infty} \frac{(-1)^{n}}{A^{2}-\pi^{2} n^{2}}=\frac{\cot A / 2-\cot A}{A}
$$

obtain an expression for $m^{+}\left(L^{-}, \omega\right)$ and, hence, $h^{+}\left(L^{+}, \omega\right)$. Plot $h^{+}\left(L^{+}, \omega\right)$ versus $\left(\omega_{s}-\omega\right) / \omega_{s}$ for $\sqrt{D T_{2}} / L=6$ and 1.4.
7.2. Using the Fermi "Golden Rule" calculate the relaxation rates (7.56) and (7.57).

## The Dynamic Susceptibility of Strongly Interacting Systems

In the previous chapter we have seen that in nonferromagnetic metals the presence of interactions leads to magnetic excitations of a wavelike nature called spin waves. In this chapter we shall investigate these excitations in magnetically ordered systems.

### 8.1 Broken Symmetry

At one time spin waves were only thought to be associated with local moment systems. But they have a far more fundamental basis. In the paramagnetic state the system is rotationally invariant. In the ferromagnetically ordered state this symmetry is broken-there is a uniform magnetization $M$ in a particular direction. In principle, this direction is arbitrary, but in practice it is determined by anisotropy. In Chap. 4 we argued that the energy associated with a gradual variation in the magnetization has the form

$$
\frac{\delta E}{V}=\frac{A}{M_{0}^{2}}|\nabla \boldsymbol{M}|^{2}
$$

This energy implies that the magnetization in any macroscopically small region is acted on by an exchange torque coming from an effective field

$$
H_{\mathrm{eff}}=-\frac{2 A}{M_{0}^{2}} \nabla^{2} \boldsymbol{M}
$$

$M$ responds to this effective field just as it does to a real magnetic field. Therefore,

$$
\begin{equation*}
\frac{d \boldsymbol{M}}{d t}=-\gamma \boldsymbol{M} \times \boldsymbol{H}_{\mathrm{eff}} \tag{8.1}
\end{equation*}
$$

Thus, a transverse fluctuation in the magnetization with a wave vector $\boldsymbol{q}$ has a frequency

$$
\omega_{\boldsymbol{q}}=\gamma \frac{2 A}{M_{0}} q^{2}
$$

Such modes are a direct consequence of having broken the continuous rotational symmetry and are referred to as "Goldstone modes". A system characterized by an Ising Hamiltonian does not possess such a continuous symmetry and, indeed, there are no spin-wave-like excitations in the ordered state. The behavior of these modes at shorter wavelengths and the form of the exchange stiffness parameter depend upon the microscopic details which we shall consider in this chapter.

### 8.2 Insulators

Let us begin by considering a lattice of spins whose interactions may be described by the Heisenberg exchange interaction (2.89). Suppose we apply a uniform static field which serves to define a $z$-axis. We now wish to determine how this system responds to the time- and space-dependent field $\boldsymbol{H}_{1} \cos (\boldsymbol{q} \cdot \boldsymbol{r}) \cos \omega t$. If this field is in the $x$ direction, the total Hamiltonian becomes

$$
\begin{equation*}
\mathcal{H}=-\sum_{i} \sum_{j \neq i} J_{i j} S_{i} \cdot S_{j}+g \mu_{B} H_{0} \sum_{i} S_{i}^{z}+g \mu_{B} H_{1} \sum_{i} S_{i}^{x} \cos \left(\boldsymbol{q} \cdot \boldsymbol{R}_{i}\right) \cos \omega t . \tag{8.2}
\end{equation*}
$$

Introducing the Fourier components defined by (4.4), we obtain

$$
\begin{align*}
\mathcal{H}= & -\sum_{\boldsymbol{q}^{\prime}} J\left(-\boldsymbol{q}^{\prime}\right) S\left(\boldsymbol{q}^{\prime}\right) \cdot S\left(-\boldsymbol{q}^{\prime}\right)+g \mu_{B} H_{0} S_{z}(0)+\frac{1}{2} g \mu_{B} H_{1} \\
& \times\left[S_{x}(\boldsymbol{q})+S_{x}(-\boldsymbol{q})\right] \cos \omega t . \tag{8.3}
\end{align*}
$$

Since this Hamiltonian is space dependent as well as time dependent, the appropriate equation of motion, analogous to (5.4), is

$$
\begin{equation*}
\frac{d \boldsymbol{M}(\boldsymbol{q})}{d t}=-\frac{i}{\hbar V}\langle[\mathcal{M}(\boldsymbol{q}), \mathcal{H}]\rangle \tag{8.4}
\end{equation*}
$$

Since we are expressing the spin in units of $\hbar$, the commutation relations have the form

$$
\begin{equation*}
\left[S_{x}(\boldsymbol{q}), S_{y}\left(\boldsymbol{q}^{\prime}\right)\right]=i S_{z}\left(\boldsymbol{q}+\boldsymbol{q}^{\prime}\right) \tag{8.5}
\end{equation*}
$$

The commutator involving the $x$ component of the spin with the Hamiltonian then becomes

$$
\begin{align*}
{\left[S_{x}(\boldsymbol{q}), \mathcal{H}\right]=} & -i \sum_{\boldsymbol{q}^{\prime}} J\left(\boldsymbol{q}^{\prime}\right)\left[S_{z}\left(\boldsymbol{q}+\boldsymbol{q}^{\prime}\right) S_{y}\left(-\boldsymbol{q}^{\prime}\right)+S_{y}\left(\boldsymbol{q}^{\prime}\right) S_{z}\left(\boldsymbol{q}-\boldsymbol{q}^{\prime}\right)\right.  \tag{8.6}\\
& \left.-S_{y}\left(\boldsymbol{q}+\boldsymbol{q}^{\prime}\right) S_{z}\left(-\boldsymbol{q}^{\prime}\right)-S_{z}\left(\boldsymbol{q}^{\prime}\right) S_{y}\left(\boldsymbol{q}-\boldsymbol{q}^{\prime}\right)\right]-i g \mu_{B} H_{0} S_{y}(\boldsymbol{q})
\end{align*}
$$

In the random-phase approximation each Fourier component is assumed to be independent. This implies that $\left\langle S_{z}\left(\boldsymbol{q}+\boldsymbol{q}^{\prime}\right) S_{y}\left(-\boldsymbol{q}^{\prime}\right)\right\rangle=\left\langle S_{z}\left(\boldsymbol{q}+\boldsymbol{q}^{\prime}\right)\right\rangle\left\langle S_{y}\left(-\boldsymbol{q}^{\prime}\right)\right\rangle$. Furthermore, in the low-temperature region we may linearize (8.4) by making the approximation

$$
\begin{equation*}
\left\langle S_{z}\left(\boldsymbol{q}^{\prime}\right)\right\rangle=N S \Delta\left(\boldsymbol{q}^{\prime}\right) \tag{8.7}
\end{equation*}
$$

With these approximations, (8.4) becomes

$$
\begin{equation*}
\frac{d M_{x}(\boldsymbol{q})}{d t}=-\left\{\gamma H_{0}+\frac{2 N S}{\hbar}[J(0)-J(\boldsymbol{q})]\right\} M_{y}(\boldsymbol{q}) \tag{8.8}
\end{equation*}
$$

where $\gamma=g \mu_{b} / \hbar$ is the gyromagnetic ratio, which we take as positive for electrons. This equation is analogous to (6.7a), and the equation for $M_{y}(\boldsymbol{q})$ is analogous to (6.7b). Therefore all the arguments leading to the susceptibility (6.18) also apply in this case. Thus we find that the imaginary part of the susceptibility of a ferromagnet at low temperatures has the form

$$
\begin{equation*}
\chi_{x x}^{\prime \prime}(\boldsymbol{q}, \omega)=\frac{\pi g^{2} \mu_{B}^{2} N S}{2 \hbar}\{\delta[\omega-\omega(\boldsymbol{q})]-\delta[\omega+\omega(\boldsymbol{q})]\} \tag{8.9}
\end{equation*}
$$

where

$$
\begin{equation*}
\omega(\boldsymbol{q})=\gamma H_{0}+\frac{2 N S}{\hbar}[J(0)-J(\boldsymbol{q})] \tag{8.10}
\end{equation*}
$$

These are the spin-wave modes. Classically, these excitations correspond to a precession of the spin system in which the phase of one spin relative to another is determined by the wave vector $\boldsymbol{q}$. An example of these modes is shown in Fig. 8.1. The $\boldsymbol{q}=0$, or uniform-precession, mode corresponds to ferromagnetic resonance. Quantum mechanically, a spin wave consists of a single spin flip propagating throughout the lattice. Since the spins are quantized, these excitations are also quantized. Consequently, they are often referred to as magnons. Because these modes are collective, in the sense that they involve

$$
\begin{aligned}
& 9999.97 P 8 \\
& \text { 999994l99859 } \\
& \text { pRER GTPR } \\
& \text { (a) } \\
& \text { (b) }
\end{aligned}
$$

Fig. 8.1. Schematic representations of a spin wave (a) propagating parallel to the applied magnetic field, and (b) propagating perpendicular to this field
all the spins in the lattice, the excitation energy varies continuously from $\gamma \hbar H_{0}$ up to the exchange energy. If the only excitations were single-particle excitations, the energy required to produce a spin deviation would be of the order of the exchange energy.

For a simple cubic lattice with lattice parameter $a$, and a nearest-neighbor exchange $J$, the long wavelength limit of $J(0)-J(\boldsymbol{q})$ is $J a^{2} q^{2} / N$. Therefore the exchange stiffness introduced at the beginning of this chapter is

$$
A=S^{2} a^{2} J / v
$$

where $v$ is the atomic volume, $V / N$.
Combining (4.16), (8.10), we see that the ratio of the maximum spinwave frequency to $k_{B} T_{C} / \hbar$ for a simple cubic lattice is $6 /(S+1)$. Therefore the high-temperature approximation used in writing (4.48) is valid only for $T / T_{C}>6 /(S+1)$.

### 8.2.1 Spin-Wave Theory

Our low-temperature approximation (8.7) has led to a set of modes that, it turns out, behave just like a system of independent harmonic oscillators. In 1940 Holstein and Primakoff introduced a very useful technique which formalizes this harmonic-oscillator behavior. Their approach was based on the expansion of spin operators in terms of the creation and annihilation operators of the harmonic oscillator. For example, consider the effect of $S_{i}^{-}$ acting on the spin state $\left|S, M_{S}\right\rangle$

$$
\begin{equation*}
S_{i}^{-}\left|S, M_{S}\right\rangle=\sqrt{\left(S+M_{S}\right)\left(S-M_{S}+1\right)}\left|S, M_{S}-1\right\rangle \tag{8.11}
\end{equation*}
$$

If we introduce the spin-deviation operator $\hat{n}_{i}=S-S_{i}^{z}$, with the quantum numbers $n_{i}=S-M_{S}$, this relation becomes

$$
\begin{equation*}
S_{i}^{-}\left|n_{i}\right\rangle=\sqrt{2 S} \sqrt{n_{i}+1} \sqrt{1-\frac{n_{i}}{2 S}}\left|n_{i}+1\right\rangle \tag{8.12}
\end{equation*}
$$

The harmonic-oscillator operator $a^{\dagger}$ has the property (as a consequence of its commutation relations) that

$$
\begin{equation*}
a^{\dagger}|n\rangle=\sqrt{n+1}|n+1\rangle \tag{8.13}
\end{equation*}
$$

Therefore Holstein and Primakoff made the associations

$$
\begin{align*}
S_{i}^{-} & =\sqrt{2 S} a_{i}^{\dagger} f_{i}(S) \\
S_{i}^{+} & =\sqrt{2 S} f_{i}(S) a_{i} \\
S_{i}^{z} & =-S+a_{i}^{\dagger} a_{i} \tag{8.14}
\end{align*}
$$

where $f_{i}(S) \equiv \sqrt{1-\left(a_{i}^{\dagger} a_{i} / 2 S\right)}$. Notice that this factor makes the transformation nonlinear. The point is that the eigenvalues of a spin system consist of a finite number $(2 S+1)$ of equally spaced values while those of the harmonic oscillator consist of an infinite number of equally spaced levels. It is an easy matter to show that the representations (8.14) satisfy the required commutation relations.

As we have seen, in dealing with coupled systems it is convenient to introduce Fourier components. This suggests that we expand the spin-deviation operators according to

$$
\begin{align*}
& a_{i}=\frac{1}{\sqrt{N}} \sum_{\boldsymbol{k}} e^{i \boldsymbol{k} \cdot \boldsymbol{r}_{i}} \boldsymbol{a}_{\boldsymbol{k}}  \tag{8.15}\\
& a_{i}^{\dagger}=\frac{1}{\sqrt{N}} \sum_{\boldsymbol{k}} e^{i \boldsymbol{k} \cdot \boldsymbol{r}_{i}} \boldsymbol{a}_{\boldsymbol{k}}^{\dagger} \tag{8.16}
\end{align*}
$$

We shall refer to $a_{\boldsymbol{k}}$ and $a_{\boldsymbol{k}}^{\dagger}$ as magnon annihilation and magnon creation operators, respectively. The spin operators may be written in terms of these operators as

$$
\begin{align*}
S_{i}^{+}= & \sqrt{\frac{2 S}{N}} \sum_{\boldsymbol{k}} e^{i \boldsymbol{k} \cdot R_{i}} a_{\boldsymbol{k}} \\
& -\frac{1}{N \sqrt{8 N S}} \sum_{\boldsymbol{k}, \boldsymbol{k}^{\prime}, \boldsymbol{k}^{\prime \prime}} e^{-i\left(\boldsymbol{k}+\boldsymbol{k}^{\prime}-\boldsymbol{k}^{\prime \prime}\right) \cdot \boldsymbol{r}_{i}} a_{\boldsymbol{k}}^{\dagger} a_{\boldsymbol{k}^{\prime}} a_{\boldsymbol{k}^{\prime \prime}}+\ldots  \tag{8.17}\\
S_{i}^{-}= & \sqrt{\frac{2 S}{N}} \sum_{\boldsymbol{k}} e^{-i \boldsymbol{k} \cdot R_{i}} a_{\boldsymbol{k}}^{\dagger} \\
& -\frac{1}{N \sqrt{8 N S}} \sum_{\boldsymbol{k}, \boldsymbol{k}^{\prime}, \boldsymbol{k}^{\prime \prime}} e^{-i\left(\boldsymbol{k}+\boldsymbol{k}^{\prime}-\boldsymbol{k}^{\prime \prime}\right) \cdot R_{i}} a_{\boldsymbol{k}}^{\dagger} a_{\boldsymbol{k}^{\prime}}^{\dagger} a_{\boldsymbol{k}^{\prime \prime}}+\ldots  \tag{8.18}\\
S_{i}^{z}= & -S+\frac{1}{N} \sum_{\boldsymbol{k}, \boldsymbol{k}^{\prime}} e^{-i\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \cdot R_{i}} a_{\boldsymbol{k}}^{\dagger} a_{\boldsymbol{k}^{\prime}} . \tag{8.19}
\end{align*}
$$

The Hamiltonian for a system of independent harmonic oscillators has the form $\sum \hbar \omega_{\boldsymbol{k}} a_{\boldsymbol{k}}^{\dagger} a_{\boldsymbol{k}}$. Therefore the objective of the Holstein-Primakoff approach is to determine the quadratic part of the Hamiltonian resulting from substitutions (8.17)-(8.19). Let us consider this procedure for a ferromagnet (other systems are treated in [150]).

The Zeeman and exchange interactions were considered above. Let us add to these the dipole-dipole interaction (2.50). The total Hamiltonian is then

$$
\begin{equation*}
\mathcal{H}=\mathcal{H}_{Z}+\mathcal{H}_{\mathrm{ex}}+\mathcal{H}_{\mathrm{dip}} \tag{8.20}
\end{equation*}
$$

The low-temperature or spin-wave approximation (8.7) corresponds to taking $f_{i}(S)=1$. This is because at very low temperatures the number of spin waves
excited is much less than the total number of spins. Therefore the average spin deviation $n_{i}$ is much less than 1 . In terms of the magnon operators, the Zeeman interaction becomes

$$
\begin{equation*}
\mathcal{H}_{z}=\gamma H_{0} \sum_{i} S_{i}^{z}=-\gamma H_{0} \sum_{i}\left(S-\frac{1}{N} \sum_{\boldsymbol{k}, \boldsymbol{k}^{\prime}} e^{-i\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \cdot R_{i}} a_{\boldsymbol{k}}^{\dagger} a_{\boldsymbol{k}^{\prime}}\right) \tag{8.21}
\end{equation*}
$$

If the lattice has translational invariance, then

$$
\begin{equation*}
\sum_{i} e^{-i\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \cdot \boldsymbol{r}_{i}}=N \Delta\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \tag{8.22}
\end{equation*}
$$

Therefore (8.21) reduces to

$$
\begin{equation*}
\mathcal{H}_{Z}=-\gamma H_{0} N S+\gamma H_{0} \sum_{\boldsymbol{k}} a_{\boldsymbol{k}}^{\dagger} a_{\boldsymbol{k}} \tag{8.23}
\end{equation*}
$$

Similarly, if the exchange coupling between an ion $i$ and those ions at positions $\delta$ relative to $i$ has the value $J$, then the exchange interaction is

$$
\begin{align*}
\mathcal{H}_{\mathrm{ex}}= & -J \sum_{i, \delta}\left[\frac{1}{2} S_{i}^{+} S_{i+\delta}^{-}+\frac{1}{2} S_{i}^{-} S_{i+\delta}^{+}+S_{i}^{z} S_{i+\delta}^{z}\right]  \tag{8.24}\\
\mathcal{H}_{\mathrm{ex}}= & -J \sum_{i, \delta}\left[\frac{S}{N} \sum_{\boldsymbol{k}, \boldsymbol{k}^{\prime}} e^{i \boldsymbol{k}^{\prime} \cdot\left(\boldsymbol{r}_{i}+\boldsymbol{\delta}\right)} a_{\boldsymbol{k}} a_{\boldsymbol{k}^{\prime}}^{\dagger}\right. \\
& +\frac{S}{N} \sum_{\boldsymbol{k}, \boldsymbol{k}^{\prime}} e^{-i \boldsymbol{k} \cdot \boldsymbol{r}_{i}} e^{i \boldsymbol{k}^{\prime} \cdot(\boldsymbol{r}+\boldsymbol{\delta})} a_{\boldsymbol{k}}^{\dagger} a_{\boldsymbol{k}^{\prime}} \\
& +\left(S-\frac{1}{N} \sum_{\boldsymbol{k}, \boldsymbol{k}^{\prime}} e^{-i\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \cdot \boldsymbol{R}_{i}} a_{\boldsymbol{k}}^{\dagger} a_{\boldsymbol{k}^{\prime}}\right) \\
& \left.\times\left(S-\frac{1}{N} \sum_{\boldsymbol{k}, \boldsymbol{k}^{\prime}} e^{-i\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \cdot\left(\boldsymbol{R}_{i}+\boldsymbol{\delta}\right)} a_{\boldsymbol{k}}^{\dagger} a_{\boldsymbol{k}^{\prime}}\right)\right] \tag{8.25}
\end{align*}
$$

In keeping with our spirit of setting $f_{i}(S)=1$, we also neglect the fourth-order terms in this expansion. Thus, if $z$ is the number of interacting neighbors,

$$
\begin{align*}
\mathcal{H}_{\mathrm{ex}}= & -J S \sum_{\boldsymbol{k}} \sum_{\delta} e^{-i \boldsymbol{k} \cdot \boldsymbol{\delta}} a_{\boldsymbol{k}} a_{\boldsymbol{k}}^{\dagger}-J S \sum_{\boldsymbol{k}} \sum_{\delta} e^{i \boldsymbol{k} \cdot \boldsymbol{\delta}} a_{\boldsymbol{k}}^{\dagger} a_{\boldsymbol{k}} \\
& -N z J S^{2}+2 z J S \sum_{\boldsymbol{k}} a_{\boldsymbol{k}}^{\dagger} a_{\boldsymbol{k}} \tag{8.26}
\end{align*}
$$

We define

$$
\gamma_{\boldsymbol{k}}=\frac{1}{z} \sum_{\delta} e^{i \boldsymbol{k} \cdot \boldsymbol{\delta}}
$$

For example, with nearest-neighbor interactions in a simple cubic crystal having a lattice parameter $a$,

$$
\gamma_{\boldsymbol{k}}=\frac{1}{3}\left(\cos k_{x} a+\cos k_{y} a+\cos k_{z} a\right) .
$$

Notice that

$$
\sum_{k} \gamma_{k}=0
$$

Thus

$$
\begin{equation*}
\mathcal{H}_{\mathrm{ex}}=-N z J S^{2}+2 z J S \sum_{\boldsymbol{k}}\left(1-\gamma_{\boldsymbol{k}}\right) a_{\boldsymbol{k}}^{\dagger} a_{\boldsymbol{k}} \tag{8.27}
\end{equation*}
$$

Let us now consider the dipole-dipole interaction, whose treatment is more tedious.

$$
\begin{align*}
\mathcal{H}_{\mathrm{dip}}= & \frac{1}{2} g^{2} \mu_{B}^{2} \sum_{i, j}\left[\frac{S_{i} \cdot S_{j}}{r_{i j}^{3}}-\frac{3\left(S_{i} \cdot \boldsymbol{r}_{i j}\right)\left(S_{j} \cdot \boldsymbol{r}_{i j}\right)}{r_{i j}^{5}}\right],  \tag{8.28}\\
\mathcal{H}_{\text {dip }}= & \frac{1}{2} g^{2} \mu_{B}^{2} \sum_{i, j}\left\{\frac{S_{i}^{+} S_{j}^{-}}{2 r_{i j}^{3}}+\frac{S_{i}^{-} S_{j}^{+}}{2 r_{i j}^{3}}+\frac{S_{i}^{z} S_{j}^{z}}{r_{i j}^{3}}\right.  \tag{8.29}\\
& \left.-\frac{3}{r_{i j}^{5}}\left[\left(\frac{1}{2} S_{i}^{+} r_{i j}^{-}+\frac{1}{2} S_{i}^{-} r_{i j}^{+}+S_{i}^{z} z_{i j}\right)\left(\frac{1}{2} S_{j}^{+} r_{i j}^{-}+\frac{1}{2} S_{j}^{-} r_{i j}^{+}+S_{j}^{z} z_{i j}\right)\right]\right\}, \\
\mathcal{H}_{\text {dip }} \approx & \frac{1}{2} g^{2} \mu_{B}^{2} \sum_{i, j}\left[S_{i}^{+} S_{j}^{-} \frac{1}{2 r_{i j}^{3}}\left(1-\frac{3}{2} \frac{r_{i j}^{+} r_{i j}^{-}}{r_{i j}^{2}}\right)+S_{i}^{-} S_{j}^{+} \frac{1}{2 r_{i j}^{3}}\left(1-\frac{3}{2} \frac{r_{i j}^{+} r_{i j}^{-}}{r_{i j}^{2}}\right)\right. \\
& \left.+S_{i}^{z} S_{j}^{z} \frac{1}{r_{i j}^{3}}\left(1-3 \frac{z_{i j}^{2}}{r_{i j}^{2}}\right)-\frac{3}{4} S_{i}^{+} S_{j}^{+} \frac{\left(r_{i j}^{-}\right)^{2}}{r_{i j}^{5}}-\frac{3}{4} S_{i}^{-} S_{j}^{-} \frac{\left(r_{i j}^{+}\right)^{2}}{r_{i j}^{5}}\right], \tag{8.30}
\end{align*}
$$

where $r_{i j}^{ \pm}=x_{i j} \pm i y_{i j}$.
The approximation symbol in (8.30) indicates that we have kept only those terms which will lead to quadratic magnon terms. In addition to neglecting three- and four-magnon terms, we have also neglected linear terms. The presence of such terms is an indication that our assumed ground-state spin configuration is not correct. To find the correct configuration we assume that the ground-state spin orientation at site $i$ has some direction, characterized by the angles $\theta_{i}$ and $\varphi_{i}$ with respect to the crystallographic axes. Setting the coefficients of the one-magnon terms to 0 determines these angles. In the dipolar
case this is a small effect, and we shall neglect it. However, in certain canted spin systems care must be exercised in choosing the proper configuration. Introducing the magnon operators, we obtain

$$
\begin{align*}
\mathcal{H}_{\mathrm{dip}}= & \frac{1}{2} g^{2} \mu_{B}^{2} \sum_{\boldsymbol{k}, \boldsymbol{k}^{\prime}} \sum_{i, j}\left[\frac{S}{N r_{i j}^{3}}\left(1-\frac{3}{2} \frac{r_{i j}^{+} r_{i j}^{-}}{r_{i j}^{2}}\right) a_{\boldsymbol{k}}^{\dagger} a_{\boldsymbol{k}^{\prime}} e^{i \boldsymbol{k} \cdot \boldsymbol{r}_{i j}} e^{i\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \cdot \boldsymbol{R}_{j}}\right. \\
& +\frac{S}{N r_{i j}^{3}}\left(1-\frac{3}{2} \frac{r_{i j}^{+} r_{i j}^{-}}{r_{i j}^{2}}\right) a_{\boldsymbol{k}}^{\dagger} a_{\boldsymbol{k}^{\prime}} e^{-i \boldsymbol{k} \cdot \boldsymbol{r}_{i j}} e^{-i\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \cdot \boldsymbol{R}_{j}}+\frac{S^{2}}{r_{i j}^{3}}\left(1-3 \frac{z_{i j}^{2}}{r_{i j}^{2}}\right) \\
& -\frac{2 S}{N r_{i j}^{3}}\left(1-3 \frac{z_{i j}^{2}}{r_{i j}^{2}}\right) a_{\boldsymbol{k}}^{\dagger} a_{\boldsymbol{k}^{\prime}} e^{-i\left(\boldsymbol{k}-\boldsymbol{k}^{\prime}\right) \cdot \boldsymbol{R}_{j}} \\
& -\frac{3 S}{2 N} \frac{\left(r_{i j}^{-}\right)^{2}}{r_{i j}^{5}} a_{\boldsymbol{k}} a_{\boldsymbol{k}^{\prime}} e^{i \boldsymbol{k} \cdot \boldsymbol{r}_{i j}} e^{i\left(\boldsymbol{k}+\boldsymbol{k}^{\prime}\right) \cdot \boldsymbol{R}_{j}} \\
& \left.-\frac{3 S}{2 N} \frac{\left(r_{i j}^{+}\right)^{2}}{r_{i j}^{5}} a_{\boldsymbol{k}}^{\dagger} a_{\boldsymbol{k}^{\prime}}^{\dagger} e^{-i \boldsymbol{k} \cdot \boldsymbol{r}_{i j}} e^{-i\left(\boldsymbol{k}+\boldsymbol{k}^{\prime}\right) \cdot \boldsymbol{R}_{j}}\right] \tag{8.31}
\end{align*}
$$

To evaluate the spatial sums we neglect boundary effects, so that the sums may be carried out independently; that is,

$$
\begin{equation*}
\sum_{\boldsymbol{R}_{j}} \sum_{\boldsymbol{R}_{i}} \rightarrow \sum_{\boldsymbol{R}_{j}} \sum_{r=\boldsymbol{R}_{i}-\boldsymbol{R}_{j}} \tag{8.32}
\end{equation*}
$$

The dipole Hamiltonian then reduces to

$$
\begin{align*}
\mathcal{H}_{\mathrm{dip}}= & \frac{1}{2} g^{2} \mu_{B}^{2}\left\{N^{2} S^{2} \sum_{\boldsymbol{r}} \frac{1}{r^{3}}\left(1-\frac{3 z^{2}}{\boldsymbol{r}^{2}}\right)+S \sum_{\boldsymbol{r}} e^{i \boldsymbol{k} \cdot \boldsymbol{r}} \frac{1}{r^{3}}\left(1-\frac{3}{2} \frac{r^{+} r^{-}}{r^{2}}\right)\right. \\
& -\left[2 S \sum_{r} \frac{1}{r^{3}}\left(1-\frac{3 z^{2}}{r^{2}}\right)-2 S \sum_{\boldsymbol{r}} e^{i \boldsymbol{k} \cdot \boldsymbol{r}} \frac{1}{r^{3}}\left(1-\frac{3}{2} \frac{r^{+} r^{-}}{r^{2}}\right)\right] a_{\boldsymbol{k}}^{\dagger} a_{\boldsymbol{k}} \\
& \left.-\left[\frac{3}{2} S \sum_{r} e^{i \boldsymbol{k} \cdot \boldsymbol{r}} \frac{\left(r^{-}\right)^{2}}{r^{5}}\right] a_{\boldsymbol{k}} a_{-\boldsymbol{k}}-\left[\frac{3}{2} S \sum_{\boldsymbol{r}} e^{-i \boldsymbol{k} \cdot \boldsymbol{r}} \frac{\left(r^{+}\right)^{2}}{r^{5}}\right] a_{\boldsymbol{k}}^{\dagger} a_{-\boldsymbol{k}}^{\dagger}\right\} . \tag{8.33}
\end{align*}
$$

We now break up the sum over $\boldsymbol{r}$ into a sum within a sphere of radius a plus an integral over the rest of the sample,

$$
\begin{equation*}
\sum_{r}=\sum^{\prime}+\frac{N}{V} \int d \boldsymbol{r} \tag{8.34}
\end{equation*}
$$

The reason for doing this is that if $a \ll 2 \pi / k$, the magnon wavelength, then the sum for a cubic crystal is 0 .

Now consider the remaining integral associated with the first term in the Hamiltonian,

$$
\begin{align*}
\frac{N}{V} \int\left(1-\frac{3 z^{2}}{r^{2}}\right) d \boldsymbol{r} & =\frac{N}{V} \int \nabla \cdot\left(\frac{\boldsymbol{z}}{r^{3}}\right) d \boldsymbol{r} \\
& =\frac{N}{V} \int_{\text {sphere }} \frac{\boldsymbol{z} \cdot d \boldsymbol{s}}{r^{3}}-\frac{N}{V} \int_{\substack{\text { sample } \\
\text { surface }}} \frac{\boldsymbol{z} \cdot d \boldsymbol{S}}{r^{3}} \\
& =\frac{N}{V}\left(\frac{4 \pi}{3}-4 \pi N_{\boldsymbol{z}}\right) \tag{8.35}
\end{align*}
$$

where the demagnetization factor

$$
N_{z} \equiv \frac{1}{4 \pi} \int_{\substack{\text { sample } \\ \text { surface }}} \frac{\boldsymbol{z} \cdot d \boldsymbol{S}}{r^{3}}
$$

gives rise to the demagnetization field and the term $4 \pi / 3$ gives rise to the Lorentz field. Now consider the integral

$$
\begin{equation*}
\frac{N}{V} \int e^{i \boldsymbol{k} \cdot \boldsymbol{r}} \frac{1}{r^{3}}\left(1-\frac{3 z^{2}}{r^{2}}\right) d \boldsymbol{r} \tag{8.36}
\end{equation*}
$$

which involves a plane-wave factor. Expanding the plane wave in spherical harmonics and recognizing that $1-3\left(z^{2} / r^{2}\right)$ is a spherical harmonic, we have

$$
\begin{align*}
& -\frac{N}{V} \int \sum_{l, m} 4 \pi(i)^{l} j_{l}(k r) Y_{l}^{m *}(\Omega) Y_{l}^{m}\left(\Omega^{\prime}\right) \frac{2}{r^{3}} \sqrt{\frac{4 \pi}{5}} Y_{2}^{0}(\Omega) r^{2} d r d \Omega \\
& \quad=-\frac{N}{V} 4 \pi\left[\frac{j_{l}(\boldsymbol{k} \boldsymbol{r})}{\boldsymbol{k} \boldsymbol{r}}\right]_{a}^{\text {surface }}\left(3 \cos ^{2} \theta_{\boldsymbol{k}}-1\right) \tag{8.37}
\end{align*}
$$

where $\theta_{\boldsymbol{k}}$ is the angle that $\boldsymbol{k}$ makes with the $z$-axis. If the sample dimension $d$ is large, then $k d \gg 1$ and $j_{l}(k d) / d k \rightarrow 0$. If $k a \ll 1$, then $j_{l}(k a) / k a \rightarrow \frac{1}{3}$. Therefore (8.36) becomes

$$
\begin{equation*}
\frac{N}{V}\left(\frac{8 \pi}{3}-4 \pi \sin ^{2} \theta_{k}\right) \tag{8.38}
\end{equation*}
$$

The condition $k d \gg 1$ gives a zero result because the magnetization on the surface of the sample alternates rapidly, averaging to 0 . This condition does not hold for small wave vectors. In particular, let us consider the $\boldsymbol{k}=0$ mode. We shall return later to a discussion of the nonzero, but small, wave vectors. For the case $\boldsymbol{k}=0$ we treat those terms involving $r^{ \pm}$as we did those involving $z^{2}$. This leads to transverse demagnetizing factors $N_{x}$ and $N_{y}$. After we have carried out all the integrals, the dipole-dipole Hamiltonian becomes

$$
\begin{align*}
\mathcal{H}_{\text {dip }}= & \sum_{\boldsymbol{k}}\left[\frac{1}{2} M V\left(4 \pi N_{z} M-\frac{4 \pi}{3} M\right)+\left\{\begin{array}{l}
\frac{1}{2} \omega_{M}\left(N_{x}+N_{y}\right)-N_{z} \omega_{M} \\
\frac{1}{2} \omega_{M} \sin ^{2} \theta_{\boldsymbol{k}}-N_{z} \omega_{M}
\end{array}\right\} a_{\boldsymbol{k}}^{\dagger} a_{\boldsymbol{k}}\right. \\
& +\left\{\begin{array}{l}
\frac{1}{4} \omega_{M}\left(N_{x}-N_{y}\right) \\
\frac{1}{4} \omega_{M} \sin ^{2} \theta_{\boldsymbol{k}} \exp \left(-2 \varphi_{\boldsymbol{k}}\right)
\end{array}\right\} a_{\boldsymbol{k}} a_{-\boldsymbol{k}} \\
& \left.+\left\{\begin{array}{l}
\frac{1}{4} \omega_{M}\left(N_{x}-N_{y}\right) \\
\frac{1}{4} \omega_{M} \sin ^{2} \theta_{\boldsymbol{k}} \exp \left(i 2 \varphi_{\boldsymbol{k}}\right)
\end{array}\right\} a_{\boldsymbol{k}}^{\dagger} a_{-\boldsymbol{k}}^{\dagger}\right] \tag{8.39}
\end{align*}
$$

where $M=N g \mu_{B} S / V$ and $\omega_{M}=4 \pi \gamma M$. The upper terms in the braces apply to the $\boldsymbol{k}=0$ mode and the lower terms apply to the $\boldsymbol{k} \neq 0$ modes. The total Hamiltonian may now be written as

$$
\begin{equation*}
\mathcal{H}=E_{0}+\sum_{k}\left(A_{\boldsymbol{k}} a_{\boldsymbol{k}}^{\dagger} a_{\boldsymbol{k}}+B_{\boldsymbol{k}} a_{\boldsymbol{k}} a_{-\boldsymbol{k}}+B_{\boldsymbol{k}}^{*} a_{\boldsymbol{k}}^{\dagger} a_{-\boldsymbol{k}}^{\dagger}\right) \tag{8.40}
\end{equation*}
$$

where $A_{\boldsymbol{k}}$ and $B_{\boldsymbol{k}}$ are determined from (8.23), (8.27), and (8.39).
This is not yet the desired form, since the dipole-dipole interaction has produced a coupling between the $+\boldsymbol{k}$ and $-\boldsymbol{k}$ spin waves. This means that the plane waves are not the correct normal modes. To find the correct modes we must diagonalize $\mathcal{H}$. Since the Hamiltonian (8.40) is the product of operators, its diagonalization is slightly different from that of a product of $c$-numbers. In particular, suppose we write the Hamiltonian as

$$
\begin{equation*}
\mathcal{H}=x^{\dagger} H x \tag{8.41}
\end{equation*}
$$

where $x$ is a column vector whose components are the operators entering the Hamiltonian and $H$ is a $c$-number matrix. For example, if we neglect the zero-point term, we may write the Hamiltonian (8.40) as

$$
\begin{equation*}
\mathcal{H}=\frac{1}{2} \sum_{\boldsymbol{k}} x_{\boldsymbol{k}}^{\dagger} H_{\boldsymbol{k}} x_{\boldsymbol{k}} \tag{8.42}
\end{equation*}
$$

where

$$
x_{\boldsymbol{k}}=\left[\begin{array}{l}
a_{k}  \tag{8.43}\\
a_{-k}^{\dagger}
\end{array}\right] \quad \text { and } \quad H_{\boldsymbol{k}}=\left[\begin{array}{cc}
A_{\boldsymbol{k}} & 2 B_{k}^{*} \\
2 B_{k} & A_{-k}
\end{array}\right] .
$$

The operator nature of $x$ may be specified by the commutator

$$
\begin{equation*}
\left[x, x^{\dagger}\right] \equiv x\left(x^{* T}\right)-\left(x^{*} x^{T}\right)^{T} \equiv g \tag{8.44}
\end{equation*}
$$

Note that when the elements of matrices are operators, the transpose of a product of such matrices is not equal to the product of the transposes in reverse order.

It is generally desired that the new modes that diagonalize the Hamiltonian have the same commutation relations as the original modes; that is, the transformation must be canonical. If the new modes are written as

$$
\begin{equation*}
x=S x^{\prime} \tag{8.45}
\end{equation*}
$$

then the condition that the transformation $S$ diagonalizes the Hamiltonian and also preserves the commutations relations is [151]

$$
\begin{equation*}
H S=g^{-1} S g \Omega_{H} \tag{8.46}
\end{equation*}
$$

where $\Omega_{H}$ is the eigenvalue matrix. Solving this eigenvalue problem for our case leads to the so called Bogolubov transformation

$$
\left[\begin{array}{c}
a_{k}  \tag{8.47}\\
a_{-k}^{\dagger}
\end{array}\right]=\left[\begin{array}{cc}
u_{k} & v_{k}^{*} \\
v_{k} & u_{k}
\end{array}\right]\left[\begin{array}{c}
\alpha_{k} \\
\alpha_{-k}^{\dagger}
\end{array}\right]
$$

where

$$
\begin{aligned}
& u_{\boldsymbol{k}}=\sqrt{\frac{A_{\boldsymbol{k}}+\omega_{\boldsymbol{k}}}{2 \omega_{\boldsymbol{k}}}} \\
& v_{\boldsymbol{k}}=\sqrt{\frac{A_{\boldsymbol{k}}-\omega_{\boldsymbol{k}}}{2 \omega_{\boldsymbol{k}}}} \exp \left(i \varphi_{\boldsymbol{k}}\right)
\end{aligned}
$$

In terms of these new modes, the Hamiltonian has the desired form

$$
\begin{equation*}
\mathcal{H}=\sum_{k} \hbar \omega_{k} \alpha_{k}^{\dagger} \alpha_{k} \tag{8.48}
\end{equation*}
$$

where

$$
\begin{aligned}
\omega_{\boldsymbol{k}} & =\sqrt{A_{\boldsymbol{k}}^{2}-4\left|B_{\boldsymbol{k}}\right|^{2}}, \\
& = \begin{cases}\sqrt{\left(\gamma H_{i}+N_{x} \omega_{N}\right)\left(\gamma H_{i}+N_{y} \omega_{M}\right)} & \boldsymbol{k}=0, \\
\sqrt{\left[\gamma H_{i}+2 z J S\left(1-\gamma_{\boldsymbol{k}}\right)\right]\left[\gamma H_{i}+2 z J S\left(1-\gamma_{\boldsymbol{k}}\right)+\omega_{M} \sin ^{2} \theta_{\boldsymbol{k}}\right]}, & \boldsymbol{k} \neq 0,\end{cases} \\
& (8.49 \mathrm{a})
\end{aligned} \text {. }
$$

and $H_{i}$ is the internal field $H_{0}-4 \pi N_{z} M$. These modes are plotted in Fig. 8.2 as a function of wave vector. Notice that as a result of the demagnetization fields the ferromagnetic resonance frequency depends on the shape of the sample. This result was first derived by Kittel [152].

The precession associated with the modes $a_{k}$ is circular and that associated with the $\alpha_{k}$ is, in general, elliptical. Owing to the nature of the coefficient $B_{k}$, the uniform precession is elliptical when the transverse demagnetization factors are different. We also find that the ellipticity associated with a spinwave mode depends on the direction of propagation with respect to the dc field. The most elliptical spin waves are those which propagate at right angles to the dc field.


Fig. 8.2. Spin-wave frequencies as a function of their wave vector

### 8.2.2 Coherent Magnon State

The reader might notice that since the representations for $S_{i}^{+}$and $S_{i}^{-}$involve odd powers of the magnon creation and annihilation operators, then $S_{i}^{x}$ and $S_{i}^{y}$ will have zero expectation value in a pure magnon state, i.e.,

$$
\left\langle n_{\boldsymbol{k}}\right| S_{i}^{\mu}(t)\left|n_{\boldsymbol{k}}\right\rangle=0 .
$$

How does this relate to the classical picture shown, for example, in Fig. 8.1? This situation is analogous to that in optics where the number of photons and the phase are conjugate variables. If a state is characterized by a given number of photons the phase is undetermined. In our magnetic case, to obtain the classical picutre where the phase is well-defined, we need a superposition of magnon states. In particular, the "coherent" magnon state, $\left|c_{\boldsymbol{k}}\right\rangle$, is defined as the eigenstate of the magnon annihilation operator, i.e.,

$$
\begin{equation*}
\alpha_{\boldsymbol{k}}\left|c_{\boldsymbol{k}}\right\rangle=c_{\boldsymbol{k}}\left|c_{\boldsymbol{k}}\right\rangle, \tag{8.50}
\end{equation*}
$$

where $c_{\boldsymbol{k}}$ is a complex number having a phase $\beta_{\boldsymbol{k}}$ and an amplitude given by the average number of magnons in the state $\left|c_{\boldsymbol{k}}\right\rangle$,

$$
\left|c_{\boldsymbol{k}}\right|^{2}=\left\langle c_{\boldsymbol{k}}\right| n_{\boldsymbol{k}}\left|c_{\boldsymbol{k}}\right\rangle .
$$

By analogy with the photon case, the coherent state is given by [153]

$$
\begin{equation*}
\left|c_{\boldsymbol{k}}\right\rangle=e^{-\frac{1}{2}\left|c_{k}\right|^{2}} \sum_{n_{k}=0}^{\infty} \frac{\left(c_{k}\right)^{n_{k}}}{\left(n_{k}!\right)^{1 / 2}}\left|n_{k}\right\rangle . \tag{8.51}
\end{equation*}
$$

The average spin components in this state are

$$
\begin{align*}
& \left\langle c_{k}\right| S_{i}^{x}(t)\left|c_{k}\right\rangle=S_{k} \cos \left(\boldsymbol{k} \cdot \boldsymbol{r}_{i}-\omega_{k} t+\beta_{k}\right)  \tag{8.52a}\\
& \left\langle c_{k}\right| S_{i}^{y}(t)\left|c_{k}\right\rangle=\epsilon_{k} S_{k} \sin \left(\boldsymbol{k} \cdot \boldsymbol{r}_{i}-\omega_{k} t+\beta_{k}\right), \tag{8.52b}
\end{align*}
$$

where

$$
\begin{equation*}
S_{k}=\left(\frac{2 S}{N}\right)^{1 / 2}\left(u_{k}-v_{k}\right)\left|c_{k}\right| \tag{8.53}
\end{equation*}
$$

and

$$
\begin{equation*}
\epsilon_{k}=\frac{u_{k}+v_{k}}{u_{k}-v_{k}} \tag{8.54}
\end{equation*}
$$

is the ellipticity. Equations $(8.52 \mathrm{a}+\mathrm{b})$ are the familiar spin precession solutions.

### 8.2.3 Magnetostatic Modes

Let us now consider those modes which, although not uniform, have a spatial variation comparable to the sample dimensions. We use the fact that at such wavelengths the exchange interaction is negligible. Therefore the problem is a classical one. Furthermore, since $k c \gg \omega$, these modes are essentially static. Thus they are described by the magnetostatic Maxwell equations

$$
\begin{align*}
\boldsymbol{\nabla} \times \boldsymbol{H} & =0  \tag{8.55}\\
\nabla \cdot \boldsymbol{H} & =-4 \pi \boldsymbol{\nabla} \cdot \boldsymbol{M} \tag{8.56}
\end{align*}
$$

plus the constitutive torque equation

$$
\begin{equation*}
\frac{d \boldsymbol{M}}{d t}=-\gamma \boldsymbol{M} \times \boldsymbol{H} \tag{8.57}
\end{equation*}
$$

The solution to (8.57) under the assumption of small transverse fields is

$$
\boldsymbol{B}=\left[\begin{array}{rrr}
\mu & -i \kappa & 0  \tag{8.58}\\
i \kappa & \mu & 0 \\
0 & 0 & 1
\end{array}\right] \boldsymbol{H},
$$

where

$$
\begin{equation*}
\mu=1+\frac{4 \pi \gamma^{2} M_{0} H_{i}}{\gamma^{2} H_{i}^{2}-\omega^{2}} \tag{8.59}
\end{equation*}
$$

and

$$
\begin{equation*}
\kappa=\frac{4 \pi \gamma M_{0} \omega}{\gamma^{2} H_{i}^{2}-\omega^{2}} . \tag{8.60}
\end{equation*}
$$

If we introduce a magnetic scalar potential $\phi$, defined by $\boldsymbol{H}=\boldsymbol{\nabla} \phi$, Maxwell's equations become

$$
\begin{align*}
\mu\left(\frac{\partial^{2} \phi}{\partial x^{2}}+\frac{\partial^{2} \phi}{\partial y^{2}}\right)+\frac{\partial^{2} \phi}{\partial z^{2}} & =0 \quad \text { (inside) } \\
\nabla^{2} \phi & =0 \quad \text { (outside) } . \tag{8.61}
\end{align*}
$$



Fig. 8.3. The $(4,3,0)$ Walker mode of a sphere showing the instantaneous positions of the radio-frequency magnetization vectors in the places transverse to the dc magnetic field. This illustrates the indexing scheme and the concept of nonuniform precession [154]

Solving these equations for an ellipsoidal sample gives the so-called magnetostatic, or Walker, modes [154]. These modes are described by a set of indices $(n, m, r)$ instead of $\left(k_{x}, k_{y}, k_{z}\right)$. For example, the $(4,3,0)$ mode is shown in Fig. 8.3. Since these modes have an inhomogeneous magnetization, they may be excited by an inhomogenous microwave field. In fact, if the sample is very large or if it is mounted on a dielectric post, the resulting inhomogeneity in the field may be enough to excite magnetostatic modes. These modes were discovered in this way [155]. A typical absorption spectrum is shown in Fig. 8.4. An interesting feature of Fig. 8.4a is that the magnetostatic resonances are not broadened by the inhomogeneous magnetic field. In a paramagnet such a field produces an inhomogeneously broadened line whose width is approximately equal to the field variation. In the ferromagnetic case, however, the magnetostatic modes are the eigensolutions to (8.61). Thus, even if $\mu$ given by (8.59), has a spatial dependence through $H_{i}$ the modes may not be as symmetrical as shown in Fig. 8.3 but will still be infinitely narrow. We might describe this as "dipolar narrowing".

### 8.2.4 Solitons

The theory of magnetostatic modes for ferromagnetic thin films was developed by Damon and Eshbach [157]. For the coordinate system shown in Figs. 8.5 and 8.6 they found that the modes for an unbounded film consisted of propagating waves of the form

$$
\begin{equation*}
m_{x, y}(z) \sim e^{-i(\boldsymbol{k} \cdot \boldsymbol{r}-\omega t)}, \tag{8.62}
\end{equation*}
$$

where the wavevector $\boldsymbol{k}$ lies in the plane of the film. They found that for angles of propagation, $\varphi$, less than a critical angle given by


Fig. 8.4. Absorption spectrum of a yttrium-iron garnet disk. The sharp edges in (a) produce nonuniform fields which excite many modes. Rounding these edges (b) suppresses the modes [156]


Fig. 8.5. Elliptical precession of the magnetization in a thin film


Fig. 8.6. Coordinate system used to define the spinwave modes of a thin film

$$
\begin{equation*}
\varphi_{c}=\tan ^{-1} \sqrt{\frac{H_{0}}{4 \pi M_{s}}} \tag{8.63}
\end{equation*}
$$

the frequencies, $\omega$, of these modes falls within the band of bulk spinwave frequencies, i.e., between $\omega=\gamma H_{0}$ and $\omega=\gamma \sqrt{H_{0}\left(H_{0}+4 \pi M_{s}\right)}$. When $\varphi$ exceeds $\varphi_{c}$ then surface waves exist with frequencies above the bulk spinwave manifold. These modes are indicated in Fig. 8.7. The terminology "forward" or "backward" volume wave indicates the sign of the group velocity, $v_{g}=$ $\partial \omega_{k} / \partial k$. A magnetostatic backward volume wave (MSBVW) has a negative group velocity. This means that as a wave packet of sinusoidal waves moves forward the sinusoidal wave moves backward. (Much like the stroboscopic effect that makes the stagecoach wheels in Western movies appear to rotate backwards!)

The surface waves are "nonreciprocal" in the sense that when $\varphi$ has one sign the mode is localized on one surface. When $\varphi$ has the opposite sign the localization is on the other surface. Also, the exponential decay away from the surface scales with the propagation wave vector $k$. Thus, as $k$ increases the response becomes more and more localized at the surface.

The existence of surface waves is of interest because of the possible application for signal processing. These waves may be excited by exposing the surface of a magnetic film to pulses of microwave radiation generated, for example, by a transmission line. Such a transducer generates a wave packet. This packet is described by an envelope function $u(z, t)$, i.e., the signal is given by

$$
\begin{equation*}
m_{y}(z, t)=M_{S} u(z, t) e^{-i(k z-\omega t)} \tag{8.64}
\end{equation*}
$$

The equation of motion for the envelope function can be obtained from the magnetostatic equations which take the form [158]

$$
\begin{equation*}
i\left[\frac{\partial u}{\partial t}+v_{g} \frac{\partial u}{\partial z}+\eta u\right]+\frac{1}{2} \omega_{k}^{\prime \prime} \frac{\partial^{2} u}{\partial z^{2}}-N|u|^{2} u=0 . \tag{8.65}
\end{equation*}
$$

$v_{g}$ is the group velocity; $\eta$ is a damping parameter; $\omega_{k}^{\prime \prime}=\partial^{2} \omega_{k} / \partial k^{2}$ and represents dispersion; $N$ represents the effect of nonlinearity, $N=\partial \omega_{k} / \partial|u|^{2}$.


Fig. 8.7. Dispersion diagrams of magnetostatic wave frequency $\omega_{k}$ vs wave number $k$ for the three basic thin-film magnetostatic wave configurations, (a) magnetostatic surface waves (MSSW), (b) magnetostatic-backward-volume waves (MSBVW), and magnetostatic-forward-volume waves (MSFVW). The relative orientations of the net static field $\boldsymbol{H}$ and the wave vector $\boldsymbol{k}$ to each other and to the film for each configuration are shown by the diagrams to the left of the dispersion diagrams. The horizontal dashed lines and the frequencies $\omega_{S}, \omega_{B}$, and $\omega_{H}$ denote band limits for the different configurations. The curves are actual calculated curves from magnetostatic wave theory for a $7.2-\mu \mathrm{m}$-thick yttrium iron garnet film with $H=1407$ Oe [158]

Dispersion tends to broaden the packet while nonlinearity tends to steepen it. If $N \omega_{k}^{\prime \prime}<0$ there are solutions to this equation corresponding to propagation of pulses that preserve their shape. Such a pulse is called a soliton. The conditions for the observation of solitons are rather restrictive. However, solitons have been observed in films of yttrium iron garnet (YIG) [158]. The film was excited with a microwave pulse having a width of several ns and detected by a stripline antenna a few mm away. As the input power (of the order of a watt) is increased the nonlinear term in (8.65) increases and when the condition for soliton formation is reached the output power increases rapidly and may also show several pulses corresponding to multi-soliton generation.

### 8.2.5 Thermal Magnon Effects

Fortunately the density of spin-wave modes is much greater than that of the magnetostatic modes, so that most of the properties of magnetic materials may be understood by considering only the simpler spin-waves modes. The importance of spin waves in determining the low-temperature properties of ferromagnets was first recognized by Bloch [159]. Let us first consider the saturation magnetization. In the spin-wave region this is given by

$$
\begin{equation*}
M(T)=-\frac{g \mu_{B}}{V} \sum_{i}\left\langle S_{i}^{z}\right\rangle=\frac{g \mu_{B}}{V} \sum_{i}\left(S-\left\langle n_{i}\right\rangle\right)=M(0)-\frac{g \mu_{B}}{V} \sum_{k}\left\langle n_{\boldsymbol{k}}\right\rangle . \tag{8.66}
\end{equation*}
$$

In principle, there is no limit to the number of magnons that may be in any given mode as long as the system does not become "saturated" as described by the factor $f_{i}(S)$ in (8.14). Their thermal occupation number is given by the Bose-Einstein distribution as

$$
\begin{equation*}
\left\langle n_{\boldsymbol{k}}\right\rangle=1 /\left[\exp \left(\hbar \omega_{\boldsymbol{k}} / k_{B} T\right)-1\right] . \tag{8.67}
\end{equation*}
$$

Since most of the modes lie in the exchange region of the spectrum, we shall neglect dipolar effects. Thus $a_{\boldsymbol{k}}$ is the correct mode, and we do not have to transform to $\alpha_{\boldsymbol{k}}$. If we also use the small $k$ expansion of (8.27) and neglect the external field, then

$$
\begin{equation*}
\hbar \omega_{k}=D k^{2} \tag{8.68}
\end{equation*}
$$

where, for example, $D$ is $2 J S a^{2}$ for a simple cubic lattice. The sum over $\boldsymbol{k}$ is now replaced by an integral, and we have

$$
\begin{equation*}
M(0)-M(T)=-\frac{g \mu_{B}}{V} \frac{4 \pi V}{(2 \pi)^{3}} \int_{0}^{\infty} \frac{k^{2} d k}{\exp \left(D k^{2} / k_{B} T\right)-1} . \tag{8.69}
\end{equation*}
$$

The integral may be written in the dimensionless form

$$
\begin{equation*}
\int_{0}^{\infty} \frac{k^{2} d k}{\exp \left(D k^{2} / k_{B} T\right)-1}=\frac{1}{2}\left(\frac{k_{B} T}{D}\right)^{3 / 2} \int_{0}^{\infty} \frac{x^{1 / 2} d x}{e^{x}-1} \tag{8.70}
\end{equation*}
$$

The evaluation of this integral is simplified by using the expansion

$$
\begin{equation*}
\frac{1}{e^{x}-1}=\sum_{r=1}^{\infty} e^{-r x} \tag{8.71}
\end{equation*}
$$

The resulting magnetization is

$$
\begin{equation*}
M(0)-M(T)=\zeta\left(\frac{3}{2}\right) \frac{g \mu_{B}}{M(0)}\left(\frac{k_{B}}{4 \pi D}\right)^{3 / 2} T^{3 / 2} \tag{8.72}
\end{equation*}
$$

where $\zeta$ is the Riemann zeta function.
This is referred to as the Bloch $T^{3 / 2}$ law. The fact that it accurately describes the magnetization at low temperatures, as shown in Fig. 8.8, is evidence of the importance of such collective modes. If we keep those terms of order $k^{4}, k^{6}$, etc., in the dispersion relation, they lead to contributions to the magnetization that vary as $T^{5 / 2}, T^{7 / 2}$, etc. If only single-particle excitations were important, the low-temperature magnetization would vary exponentially, with an activation energy of the order of the exchange energy.


Fig. 8.8. The temperature dependence of the magnetization of EuO. The broken curve corresponds to noninteracting spin waves; the dotted curve corresponds to the series expansion (8.71) leading to terms of the form $T^{3 / 2}, T^{5 / 2}$, etc. The solid curve, calculated from spin-wave theory, includes the effects of dynamical interactions between pairs of magnons and subsequent renormalization of the spin-wave energies used in evaluating the magnon populations. Experimental points: ( $\mathbf{\Lambda}$ ) observations corrected to infinite applied field; ( $\mathbf{v}$ ) observations corrected to zero applied field [160]

The spin-wave contribution to the specific heat is given by

$$
\begin{equation*}
C_{V}=\frac{\partial}{\partial T} \sum_{\boldsymbol{k}} \hbar \omega_{\boldsymbol{k}}\left\langle n_{\boldsymbol{k}}\right\rangle . \tag{8.73}
\end{equation*}
$$

With the same approximations employed in obtaining the magnetization, (8.73) gives

$$
\begin{equation*}
C_{V}=\frac{15}{4} \zeta\left(\frac{5}{2}\right) k_{B}\left(\frac{k_{B}}{4 \pi D}\right)^{3 / 2} T^{3 / 2} \tag{8.74}
\end{equation*}
$$

### 8.2.6 Nonlinear Processes

So far our treatment has been entirely linear. That is, we have restricted ourselves to those terms in the Hamiltonian that involve quadratic products of magnon operators and may therefore be transformed into a set of non-interacting harmonic oscillators. The presence of higher-order terms corresponds to coupling between these oscillators. This coupling has important consequences for many properties of ordered systems.

Renormalization. The lowest-order nonlinear terms arising from the isotropic exchange interaction are the four-magnon terms

$$
\begin{equation*}
\mathcal{H}_{\mathrm{ex}}^{(4)}=\frac{1}{2} \sum_{\boldsymbol{k}, \boldsymbol{k}^{\prime}, \boldsymbol{k}^{\prime \prime}}\left[J(\boldsymbol{k})+J\left(\boldsymbol{k}+\boldsymbol{k}^{\prime}-\boldsymbol{k}^{\prime \prime}\right)-2 J\left(\boldsymbol{k}-\boldsymbol{k}^{\prime \prime}\right)\right] a_{\boldsymbol{k}}^{\dagger} a_{\boldsymbol{k}^{\prime}}^{\dagger} a_{\boldsymbol{k}^{\prime \prime}} a_{\boldsymbol{k}+\boldsymbol{k}^{\prime}+\boldsymbol{k}^{\prime \prime}} \tag{8.75}
\end{equation*}
$$

The effect of such spin-wave interactions on the magnetization was first analyzed by Dyson [161], who found that, in addition to the terms discussed above, there is a contribution to $M(0)-M(T)$ which is proportional to $T^{4}$. Although it is experimentally difficult to distinguish this contribution from $T^{3 / 2}$ and $T^{5 / 2}$, it has important theoretical consequences in that any alternative approach to computing $M(T)$ must reproduce Dyson's result at low temperatures.

A quantity that is more directly affected by the nonlinear terms of (8.75) is the magnon frequency itself. Let us consider only the exchange interaction. In the linear approximation the magnon frequency as given by (8.49) is independent of temperature. Applying the random-phase approximation and considering only nearest-neighbor interactions, we may write (8.75) as

$$
\begin{equation*}
-\left(2 z J S^{2} N\right)^{-1} \sum_{\boldsymbol{k}} \omega_{\boldsymbol{k}}\left\langle n_{\boldsymbol{k}}\right\rangle \sum_{\boldsymbol{k}^{\prime}} \omega_{\boldsymbol{k}^{\prime}}\left\langle n_{\boldsymbol{k}^{\prime}}\right\rangle . \tag{8.76}
\end{equation*}
$$

If we add this expression to the linear part $\sum \omega_{\boldsymbol{k}}\left\langle n_{\boldsymbol{k}}\right\rangle$ and minimize the free energy with respect to $\left\langle n_{\boldsymbol{k}}\right\rangle$, we obtain the same form as (8.67), but with the renormalized frequency

$$
\begin{equation*}
\omega_{\boldsymbol{k}}(T)=\omega_{\boldsymbol{k}}\left[1-\left(z J S^{2} N\right)^{-1} \sum_{\boldsymbol{k}^{\prime}} \omega_{\boldsymbol{k}^{\prime}}\left\langle n_{\boldsymbol{k}^{\prime}}\right\rangle\right] . \tag{8.77}
\end{equation*}
$$

We recognize the sum in this expression as the total energy in the spin-wave system. As the temperature increases this energy also increases, causing a decrease in the spin-wave frequencies. This decrease has been observed by neutron scattering, which we shall discuss in Chap. 10.

Relaxation. Nonlinearity also plays an imporant role in spin-wave relaxation phenomena. Consider, for example, the lowest-order nonlinear terms arising from the dipolar interaction. These are the three-magnon terms

$$
\begin{equation*}
\mathcal{H}_{\mathrm{dip}}^{(3)}=\sum_{\substack{\boldsymbol{k}, \boldsymbol{k}^{\prime} \\ \boldsymbol{k} \neq 0}}\left(g_{\boldsymbol{k}} \alpha_{\boldsymbol{k}} \alpha_{\boldsymbol{k}^{\prime}} \alpha_{\boldsymbol{k}+\boldsymbol{k}^{\prime}}^{\dagger}+g_{\boldsymbol{k}}^{*} \alpha_{\boldsymbol{k}}^{\dagger} \alpha_{\boldsymbol{k}^{\prime}}^{\dagger} \alpha_{\boldsymbol{k}+\boldsymbol{k}^{\prime}}\right), \tag{8.78}
\end{equation*}
$$

where

$$
\begin{equation*}
g_{\boldsymbol{k}}=-\frac{4 \pi}{V} \sqrt{2 N S} g^{2} \mu_{B}^{2} \cos \theta_{\boldsymbol{k}} \sin \theta_{\boldsymbol{k}} \exp \left(i \phi_{\boldsymbol{k}}\right) \tag{8.79}
\end{equation*}
$$

Since $\alpha_{\boldsymbol{k}}^{\dagger}$ corresponds to the creation of a magnon with wave vector $\boldsymbol{k}$ and $\alpha_{\boldsymbol{k}}$ corresponds to the annihilation of a magnon with wave vector $\boldsymbol{k}$, the


Fig. 8.9. Representation of (a) three-magnon confluence process and (b) threemagnon splitting process
processes involved in (8.78) may be represented schematically as shown in Fig. 8.9. Figure 8.9a shows the confluence of a magnon $\boldsymbol{k}$ with a magnon $\boldsymbol{k}^{\prime}$ to produce a third magnon $\boldsymbol{k}+\boldsymbol{k}^{\prime}$. This type of process constitutes a relaxation channel for the magnon $\boldsymbol{k}$ (or $\boldsymbol{k}^{\prime}$ ).

Since we are dealing with a ferromagnet, the exchange-narrowing effect, which was discussed in Chap. 5 , with be quite pronounced. The origin of this narrowing has to do with the fact that when the frequency spectrum of the effective field is very broad, only a narrow band of nearly degenerate modes influences the relaxation. Under this condition the relaxation frequency may be calculated by time-dependent perturbation theory. This is a particularly convenient way of computing magnon relaxation frequencies. As an illustration of this approach consider the three-magnon process of Fig. 8.9. The assumption that the magnon occupation number, if disturbed, relaxes exponentially to its equilibrium value $\left\langle n_{\boldsymbol{k}}\right\rangle$ enables us to define a relaxation frequency $\eta_{\boldsymbol{k}}$ by the rate equation

$$
\begin{equation*}
\frac{d n_{\boldsymbol{k}}}{d t}=-\eta_{k}\left(n_{\boldsymbol{k}}-\left\langle n_{\boldsymbol{k}}\right\rangle\right) . \tag{8.80}
\end{equation*}
$$

The rate of change of the number of magnons in mode $\boldsymbol{k}$ is also given by

$$
\begin{equation*}
\frac{d n_{\boldsymbol{k}}}{d t}=W_{n_{\boldsymbol{k}} \rightarrow n_{\boldsymbol{k}}+1}-W_{n_{\boldsymbol{k}} \rightarrow n_{\boldsymbol{k}}-1} \tag{8.81}
\end{equation*}
$$

where $W$ is the transition probability per unit time. For the three-magnon interaction (8.68), this is given by [162]

$$
\begin{align*}
W_{n_{\boldsymbol{k}} \rightarrow n_{\boldsymbol{k}}+1}= & \frac{2 \pi}{\hbar^{2}} \sum_{\boldsymbol{k}^{\prime}}\left|g_{\boldsymbol{k}}^{*}+g_{\boldsymbol{k}^{\prime}}^{*}\right|^{2}\left(n_{\boldsymbol{k}}+1\right)\left(n_{\boldsymbol{k}^{\prime}}+1\right) \\
& \times n_{\boldsymbol{k}+\boldsymbol{k}^{\prime}} \delta\left(\omega_{\boldsymbol{k}}+\omega_{\boldsymbol{k}^{\prime}}-\omega_{\boldsymbol{k}+\boldsymbol{k}^{\prime}}\right) \tag{8.82}
\end{align*}
$$

The result is that this three-magnon confluence process gives a relaxation frequency which, for small wave vectors, is proportional to the magnitude of the wave vector and is linear in temperature. These features, as well as the order of magnitude, are found to agree well with experimental measurements of $\eta_{\boldsymbol{k}}$ in the ferromagnetic insulator yttrium-iron garnet. This process is not found
to describe the relaxation of the $\boldsymbol{k}=0$, or ferromagnetic resonance, mode. It appears that surface and volume inhomogeneities provide the dominant relaxation channel for this mode [163].

## Parametric Excitation

Suhl Instabilities. Since the $\boldsymbol{k} \neq 0$ magnons have such short wavelengths, they cannot be directly excited by an electromagnetic field. However, there are a number of mechanisms by which they may be indirectly excited. Some of these mechanisms involve the nonlinearities discussed above. For example, consider the three-magnon terms in (8.68), in which $\boldsymbol{k}^{\prime}=-\boldsymbol{k}$, that is,

$$
\sum_{\boldsymbol{k}}\left(g_{\boldsymbol{k}} \alpha_{\boldsymbol{k}} \alpha_{-\boldsymbol{k}} \alpha_{0}^{\dagger}+g_{\boldsymbol{k}}^{*} \alpha_{\boldsymbol{k}}^{\dagger} \alpha_{-\boldsymbol{k}}^{\dagger} \alpha_{0}\right)
$$

These terms describe the relaxation of the $\boldsymbol{k}=0$, or uniform-precession, mode by decay into two magnons with equal and opposite wave vectors. Since energy must be conserved in this process, the resultant magnons will each have a frequency of $\omega_{0} / 2$, as illustrated in Fig. 8.10.

The essential feature of this relaxation process is that it is nonlinear. That is, the rate at which the uniform-precession mode decays in this fashion depends on the occupation number $\left\langle n_{\boldsymbol{k}}\right\rangle$ of the final-state magnons, as seen for example in (8.82). This occupation number, however, depends on the magnon relaxation rate $\eta_{\boldsymbol{k}}$, as well as on the amplitude of the uniform precession $\left\langle n_{0}\right\rangle$ which is driving it. There is a critical value of $\left\langle n_{0}\right\rangle$ at which the rate of increase in the number of magnons in mode $\boldsymbol{k}$ exceeds their rate of decrease through relaxation. At this point the number of magnons $\left\langle n_{\boldsymbol{k}}\right\rangle$ increases abruptly, producing a corresponding increase in the relaxation rate of the uniform precession. Since the amplitude of the uniform precession $\left\langle n_{0}\right\rangle$ is proportional to the amplitude of the driving microwave field $H_{1}$, this process appears as a saturation phenomenon. It turns out, however, that the field at which this


Fig. 8.10. Representation of the first-order Suhl instability in which uniform precession magnons split into $(\boldsymbol{k},-\boldsymbol{k})$ pairs
saturation happens is lower than that associated with the longitudinal relaxation time $T_{1}$ (see Sect.6.4.1). The observation of this "premature" saturation in ferrites by Bloembergen and Damon in 1952 opened an era of exploration of nonlinear phenomena in microwave ferrites [164]. The explanation of this saturation was given by Suhl and is referred to as the first-order Suhl instability [165]. There is also a second-order Suhl instability which arises from terms in (8.65) of the form $\alpha_{\boldsymbol{k}}^{\dagger} \alpha_{-\boldsymbol{k}}^{\dagger} \alpha_{0} \alpha_{0}$, in which two uniform precession magnons decay into a $(\boldsymbol{k},-\boldsymbol{k})$ magnon pair.
Parallel Pumping. Since all these processes involve the magnon relaxation rate $\eta_{k}$, they serve to measure this quantity. However, the onset of these processes is sometimes difficult to determine experimentally. A more accurate determination of $\eta_{\boldsymbol{k}}$ is obtained by means of the so-called parallel-pumping instability. In parallel pumping, as the name implies, a microwave magnetic field $H_{1} \cos \omega t$ is applied parallel to the dc magnetic field. From (8.19) we find that the interaction Hamiltonian is

$$
\begin{equation*}
\mathcal{H}_{1}=-g \mu_{B} H_{1} \cos \omega t \sum_{\boldsymbol{k}} a_{\boldsymbol{k}}^{\dagger} a_{\boldsymbol{k}} \tag{8.83}
\end{equation*}
$$

We saw that because of the dipolar interaction the $a_{\boldsymbol{k}}$ are not the normal modes. When (8.47) is used to express the interaction in terms of the normal modes $\alpha_{\boldsymbol{k}}$ we obtain terms of the form

$$
\begin{equation*}
g \mu_{B} H_{1} \cos \omega t \sum_{\boldsymbol{k}} \frac{\left|B_{\boldsymbol{k}}\right|}{\omega_{\boldsymbol{k}}} \exp \left(i 2 \varphi_{\boldsymbol{k}}\right) \alpha_{\boldsymbol{k}}^{\dagger} \alpha_{-\boldsymbol{k}}^{\dagger} \tag{8.84}
\end{equation*}
$$

These terms correspond to the creation of $(\boldsymbol{k},-\boldsymbol{k})$ magnon pairs. Again, since this is a nonlinear process, the rate at which energy flows into these magnons depends on their occupation number $\left\langle n_{\boldsymbol{k}}\right\rangle$. This, in turn, depends upon the amplitude of the driving field, as well as on the relaxation rate $\eta_{\boldsymbol{k}}$. When the driving rate exceeds the relaxation rate, the magnon occupation number becomes very large. This results in an increased in absorption. The threshold for this process is given by

$$
\begin{equation*}
\left(H_{1}\right)_{\mathrm{crit}}=\min \left(\frac{2 \omega \eta_{\boldsymbol{k}}}{\gamma \omega_{M} \sin ^{2} \theta_{\boldsymbol{k}}}\right) \tag{8.85}
\end{equation*}
$$

where min means that we use that value of $\boldsymbol{k}$ giving the minimum.
Notice that those magnons which propagate perpendicular to the dc field, and hence have the greatest ellipticity, are the first to become unstable. Since there is essentially no absorption below this threshold, its onset provides us with an accurate means of determining the spin-wave relaxation frequency $\eta_{\boldsymbol{k}}$.

### 8.2.7 Chaos

If the driving fields in the first- or second-order Suhl instabilities or in the parallel-pumping instability are increased beyond their critical values a variety
of time dependent phenomena appear. Consider, for example, the secondorder Suhl process in which the ferromagnetic resonance is excited to a large amplitude. When the microwave field $\boldsymbol{H}_{1}$ reaches the critical value

$$
\begin{equation*}
\left(H_{1}\right)_{\text {crit }}=\frac{\eta_{0}}{\gamma}\left(\frac{2 \eta_{\boldsymbol{k}}}{\omega_{M}}\right)^{1 / 2} \tag{8.86}
\end{equation*}
$$

the amplitude of the spinwave mode with frequency $\omega_{k}=\omega$ and $\theta_{k}=0$ begins to grow. This results in the "premature" saturation of the amplitude of the uniform precession. Unexplained so-called auto-oscillations had also been reported at high power levels. To study these phenomena Gibson and Jeffries [166] used the experimental arrangement shown in Fig. 8.11 in which a pickup coil monitors changes in the transverse magnetization of a Ga-YIG sample that is being excited by an rf field $H_{1}$ at a frequency of 1.3 GHz . When the rf field reaches a value several times $\left(H_{1}\right)_{\text {crit }}$ the voltage across the pickup coil develops auto-oscillations at a frequency of 16 kHz . As $\boldsymbol{H}_{1}$ is increased further sucessive period doublings occur as shown in Fig. 8.12. These results are part of a broad range of phenomena referred to as "chaos". Virtually all physical systems show chaotic behavior, and a large body of literature exists on chaotic dynamics. Nonlinearity is an essential part of chaos. Thus the description of a system showing chaotic behavior is generally based on a set of differential equations containing nonlinearity. For example, in 1963 Lorenz developed a set of three differential equations to describe thermal convection. The variables are related to the flow velocity and the temperature. The solution consists of


Fig. 8.11. Experimental arrangements used by Gibson and Jeffries to study autooscillations and chaos in the second-order Suhl processes showing a Ga-YIG sphere subjected to an rf field $h_{1}$ at $f_{p}=1.3 \mathrm{GHz}$ and a dc field $H_{d c} \approx 460 \mathrm{Oe}$. A pickup coil generates a signal $V_{s}$ proportional to the time derivative of the transverse magnetization of the sample [166]


Fig. 8.12. Real-time signals, $V_{s}(t)$, for auto-oscillations: (a) auto-oscillation frequency $f_{o} \approx 16 \mathrm{kHz}$; (b) at higher $h$, bifurcation of $f_{o} / 2$; (c) bifurcation to $f_{o} / 4$; (d) chaos [166]
knowing how these variables behave with time and how they vary relative to one another. What Lorenz found was that there is a rich variety of solutions depending upon the parameters that enter the differential equations. In some cases a variable may relax to a stationary value, or "fixed point". For other parameters the solution may jump between stationary values. If one plots the solutions in a space whose coordinates are the variables themselves then the allowed solutions will, in general, map out a trajectory as a function of time
called the "attractor". In some cases the attractor spans a continuum in this phase space and we call it a "strange attractor". In this case the motion is chaotic.

In our magnetic case the nonlinearity arises from the higher-order terms in the Hamiltonian of the form (8.75) and (8.78). Since the Gibson-Jeffries experiment involves the second-order Suhl process the appropriate nonlinear terms are the 4 -magnon terms

$$
\begin{equation*}
\mathcal{H}^{(4)^{\prime}}=\hbar \sum_{\boldsymbol{k}} \frac{1}{2} S_{0 \boldsymbol{k}} \alpha_{0}^{\dagger} \alpha_{0}^{\dagger} \alpha_{\boldsymbol{k}} \alpha_{-\boldsymbol{k}}+\text { c.c. } \tag{8.87}
\end{equation*}
$$

Removing the high frequency part of the magnon amplitude with the transformation,

$$
\begin{equation*}
\tilde{a}_{\boldsymbol{k}}=\left\langle\alpha_{\boldsymbol{k}}\right\rangle e^{i \chi_{\boldsymbol{k}}} e^{i(\omega / 2) t} \tag{8.88}
\end{equation*}
$$

where $\chi_{\boldsymbol{k}}$ is a real phase, the equations for these amplitudes become

$$
\begin{align*}
\frac{d \tilde{\alpha}_{0}}{d t}= & -\left(\eta_{0}+i \Delta \omega_{0}\right) \tilde{\alpha}_{0}-i\left(S_{00} \tilde{\alpha}_{0}^{2}+\sum_{\boldsymbol{k} \neq 0} S_{\boldsymbol{k} 0} \tilde{\alpha}_{\boldsymbol{k}}^{2}\right) \tilde{\alpha}_{0}^{*} \\
& -i \gamma \sum_{\boldsymbol{k} \neq 0} T_{\boldsymbol{k}_{0}}\left|\tilde{\alpha}_{\boldsymbol{k}}\right|^{2} \tilde{\alpha}_{\boldsymbol{k}}-i \gamma\left(\frac{S N}{2}\right)^{\frac{1}{2}} h \\
\frac{d \tilde{\alpha}_{\boldsymbol{k}}}{d t}= & -\left(\eta_{\boldsymbol{k}}+i \Delta \omega_{\boldsymbol{k}}\right) \tilde{\alpha}_{\boldsymbol{k}}-i\left(S_{\boldsymbol{k} 0} \tilde{\alpha}_{0}^{2}+S_{\boldsymbol{k}} \tilde{\alpha}_{\boldsymbol{k}}^{2}\right) \tilde{\alpha}_{\boldsymbol{k}}^{*}-i 2 T_{\boldsymbol{k} 0}\left|\tilde{\alpha}_{0}\right|^{2} \tilde{\alpha}_{\boldsymbol{k}} \tag{8.89}
\end{align*}
$$

Rezende et al. [167] have analyzed these equations assuming the $\theta_{\boldsymbol{k}}=0$ magnon provides the dominant contribution. Figure 8.13 shows the magnon populations $n_{0}$ and $n_{\boldsymbol{k}}$ for this "two-mode" approximation. This figure clearly shows the successive period doubling bifurcations.

### 8.2.8 Optical Processes

Infrared Absorption. There are other mechanisms for exciting magnons which do not involve nonlinearities [168]. For example, consider the antiferromagnet $\mathrm{MnF}_{2}$. The ground state of the $\mathrm{Mn}^{2+}$ ion is an orbital singlet. However, since $S=\frac{5}{2}$, there are six spin states, which in the magnetically ordered crystal are split by the exchange interaction. Those ions which occupy, say, the $A$ sublattice have $M_{S}=-\frac{5}{2}$ as their ground state, while the ground state for those ions on the $B$ sublattice is $M_{S}=+\frac{5}{2} . A(\boldsymbol{k},-\boldsymbol{k})$ magnon pair may be excited by the process illustrated in Fig. 8.14. First, the applied radiation induces an electric dipole transition to a high-lying state of one of the $\mathrm{Mn}^{2+}$ ions. Since this is a virtual process, it need not conserve energy. However, it must conserve parity, which means that the high-lying state must be opposite


Fig. 8.13. Limit cycles projected onto the $n_{0}-n_{k}$ plane for different values of $R=h / h_{c}$ where $h_{c}$ is the critical value for the mode with the lowest threshold [167]


Fig. 8.14. Representation of the mechanism for the excitation to two magnons
in parity from the ground state. Then, as a result of the Coulomb interaction between this ion and a neighboring ion on the opposite sublattice, the excited ion drops down to its first excited $\operatorname{spin}$ state $\left(M_{S}=-\frac{3}{2}\right)$, while the second ion is simultaneously excited up to its first excited spin state $\left(M_{S}=+\frac{3}{2}\right)$. Thus we end up with two spin deviations. Since any pair of ions may be excited, the final state will be a linear combination of such pair excitations. This results in the excitation of two magnons. The absorption coefficient for this process is proportional to the density of final states. Therefore, since the magnon density of states is largest at the Brillouin zone boundary, the absorption is strongest at a frequency approximately twice that of a Brillouin zone magnon, corresponding to an infrared frequency. However, the detailed shape of the absorption is complicated by the interaction between the two output magnons.
Spin-wave Sidebands. In addition to this infrared two-magnon absorption, there is an optical exciton-magnon absorption [169]. In this process the ion on
sublattice $A$ in Fig. 8.14 ends up in its first excited orbital state rather than its first excited spin state. This orbital excitation then propagates throughout the lattice, forming what is known as a Frenkel exciton. The absorption frequency for this process is approximately that of the exciton plus a magnon. In $\mathrm{MnF}_{2}$ the first excited orbital state lies in the green part of the optical spectrum. The absorption of a single $\mathrm{Mn}^{2+}$ ion into this state appears as a very weak magnetic-dipole transition. The exciton-magnon absorption appears as a stronger electric-dipole sideband on the high-frequency side of this "no-magnon" line.
Light Scattering. Magnons may also be excited as the result of light scattering [170]. One mechanism for such scattering is illustrated in Fig. 8.15. The incident photon is virtually absorbed in an electric dipole process. The spin-orbit interaction then produces a spin flip in the excited state and a second photon is virtually emitted leaving the system with a spin excitation. Macroscopically this gives rise to a dielectric function which depends upon the magnetization or spin density,

$$
\begin{equation*}
\epsilon^{\alpha \beta}=\epsilon_{0} \delta_{\alpha \beta}+\delta \epsilon^{\alpha \beta}(S(\boldsymbol{r}, t)) \tag{8.90}
\end{equation*}
$$

where $\alpha, \beta=(x, y, z)$. The spin-dependent part may be expanded in powers of the spin density

$$
\begin{equation*}
\delta \epsilon^{\alpha \beta}=\sum_{\gamma} K_{\alpha \beta \gamma} S_{\gamma}(\boldsymbol{r}, t)+\ldots \tag{8.91}
\end{equation*}
$$

for a cubic material $K_{\alpha \beta \gamma}= \pm K$ if all the indices are different, and zero otherwise. For the mechanism described in Fig. $8.15 K$ would be proportional to

$$
\begin{equation*}
\frac{\lambda\left\langle 0^{*}\right| \beta|2\rangle\langle 2| L_{\gamma}|1\rangle\langle 1| \alpha|0\rangle}{\left(E_{1}-E_{0}\right)\left(E_{2}-E_{0}\right)} \tag{8.92}
\end{equation*}
$$



Fig. 8.15. Schematic representation of a perturbation process contributing to magnon scattering. The electric dipole transitions are "virtual" in the sense that they do not conserve energy, i.e., $E_{1}-E_{0} \neq h \omega_{0}$

The static contributions to $\delta \epsilon$ lead to magnetooptic effects while the fluctuating contributions are responsible for the light scattering. Thus, in a cubic material, at least, magnetooptical effects and light scattering are governed by the same parameter $K$.

To see how the intensity of the scattered light depends upon the magnetic fluctuations consider an incident wave

$$
\begin{equation*}
\mathcal{E}_{\text {inc }}^{\alpha}(\boldsymbol{r}, t)=\mathcal{E}_{0}^{\alpha} \exp \left[i\left(\boldsymbol{k}_{0} \cdot \boldsymbol{r}-\omega_{0} t\right)\right] . \tag{8.93}
\end{equation*}
$$

Inside the medium the total electric field will consist of this incident wave plus the scattered wave,

$$
\begin{equation*}
\mathcal{E}^{\alpha}(\boldsymbol{r}, t)=\mathcal{E}_{\text {inc }}^{\alpha}(\boldsymbol{r}, t)+\mathcal{E}_{\text {scat }}^{\alpha}(\boldsymbol{r}, t) . \tag{8.94}
\end{equation*}
$$

which is related to the displacement vector by

$$
\begin{equation*}
D^{\alpha}(\boldsymbol{r}, t)=\epsilon^{\alpha \beta} \mathcal{E}^{\beta}(\boldsymbol{r}, t) \tag{8.95}
\end{equation*}
$$

Assuming $\delta \epsilon^{\alpha \beta}$ and $\mathcal{E}_{\text {scat }}^{\alpha}$ are small, a linearization of Maxwell's equations leads to a driven wave equation for $\mathcal{E}_{\text {scat }}^{\alpha}$ where the driving, or source, term involves the product $\delta \epsilon^{\alpha \beta}(\boldsymbol{r}, t) \mathcal{E}_{\text {inc }}^{\beta}(\boldsymbol{r}, t)$. The field at the detector is obtained by multiplying this source term by the so-called Green's function for the wave equation, a function that describes how a disturbance propagates, and integrating over the sample volume and over all time,

$$
\begin{equation*}
\mathcal{E}_{\mathrm{scat}}^{\alpha}(\boldsymbol{r}, t) \sim\left(\frac{\omega_{0}}{c}\right)^{2} \int d \boldsymbol{r}^{\prime} \int d t G_{\alpha \beta}\left(\boldsymbol{r}, \boldsymbol{r}^{\prime} ; t, t^{\prime}\right) \delta \epsilon^{\beta \gamma}\left(\boldsymbol{r}^{\prime}, t^{\prime}\right) \mathcal{E}_{\mathrm{inc}}^{\gamma}\left(\boldsymbol{r}^{\prime}, t^{\prime}\right) \tag{8.96}
\end{equation*}
$$

The scattered intensity is found by squaring this field and then performing an ensemble average $\langle\ldots\rangle$ over the fluctuations in $\delta \epsilon$. This results in the correlation function

$$
\begin{equation*}
\left\langle\delta \epsilon^{\beta^{\prime} \gamma^{\prime}}(\boldsymbol{r}, t) \delta \epsilon^{\beta \gamma}\left(\boldsymbol{r}^{\prime}, t^{\prime}\right)\right\rangle . \tag{8.97}
\end{equation*}
$$

For a bulk geometry this is a function only of $\boldsymbol{r}-\boldsymbol{r}^{\prime}$ and $t-t^{\prime}$. Introducing the time and spatial dependencies in $G$ and $\mathcal{E}_{\text {inc }}$ one finds, for example, that the intensity of light scattered with a polarization $z$, when the incident polarization is $x$, is

$$
\begin{equation*}
\int d \boldsymbol{r} \int d t e^{i(\boldsymbol{q} \cdot \boldsymbol{r}-\Omega t)}\left\langle S_{y}(\boldsymbol{r}, t) S_{y}(0,0)\right\rangle, \tag{8.98}
\end{equation*}
$$

where $\boldsymbol{q}$ is the momentum transfer, $\boldsymbol{q}=\boldsymbol{k}_{s}-\boldsymbol{k}_{0}$, and $\Omega$ is the excitation energy $\Omega=\omega_{s}-\omega_{0}$. The maximum momentum transfer occurs for back scattering,

$$
\begin{equation*}
q_{\max }=2\left|\boldsymbol{k}_{0}\right|=\frac{2 n \omega_{0}}{c}, \tag{8.99}
\end{equation*}
$$

which, for typical optical frequencies is of the order of $3 \times 10^{5} \mathrm{~cm}^{-1}$. This is to be compared with the Brillouin zone wave vector, $\boldsymbol{q}_{B Z} \sim 3 \times 10^{8} \mathrm{~cm}^{-1}$.


Fig. 8.16. Brillouin spectrum of light scattered from magnons in iron

Thus light scattering probes only the very long-wavelength excitations. If the frequencies exceed $1 \mathrm{~cm}^{-1}$ we speak of Raman scattering, while scattering at smaller frequencies is referred to as Brillouin scattering, the distinction being largely based on experimental technique.

If we expand the correlation function $\left\langle S_{y}(\boldsymbol{r}, t) S_{y}(0,0)\right\rangle$ in terms of the spin-wave amplitudes introduced above, we obtain two terms: $\left\langle a_{\boldsymbol{q}} a_{\boldsymbol{q}}^{\dagger}\right\rangle=n_{\boldsymbol{q}}+1$ and $\left\langle a_{\boldsymbol{q}}^{\dagger} a_{\boldsymbol{q}}\right\rangle=n_{\boldsymbol{q}}$. The first corresponds to the creation of a spin wave. The scattered light appears at a frequency $\omega_{0}-\Omega_{\boldsymbol{q}}$ with an intensity proportional to $n_{\boldsymbol{q}}+1$ and is referred to as the Stokes line. The second term gives an anti-Stokes line at the frequency $\omega_{0}+\omega_{\boldsymbol{q}}$.

In Fig. 8.16 we show the result for light scattering from iron. Since the skin depth is relatively small, the intensity of the surface mode is relatively strong. Notice that it only appears on one side (anti-Stokes side in this case) of the exciting frequency. This is a direct consequence of the nonreciprocal nature of surface magnons which we pointed out above.

### 8.3 High Temperatures

We have seen how effectively the spin-wave concept describes the low-temperature properties of magnetically ordered systems. However, near the transition temperature, and particularly above it, the lifetime of the spin waves becomes too short for them to be a useful concept. At very high temperatures the relaxation-function approach developed in Chap. 5 is applicable. There we found that a strong exchange modulation of the magnetic dipolar field led to a long-time spin-spin correlation function which has the form

$$
\begin{equation*}
\left\langle\mathcal{M}_{x}(t) \mathcal{M}_{x}\right\rangle_{T \rightarrow \infty}=\frac{1}{3} N S(S+1) g^{2} \mu_{B}^{2} \exp \left(i \omega_{0} t\right) \exp \left[-\left(2 M_{2} / \omega_{\mathrm{ex}}\right) t\right] \tag{8.100}
\end{equation*}
$$

where $M_{2}$ is the Van Vleck second moment and $\omega_{\text {ex }}$ characterizes the rate at which the exchange interaction modulates the dipolar field. This result was
derived under the assumption that the exchange energy was small in comparison with the Zeeman energy. When the exchange energy is very large, as in the case we are now considering, the off-diagonal elements of the dipole-dipole interaction become important, with the result that the exponent $2 M_{2} / \omega_{\text {ex }}$ in (8.100) is larger by a factor of about $\frac{10}{3}$ (the factor is exactly $\frac{10}{3}$ for a polycrystalline sample with cubic symmetry).

The theory of relaxation phenomena at finite temperatures is a complex subject. Consequently, we shall restrict ourselves to a few qualitative remarks that give some indication of the problems involved (most of this discussion is based on [171]). Let us begin by considering the temperature dependence of the second moment. In the finite-temperature region this is

$$
\begin{equation*}
M_{2}=-\frac{\left\langle\left[\mathcal{H}_{\mathrm{dip}}^{\prime}, \mathcal{M}_{x}\right]^{2}\right\rangle}{\hbar^{2}\left\langle\mathcal{M}_{x}^{2}\right\rangle} \tag{8.101}
\end{equation*}
$$

where $\mathcal{H}_{\text {dip }}^{\prime}$ is given by (5.48). After computing this commutator and squaring the result, we are left with a numerator involving terms such as $\left\langle S_{i}^{z} S_{j}^{y} S_{m}^{z} S_{n}^{y}\right\rangle$. Making the random-phase approximation and using the high-temperature form of the fluctuation-dissipation theorem,

$$
\left\langle\mathcal{M}_{x}^{2}\right\rangle=2 \pi k_{B} T \chi(\boldsymbol{q}=0, \omega=0)
$$

we obtain

$$
\begin{equation*}
M_{2}=\frac{9 g^{2} \mu_{B}^{2} \sum_{\boldsymbol{q}}|F(\boldsymbol{q})|^{2}\left\langle S_{z}(\boldsymbol{q}) S_{z}(-\boldsymbol{q})\right\rangle^{2}}{2 \pi \hbar^{2} k_{B} T \chi} \tag{8.102}
\end{equation*}
$$

where

$$
\begin{equation*}
F(\boldsymbol{q})=N g^{2} \mu_{B}^{2} \sum_{r} \frac{3 \cos ^{2} \theta-1}{r^{3}} e^{i \boldsymbol{q} \cdot \boldsymbol{r}} \tag{8.103}
\end{equation*}
$$

From (4.45) we have

$$
\begin{equation*}
\left\langle S_{z}(\boldsymbol{q}) S_{z}(-\boldsymbol{q})\right\rangle=\frac{k_{B} T V}{g^{2} \mu_{B}^{2}} \chi(\boldsymbol{q}, \omega=0) \tag{8.104}
\end{equation*}
$$

Converting the sum over $\boldsymbol{q}$ in (8.102) into an integral, we find that for a ferromagnet the second moment varies as $\left(T-T_{c}\right)^{1 / 2}$. If the linewidth were described by the second moment alone, this would indicate that the paramagnetic resonance line should narrow as the temperature approaches the Curie point. For an antiferromagnet, however, the uniform static susceptibility does not diverge, with the result that the second moment increases as $\left(T-T_{N}\right)^{-1 / 2}$ where $T_{N}$ is the Neél temperature.

This is not the complete story, for the exchange frequency is also temperature dependent. The exchange frequency was defined in (6.71) as

$$
\begin{equation*}
\langle\Delta \omega(\tau) \Delta \omega\rangle=M_{2}\left(1-\omega_{\mathrm{ex}}^{2} \tau^{2}\right) \tag{8.105}
\end{equation*}
$$

With the same approximations used in obtaining (8.102), this may also be written as

$$
\begin{equation*}
\langle\Delta \omega(\tau) \Delta \omega\rangle=\sum_{\boldsymbol{q}}|F(\boldsymbol{q})|^{2}\left\langle S_{z}(\boldsymbol{q}, \tau) S_{z}(-\boldsymbol{q})\right\rangle^{2} \tag{8.106}
\end{equation*}
$$

Therefore the exchange frequency is given by

$$
\begin{equation*}
\omega_{\mathrm{ex}}^{2}=-\frac{1}{M_{2}} \sum_{\boldsymbol{q}}|F(\boldsymbol{q})|^{2}\left\langle S_{z}(\boldsymbol{q}) S_{z}(-\boldsymbol{q})\right\rangle \frac{d^{2}}{d \tau^{2}}\left\langle S_{z}(\boldsymbol{q}, \tau) S_{z}(-\boldsymbol{q})\right\rangle \tag{8.107}
\end{equation*}
$$

We see that this expression involves the second derivative of the correlation function. Without evaluating this quantity it is possible to say something very important about (8.107), namely, that its numerator does not diverge or go to 0 as the temperature approaches the critical temperature.

To see this let us rewrite the derivative of the correlation function in terms of individual spins as

$$
\left\langle\left(d^{2} / d \tau^{2}\right) S_{i}^{z}(\tau) S_{j}^{z}\right\rangle e^{i \boldsymbol{q} \cdot \boldsymbol{r}_{i j}} .
$$

We now apply a thermodynamic result derived by Kubo [172] which says that this derivative is proportional to $\left\langle\left[\left[\mathcal{H}_{0}, S_{i}^{z}\right], S_{j}^{z}\right]\right\rangle$. The consequence of these commutators is that the derivative of the correlation function is nonzero only for spins very close to one another. This, in turn, implies that the correlation function in the numerator of (8.107) involving the second derivative shows no drastic temperature dependence as the critical temperature is approached, since only short-range static correlations are involved, and these do not change suddenly near the critical point. These considerations lead us to the result that the square of the exchange frequency also goes to 0 as $\left(T-T_{c}\right)^{1 / 2}$. Therefore, if we assume that the method of moments provides an adequate description of a ferromagnet in its paramagnetic region, we are led to the conclusion that the resonance linewidth remains exchange narrowed as the temperature decreases toward the Curie point, decreasing as $\left(T-T_{c}\right)^{1 / 4}$. Evidence of such behavior is indicated for the ferromagnet $\mathrm{CrBr}_{3}$ in Fig. 8.17.

The above arguments assume zero applied field. In a finite field the divergences are masked, and the simple power-law dependencies are not expected to hold in the immediate vicinity of $T_{c}$. Since resonance linewidths are measured in finite fields of appreciable magnitude, we may expect considerable departure from these simple relations. In particular, the ferromagnetic-resonance linewidth does not go to 0 at the critical temperature but in typical situations decreases by only about an order of magnitude from its high-temperature value (explicit calculations of the moments, taking the finite field into account, are reported in [173]). In an antiferromagnet the concept of exchange narrowing breaks down. Our simple ideas predict that the linewidth should diverage as $\left(T-T_{N}\right)^{1 / 4}$. The experimental data on $\mathrm{MnF}_{2}$, shown in Fig. 8.18 indicate that the zero-field linewidth does, in fact, increase as $\left(T-T_{N}\right)^{-3 / 8}$.


Fig. 8.17. Linewidth as a function of reduced temperature in $\mathrm{CrBr}_{3}$. The solid line is proportional to $\left[\left(T / T_{c}\right)-1\right]^{1 / 4}[171]$


Fig. 8.18. Linewidth as a function of temperatures in $\mathrm{MnF}_{2}$ [174]

### 8.4 Micromagnetics

The magnetostatic modes discussed above have spatial variations that are large compared with interatomic spacings. Therefore, we did not include exchange. On the other hand, spinwaves are capable of describing very short wavelength excitations in which exchange plays an important role. However, these modes are small amplitude excitations relative to the saturated ferromagnetic (or antiferromagnetic) state. How do we describe large changes in the magnetization, such as a complete magnetic reversal? Micromagnetic modelling is particularly useful for such cases. The principles of micromagnetics were first formulated by Landau and Lifshitz [175] and later developed into a self-consistent theory by Brown [176]. This theory has been applied to
many situations, particularly by Zhu [177]. In this theory the magnetic system is described by the magnetization at a position $i$ by the vector $\boldsymbol{M}_{i}=M_{S} \boldsymbol{m}_{i}$ where $M_{S}$ is the saturation magnetization. The dynamics of the magnetization are governed by equations of the form (8.1) at every point $i$. Since the fields $\boldsymbol{H}_{i}$ arise from all the other points this leads to coupled, nonlinear differential equations for the magnetization at every point in the system. In general, analytic solutions do not exist. Early work was confined to one-dimensional models and was often based on linear approximations. The introduction of modern computers have made it possible to numerically solve realistic micromagnetic problems.

The first step in setting up a micromagnetic calculation is to discretize the magnetic system with a three-dimensional mesh. The energy density is then calculated for each discrete point. The exchange energy density, for example, has the continuum form introduced at the beginning of this chapter,

$$
\begin{equation*}
E_{\mathrm{ex}}(\boldsymbol{r})=2 A\left[\left(\frac{\partial \boldsymbol{m}}{\partial x}\right)^{2}+\left(\frac{\partial \boldsymbol{m}}{\partial y}\right)^{2}+\left(\frac{\partial \boldsymbol{m}}{\partial z}\right)^{2}\right] . \tag{8.108}
\end{equation*}
$$

In discrete form this becomes

$$
\begin{equation*}
E_{\mathrm{ex}}\left(\boldsymbol{r}_{i}\right)=-\frac{2 A}{M_{S}^{2} a^{2}} \boldsymbol{M}_{i} \cdot \sum_{n n} \boldsymbol{M}_{j} \tag{8.109}
\end{equation*}
$$

where $a$ is the distance between neighboring sites in the mesh. Energy densities for the dipole-dipole (magnetostatic) interaction, anisotropy, and the Zeeman interaction are similarly introduced giving a total energy density, $E_{\text {tot }}\left(\boldsymbol{r}_{i}\right)$. The effective magnetic field acting on the magnetization at the $i^{\text {th }}$ site is

$$
\begin{equation*}
\boldsymbol{H}_{i}=-\frac{\partial E_{\mathrm{tot}}\left(\boldsymbol{r}_{i}\right)}{\partial \boldsymbol{M}_{i}} \tag{8.110}
\end{equation*}
$$

Introducing reduced units $\tau=\gamma M_{S} t$ and $\boldsymbol{h}_{i}=\boldsymbol{H}_{i} / M_{S}$ the Landau-Lifshitz equation takes the form

$$
\begin{equation*}
\frac{d \boldsymbol{m}_{i}}{d t}=-\gamma \boldsymbol{m}_{i} \times \boldsymbol{h}_{i} \tag{8.111}
\end{equation*}
$$

Not only did modern computers make micromagnetic calculations practical, but the development of the magnetic force microscope (MFM) made it possible to validate this theoretical approach. This instrument is described in the next section.

### 8.4.1 Magnetic Force Microscope

In 1986 Binning, Quate, and Gerber [178] showed how the scanning tunneling microscope could be employed to measure extremely small forces. It was quickly realized that this "atomic force microscope" (AFM) could be modified
to image magnetostatic fields emanating from a magnetic sample. The magnetic force microscope consists of a miniature cantilever beam clamped at one end that acts as a force-sensing spring (Fig. 8.19). A tip is integrated into the single-crystal silicon cantilever by etching techniques and then coated with a magnetic material. The deflection or frequency of the cantilever is monitored by reflecting a laser beam off the back of the cantilever and sensing the beam with a split photodiode detector. The tip is scanned across the sample by means of a piezoelectric scanner.

Row A of Fig. 8.20 shows an MFM image of a 30 nm thick permalloy film. This film was prepared by sputtering permalloy onto a NiO substrate and then patterning it into a $20 \times 10 \mathrm{~nm}$ rectangle by lithography. The antiferromagnetic NiO produces exchange coupling which stabilizes the domain structure during the MFM measurement.


Fig. 8.19. Microphotograph of cantilevered probe tip used in a magnetic force microscope (C.F. Quate)


Fig. 8.20. The magnetization switching process of a permalloy thin film. Row A is the magnetic force microscope images. Row B is the calculated magnetic charge density from micromagnetic simulation. Row C is the simulated magnetization patterns [179]

The external magnetic field is initially applied downward along the long axis of the rectangular film. Under this applied field, the thin film is in a quasisingle domain state, as shown in state A1 in Fig. 8.20. There are small curved edge domains at both ends of the film because the applied field is not strong enough to drive them completely out of the film. The existence of these curved edge domains also help to minimize the magnetostatic energy that would otherwise arise from the magnetic poles on the film surfaces. The applied field is then gradually reduced to zero and then increased in the opposite direction to reverse the magnetization of the thin film. The state A8 in Fig. 8.20 shows the fully reversed state. The domain configuration in this state is symmetric to the initial state around the center line of the film (along the short axis). The states A2 to A8 in Fig. 8.20 show the subsequent domain images observed along the reversal process between state A1 and A8. In A2 and A3, the curved domain walls that extend from the two ends to the center of the thin film move towards the center and close to each other. In A4, a diamond shaped domain is formed at the center of the film, resulting in a flux-closure multi-domain structure in the permalloy thin film. With further change of the external field, the domains that are parallel to the direction of the applied field expand at the expense of the domains that are antiparallel to the applied field. This is clearly seen in the states A5, A6 and A7 in Fig. 8.20. As a result, the diamond shaped domain in the center narrows. The two edges of this center domain eventually cross each other, move away from the center of the thin film and away from each other, and reaches the final reversed state A8.

States B1 to B8 in Fig. 8.20 are the domain images obtained from the micromagnetic simulation. These are gray scale images which map the magnetic charge density calculated from the simulated magnetization distribution of the permalloy thin film. Since the MFM detects the magnetic field gradient which results from the magnetic charges on the permalloy thin film, the MFM images closely resemble the magnetic charge density distribution. Comparing the MFM images (A1 to A8) and the simulated domain configurations (B1 to B8) in Fig. 8.20, we can clearly see that excellent agreement between them. This strongly validates the ability of the micromagnetic model to simulate the domain configurations during the magnetic reversal process.

The vector plots C1 to C8 in Fig. 8.20 show the corresponding magnetization distribution of the thin film, obtained directly from the micromagnetic simulation. The cell size is $10 \times 10 \times 12.5 \mathrm{~nm}$. The arrows in these plots indicate the directions of the magnetization. The ability to give direct information on the magnetization distribution is one of the powerful features of micromagnetic simulation. This enables us to better understand the reversal process. As we can see from C1, the two edge domains observed in the initial state are two vortices. The center part of the thin film is uniformly magnetized downward. The two vortices are formed at the two ends in order to reduce the free magnetic charges otherwise would occur at the two end surfaces. As the applied field changes, the top vortex moves toward the left, while the bottom vortex moves towards the right. As a result, the net magnetization in
the downwards direction decreases. This is clearly seen from C1 to C4. In C4 a near-perfect flux closure structure is formed, with very little net magnetization in the downwards direction. Further increase of the applied field in the upward direction continues to drive the motions of the two vortices. In C5 the net magnetization has been reversed to the upward direction. This is followed by C6 and C7 where the vortices are driven further to the side. Eventually the center part of the magnetization is reversed completely to the upwards direction, and the thin film reaches the reversed state C8.

### 8.4.2 Phenomenological Damping

In our preface to this section we said one of the features of micromagnetic modeling was its applicability to time-dependent phenomena. Figure 8.21 shows the micromagnetic response based on (8.111) of a permalloy film to a field of 250 Oe suddenly applied in the reverse direction. At $t=0$ the Zeeman energy density is $M_{S} H$. At 1.5 ns the magnetization has predominantly reversed, giving a Zeeman energy density $-M_{S} H$. The variations in the magnetization shown in Fig. 8.21b indicate that this change in Zeeman energy density has gone into exchange energy density. That is, the energy has spread throughout the spin-wave spectrum shown in Fig. 8.2.

Since (8.111) describes a precession of the magnetization $\boldsymbol{m}_{i}$ about the local field $\boldsymbol{h}_{i}$ the spins in Fig. 8.21b are precessing about their local fields. However, we know that the magnetization eventually relaxes into the direction of $\boldsymbol{h}_{i}$. It does this by transferring energy to the lattice. This relaxation effect is incorporated by adding a phenomenological damping term. Landau and Lifshitz did this by introducing a term that can be written in the form [175]


Fig. 8.21. Micromagnetic description of the magnetization reversal in a permalloy film including only precessional terms [180]


Fig. 8.22. Micromagnetic description of the magnetization reversal in a permalloy film including phenomenological damping [180]

$$
-\frac{\lambda}{M^{2}} \boldsymbol{M} \times \boldsymbol{M} \times \boldsymbol{H}
$$

which is perpendicular to the plane of $\boldsymbol{M} \times \boldsymbol{H}$. In 1955 Gilbert developed a damping term based on a variational approach [181] which has the form

$$
-\frac{\alpha}{M} \boldsymbol{M} \times \frac{\partial \boldsymbol{M}}{\partial t}
$$

The Landau-Lifshitz damping term may be shown to be identical to Gilbert's if one modifies the gyromagnetic term in the Landau-Lifshitz equation to have the coefficient $\gamma /\left(1+\alpha^{2}\right)$. That is, in order to describe Gilbert's damping in terms of a triple cross-product the gyromagnetic ratio must become a function of the damping. The resulting Landau-Lifshitz-Gilbert equation becomes

$$
\begin{equation*}
\frac{d \boldsymbol{m}_{i}}{d \tau}=\gamma^{*} \boldsymbol{m}_{i} \times \boldsymbol{h}_{i}-\alpha \boldsymbol{m}_{i} \times\left(\boldsymbol{m}_{i} \times \boldsymbol{h}_{i}\right) \tag{8.112}
\end{equation*}
$$

where $\gamma^{*}=\gamma /\left(1+\alpha^{2}\right)$. If the micromagnetic calculation for the permalloy rectangle is now carried out using (8.112) with a damping parameter $\alpha=0.005$ we obtain the results in Fig. 8.22. We see that the exchange energy eventually decreases to zero. The "total" energy is not conserved because it does not include the energy that has been transferred to the lattice.

### 8.5 Metals

Let us now consider the response of a ferromagnetic metal to a time-dependent field. The Fermi liquid formulation, which we used in the last chapter to study the response of nonmagnetic metals, is not rigorous inthis case. This is because

Fermi liquid theory rests on the assumption that the quasiparticle excitation spectrum lies close to the Fermi surface. In a ferromagnet this may not be the case. For example, when the spin of a quasiparticle at the Fermi surface is reversed, the resulting quasiparticle state will not, in general, lie close to the Fermi surface and will therefore have a finite decay time. Therefore, we shall consider the microscopic model discussed in Chaps. 4 and 5 which was characterized by the delta-function interaction. In Chap. 5 we obtained the generalized susceptibility,

$$
\begin{equation*}
\chi_{-+}(\boldsymbol{q}, \omega)=\frac{2 \mu_{B}^{2} \Gamma(\boldsymbol{q}, \omega)}{1-2 I \Gamma(\boldsymbol{q}, \omega)} \tag{8.113}
\end{equation*}
$$

where

$$
\begin{equation*}
\Gamma(\boldsymbol{q}, \omega)=\frac{1}{V} \sum_{k} \frac{n_{\boldsymbol{k} \uparrow}-n_{\boldsymbol{k}+\boldsymbol{q} \downarrow}}{\hbar \omega-\left(\tilde{\epsilon}_{\boldsymbol{k} \uparrow}-\tilde{\epsilon}_{\boldsymbol{k}+\boldsymbol{q} \downarrow}\right)} . \tag{8.114}
\end{equation*}
$$

Adding the constant $I$ to the energy does not change the energy difference in $\Gamma(\boldsymbol{q}, \omega)$ and enables us to write

$$
\begin{equation*}
\tilde{\epsilon}=\epsilon_{\boldsymbol{k}}+\frac{n I}{2}-\sigma \frac{n I}{2} \zeta \tag{8.115}
\end{equation*}
$$

where $\zeta=\left(n_{\uparrow}-n_{\downarrow}\right) / n$ is the relative magnetization and $\sigma= \pm 1$. For parabolic energy bands $\Gamma(\boldsymbol{q}, \omega)$ may be evaluated exactly for $T=0$ :

$$
\begin{align*}
\Gamma(\boldsymbol{q}, \omega)= & -\frac{N\left(\epsilon_{F}\right)}{4 \tilde{q}}\left\{A(\tilde{q}-\tilde{\omega} / \tilde{q})+\frac{1}{2}\left[A^{2}+(\tilde{q}-\tilde{\omega} / \tilde{q})^{2}\right] \ln \frac{\tilde{q}-\tilde{\omega} / \tilde{q}+A}{\tilde{q}-\tilde{\omega} / \tilde{q}-A}\right. \\
& \left.+B(\tilde{q}+\tilde{\omega} / \tilde{q})+\frac{1}{2}\left[B^{2}-(\tilde{q}+\tilde{\omega} / \tilde{q})^{2}\right] \ln \frac{\tilde{q}+\tilde{\omega} / \tilde{q}+B}{\tilde{q}+\tilde{\omega} / \tilde{q}-B}\right\} \tag{8.116}
\end{align*}
$$

where

$$
\begin{aligned}
\tilde{q} & =a / 2 q_{F}, \quad \tilde{\omega}=(\omega-n I \zeta) / 4 \epsilon_{F} \\
A & =(1+\zeta)^{1 / 3}, \quad B=(1-\zeta)^{1 / 3}
\end{aligned}
$$

Since $\ln z=\ln r+i \theta$ where $z=r e^{i \theta}$, the appearance of the logarithms in (8.116) gives rise for $\zeta<1$ to four regions in the $\omega-q$ plane. Three of these are characterized by $\Gamma^{\prime \prime}(\boldsymbol{q}, \omega) \neq 0$ corresponding to single-particle spin-flip, or "Stoner", excitations. These three regions are indicated by the shaded portions of Fig. 8.23. In the fourth region $\Gamma^{\prime \prime}(\boldsymbol{q}, \omega)=0$. Therefore, since

$$
\begin{equation*}
\chi_{-+}^{\prime \prime}(\boldsymbol{q}, 0 \omega)=\frac{2 \mu_{B}^{2} \Gamma^{\prime \prime}(\boldsymbol{q}, \omega)}{\left[1-2 I \Gamma^{\prime}(\boldsymbol{q}, \omega)\right]^{2}+4 I^{2} \Gamma^{\prime \prime}(\boldsymbol{q}, \omega)^{2}} \tag{8.117}
\end{equation*}
$$

in the limit $\Gamma^{\prime \prime}(\boldsymbol{q}, \omega) \rightarrow 0$,

$$
\begin{equation*}
\chi^{\prime \prime}(\boldsymbol{q}, \omega) \rightarrow \frac{\mu_{B}^{2}}{I} \delta\left[1-2 I \Gamma^{\prime}(\boldsymbol{q}, \omega] .\right. \tag{8.118}
\end{equation*}
$$

From the property of the delta function,

$$
\delta[f(\omega)]=\delta\left(\omega-\omega_{\boldsymbol{q}}\right)|\partial f / \partial \omega|_{\omega_{\boldsymbol{q}}}^{-1}
$$

where $\omega_{\boldsymbol{q}}$ is defined by $f\left(\omega_{\boldsymbol{q}}\right)=0$, we see that the imaginary part of the susceptibility contains poles at $\omega=\omega_{q}$. These correspond to collective excitations, or spin waves.

To find the dispersion relation for these spin waves we expand $\Gamma^{\prime}(\boldsymbol{q}, \omega)$ for small $q$ and $\omega$ and set the result equal to $1 / 2 I$. The result is [182]

$$
\begin{align*}
\hbar \omega(q)= & \frac{1}{N_{\uparrow}-N_{\downarrow}}  \tag{8.119}\\
& \times \sum_{\boldsymbol{k}}\left[\frac{1}{2}\left(n_{\boldsymbol{k} \uparrow}+n_{\boldsymbol{k} \downarrow}\right)\left(\boldsymbol{q} \cdot \frac{\partial}{\partial \boldsymbol{k}}\right)^{2} \epsilon_{\boldsymbol{k}}-\frac{N\left(n_{\boldsymbol{k} \uparrow}-n_{\boldsymbol{k} \downarrow}\right)}{I\left(N_{\uparrow}-N_{\downarrow}\right)}\left(\boldsymbol{q} \cdot \frac{\partial \epsilon_{\boldsymbol{k}}}{\partial \boldsymbol{k}}\right)^{2}\right]
\end{align*}
$$

This has the same quadratic dependence upon $q$ that we found for the spinwave spectrum of a ferromagnetic insulator. The first term in (8.119) corresponds to the additional kinetic energy that the electrons develop as they change their spin directions to keep up with the change in the macroscopic spin direction of the spin wave. It can be shown [183] that this is always positive and vanishes for a filled band. The second term corresponds to a reduction in this kinetic energy due to a tilting of the electron spin out of the plane in which the macroscopic magnetization varies.

From Fig. 8.23 we see that for wave vectors for which undamped spin waves exist there will be contributions to $\chi^{\prime \prime}(\boldsymbol{q}, \omega)$ from the nonzero values of $\Gamma^{\prime \prime}(\boldsymbol{q}, \omega)$ corresponding to virtual Stoner excitations. If we imagine a vertical cut through the $\omega-q$ plane at increasingly larger wave vectors, the susceptibility behaves [184] as shown in Fig. 8.24. The spin waves becomes heavily damped as they approach and merge into the Stoner excitation region. This limits their experimental identification to relatively small wave vectors.


Fig. 8.23. Regions of $\Omega-\boldsymbol{q}$ space showing Stoner excitations and spin waves. Here $\Omega=\omega / 4 \epsilon_{F}$ and $\Delta=n I \zeta / 4 \epsilon_{F}$ is the Stoner gap


Fig. 8.24. Behavior of the spectral function $\chi^{\prime \prime}(q, \omega)$ as $\boldsymbol{q}$ increases toward $\boldsymbol{q}_{1}$, in Fig. 8.23

In most ferromagnetic metals the low-temperature magnetization is found to follow the Bloch $T^{3 / 2}$ law. This is usually taken as evidence of the importance of the spin-wave modes. However, in weak itinerant ferromagnets, such as $\mathrm{ZrZn}_{2}$, the Stoner excitations may dominate, producing a $T^{2}$ contribution to the magnetization.

The first direct evidence of spin waves in metals was made by Lowde, who observed the inelastic scattering of neutrons from iron [185]. Figure 8.25 shows the spin-wave dispersion relations for iron and nickel. In addition to confirming the quadratic dependence on $q$, these results show an interesting aspect of these spin waves, namely, their existence well above the Curie temperature.

The existence of spin waves above $\mathrm{T}_{c}$ has been confirmed by large scale computer simulation [188]. These simulations indicate that the spin waves will be propagating, as opposed to dissipative, when their wavelengths are smaller than the correlation length which measures the short range order. For iron at $T=1.1 T_{c}$ the correlation length is approximately twice the bcc lattice parameter, i.e., $2 a$. Therefore we only have propagating spin waves for wavevectors $k \geq 0.77 \AA$.


Fig. 8.25. Spin-wave dispersion relations in iron [186] and nickel [187]. The iron sample was alloyed with silicon to bring the Curie temperature down to a convenient value

Seavey and Tannenwald observed the microwave excitation of standing spin waves in thin films of permalloy [189], and light scattering has also proven useful in studying spin waves in metals [190].

## Problems

8.1.
(a) Express $|\boldsymbol{M}|$ and $M_{z}$ in terms of the number of magnons, $n_{\boldsymbol{k}}$. How many magnons are involved in changes of these quantities?
(b) Which of the following magnon scattering processes (Fig. 8.26) represent microscopic mechanisms for the phenomenological damping parameter $\alpha$ ?

(i)

(iii)

Fig. 8.26. Relaxation processes that may, or may not, be described by " $\alpha$ "
8.2. Consider 1-magnon scattering described by the Hamiltonian

$$
\mathcal{H}=\sum_{\boldsymbol{k}} g_{0 \boldsymbol{k}}\left(a_{\boldsymbol{k}}^{+} a_{0}+a_{0}^{+} a_{\boldsymbol{k}}\right) .
$$

Using perturbation theory calculate the relaxation rate of the uniform precession mode and determine the frequency dependence of the FMR linewidth.
8.3. From the kinetic theory of gases the thermal conductivity is given by

$$
\kappa=\frac{1}{3} C \eta \Lambda,
$$

where $C$ is the heat capacity per unit volume, $v$ is the particle velocity, and $\Lambda$ the mean free path. Calculate the thermal conductivity of a "magnon gas" where $C(\boldsymbol{k})=\frac{\partial}{\partial T}\left(n_{k} \varepsilon_{k}\right), v$ is the group velocity $v=\frac{\partial \varepsilon_{k}}{\partial_{k}}$, and $\Lambda$ is independent of $\boldsymbol{k}$. Use the same approximations in obtaining the heat capacity (8.74).

## Thin Film Systems

The development of thin film deposition systems, such as molecular beam epitaxy and sputtering during the 1970s and 1980s and pulsed laser deposition in the 1990s made it possible to synthesize novel materials systems which exhibited new phenomena. Quantum wells, for example, led to the quantum Hall effect.

Similarly, thin magnetic films led to the giant magnetoresistance (GMR) effect. In this chapter we shall explore the concepts associated with magnetic multilayer structures. We shall begin with a single interface and then consider magnetic layers separated by thin conducting and insulating layers.

### 9.1 Interfaces

### 9.1.1 Exchange Bias

Just as there is exchange between the sublattices of an antiferromagnet or ferrimagnet, we expect there to be exchange across the interface between two dissimilar magnetic materials. Consider, for example, the interface between the [111] plane of antiferromagnetic CoO and Co metal. The [111] plane of CoO corresponds to one of the sublattices. Therefore, in the antiferromagnetic state the spins on this plane are all parallel. Suppose this antiferromagnet is in proximity with a ferromagnet at a temperature $T$ such that $T_{N}<T<T_{c}$ and is then cooled below $T_{N}$. This aligns the spins on the surfaces of the antiferromagnet with the ferromagnet. Below $T_{N}$ the anisotropy of the antiferromagnet "locks in" the spin configuration. The ferromagnet now "sees" a unidirectional exchange from the antiferromagnet. Figure 9.1 shows the hysteresis loop of Co particles coated with CoO. The loop is shifted by 2 Oe. This is referred to as exchange bias. This is a very important phenomenon because it may be used to bias ferromagnetic films for a variety of applications.

To describe this effect let us assume that the exchange across the interface between the antiferromagnetic spins and the ferromagnetic spins may be expressed in terms of an exchange energy density (per unit area) as $J \cos (\alpha-\beta)$,


Fig. 9.1. Hysteresis loops of fine oxide-coated particles of cobalt taken at $77^{\circ} \mathrm{K}$. The dashed lines show the hysteresis loop when the material is cooled in the absence of a magnetic field. The solid lines show the hysteresis loop when the material is cooled in a saturating magnetic field [191]


Fig. 9.2. Definition of angles used in describing the coupling between an antiferromagnet (AFM) and a ferromagnet (FM)
where the angle $\alpha$ is the direction of the magnetization and the angle $\beta$ is the direction of the antiferromagnetic axis (see Fig. 9.2). If an external field $H$ is applied at an angle $\theta$ the Zeeman energy density is $-H M t_{F} \cos (\theta-$ $\alpha$ ), where $t_{F}$ is the thickness of the ferromagnet. If we add an anisotropy term to the ferromagnet then the problem of determining the direction of the magnetization of the ferromagnet is identical to the Stoner-Wohlfarth model discussed in Sect. 4.6, except the hysteresis loop is now shifted by an amount

$$
\begin{equation*}
H_{E}=\frac{J}{M t_{F}} \tag{9.1}
\end{equation*}
$$

While this simple model seems to describe this effect, there are quantitative discrepancies. First of all, we would expect the interface exchange to be comparable to the exchange in the materials on either side. However, the observed values of $H_{E}$ lead to values of $J$ which are several orders of magnitude too small. Secondly, $H_{E}$ is found to depend upon the thickness of the antiferromagnet, $t_{A F}$. In particular, $H_{E}$ vanishes for antiferromagnetic thicknesses less than a critical value.

The second observation suggests that perhaps the assumption that the antiferromagnetic spin structure remains rigid is not valid. Antiferromagnets do exhibit domains. These domains are separated by walls very similar to those found in ferromagnets. The energy per unit wall area of an antiferromagnetic wall is given by

$$
\begin{equation*}
\sigma_{w}=\sqrt{A_{A F} K_{A F}} \tag{9.2}
\end{equation*}
$$

where $A_{A F}$ and $K_{A F}$ are the exchange and anisotropy parameters in the antiferromagnet, respectively. Let us assume that as the magnetization of the ferromagnet is pulled around in the plane of the film by an external field this induces a twist in the antiferromagnetic through an angle $\beta$. The energy density is then $\sigma_{w}(1-\cos \beta)$. The total energy density is now

$$
\begin{equation*}
\varepsilon=-H M t_{F} \cos (\theta-\alpha)+J \cos (\beta-\alpha)+\sigma_{w}(1-\cos \beta) \tag{9.3}
\end{equation*}
$$

The equilibrium equations are

$$
\frac{\partial \varepsilon}{\partial \alpha}=0, \quad \frac{\partial \varepsilon}{\partial \beta}=0
$$

In a reverse field $(\theta=\pi)$ where the magnetization has rotated half way around ( $\alpha=\frac{\pi}{2}$ ) these equations become

$$
\begin{align*}
& -H M t_{F}+J \cos \beta=0  \tag{9.4}\\
& -J \cos \beta+\sigma_{w} \sin \beta=0 \tag{9.5}
\end{align*}
$$

Solving for $\cos \beta$ gives

$$
\begin{equation*}
\cos \beta=\sqrt{\frac{\sigma_{w}^{2}}{J^{2}+\sigma_{w}^{2}}} \tag{9.6}
\end{equation*}
$$

The value of the exchange deduced from a hysteresis loop in this case is

$$
\begin{equation*}
J_{h \ell}=M t_{F} H_{e} \tag{9.7}
\end{equation*}
$$

where $H_{e}$ is the field required to drive the magnetization to zero,

$$
\begin{equation*}
H_{e}=\frac{J}{M t_{F}} \cos \beta . \tag{9.8}
\end{equation*}
$$



Fig. 9.3. Exchange interactions at the interface between an antiferromagnetic (AFM) and a ferromagnet (FM)

Therefore

$$
\begin{equation*}
J_{h \ell}=\frac{J \sigma_{w}}{\sqrt{J^{2}+\sigma_{w}^{2}}} \tag{9.9}
\end{equation*}
$$

Thus, if the antiferromagnet is allowed to twist, the exchange deduced from a hysteresis loop measurement is renormalized by the wall energy. In particular, the loop can never be shifted by more than $\sigma_{w}$, no matter how large the direct exchange $J$. There are other mechanisms that can lead to a reduced exchange bias. Malozemoff [192], for example, has pointed out that interface roughness will produce a random magnetic field which, according to Imry and Ma [193], will lead to domains in the antiferromagnet at the interface.

There is independent evidence for the role of interface roughness in exchange bias. Namely, the linewidth of the ferromagnetic resonance (FMR) associated with a ferromagnetic/antiferromagnetic (FM/AFM) bilayer is an order of magnitude larger than the linewidth without exchange bias and increases with decreasing thickness of the FM film. Rezende et al. [194] argue that this is due to two-magnon scattering in which the uniform mode (the FMR) is scattered into a $\boldsymbol{k} \neq 0$ mode by the fluctuations in the exchange at the FM/AFM interface. This is analogous to the origin of the FMR linewidth in a YIG sphere due to magnon scattering induced by the dipole fields produced by surface roughness [163] (see, also Problem 8.2).

### 9.1.2 Biquadratic Exchange

Neutron scattering studies of superlattices composed of antiferromagnetic CoO and ferrimagnetic $\mathrm{Fe}_{3} \mathrm{O}_{4}$ show that when the $\mathrm{Fe}_{3} \mathrm{O}_{4}$ is magnetized the CoO spins align in domains with spins perpendicular to the net $\mathrm{Fe}_{3} \mathrm{O}_{4}$ moment. This is attributed to an exchange energy proportional to $\cos ^{2} \theta$, where $\theta$ is the angle between the $\mathrm{Fe}_{3} \mathrm{O}_{4}$ moment and the AFM sublattice.

To understand the origin of this phenomenon let us consider a FM/AFM interface as shown in Fig. 9.3. Due to the surface roughness both compensated and uncompensated interfaces will have a surface energy consisting of exchange coupling between the FM spins, $\tilde{f}$, and the two AFM sublattice spins $\boldsymbol{a}$ and $\boldsymbol{b}$, i.e., $\boldsymbol{a} \cdot \boldsymbol{f}$. Let $J_{a}$ and $J_{b}$ be the exchange between a FM spin and an AFM spin at sublattice $a$ or $b$, respectively. The interface energy then becomes

$$
\begin{equation*}
\mathcal{H}_{\mathrm{int}}=-J_{a} \boldsymbol{a} \cdot \boldsymbol{f}-J_{b} \boldsymbol{b} \cdot \boldsymbol{f} \tag{9.10}
\end{equation*}
$$



Fig. 9.4. Interface between a FM and AFM in which the AFM has fluctuated into its spin-flop state

It is convenient to introduce the sum and difference vectors,

$$
\ell=a+b, \quad t=a-b
$$

The interface energy then becomes

$$
\begin{equation*}
\mathcal{H}_{\mathrm{int}}=-\left(\frac{J_{a}+J_{b}}{2}\right) \boldsymbol{\ell} \cdot \boldsymbol{f}-\left(\frac{J_{a}-J_{b}}{2}\right) \boldsymbol{t} \cdot \boldsymbol{f} \tag{9.11}
\end{equation*}
$$

If the interface is uncompensated; for example if $\boldsymbol{b}=-\boldsymbol{a}$ (i.e., $\boldsymbol{\ell}=0$ ) but $J_{a} \neq J_{b}$, then

$$
\begin{equation*}
\mathcal{H}_{\mathrm{int}}=-\left(J_{a}-J_{b}\right) \boldsymbol{a} \cdot \boldsymbol{f} \tag{9.12}
\end{equation*}
$$

If the interface is compensated, i.e., $\boldsymbol{b}=-\boldsymbol{a}$ and $J_{a}=J_{b}$, then $\mathcal{H}_{\text {int }}=0$. However, the AFM may fluctuate into the spin-flop state (Fig. 9.4).

This "twist" penetrates into the AFM and has an energy associated with it equal to the wall energy, $\sigma_{w}$. Now $\boldsymbol{b}^{\prime} \neq-\boldsymbol{a}^{\prime}$ and the change in energy according to second order perturbation theory is

$$
\begin{equation*}
\frac{\left(\frac{J_{a}+J_{b}}{2}\right)^{2}\left(\ell^{\prime} \cdot \boldsymbol{f}\right)^{2}}{\sigma_{w}}=\frac{\left(J_{a}+J_{b}\right)^{2} \theta^{2}}{\sigma_{w}}(\boldsymbol{a} \cdot \boldsymbol{f})^{2} \tag{9.13}
\end{equation*}
$$

where $\theta$ is the canting angle. Thus, if the AFM surface is compensated, one of the "sublattices will be frustrated", i.e., points in a direction opposite to that preferred by the neighboring FM. This leads to the biquadratic exchange favoring a perpendicular alignment.

### 9.2 Trilayers

Very interesting behavior is found in magnetic systems consisting of two magnetic films separated by a nonmagnetic layer. In anticipation of fabricating magnetic multilayers theoretical analyses predicted a variety of magnetic structures. Majkrzek et al. [195] and Grunberg et al. [196] independently demonstrated exchange coupling between magnetic films separated by nonmagnetic spacers. Majkrzek et al. studied $G d_{n} Y_{m}$ superlattices using neutron diffraction while Grunberg et al. studied light scattering from spinwaves in


Fig. 9.5. Magnetostatic coupling across a nonmagnetic spacer layer associated with magnetic poles generated by surface roughness. (This is referred to as "orange peel" coupling after the texture of the surface of an orange)
$\mathrm{Fe}-\mathrm{Cr}-\mathrm{Fe}$ and $\mathrm{Fe}-\mathrm{Au}-\mathrm{Fe}$ trilayers. Both groups observed antiferromagnetic coupling at certain spacer thicknesses.

There are several mechanisms for coupling to occur across the spacer layer. If the spacer is too thin the most obvious coupling is through "pin holes", or regions in which the magnetic material connect through the spacer. This can be avoided by growing high quality films.

Néel also pointed out that surface roughness will develop magnetic poles that lead to magnetostatic coupling across the spacer (see Fig. 9.5). Since the roughness tends to propogate through the structure, the topology on both sides of the spacer will generally have the same "phase". This leads to ferromagnetic coupling. The observed antiferromagnetic coupling is believed to be intrinsically associated with the metallic spacer. In the next two sections we shall describe two models that give antiferromagnetic coupling.

### 9.2.1 The RKKY Ineraction

As we saw in Sect.2.2, there is a contact hyperfine interaction between $s$-state electrons and nuclear moments. Fröhlich and Nabarro were the first to suggest that this interaction could lead to a polarization of the nuclear moments [197]. The actual form of this interaction, however, was obtained by Ruderman and Kittel [198]. In analogy with this nuclear coupling, the exchange interaction between conduction electrons and localized electrons can also lead to indirect coupling between localized electronic moments. Zener [199] proposed that this was the origin of ferromagnetism in transition metals. Kasuya investigated this interaction in more detail, particularly with respect to its effect on spin waves and electrical resistivity [200]. Yosida also employed this interaction to explain the magnetic properties of $\mathrm{Cu}-\mathrm{Mn}$ alloys [201]. As a result of these developments, the indirect coupling of magnetic moments by condution electrons is referred to as the Ruderman-Kittel-Kasuya-Yosida (RKKY) interaction.

The form of the RKKY interaction is easily obtained within the framework of our generalized susceptibility. Let us assume that the interaction between
a localized spin $S_{\alpha}$ located at $\boldsymbol{r}=0$ and the conduction spins $\boldsymbol{s}_{i}$ has the form

$$
-J \sum_{i} \boldsymbol{S}_{\alpha} \cdot \boldsymbol{s}_{i}(\boldsymbol{r})
$$

Each conduction spin therefore experiences an effective field given by

$$
\begin{equation*}
\boldsymbol{H}_{\mathrm{eff}}(\boldsymbol{r})=-\frac{J}{g \mu_{B}} \boldsymbol{S}_{\alpha} \delta(\boldsymbol{r}) \tag{9.14}
\end{equation*}
$$

The response of an electron gas to such a field is determined by its susceptibility $\chi(\boldsymbol{q})$. Since the Fourier transform of this field is

$$
\begin{equation*}
\boldsymbol{H}_{\mathrm{eff}}(\boldsymbol{q})=-\frac{J}{g \mu_{B}} \boldsymbol{S}_{\alpha} \tag{9.15}
\end{equation*}
$$

the spin density at $\boldsymbol{r}$ is

$$
\begin{equation*}
s(\boldsymbol{r})=\frac{J}{g^{2} \mu_{B}^{2} V} \sum_{q} \chi(\boldsymbol{q}) e^{i \boldsymbol{q} \cdot \boldsymbol{r}} \boldsymbol{S}_{\alpha} \tag{9.16}
\end{equation*}
$$

For a free-electron gas $\chi(\boldsymbol{q})$ is given by (3.97). The sum over $\boldsymbol{q}$ is evaluated by converting it into an integral. This integral is easily evaluated by using the integral representation [H. Levine, private communication].

$$
\begin{equation*}
\ln \left|\frac{2 k_{F}+q}{2 k_{F}-q}\right|=2 \int_{0}^{\infty} \frac{d x \sin \left(2 k_{F} x\right) \sin (q x)}{x} \tag{9.17}
\end{equation*}
$$

The result is

$$
\begin{align*}
\frac{1}{V} \sum_{\boldsymbol{q}} \chi(\boldsymbol{q}) e^{i \boldsymbol{q} \cdot r} & =\frac{3 g^{2} \mu_{B}^{2}(N / V)}{3 \varepsilon_{F}} \frac{1}{2 \pi^{2} r} \int d q q F\left(\frac{q}{2 k_{F}}\right) \sin q r  \tag{9.18}\\
& =\frac{3 g^{2} \mu_{B}^{2}(N / V)}{8 \varepsilon_{F}} \frac{k_{F}^{3}}{16 \pi}\left[\frac{\sin 2 k_{F} r-2 k_{F} r \cos 2 k_{F} r}{\left(k_{F} r\right)^{4}}\right]
\end{align*}
$$

The part of this expression within the brackets is plotted in Fig. 9.6.
Thus we see that when a localized moment is introduced into a metal, the conduction spins develop an oscillating polarization in the vicinity of this moment. These spin-density oscillations have the same form as the Friedel charge-density oscillations that result when an electron gas screens out a charge impurity.

The most direct evidence for the oscillatory nature of this interaction comes from NMR studies. In CuFe, for example, the nuclear resonance spectrum consists of the strong Knight-shifted $\mathrm{Cu}^{63}$ line found in pure Cu plus various satellites corresponding to Cu nuclei which lie within the RKKY oscillations around an Fe impurity. These Cu nuclei feel a contact hyperfine field


Fig. 9.6. Plot of the conduction-electron spin density produced by an impurity spin in a metallic host

$$
\delta H(\boldsymbol{r}, T)=-\frac{8}{3} \pi g \mu_{B} \sigma(\boldsymbol{r}, T),
$$

where

$$
\sigma(\boldsymbol{r}, T)=\chi_{\mathrm{imp}}(T) H f(\boldsymbol{r})
$$

Here $\chi_{i m p}(T)$ is the susceptibility of a single Fe impurity and $f(\boldsymbol{r})$ characterizes the RKKY spatial dependence. An external field polarizes the impurity which in turn increases $\sigma(\boldsymbol{r}, T)$. Thus the satellites should move away from the main line with increasing field with a slope that depends upon $f(\boldsymbol{r})$. Figure 9.7 shows the field dependence of five such satellites [202]. The appearance of both positive and negative slopes results from the oscillatory nature of $f(\boldsymbol{r})$.

If there is another localized spin $\boldsymbol{S}_{\beta}$ at $\boldsymbol{r}$, it interacts with this induced spin density, leading to an effective interaction between the localized spins of the form

$$
\begin{equation*}
\mathcal{H}_{R K K Y}=-\frac{J^{2}}{g^{2} \mu_{B}^{2} V} \sum_{\boldsymbol{q}} \chi(\boldsymbol{q}) e^{i \boldsymbol{q} \cdot r} \boldsymbol{S}_{\alpha} \cdot \boldsymbol{S}_{\beta} \tag{9.19}
\end{equation*}
$$

This interaction manifests itself in many ways. Ruderman and Kittel [198] showed that it leads to a broadening of the nuclear magnetic resonance absorption. This interaction is also the origin of the exchange coupling between the localized moments in the rare-earth metals. As we saw in Chap. 4, its oscillatory nature leads to helimagnetism in these materials.


Fig. 9.7. Magnetic field dependance of satellite separations from the main $\mathrm{Cu}^{63}$ resonance at 300 K in CuFe [202]

### 9.2.2 Quantum Well Model

When the moments being coupled are itinerant, such as in an $\mathrm{Fe} / \mathrm{Cu} / \mathrm{Fe}$ trilayer, it is appropriate to describe the whole trilayer in a band picture. An electron moving in a ferromagnet will experience an exchange potential. We represent this by a difference in the potentials for spin up and spin down. Thus, the trilayer potential for a spin up when the two ferromagnets are antiparallel is shown in Fig. 9.8a. The objective is to calculate the energy levels associated with each of these potentials and then determine the total energy when these


Fig. 9.8. Squarewell potentials seen by an electron moving in a trilayer consisting of two ferromagnets separated by a nonmagnetic, but conducting, spacer
levels are filled up to the Fermi level [205]. Since we are dealing with a large number of particles it is convenient to work with the grand thermodynamic potential, $\Omega$, we introduced in our discussion of the deHaas-Van Alphen effect, (3.75):

$$
\begin{align*}
\Omega & =k_{B} T \sum_{i} \ln \left(1+\exp \left[-\beta\left(E_{i}-E_{F}\right)\right]\right) \\
& =-k_{B} T \int_{-\infty}^{\infty} \ln \left[1+\exp \left(\frac{\varepsilon_{F}-\varepsilon}{k_{B} T}\right)\right] n(\varepsilon) d \varepsilon \tag{9.20}
\end{align*}
$$

where $n(\varepsilon)$ is the density of states. Integrating by parts gives

$$
\Omega=-\int_{-\infty}^{\infty} N(\varepsilon) f(\varepsilon) d \varepsilon
$$

where $N(\varepsilon)$ is the integrated density of states,

$$
N(\varepsilon)=\int_{-\infty}^{\varepsilon} n\left(\varepsilon^{\prime}\right) d \varepsilon^{\prime}
$$

and $f(\varepsilon)$ is the Fermi function. At $T=0$

$$
\Omega \rightarrow-\int_{-\infty}^{\varepsilon_{F}} N(\varepsilon) d \varepsilon
$$

Thus, our problem reduces to calculating the density of states associated with the potentials in Fig. 9.8. Since we are interested in how the density of states changes with the thickness of the spacer layer we focus our attention on this layer. When an electron in the spacer layer moving to the right with momentum $k^{+}$is incident on the ferromagnetic layer its wave function is reflected and transmitted. Let us denote the reflection coefficient for a spin up striking the $B$ ferromagnet when its moment is also "up" as $R_{B}^{\uparrow}$. The electron then moves back to the $A$ ferromagnet where it is reflected with a coefficient $R_{A}^{\uparrow}$ if the $A$ moment is also "up". Bruno [203] has shown that this confinement of up-spin electrons in the spacer bound by ferromagnetically aligned moments produces a change in the integrated density of states equal to

$$
\begin{equation*}
\Delta N(\varepsilon)=-\frac{2}{\pi} \operatorname{Im} \ln \left(1-R_{A}^{\uparrow} R_{B}^{\uparrow} e^{i q D}\right) \tag{9.21}
\end{equation*}
$$

where $q=k^{+}-k^{-}$. The change in the thermodynamic potential $\Omega$, associated with this change in the integrated density of states gives the change in energy

$$
\begin{equation*}
\Delta E_{F}^{\uparrow}=\frac{2}{\pi} \operatorname{Im} \int_{-\infty}^{\infty} \ln \left(1-R_{A}^{\uparrow} R_{B}^{\uparrow} e^{i q D}\right) d \varepsilon \tag{9.22}
\end{equation*}
$$

Considering the other three configurations and generalizing to threedimensions we obtain


Fig. 9.9. Fermi surface of gold showing the two spanning vectors that govern the coupling between magnetic films placed on either side of the gold


Fig. 9.10. Magnetization in the plane of an Fe film separated from an Fe whisker by a gold wedge showing that the coupling varies with the thickness of the wedge [204]

$$
\begin{align*}
\Delta E_{F}-\Delta E_{A F}= & \frac{1}{4 \pi^{3}} \operatorname{Im} \int d^{2} k_{\|} \int_{-\infty}^{+\infty} f(\varepsilon)  \tag{9.23}\\
& \times \ln \left[\frac{\left(1-R_{A}^{\uparrow} R_{B}^{\uparrow} e^{i q_{\perp} D}\right)\left(1-R_{A}^{\downarrow} R_{B}^{\downarrow} e^{i q_{\perp} D}\right)}{\left(1-R_{A}^{\uparrow} R_{B}^{\downarrow} e^{i q_{\perp} D}\right)\left(1-R_{A}^{\downarrow} R_{B}^{\uparrow} e^{i q_{\perp} D}\right)}\right] d \varepsilon .
\end{align*}
$$

In the limit of weak confinement this may be written

$$
\begin{equation*}
E_{F}-E_{A F}=-\frac{1}{\pi^{3}} \operatorname{Im} \int d^{2} k_{\|} \int_{-\infty}^{\infty} f(\varepsilon) \Delta R_{A} \Delta R_{B} e^{i q_{\perp} D} d \varepsilon \tag{9.24}
\end{equation*}
$$

Table 9.1. Exchange Oscillation Periods for $\mathrm{Fe} / \mathrm{Au} / \mathrm{Fe}$ (100)

| SEMPA | $2.48 \pm 0.05$ | $8.6 \pm 0.3$ |
| :--- | :---: | :---: |
| dHvA | 2.51 | 8.60 |

where $\Delta R=R^{\uparrow}-R^{\downarrow}$. The factor $\exp \left(i q_{\perp} D\right)$ describes the propagation through this spacer. Since $q_{\perp}=2 k_{F}$ this predicts that the coupling oscillates as a function of spacer thickness with a period given by $2 k_{F}$. When $2 k_{F}$ connects regions of the Fermi surfaces that are relatively flat the integral over $k_{\|}$will weight these contributions more heavily. We refer to these particular vectors as the spanning vectors of the Fermi surface. Figure 9.9 shows the Fermi surfaces of gold in the extended zone scheme. For a spacer oriented in the (100) direction there are two spanning vectors. This would suggest that the coupling between two magnetic films separated by gold with a (100) orientation should show a variation with thickness that is the superposition of a long and a short period. Such behavior has been observed in a very nice experiment on $\mathrm{Fe} / \mathrm{Au} / \mathrm{Fe}$ by Unquris, et al. [204]. As shown in Fig. 9.10, they deposit a thin iron layer on top of a gold wedge-shaped spacer which is in turn deposited on top of an iron whisker with two magnetic domains. The direction of the magnetization in the top layer is measured by Scanning Electron Microscopy with Polarization Analysis (SEMPA). The periods deduced from the SEMPA measurement are compared with those obtained from deHaas-van Alphen measurements in Table 9.1 [204].

### 9.2.3 Giant Magnetoresistance (GMR)

When current flows through a magnetic film, as shown in Fig. 9.11 the resistivity depends upon the angle the current makes with the magnetization according to

$$
\begin{equation*}
\rho=\rho_{0}+\Delta \rho \cos ^{2} \theta \tag{9.25}
\end{equation*}
$$

This is called the anisotropic magnetoresistance (AMR) and is due to the scattering of the conduction electrons from the d-moments of the magnetization.


Fig. 9.11. Geometry for the AMR effect


Fig. 9.12. Geometry of the Current-In-Plane (CIP) GMR effect. (a) high resistance; (b) low resistance

The largest effect has been found in permalloy where $\Delta \rho / \rho_{0}=2 \%$. With the development of thin film deposition techniques, it was natural to measure the magnetoresistance of magnetic multilayers. The surprising result was that the magnetoresistance of an $\mathrm{Fe} / \mathrm{Cr} / \mathrm{Fe}$ trilayer was $200 \%$ (at 4.2 K ) [206]. However, in the case of the trilayer, the resistance depends upon the relative orientation of the magnetizations in the magnetic layers.

If the metallic inner layer provides an antiferromagnetic coupling, the magnetizations in zero field will be antiparallel as shown in Fig.9.12a. In the presence of a strong enough field, the moments become parallel as shown in Fig. 9.12b. The resistance is always found to be larger in the antiparallel configuration. This effect is also independent of the relative orientation of the magnetizations and the bias current. However, the magnitude of the effect is larger when the current flows perpendicular to the plane of the magnetization (CPP) as opposed to the current being in the plane (CIP) - as is the case in Fig. 9.12. Thus, the resistivity of this "giant magnetoresistance" (GMR) effect may be expressed as

$$
\begin{equation*}
\rho=\rho_{0}+\Delta \rho \cos \left(\theta_{1}-\theta_{2}\right) \tag{9.26}
\end{equation*}
$$

For a summary of experimental aspects of GMR see [207]. The microscopic explanation of the GMR effect may be understood by first considering the scattering of electrons in a ferromagnet. As we saw in Sect.5.3, the spin-up and spin-down $d$-bands are exchange split, the s-bands less so as illustrated in Fig. 9.13. The current is largely carried by the s-electrons. However, when they scatter, from impurities or lattice irregularities, for example, the probability of scattering into a $d$-state is large because the density of $d$-states is larger.

Since the probability of spin flip scattering is smaller, we shall not include this process. Now, let us consider how this scattering affects the transport in a $\mathrm{Co} / \mathrm{Cr} / \mathrm{Co}$ trilayer. Consider the down-spin (1) (relative to the direction of the magnetization) in Fig. 9.14a. When this electron reaches the Cr interface it scatters back into the Co with a probability that is proportional to the Co $d$-electron down-spin density, $\mathrm{N}_{d \downarrow}$. The up-spin (2) successfully transverses the


Fig. 9.13. Simplified band structure of a ferromagnet showing s-electrons being scattered into $d$-states


Fig. 9.14. Most likely scattering processes in a trilayer whose magnetic layers have a band structure like that shown in Fig. 9.13
$\mathrm{Co}-\mathrm{Cr}$ interface because the majority spin $d$-band density of states for the bands shown in Fig. 9.13 is smaller. However, when this electron reaches the interface with the top magnetic layer there are two possibilities depending upon whether the magnetization of this layer is parallel or antiparallel to the bottom layer. If it is parallel (Fig. 9.14b), the probability is again small and the electron continues on its way. If the magnetization is antiparallel (Fig. 9.14a), then the up-spin electron finds itself in an environmment in which it is effectively a "down-spin" and therefore, scatters more strongly. This argument suggests that the average mean free path in the case of parallel magnetizations is larger than that of antiparallel magnetizations, giving the parallel configuration a smaller resistivity.

The GMR serves as the basis for very sensitive detection of magnetic fields. In this application one of the magnetic layers is "pinned", generally by placing it in contact with an antiferromagnet and utilizing the exchange bias. ${ }^{1}$ The

[^3]other layer is designed to have a very small coercivity, so it is free to be oriented by the field one is sensing. This configuration is called a spin valve.

In order to maximize the GMR one needs a theory that incorporates the physics necessary to predict the GMR behavior.
Kubo Formula. In keeping with the linear response approach adopted in this text one can apply the same formalism to calculate the electrical conductivity $\sigma_{\alpha \beta}$, that we used to calculate the susceptibility. We apply a perturbing electric field and calculate the current response. Since the applied field produces currents which, in turn, produce electric fields, the conductivity is defined by the current response to the total electric field, $\mathcal{E}(\boldsymbol{r}, t)$,

$$
\begin{equation*}
J_{\alpha}(\boldsymbol{r}, t)=\int d^{3} r^{\prime} \int d t^{\prime} \sigma_{\alpha \beta}\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}, t-t^{\prime}\right) \mathcal{E}_{\beta}\left(\boldsymbol{r}^{\prime}, t^{\prime}\right) \tag{9.27}
\end{equation*}
$$

The current density at $\boldsymbol{r}$ is given by averaging the velocity of the particles over volume $\Omega$,

$$
\begin{equation*}
J_{\alpha}(\boldsymbol{r}, t)=e\left\langle\sum_{i} v_{i \alpha} \delta\left(\boldsymbol{r}-\boldsymbol{r}_{i}\right)\right\rangle . \tag{9.28}
\end{equation*}
$$

The velocity is given by

$$
\begin{equation*}
\boldsymbol{v}_{i}=\frac{1}{m}\left[\boldsymbol{p}_{i}-\frac{e}{c} \boldsymbol{a}\left(\boldsymbol{r}_{i}\right)\right] \tag{9.29}
\end{equation*}
$$

Therefore

$$
\begin{equation*}
J_{\alpha}(\boldsymbol{r}, t)=\frac{e}{m \Omega} \sum_{i}\left\langle p_{i \alpha}\right\rangle-\frac{e^{2}}{m c} \sum_{i}\left\langle A_{\alpha}\left(\boldsymbol{r}_{i}\right)\right\rangle \tag{9.30}
\end{equation*}
$$

Since the momentum is related to the current by $\boldsymbol{i}_{i}=\frac{e}{m} \boldsymbol{p}_{i}$,

$$
\begin{equation*}
J_{\alpha}(\boldsymbol{r}, t)=\frac{1}{\Omega} \sum_{i}\left\langle i_{i \alpha}\right\rangle-\frac{e^{2}}{m c} \sum_{i}\left\langle A_{\alpha}\left(\boldsymbol{r}_{i}\right)\right\rangle \tag{9.31}
\end{equation*}
$$

The vector potential is related to the electric field by $A_{\alpha}\left(\boldsymbol{r}_{i}\right)=-i \frac{c}{\omega} \mathcal{E}_{\alpha}\left(\boldsymbol{r}_{i}\right)$. The number of particles in the sum over $i$ is $n \Omega$ where $n$ is the particle density. This sum gives the macroscopic average,

$$
\begin{equation*}
J_{\alpha}(\boldsymbol{r}, t)=\left\langle j_{\alpha}(\boldsymbol{r}, t)\right\rangle+i \frac{n e^{2}}{m \omega} \mathcal{E}_{\alpha}(\boldsymbol{r}, t) \tag{9.32}
\end{equation*}
$$

To obtain $\sigma_{\alpha \beta}$ we must calculate $\left\langle j_{\alpha}(\boldsymbol{r}, t)\right\rangle$ to lowest order in $\mathcal{E}_{\alpha}(\boldsymbol{r}, t)$. The result is [208].

$$
\begin{equation*}
\sigma_{\alpha \beta}(\boldsymbol{q}, \omega)=\frac{1}{\omega \Omega} \int_{0}^{\infty} d t e^{i \omega t}\langle\psi| j_{\alpha}^{\dagger}(\boldsymbol{q}, t), j_{\beta}(\boldsymbol{q}, 0)|\psi\rangle+i \frac{n e^{2}}{m \omega} \delta_{\alpha \beta} \tag{9.33}
\end{equation*}
$$

Thus, the conductivity is given by the average value of the current-current correlation function where the wavefunction $\mid \psi>$ is the ground state of the many body system. Equation (9.33) is known as the Kubo formula. The problem with this approach is that one does not always know the ground state $\mid \psi>$. Butler and his colleagues, for example, have employed the local spin density approximation to the density functional theory we discussed on page 177 to calculate the transport properties of multilayers [209].
Boltzmann Equation. An alternative approach to describing the GMR effect which relates more directly to the physical picture we gave at the beginning of this section is the semiclassical approach based on the Boltzmann equation. In this approach the electron is described by a distribution function, $f^{\sigma}(\boldsymbol{r}, \boldsymbol{k}, t)$, which gives the probability of finding an electron with spin $\sigma$ at $r$ with a momentum $\hbar \boldsymbol{k}$. Conceptually, this is the basis for the Fermi liquid approach we introduced in Chap. 7. This probability will change over time due to forces acting on the electron, and also simply due to the fact that the electron is moving through space. The total time rate of change is given by

$$
\begin{equation*}
\frac{d f}{d t}=\frac{\partial f}{\partial t}+\dot{\boldsymbol{r}} \cdot \nabla_{r} f+\dot{\boldsymbol{k}} \cdot \nabla_{\boldsymbol{k}} f+\left.\frac{\partial f}{\partial t}\right|_{\mathrm{scat}}, \tag{9.34}
\end{equation*}
$$

where the last term is the change due to scattering. In equilibrium the total time derivative is zero. Therefore

$$
\begin{equation*}
\frac{\partial f}{\partial t}=-\dot{\boldsymbol{r}} \cdot \nabla_{\boldsymbol{r}} f-\dot{\boldsymbol{k}} \cdot \nabla_{\boldsymbol{k}} f-\left.\frac{\partial f}{\partial t}\right|_{\mathrm{scat}} \tag{9.35}
\end{equation*}
$$

$\dot{\boldsymbol{k}}$ is given by the forces,

$$
\begin{equation*}
\hbar \dot{\boldsymbol{k}}=-|e| \mathcal{E}-|e| \boldsymbol{v} \times \boldsymbol{B} . \tag{9.36}
\end{equation*}
$$

The term involving the magnetic field is generally small and, therefore, neglected. Let us also restrict our consideration to the dc conductivity so that $f$ is not a function of time.

Let $\mathcal{P}_{\boldsymbol{k}, \boldsymbol{k}^{\prime}}$ be the probability that an electron scatters from state $\boldsymbol{k}$ to $\boldsymbol{k}^{\prime}$. We shall neglect spin-flip scattering since its probability is small. The scattering may, however, be different for the two spin directions giving rise to spin-dependent scattering. We shall suppress the spin index, keeping in mind that there are two spin channels. Then the scattering term may be written.

$$
\begin{align*}
\left.\frac{\partial f}{\partial t}\right|_{\mathrm{scat}}= & \sum_{\boldsymbol{k}^{\prime}} P_{\boldsymbol{k} \boldsymbol{k}^{\prime}}[1-f(\boldsymbol{r}, \boldsymbol{k})] f\left(\boldsymbol{r}, \boldsymbol{k}^{\prime}\right) \\
& -P_{\boldsymbol{k}^{\prime} \boldsymbol{k}}\left[1-f\left(\boldsymbol{r}, \boldsymbol{k}^{\prime}\right)\right] f(\boldsymbol{r}, \boldsymbol{k}) \tag{9.37}
\end{align*}
$$

Microscopic reversibility requires $P_{\boldsymbol{k}^{\prime} \boldsymbol{k}}=P_{\boldsymbol{k} \boldsymbol{k}^{\prime}}$. Therefore

$$
\begin{equation*}
\left.\frac{\partial f}{\partial t}\right|_{\text {scat }}=\sum_{\boldsymbol{k}^{\prime}} P_{\boldsymbol{k} \boldsymbol{k}^{\prime}}\left[f\left(\boldsymbol{r}, \boldsymbol{k}^{\prime}\right)-f(\boldsymbol{r}, \boldsymbol{k})\right] . \tag{9.38}
\end{equation*}
$$

In equilibrium, in the absence of an applied field, the distribution function is the Fermi-Dirac function

$$
f_{0}(\boldsymbol{k})=\frac{1}{1+e^{\left[E(\boldsymbol{k})-E_{F}\right] / k_{B} T}}
$$

Again, in the spirit of linear response theory, we assume $f(\boldsymbol{r}, \boldsymbol{k})$ may be written as $f_{0}(\boldsymbol{k})$ plus a small deviation $g(\boldsymbol{r}, \boldsymbol{k})$, i.e.,

$$
\begin{equation*}
f(\boldsymbol{r}, \boldsymbol{k})=f_{0}(\boldsymbol{k})+g(\boldsymbol{r}, \boldsymbol{k}) . \tag{9.39}
\end{equation*}
$$

The equation for $g(\boldsymbol{r}, \boldsymbol{k})$ then becomes

$$
\begin{equation*}
\boldsymbol{v}(\boldsymbol{k}) \cdot \nabla_{r} g(\boldsymbol{r}, \boldsymbol{k})-|e| \mathcal{E} \cdot \boldsymbol{v}(\boldsymbol{k}) \frac{\partial f_{0}(\boldsymbol{k})}{\partial E(\boldsymbol{k})}=\sum_{\mathbf{k}^{\prime}} P_{\boldsymbol{k} \boldsymbol{k}^{\prime}}\left[g\left(\boldsymbol{r}, \boldsymbol{k}^{\prime}\right)-g(\boldsymbol{r}, \boldsymbol{k})\right] \tag{9.40}
\end{equation*}
$$

To simplify the scattering term we assume that $g\left(\boldsymbol{r}, \boldsymbol{k}^{\prime}\right)$ is proportional to $g(\boldsymbol{r}, \boldsymbol{k})$ where the coefficient of proportionality depends upon $\boldsymbol{k}$ and $\boldsymbol{k}^{\prime}$, i.e.,

$$
g\left(\boldsymbol{r}, \boldsymbol{k}^{\prime}\right)=c\left(\boldsymbol{k}, \boldsymbol{k}^{\prime}\right) g(\boldsymbol{r}, \boldsymbol{k})
$$

The scattering term then reduces to $\frac{g(\boldsymbol{r}, \boldsymbol{k})}{\tau(\boldsymbol{k})}$ where

$$
\frac{1}{\tau(\boldsymbol{k})}=\sum_{\mathbf{k}^{\prime}} P_{\boldsymbol{k} \boldsymbol{k}^{\prime}}\left[c\left(\boldsymbol{k}, \boldsymbol{k}^{\prime}\right)-1\right]
$$

It turns out that $c\left(\boldsymbol{k}, \boldsymbol{k}^{\prime}\right)-1$ varies as $1-\cos \theta$ where $\theta$ is the angle between $\boldsymbol{k}$ and $\boldsymbol{k}^{\prime}$. That is, large angle scattering is weighted more heavily in determining $\tau(\boldsymbol{k})$. Equation (9.40) becomes

$$
\begin{equation*}
\boldsymbol{v}(\boldsymbol{k}) \cdot \nabla_{\boldsymbol{r}} g(\boldsymbol{r}, \boldsymbol{k})-|e| \mathcal{E} \cdot \boldsymbol{v}(\boldsymbol{k}) \frac{\partial f_{0}(\boldsymbol{k})}{\partial E(\boldsymbol{k})}=\frac{g(\boldsymbol{r}, \boldsymbol{k})}{\tau(\boldsymbol{k})} \tag{9.41}
\end{equation*}
$$

This simplication of the scattering term is referred to as the relaxation time approximation.

Before considering the multilayer geometry it is of interest to consider a homogeneous system where $\nabla_{\boldsymbol{r}} g(\boldsymbol{r}, \boldsymbol{k})=0$. Then the solution to (9.41) becomes

$$
g(\boldsymbol{k})=|e| \tau(\boldsymbol{k}) \frac{\partial f_{0}(\boldsymbol{k})}{\partial E(\boldsymbol{k})} \cdot \boldsymbol{v}(\boldsymbol{k}) \cdot \mathcal{E}
$$

The current density is

$$
\begin{equation*}
\boldsymbol{j}(\boldsymbol{r})=\frac{|e|}{\Omega} \sum_{\boldsymbol{k}} \boldsymbol{v}(\boldsymbol{k}) g(\boldsymbol{k}) \tag{9.42}
\end{equation*}
$$

Therefore the conductivity is

$$
\begin{equation*}
\sigma_{\alpha \beta}=\frac{|e|^{2}}{\Omega} \sum_{\boldsymbol{k}} v_{\alpha}(\boldsymbol{k}) v_{\beta}(\boldsymbol{k}) \tau(\boldsymbol{k}) \frac{\partial f_{0}(\boldsymbol{k})}{\partial E(\boldsymbol{k})} . \tag{9.43}
\end{equation*}
$$

While (9.43) can be derived from the Kubo formula (9.33), the derivation is not trivial (see [208], Sect. 8.1.2).

Let us now consider a trilayer structure consisting of two magnetic layers (e.g., Fe or Co.) separated by a thin conductor (e.g., Cu or Cr) [210]. Assume the electric field is applied in the plane of the trilayer ( $x$-direction) and that the normal to the sandwich defines the $z$-direction. Then (9.41) reduces to

$$
\begin{equation*}
\frac{\partial g(z, \boldsymbol{k})}{\partial z}-\frac{g(z, \boldsymbol{k})}{v_{z}(\boldsymbol{k}) \tau(\boldsymbol{k})}-\frac{|e| \mathcal{E} v_{x}(\boldsymbol{k})}{v_{z}(\boldsymbol{k})} \frac{\partial f_{0}(\boldsymbol{k})}{\partial E(\boldsymbol{k})}=0 . \tag{9.44}
\end{equation*}
$$

We shall solve this equation piecewise for the different layers. Furthermore, the solution for $v_{z}(\boldsymbol{k})>0$ is different than that for $v_{z}(\boldsymbol{k})<0$. Denoting those solutions by $\pm$, we obtain for a given layer

$$
\begin{equation*}
g_{ \pm}(z, \boldsymbol{k})=e \tau(\boldsymbol{k}) \mathcal{E} v_{x}(\boldsymbol{k}) \frac{\partial f_{0}(\boldsymbol{k})}{\partial E(\boldsymbol{k})}\left[1+A^{ \pm}(\boldsymbol{k}) e^{\mp z / \tau(\boldsymbol{k})\left|v_{z}(\boldsymbol{k})\right|}\right] . \tag{9.45}
\end{equation*}
$$

The coefficients $A^{ \pm}(\boldsymbol{k})$ are obtained from boundary conditions. For example, consider the following boundary:


The electron moving away from the boundary on the left could come from the reflection of the electron incident on the boundary from the left or from the transmission of the electron incident on the boundary from the right, i.e.,

$$
g_{L^{-}}=R g_{L^{+}}+T g_{R^{-}},
$$

where $R$ and $T$ are the reflection and transmission coefficients, respectively.
The spin dependence arising from the spin-dependent scattering enters through the relative orientation, $\theta$, of the magnetizations in the two layers. Camley and Barnaś dealt with this by introducing an artificial interface in the middle of the conducting spacer where the spin quantization axis is rotated by $\theta$. Based on our discussion of the change of the spin wavefunction with quantization direction in Sect. 2.2.10, the probabilities $g^{\sigma}$ have the following relationships:


Fig. 9.15. Magnetoresistance versus ferromagnetic layer thickness in $(\mathrm{FM} / \mathrm{NM})_{N} \mathrm{FM}$ multilayers for bulk (the solid lines) and interface (the dashed line) scattering as calculated using the semiclassical free-electron model. $\lambda_{N M}=20 \mathrm{~nm}$ and diffuse outer boundary scattering are assumed in the calculation. The other parameters are set as follows: $\lambda_{F M}^{\uparrow}=12 \mathrm{~nm}, \lambda_{F M}^{\downarrow}=0.6 \mathrm{~nm}, T^{\uparrow}=T^{\downarrow}=0.1$ for interface spin-dependent scattering. After Dieny [214]

$$
\begin{array}{l|}
\xrightarrow[g_{L+}^{\sigma}]{g_{L+}^{-\sigma}}
\end{array} \left\lvert\, \overrightarrow{g_{R+}^{\sigma}=\cos ^{2} \frac{\theta}{2} g_{L+}^{\sigma}+\sin ^{2} \frac{\theta}{2} g_{L+}^{-\sigma}}\right.
$$

and, similarly,

$$
g_{L-}^{\sigma}=\cos ^{2} \frac{\theta}{2} g_{R-}^{\sigma}+\sin ^{2} \frac{\theta}{2} g_{R-}^{-\sigma}
$$

In principle, the reflection and transmission coefficients, $R$ and $T$, may be calculated. However, they were regarded as parameters by Camley and Barnaś. In fact, they assumed that when the magnetic layers and the conducting spacer are transition metals, like $\mathrm{Fe} / \mathrm{Cr} / \mathrm{Fe}$, the reflection coefficient is zero. Since this does not account for scattering at the $\mathrm{Fe} / \mathrm{Cr}$ interface they introduced a diffusive scattering parameter, $D$, by setting $T=1-D$. In a subsequent paper, Johnson and Camley [211], replaced the concept of diffusive scattering at the internal interfaces by introducing "mixed" regions between the magnetic layers and the conducting layer. This gives six regions, each having their own coefficients $A_{\sigma}^{ \pm}(\boldsymbol{k})$ in (9.45). There are 24 boundary conditions to determine these 24 coefficients which are solved numerically [212]. Once one knows $g_{ \pm}^{\sigma}$ for all the regions the current density in each region can be calculated from (9.42). The total current is obtained by integrating $j_{x}(z)$ over $z$.

It turns out, [213], that the introduction of mixed regions is necessary to obtain an equivalence between the Kubo formalism and the Boltzmann formalism. Nevertheless, the use of a diffusive scattering parameter is convenient for obtaining qualitative understanding of the GMR effect. For example, suppose
we wish to understand how a multilayer, $(\mathrm{FM} / \mathrm{NM})_{N} \mathrm{FM}$, behaves relative to a simple trilayer, FM/NM/FM. If we assume that the spin dependance arises from scattering within the ferromagnetic layers, then the scattering time, $\tau_{\sigma}$, or, equivalently, the mean free path, $\lambda_{\sigma}$, is taken to be different for spin up and spin down, while the transmission coefficients, $T_{\sigma}$, are both taken to be 1 . On the other hand, if the spin dependence arises from scattering at the interface, then we set $\lambda_{\uparrow}=\lambda_{\downarrow}$. Figure 9.15 shows the magnetoresistance obtained from the Boltzmann equation as a function of the thickness of the ferromagnet for various multilayer configurations [214]. The solid lines assume the scattering within the ferromagnets is spin-dependent while the dashed line is for spin-dependent interface scattering. There are several observations. One is that the GMR for multilayers is larger than that of a trilayer (spin valve). This is due to the fact that in calculating the magnetoresistance in Fig. 9.15 it was assumed that the electrons are diffusely scattered at the outer boundaries. Therefore, for bulk spin-dependent scattering, the GMR will increase with multilayer thickness until this thickness becomes comparable to the mean free path, $\lambda_{\uparrow}$. Once the multilayer thickness exceeds $\lambda_{\uparrow}$ the role of the diffuse scattering decreases and further increase in the thickness simply provides a shunting path which reduces the GMR.

This argument suggests that the magnetoresistance is very sensitive to the outer boundary. As we mentioned above, one of the magnetic layers in a spin valve is pinned by placing it next to an antiferromagnet. The popular choice, FeMn, is generally believed to produce diffuse scattering. The GMR can be enhanced by using NiO as the pinning antiferromagnet. This enhancement is due to the fact that NiO is an insulator and reflects back the electrons, i.e., increases the specular scattering. A layer of Cu at the back of the magnetic layers also enhances the GMR. This is a "spin filtering" effect due to the fact that for $\mathrm{Co} / \mathrm{Cu}$, for example, the Fermi surface of the Co majority ( $\uparrow$ ) spins is very similar to that of Cu whereas that of the Co minority ( $\downarrow$ ) spins is very different. Therefore, the majority spins pass through the interface more easily.

### 9.2.4 Tunneling

Another trilayer structure that has enormous practical applications is that in which the intermediate layer, between the two metal electrodes, is a thin insulator. When a voltage is applied across this structure a small current is observed. This current occurs because the insulator represents a finite potential barrier of the order of the bandgap of the insulator as illustrated in Fig. 9.16. The bandgap of $\mathrm{Al}_{2} \mathrm{O}_{3}$, for example, is 6.6 eV . This means the wave function for an electron with an energy below the barrier height is an evanescent wave and an electron in the left electrode will therefore have a finite probability of tunneling into the right electrode.

There are a variety of approaches to calculating the tunneling conductance. One of these, introduced by Bardeen [215], is based on a tunneling Hamiltonian. If $c_{\boldsymbol{q} \sigma}$ destroys an electron with momentum $\mathbf{q}$ and $\operatorname{spin} \sigma$ on one


Fig. 9.16. Wavefunction associated with tunnel barrier
side of the junction and $c_{\boldsymbol{k} \sigma}^{\dagger}$ creates one with momentum $\boldsymbol{k}$ and spin $\sigma$ on the other side the tunneling may be represented by a Hamiltonian of the form

$$
\begin{equation*}
\mathcal{H}_{T}=\sum_{\boldsymbol{k}, \boldsymbol{q}}\left(T_{\boldsymbol{k} \boldsymbol{q}}^{\sigma} c_{\boldsymbol{k} \sigma}^{\dagger} c_{\boldsymbol{q} \sigma}+T_{\boldsymbol{q} \boldsymbol{k}}^{\sigma} c_{\boldsymbol{q} \sigma}^{\dagger} c_{\boldsymbol{k} \sigma}\right) . \tag{9.46}
\end{equation*}
$$

The total probability that an electron tunnels from one side, say 1 , to the other, 2 , is

$$
\begin{equation*}
\left.W_{1 \rightarrow 2}=\frac{2 \pi}{\hbar} \sum_{l}\left|\langle l| \mathcal{H}_{T}\right| 0\right\rangle\left.\right|^{2} \delta\left(E_{l}-E_{0}\right) \tag{9.47}
\end{equation*}
$$

where $|0\rangle$ and $|l\rangle$ are products of the eigenstates of the Hamiltonians appropriate for each side. If one now writes

$$
\begin{equation*}
\delta\left(\varepsilon_{\boldsymbol{q} \sigma}+\mathrm{eV}-\varepsilon_{\boldsymbol{k} \sigma}\right)=\int_{-\infty}^{\infty} d E \delta\left(\varepsilon_{\boldsymbol{q} \sigma}-E\right) \delta\left(\varepsilon_{\boldsymbol{k} \sigma}-\mathrm{eV}-E\right) \tag{9.48}
\end{equation*}
$$

and converts the sums over $\boldsymbol{q}$ and $\boldsymbol{k}$ into integrals over $\varepsilon_{\boldsymbol{q}}$ and $\varepsilon_{\boldsymbol{k}}$ one finds that the tunneling current associated with spin $\sigma$ is

$$
\begin{equation*}
\left.I_{\sigma}=\left.\frac{2 \pi e}{\hbar} \int_{-\infty}^{\infty} d E\langle | T_{k \boldsymbol{q}}^{\sigma}\right|^{2}\right\rangle N_{1 \sigma}(E+e V) N_{2 \sigma}(E)[f(E+e V)-f(E)] \tag{9.49}
\end{equation*}
$$

where $\left.\left.\langle | T\right|^{2}\right\rangle$ is the average of the tunneling probability. If we assume that the densities of states, $N_{1 \sigma}$ and $N_{2 \sigma}$, are not strong functions of energy they may be replaced by their values at the Fermi energy and taken outside the integral. The tunneling conductance $G_{\sigma}=d I_{\sigma} / d V$ then becomes

$$
\begin{equation*}
\left.G_{\sigma}=\left.\frac{2 \pi e^{2}}{\hbar}\langle | T_{k q}^{\sigma}\right|^{2}\right\rangle N_{1 \sigma}\left(E_{F}\right) N_{2 \sigma}\left(E_{F}\right) . \tag{9.50}
\end{equation*}
$$

If the two magnetic electrodes have their magnetizations parallel (see Fig. 9.17) then the tunneling takes place between the majority ( M ) spin bands and minority (m) spin bands. Therefore, the conductance is given by

$$
G_{\uparrow \uparrow}=G_{\uparrow}+G_{\downarrow} \sim N_{M 1} N_{M 2}+N_{m 1} N_{m 2}
$$


(a)

$\mathrm{M}_{1} \uparrow$

(b)

Fig. 9.17. Tunneling processes for parallel (a) and antiparallel (b) electrodes

If the magnetic electrodes are magnetized antiparallel, then

$$
G_{\uparrow \downarrow}=G_{\uparrow}+G_{\downarrow} \sim N_{M 1} N_{m 2}+N_{m 1} N_{M 2}
$$

The tunneling magnetoresistance (TMR) is defined by

$$
\begin{equation*}
\mathrm{TMR}=\frac{G_{\uparrow \uparrow}-G_{\uparrow \downarrow}}{G_{\uparrow \downarrow}} . \tag{9.51}
\end{equation*}
$$

When we have exchange-split bands, the densities of states at the Fermi level for the different spin directions are different. These differences define the spin polarization, i.e.,

$$
\begin{equation*}
P_{1}=\frac{N_{M 1}\left(E_{F}\right)-N_{m 1}\left(E_{F}\right)}{N_{M 1}\left(E_{F}\right)+N_{m 1}\left(E_{F}\right)} . \tag{9.52}
\end{equation*}
$$

The TMR may then be expressed in terms of the spin polarizations of the two electrodes as

$$
\begin{equation*}
\mathrm{TMR}=\frac{2 P_{1} P_{2}}{1-P_{1} P_{2}} \tag{9.53}
\end{equation*}
$$

This expression was first derived by Julliere [216] to explain his tunneling results in films of $\mathrm{Fe} / \mathrm{Ge} / \mathrm{Co}$.

In order to test the simple relation (9.53) we need to know the polarizations of the electrode materials. There are three techniques used to measure the spin polarizations - tunneling in which one of the electrodes is a superconductor, Andreev reflection using a superconducting point contact, and spin-resolved photoemission.


Fig. 9.18. Density of states for an $\mathrm{Al}-\mathrm{Al}_{2} \mathrm{O}_{3}-\mathrm{Ni}$ junction in which the Al is superconducting


Fig. 9.19. Experimental results for the normalized conductance as a function of applied voltage for an $\mathrm{Al}-\mathrm{Al}_{2} \mathrm{O}_{3}-\mathrm{Ni}$ tunneling junction for different values of the applied field $H$ (kOe). After Meservey and Tedrow [217]

Spin-Dependent Tunneling. When one of the electrodes of a tunnel junction is a superconductor in its superconducting state the electrons are bound in $(\boldsymbol{k} \uparrow,-\boldsymbol{k} \downarrow)$ pairs. When the pairs are excited they form quasiparticles with energies

$$
E_{\boldsymbol{k} \sigma}=\left(\varepsilon_{\boldsymbol{k}}^{2}+\Delta^{2}\right)^{\frac{1}{2}}-\sigma \mu_{B} H
$$

where $\Delta$ is the superconducting energy gap. The resulting density of states is shown on the left side of Fig. 9.18. The splitting in the magnetic field manifests itself in the tunneling conductance as shown in Fig. 9.19. The two peaks or shoulders in the conductance curve are the results of the superposition of tunneling from/into the two spin bands of the ferromagnet and provide a direct

Table 9.2. Measured spin polarization values for various magnetic materials

| Materials | $\mathrm{Ni}_{80} \mathrm{Fe}_{20}$ | Ni | Co | Fe | $\mathrm{Co}_{50} \mathrm{Fe}_{50}$ | $\mathrm{La}_{0} \cdot 7 \mathrm{Sr}_{0.3} \mathrm{CrO}_{3}$ | $\mathrm{Fe}_{3} \mathrm{O}_{4}$ |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Spin polarization <br> measured by using | $37 \%$ | $43 \%$ | $43 \%$ | $45 \%$ | - | $78 \%$ | - |
| Andreev reflection <br> method [218] |  |  |  |  |  |  |  |
| Spin polarization <br> measured on | $48 \%$ | $33 \%$ | $42 \%$ | $45 \%$ | $55 \%$ |  | - |
| FM/AlOx/Al <br> Tunnel junction [219] <br> Spin polarization <br> measured by using |  |  |  |  |  |  |  |
| spin-resolved <br> photoemission [220] |  | - | - | - | - | $100 \%$ | $-80 \%$ |

measurement of the ratio of their densities of states, that is, the polarization. In Table 9.2 we list the polarizations obtained in this manner for several magnetic materials.

Andreev Reflection. In this technique a superconducting tip is placed in contact with the magnetic sample. Current in the superconductor is carried by electron pairs. Therefore, if a spin up electron from the ferromagnet enters the superconductor it must do so by pairing with a spin down electron created at the interface. This leaves a spin up hole which is reflected back into the ferromagnet. These "Andreev reflected" holes provide a parallel conduction channel. When the sample is unpolarized the conductance of the contact is twice that when the superconductor is normal. As the polization increases the current at zero bias decreases, becoming zero for a $100 \%$ spin polarized ferromagnet. Spin polarizations obtained by this technique are also listed in Table 9.2.

We notice that the polarizations deduced from the different techniques are different. Part of this difference has to do with the fact that the spin polarization is weighted differently in the different techniques. The quality of the tunneling barrier and the point contact are also important. The point contact transport, for example, may vary from being ballistic to diffusive.

Even if we had accurate values for the spin polarizations the Julliere expression (9.53) does not capture all the features experimentally observed in magnetic tunnel junctions. For example, the TMR shows a strong decrease with bias voltage. In the tunneling Hamiltonian approach described above we treated the tunneling matrix elements as constants as functions of energy. This ignores the details of the barrier. To incorporate the details of the barrier we must solve the tunneling problem.

The contribution of an electron in state $\boldsymbol{k}$ with spin $\sigma$ to the tunneling current density, $J_{\sigma}$, is given by its probability of getting through the barrier,
$T(\boldsymbol{k})$, times the frequency with which it hits the barrier $\nu_{\boldsymbol{k} \sigma}$. Thus the current per unit area is

$$
\begin{equation*}
J_{\sigma}=\sum_{\boldsymbol{k}} \frac{e}{A} T(\boldsymbol{k}) \nu_{\boldsymbol{k}, \sigma} f_{\boldsymbol{k} \sigma} \tag{9.54}
\end{equation*}
$$

where $f_{k \sigma}$ is the Fermi function and $A$ is the area of the junction. The frequency of striking the barrier is $v_{z} / 2 L$ where $L$ is the thickness of the electrode. Converting the sum over $\boldsymbol{k}$ into an integral according to

$$
\begin{equation*}
\sum_{k} \frac{A L}{(2 \pi)^{3}} \iint d k_{z} d k_{\|}^{2} \rightarrow \frac{V}{(2 \pi)^{3}} \int d E /\left(d E / d k_{z}\right) \int d k_{\|}^{2} \tag{9.55}
\end{equation*}
$$

the current density becomes

$$
\begin{equation*}
J_{\sigma}=\frac{A L}{(2 \pi)^{3}} \frac{e}{A L} \frac{1}{2 \hbar} \int \frac{d E}{d E / d k_{z}} \int d k_{\|}^{2} T\left(k_{\|}, E\right) \frac{d E}{d k_{z}} f_{k \sigma} \tag{9.56}
\end{equation*}
$$

If we assume that the temperature is zero and that the energy dependence of $T\left(\boldsymbol{k}_{\|}, E\right)$ over the energy range eV is not large, then the integral over $E$ just gives eV, and

$$
J_{\sigma}=\frac{e^{2} V}{(2 \pi)^{3}} \frac{1}{2 \hbar} \int d k_{\|}^{2} T\left(k_{\|}\right)
$$

The transmission probability $T\left(\boldsymbol{k}_{\| \mid}\right)$is obtained by solving the 1D Schrödinger equation. For a simple rectangular barrier as shown in Fig. 9.16 the transmission probability is given by

$$
\begin{equation*}
T\left(k_{\|}\right)=\frac{16 k_{1} \kappa^{2} k_{2} e^{-2 d \kappa}}{\kappa^{2}\left(k_{1}+k_{2}\right)^{2}+\left(\kappa^{2}-k_{1} k_{2}\right)^{2}}, \tag{9.57}
\end{equation*}
$$

where

$$
\begin{aligned}
k_{1} & =\sqrt{\left(2 m / \hbar^{2}\right)\left(E_{F}-V_{1}\right)-k_{\|}^{2}}, \\
k_{2} & =\sqrt{2 m / \hbar^{2}\left(E_{F}-V_{2}\right)-k_{\|}^{2}} \\
\kappa & =\sqrt{\left(2 m / \hbar^{2}\right)\left(V_{b}-E_{F}\right)+k_{\|}^{2}} .
\end{aligned}
$$

In the case of a magnetic tunnel junction we have four different spin orientations analogous to Fig. 9.8. These are shown in Fig. 9.20. Slonezewski [221] applied the free-electron results above to this situation and obtained an expression for the tunneling magnetoresistance of the same form as Julliere's, i.e.,

$$
\begin{equation*}
\mathrm{TMR}=\frac{2 P_{\mathrm{eff}}^{2}}{1-P_{\mathrm{eff}}^{2}} \tag{9.58}
\end{equation*}
$$



Fig. 9.20. Squarewell potentials seen by an electron moving in a trilayer consisting of two ferromagnets separated by a nonmagnetic insulating barrier
but with an effective polarization

$$
\begin{equation*}
P_{\mathrm{eff}}=P \frac{\kappa_{0}^{2}-k_{\uparrow} k_{\downarrow}}{\kappa_{0}^{2}+k_{\uparrow} k_{\downarrow}}, \tag{9.59}
\end{equation*}
$$

where $k_{\uparrow}$ and $k_{\downarrow}$ are evaluated at $k_{\|}=0$, and $\kappa_{0}$ at $V_{b}=0$. This simple free electron model illustrates how sensitive the tunneling magnetoresistance is to the details of the barrier. In Fig. 9.21 we show the voltage dependence of the TMR. Such a strong voltage dependence is a characteristic of magnetic tunnel junctions.

Neither Julliere's model nor the free-electron model can treat realistic electrode and barrier materials. To do this, one must employ a Kubo formalism that incorporates first-principles calculations of the electronic states. One of the great successes of such calculations was the prediction that a barrier consisting of MgO should give a high TMR [222]. Such large TMR's were subsequently observed [223].

### 9.2.5 Spin Transfer

In addition to the giant magnetoresistance that occurs in a trilayer structure when the current flows perpendicular to the plane (CPP) of the structure there is another interesting phenomenon. Namely, since the conduction elections in a ferromagnet are partially spin polarized by the $d$-electrons they can transfer spin angular momentum from one magnetic layer to the other. This can have the result of exciting spinwaves in the "receiving" layer or even completely reversing the magnetization of this layer. These possibilities were first predicted independently by Slonczewski [224] and Berger [225] and subsequently observed by various groups [226-228].

Let us begin by considering a single ferromagnetic layer embedded between two semi-infinite Cu leads. We shall assume this layer is relatively thick and the magnetization fixed. This situation may be analyzed by the Boltzmann


Fig. 9.21. Voltage dependence of TMR associated with shape of the barrier [Chando Park]


Fig. 9.22. Spin polarization in Cu leads attached to a ferromagnetic film based on a Boltzmann equation calculation [229]
equation approach we used in describing the GMR effect. Suppose we consider current flowing from right to left (which we define as a "negative" current) so that electrons are moving left to right. And suppose that the reflection coefficients are such that $R_{\uparrow} \ll R_{\downarrow}$. We also incorporate spin-flip scattering in the Cu by introducing a spin-flip mean free path, $\lambda_{\uparrow \downarrow}=v_{F} \tau_{\uparrow \downarrow}$ (for Cu this is estimated to be 2000 nm ). If $\lambda$ is the mean free path, then the spin diffusion length is given by $\sqrt{\lambda \lambda_{\uparrow \downarrow}}$. The result is that there is an imbalance in the number of up and down spins in the vicinity of the $\mathrm{FM} / \mathrm{Cu}$ interface as shown in Fig. 9.22. We refer to this as spin accumulation.

Suppose we now add a second magnetic layer (free layer) with thickness $d_{2}$ separated from the first (reference layer) by a distance less than the spin diffusion length (Fig. 9.23). We now have spin-polarized electrons entering the second magnetic layer. These electrons interact with the magnetization in this layer through the $s-d$ exchange interaction, $-2 J_{s d} \boldsymbol{s} \cdot \boldsymbol{S}(\boldsymbol{r})$. This interaction gives rise to a large effective field, of the order of 1000 T , acting on the the "incoming" conduction electrons. This causes the spins of these electrons to

(a)

(b)

Fig. 9.23. Origin of the torque $(\boldsymbol{\tau})$ on a free layer due to spin accumulation from a reference layer
precess rapidly around the direction of $\boldsymbol{S}(\boldsymbol{r})$. Slonczewski has shown [224] that the transverse component of the spin, after the electron has traveled a distance $L_{0}$ in the free layer of the order of $\pi /\left(k_{\uparrow}-k_{\downarrow}\right)$, where $k_{\uparrow}$ and $k_{\downarrow}$ are the spin-up and spin-down wavevectors, is zero. For Co $L_{0}$ is approximately 9.5 nm . By conservation of angular momentum this spin angular momentum is transferred to $\boldsymbol{S}(\boldsymbol{r})$. Each spin therefore contributes an angular momen $(\hbar / 2) \sin \theta$ where $\theta$ is the angle between $\boldsymbol{s}$ and $\boldsymbol{S}$. The number of conduction electrons flowing through a cross sectional area in unit time is $j / e$, where $j$ is the current density. Therefore, the amount of angular momentum transferred to the volume (unit area) $d_{2}$ in unit time, i.e., the torque, is $\left(\hbar / 2 e d_{2}\right) j \sin \theta$. We shall also introduce a spin polarization factor

$$
P=\frac{n_{\uparrow}-n_{\downarrow}}{n_{\uparrow}+n_{\downarrow}}
$$

to account for any loss in polarization as the electrons traverse the nonmagnetic separator. If we identify the direction of $s$ with the magnetization of the reference layer, $\boldsymbol{M}_{1}$, and note that $\hat{\boldsymbol{M}}_{1} \times \hat{\boldsymbol{M}}_{2}=\sin \theta$, then the direction of the torque may be written as $\hat{\boldsymbol{M}}_{2} \times\left(\hat{\boldsymbol{M}}_{1} \times \hat{\boldsymbol{M}}_{2}\right)$. Since the magnetization is related to the angular momentum per unit volume through the gyromagnetic ratio $\gamma$ we have

$$
\begin{equation*}
\frac{d \boldsymbol{M}_{2}}{d t}=\frac{\hbar \gamma P j}{2 e d_{2}} \hat{\boldsymbol{M}}_{2} \times\left(\hat{\boldsymbol{M}}_{1} \times \hat{\boldsymbol{M}}_{2}\right) . \tag{9.60}
\end{equation*}
$$

The implications of this torque on the dynamics of the magnetization may be studied by adding this term to the Landau-Lifshitz-Gilbert equation we


Fig. 9.24. The precession of magnetization under the influence of a spin current. Uniaxial anisotropy alone. (a) Time dependence of $M_{z}$. (b) Time dependence of $M_{x}$. (c) A 3D portrait of the spiral motion of the tip of $M[230] h_{s}$ is the spin current amplitude in dimensionless units
described in Sect.8.4 This torque term adds a great deal of richness to the solutions. First of all, note that this term can be positive or negative. Consider, for example, Fig. 9.23a in which the two magnetic layers are initially parallel and the current is negative, i.e., electrons flow from the thick layer to the thin layer. In this case, (9.60) gives a torque that adds to the damping. In Fig. 9.23b the current is positive and the torque tends to pull the magnetization $\boldsymbol{M}_{2}$ away from the parallel state. Sun [230] has numerically solved the LLG equation including the spin transfer term. A solution showing switching behavior is shown in Fig. 9.24.

In the presence of a large applied magnetic field complete reversal of the magnetization is inhibited. In this case spinwaves are excited. The threshold for this excitation is readily obtained by expanding the magnetization $\boldsymbol{M}_{2}$ in (9.60) in terms of spinwave amplitudes according to (8.14) and adding this term to the linearized spinwave amplitude equation of motion. The result is [231]

$$
\begin{equation*}
\frac{d \alpha_{k}}{d t}=-i \omega_{k} \alpha_{k}-\left(\eta_{k}-\beta j\right) \alpha_{k} \tag{9.61}
\end{equation*}
$$

where $\beta=\hbar \gamma P / 2 e d_{2} M_{2}$ and $\omega_{k}$ is the frequency of the spinwave with wavevector $k$ and $\eta_{k}$ is the spinwave relaxation rate. The solution of this equation is

$$
\begin{equation*}
\alpha_{k}(t)=\alpha_{k}(0) e^{i \omega_{k} t} e^{-\left(\eta_{k}-\beta j\right) t} \tag{9.62}
\end{equation*}
$$

We see that the spinwave amplitude will grow exponentially when the current density exceeds the critical value


Fig. 9.25. The point contact $d V / d I(V)$ spectra for a series of magnetic fields $(2,3,5,6,7$, and 8 T$)$ revealing an upward step and a corresponding peak in $d V / d I$ at a certain negative bias voltage $V^{*}(H)$. The inset shows that $V^{*}(H)$ increases linearly with the applied magnetic field $H$ [226]

$$
\begin{equation*}
j_{c}=\frac{2 e d_{2} M_{2} \eta_{k}}{\hbar \gamma P} \tag{9.63}
\end{equation*}
$$

This "pumping" of spinwaves by a spin-polarized current is analogous to the Suhl instabilities we discussed in Sect.8.2.6. In particular, this pumping can lead to chaotic phenomena as well [232].

The first observations of spin-polarized current-driven excitations in a magnetic multilayer were made by Tsoi, et al. [226]. Figure 9.25 shows the differential resistance of a $\mathrm{Co} / \mathrm{Cu}$ multilayer stack excited by current injected through a point contact. We immediately see the asymmetry with current direction predicted above. The peaks scale linearly with field. In this experiment the magnetic field is applied perpendicular to the plane of the layers. In this configuration the frequency of the $\boldsymbol{k}=0$ spinwave, or ferromagnetic resonance (FMR) mode is $\omega_{\boldsymbol{k}=0}=\gamma\left(H-4 \pi M_{s}\right)$. Therefore, Fig. 9.25 is evidence for the current-driven excitation of $\boldsymbol{k}=0$ spinwaves.

### 9.2.6 Spin Hall Effect

Spin accumulation can also occur in the direction transverse to the current flow in a single conducting film. There are, in fact, two mechanisms by which this can occur. The most direct (Fig. 9.26) is the spin polarization that results from the response of the metal to the magnetic field produced by the current itself through $\boldsymbol{\nabla} \times \boldsymbol{H}=4 \pi \boldsymbol{j} / c$. This response is proportional to the Pauli susceptibility and is very small. A larger effect occurs through spin-orbit scattering, (Fig. 9.27), which is also the origin of the "anomalous" Hall effect in


Fig. 9.26. Spin Polarization across film due to field of current


Fig. 9.27. Spin polarization at edges of film due to spin-dependent scattering
ferromagnets. These two mechanisms are quite different. In the case of "the Pauli polarization" the Fermi levels of the up- and down-spins are equal but vary across the film. In the case of spin-orbit scattering the Fermi levels of the up- and down-spins are not equal and are maintained in this nonequilibrium state by the current flow.

Let us consider the scattering process. When an electron is incident on a spinless scattering center the potential it sees is given by

$$
\begin{equation*}
V(r)=V_{c}(r)+V_{s}(r) \boldsymbol{\sigma} \cdot \boldsymbol{L} \tag{9.64}
\end{equation*}
$$

where $V_{c}(r)$ is the Coulomb potential and $V_{s}(r)$ is the spin-orbit scattering potential. As a result of the $V_{s}(r)$ term, up- and down-spin electrons will be scattered differently toward the left and right.

There are two effects of this spin-orbit scattering. In one, the amplitude of the scattered electron wave as it propagates away from the scattering center is different for spin-up and spin-down. This is called "skew scattering". In the other, the apparent center from which the scattered wave propagates is different for spin-up and spin-down. This is called "side jump". The side jump may also be understood as arising from an "anomalous" velocity. In particular, the velocity operator is obtained from the Hamiltonian by $\boldsymbol{v}=(1 / \hbar) \partial \mathcal{H} / \partial \boldsymbol{k}$. If $\mathcal{H}=p^{2} / 2 m$ we obtain the usual velocity operator $\boldsymbol{v}=\hbar \boldsymbol{k} / m$. But when the spin-orbit potential (9.64) is included we obtain an additional "anomalous" contribution $\left(\hbar \alpha / \tau^{\sigma}\right) \boldsymbol{k} \times \boldsymbol{\sigma}$, where $\alpha$ is the spin-orbit coupling constant and $\tau^{\sigma}$ is the non-slip-flip relaxation time [233].

The sign and magnitude of the spin accumulation depends upon $V_{s}(r)$. If the current is polarized, as in an itinerant ferromagnet, then there will also be an imbalance of charge created. This is the anomalous Hall effect. The


Fig. 9.28. Change in electron distribution function due to shift of Fermi sphere


Fig. 9.29. Change in electron distribution due to change in Fermi radius
resistivity $\left(\mathcal{E}_{y} / j_{x}\right)$ is written

$$
\begin{equation*}
\rho_{H}=R_{0} B+4 \pi R_{s} M \tag{9.65}
\end{equation*}
$$

Therefore the experimental anomalous Hall coefficient $R_{s}$ provides a measure of the spin Hall voltage. In particular, for a current of up spins $M=n_{\uparrow} \mu_{B}$ and the Hall voltage associated with (9.65) is

$$
\begin{equation*}
V_{H}=4 \pi R_{s} w j_{x} n_{\uparrow} \mu_{B} \tag{9.66}
\end{equation*}
$$

For down spins there will be an equal (with $n_{\downarrow}$ ) but opposite voltage. Thus, since $n_{\uparrow}=n_{\downarrow}=n / 2$ in a paramagnet there will not be a charge buildup, but there will be a spin accumulation. We may therefore describe this as a spin Hall voltage [234],

$$
\begin{equation*}
V_{S H}=2 \pi R_{s} w j_{x} n \mu_{B} \tag{9.67}
\end{equation*}
$$

The spin accumulation will vary across the film. One approach to determining this spatial variation is to solve the Boltzmann equation introduced in (9.34) for the electron distribution function $f^{\sigma}(\boldsymbol{r}, \boldsymbol{k})$. In the case of GMR the change in the distribution function arises from a displacement of the Fermi surface (Fig. 9.28). In the case of spin accumulation we must also allow for a difference in the radii of the spin-up and spin-down Fermi surfaces (Fig. 9.29). Therefore, we describe the distribution function by two nonequilibrium terms,

$$
\begin{equation*}
f^{\sigma}(\boldsymbol{r}, \boldsymbol{k})=f^{0}(\boldsymbol{k})+\left[g^{\sigma}(\boldsymbol{r}, \boldsymbol{k})+e \mu^{\sigma}(\boldsymbol{r})\right]\left(-\frac{\partial f^{0}}{\partial \varepsilon_{F}}\right) . \tag{9.68}
\end{equation*}
$$

We have explicitly recognized that this is a Fermi surface phenomenon by introducing the factor $\left(-\partial f^{0} / \partial \varepsilon_{F}\right)$, and we have written the $k$-independent part as a voltage. When this assumed form for $f^{\sigma}(\boldsymbol{r}, \boldsymbol{k})$ is substituted into the Boltzmann equation, and a spin-flip relaxation term is included, we obtain

$$
\begin{equation*}
\boldsymbol{k} \cdot \nabla g^{\sigma}(\boldsymbol{r}, \boldsymbol{k})+e \varepsilon^{\sigma}(\boldsymbol{r}) \cdot \boldsymbol{k}=-g^{\sigma}(\boldsymbol{r}, \boldsymbol{k}) / \tau_{\sigma}+\frac{e \mu^{\sigma}(\boldsymbol{r})-e \mu^{-\sigma}(\boldsymbol{r})}{\tau_{\uparrow \downarrow}} \tag{9.69}
\end{equation*}
$$

where $\mathcal{E}^{\sigma}(\boldsymbol{r})=\mathcal{E}-\nabla \mu^{\sigma}(\boldsymbol{r})$, showing that $\mu^{\sigma}(\boldsymbol{r})$ plays the role of a spindependent chemical potential. If we assume $\tau_{\uparrow \downarrow}$ is very long relative to $\tau_{\sigma}$ and that $g^{\sigma}(\boldsymbol{r}, \boldsymbol{k})$ is slowly varying in space we find

$$
\begin{equation*}
g^{\sigma}(\boldsymbol{r}, \boldsymbol{k})=-e \tau_{\sigma} \mathcal{E}^{\sigma}(\boldsymbol{r}) \cdot \boldsymbol{k} \tag{9.70}
\end{equation*}
$$

and that $\mu^{\sigma}(\boldsymbol{r})$ satisfies the diffusion equation

$$
\begin{equation*}
\nabla^{2}\left[\mu^{\sigma}(\boldsymbol{r})-\mu^{-\sigma}(\boldsymbol{r})\right]=\frac{\mu^{\sigma}(\boldsymbol{r})-\mu^{-\sigma}(\boldsymbol{r})}{D^{2}} \tag{9.71}
\end{equation*}
$$

where the spin diffusion coefficient is given by $\frac{1}{D^{2}}=\frac{1}{D_{\uparrow}^{2}}+\frac{1}{D_{\downarrow}^{2}}$ and $D_{\sigma}=$ $\frac{\hbar k_{F}^{\sigma}}{m} \sqrt{\tau_{\sigma} \tau_{\uparrow \downarrow} / 3}$. This equation has the solution

$$
\begin{equation*}
\mu^{\uparrow}(y)-\mu^{\downarrow}(y)=A e^{y / D}+B e^{-y / D} \tag{9.72}
\end{equation*}
$$

where the coefficients $A$ and $B$ are determined by the boundary conditions on the spin current density, $j_{y}^{\sigma}(y)$. In particular, for the geometry shown above, $j_{y}^{\uparrow}(y)+j_{y}^{\downarrow}(y)=0$.

The current-density is given by the average of the current operator. When the spin-orbit interaction is included in the Hamiltonian the current operator is $\hbar \boldsymbol{k} / m$ plus the anomalous contribution introduced above, $\left(\hbar \alpha / \tau^{\sigma}\right) \boldsymbol{k} \times \boldsymbol{\sigma}$. Using (9.68) to calculate the current density analogous to (9.42) gives [235]

$$
\begin{equation*}
\boldsymbol{j}^{\sigma}(\boldsymbol{r})=c^{\sigma} \mathcal{E}^{\sigma}(\boldsymbol{r})+c_{H}^{\sigma} \mathcal{E}^{\sigma}(\boldsymbol{r}) \times \boldsymbol{\sigma} \tag{9.73}
\end{equation*}
$$

where

$$
\begin{aligned}
c^{\sigma} & =\frac{e^{2} \tau^{\sigma}\left(k_{F}^{\sigma}\right)^{3}}{6 \pi^{2} m} \\
c_{H}^{\sigma} & =\frac{e^{2} \alpha\left(k_{F}^{\sigma}\right)^{3}}{6 \pi^{2}} .
\end{aligned}
$$

Notice that $\mu^{\sigma}(\boldsymbol{r})$ enters the current density through $\mathcal{E}^{\sigma}(\boldsymbol{r})$. Taking the gradient of (9.72) the boundary condition enables us to determine the coefficients $A$ and $B$. For a paramagnetic metal where $c^{\uparrow}=c^{\downarrow}$ and $c_{H}^{\uparrow}=c_{H}^{\downarrow}$,

$$
\mu^{\uparrow}(y)-\mu^{\downarrow}(y)=\frac{c_{H}}{2 c^{2}} w j \times \frac{2 D}{w} \frac{\sinh (y / D)}{\cosh (w / 2 D)}
$$

Figure 9.30 shows $\left(\mu^{\uparrow}-\mu^{\downarrow}\right) /\left(c_{H} w j_{x} / 2 c^{2}\right)$ as a function of the distance across the film. From (9.65) $\varepsilon_{y} / j_{x}=4 \pi R_{s} M$. Also, since $\varepsilon_{y} / j_{x}=\sigma_{x y} / \sigma_{x x}^{2}=c_{H} / c^{2}$, the value of $\mu^{\uparrow}( \pm w / 2)-\mu^{\downarrow}( \pm w / 2)$ is the same as Hirch's $V_{S H}$ (9.67) when $w \ll D$.

Kato et al. [234] have used Kerr rotation microscopy to image the spin polarization across a semiconductor channel and observed a dependence very much like curve (c) in Fig. 9.30.


Fig. 9.30. Predicted dependence of spin accumulation as a function of distance across a semiconductor channel

## Problems

9.1. Can the presence of a localized spin in a metal induce a uniform magnetization? (Hint: determine how the average spin density, $\overline{s(\boldsymbol{r})}$, averaged over the range $0<q<\frac{1}{r}$ varies with $r$.)
9.2. Discuss how you would expect the RKKY interraction to be modified by (a) exchange enhancement and (b) a finite electron mean free path (see [237]).
9.3. What value of GMR would be expected for magnetic layers having the following density of states:

9.4. Solve the Boltzmann equation for a single layer of Cu bounded by insulating magnetic layers which completely spin polarize the Cu electrons when they are reflected from the interface. What is the GMR?

## Neutron Scattering

The scattering of neutrons provides us with an exceedingly powerful probe for studying condensed matter. This usefulness arises from the fact that thermal $(300 \mathrm{~K})$ neutrons have a wavelength $\lambda \simeq 1.6 \AA$. This means that their energy and wavelength are comparable to those of the excitations in solids. In fact, neutron scattering has become almost the last word in determining spin orderings, spin-density distributions, and spin-wave dispersion relations. A detailed discussion of the experimental techniques employed in neutron scattering, with reference to the original papers, may be found in [238].

There are two sources of neutrons for scattering. One is a nuclear reactor in which a fissile nucleus, generally ${ }^{239} \mathrm{U}$ or ${ }^{239} \mathrm{Pu}$, captures a neutron and splits into two nearly equal-mass fragments together with approximately 2.5 neutrons, each having an average energy of 2 MeV . The second source of neutrons is spallation, in which high energy particles from an accelerator, such as 1 GeV protons, collide with a heavy nucleus, such as uranium or lead. The excited nucleus decays by evaporating neutrons. The spallation process produces approximately 20 neutrons, with average energies of 2 MeV , for each colliding proton. Most spallation sources operate in a pulsed mode with pulse widths less than one microsecond and pulse rates between 10 Hz and 60 Hz . The MeV neutrons must be slowed down to thermal velocities $(\sim 30 \mathrm{meV})$, or even colder, by passing them through moderators consisting of beryllium or heavy water $\left(\mathrm{D}_{2} \mathrm{O}\right)$.

### 10.1 Neutron Scattering Cross Section

Let us consider sending a collimated beam of monochromatic neutrons into a sample and measuring the energy spectrum of the neutrons scattered in some direction. This is the differential scattering cross section. For the rest of this section we shall be concerned with how the scattering cross section depends on the state of the crystal [239, 240].

If the neutrons interact with the scatterer through some interaction $V(\boldsymbol{r})$, then the probability that the neutron will be scattered from an initial state $\left(\boldsymbol{k}, m_{s}\right)$ into a final state ( $\left.\boldsymbol{k}^{\prime}, m_{s}^{\prime}\right)$ while the system goes from state $\alpha$ to $\alpha^{\prime}$ is, in the Born approximation,

$$
\begin{equation*}
\left.\frac{2 \pi}{\hbar}\left|\left\langle\alpha^{\prime}, m_{s}^{\prime}\right| \frac{1}{L^{3}} \int d \boldsymbol{r} e^{i \boldsymbol{\kappa} \cdot \boldsymbol{r}} V(\boldsymbol{r})\right| \alpha, m_{s}\right\rangle\left.\right|^{2} \delta\left(\frac{\hbar^{2} k^{\prime 2}}{2 m_{0}}+E_{\alpha^{\prime}}-\frac{\hbar^{2} k^{2}}{2 m_{0}}-E_{\alpha}\right) \tag{10.1}
\end{equation*}
$$

where $\boldsymbol{\kappa} \equiv \boldsymbol{k}-\boldsymbol{k}^{\prime}, L^{3}$ is the volume of the sample, and $m_{0}$ is the neutron mass. The number of neutrons scattered into the solid angle $d \Omega^{\prime}$ in the direction $\boldsymbol{k}^{\prime}$ with momentum between $\hbar k^{\prime}$ and $\hbar\left(k^{\prime}+d k^{\prime}\right)$ is obtained by multiplying (10.1) by the number of states in this incremental volume of phase space, which is

$$
\begin{equation*}
\frac{k^{\prime 2} d k^{\prime} d \Omega^{\prime}}{(2 \pi / L)^{3}} \tag{10.2}
\end{equation*}
$$

Since the neutron energy and momentum are related by $E^{\prime}=\hbar^{2} k^{\prime 2} / 2 m_{0}$, this becomes

$$
\begin{equation*}
\frac{m_{0} L^{3} k^{\prime}}{8 \pi^{3} \hbar^{2}} d \Omega^{\prime} d E^{\prime} \tag{10.3}
\end{equation*}
$$

The differential scattering cross section is defined as the scattering intensity per unit solid angle per unit incident flux. The incident flux associated with a beam of neutrons with velocity $v$ is

$$
\begin{equation*}
\frac{v}{L^{3}}=\frac{\hbar k}{m_{0} L^{3}} . \tag{10.4}
\end{equation*}
$$

Therefore the differential scattering cross section becomes

$$
\begin{align*}
\left.\frac{d^{2} \sigma}{d \Omega^{\prime} d E^{\prime}}\right|_{\alpha, m_{s} \rightarrow \alpha^{\prime}, m_{s}^{\prime}}= & \left.\frac{k^{\prime}}{k}\left(\frac{m_{0}}{2 \pi \hbar^{2}}\right)^{2}\left|\left\langle\alpha^{\prime} m_{s}^{\prime}\right| V(-\kappa)\right| \alpha, m_{s}\right\rangle\left.\right|^{2} \\
& \times \delta\left(\frac{\hbar^{2} k^{\prime 2}}{2 m_{0}}+E_{\alpha^{\prime}}-\frac{\hbar^{2} k^{2}}{2 m_{0}}-E_{\alpha}\right) . \tag{10.5}
\end{align*}
$$

We must now sum over the final states $\alpha^{\prime}$ and $m_{s}^{\prime}$ as well as average over the initial states $\alpha$ and $m_{s}$, using a probability factor $P_{\alpha}$. This factor might have the Boltzmann form

$$
\begin{equation*}
P_{\alpha}=\frac{\exp \left(-E_{\alpha} / k_{B} T\right)}{\sum_{\alpha} \exp \left(-E_{\alpha} / k_{B} T\right)} \tag{10.6}
\end{equation*}
$$

or some other form such as the Bose-Einstein form in the case of phonons. Thus

$$
\left.\begin{array}{rl}
\frac{d^{2} \sigma}{d \Omega^{\prime} d E^{\prime}}= & \left.\sum_{\alpha, m_{s}} P_{\alpha} P_{m_{s}} \sum_{\alpha^{\prime} m_{s}^{\prime}} \frac{k^{\prime}}{k}\left(\frac{m_{0}}{2 \pi \hbar^{2}}\right)^{2}\left|\left\langle\alpha^{\prime}, m_{s}^{\prime}\right| V(-\kappa)\right| \alpha, m_{s}\right\rangle\left.\right|^{2}  \tag{10.7}\\
& \times \delta\left(\frac{\hbar^{2} k^{\prime 2}}{2 m_{0}}+E_{\alpha^{\prime}}-\frac{\hbar^{2} k^{2}}{2 m_{0}}-E_{\alpha}\right)
\end{array}\right\}
$$

This is the general result which forms the basis of our discussion of neutron scattering.

The neutron interacts with the crystal in two ways: through the nuclear interaction and through the magnetic dipole-dipole interaction.

### 10.2 Nuclear Scattering

Although our main interest will be in magnetic scattering, we shall briefly consider the nuclear contribution to see how it complicates the experimental results. Let us begin by considering the nuclear scattering from a single fixed zero-spin nucleus located at $\boldsymbol{R}$. Since the interaction has such a short range, the scattering will be isotropic at these neutron energies. This is because at short distances from the nucleus the neutron's angular momentum is very small. Hence we have only $s$-wave scattering. The only form of $\boldsymbol{V}(\boldsymbol{r})$ which gives isotropic scattering in the Born approximation is a delta function.

Thus we set

$$
\begin{equation*}
V(\boldsymbol{r})=\frac{2 \pi \hbar^{2}}{m_{0}} b \delta(\boldsymbol{r}-\boldsymbol{R}) \tag{10.8}
\end{equation*}
$$

where $b$ is called the scattering length. It represents a phenomenological description of the nuclear scattering process which is very difficult to compute directly. Equation (10.8) is called the Fermi pseudopotential and gives a total cross section

$$
\begin{equation*}
\sigma=4 \pi b^{2} \tag{10.9}
\end{equation*}
$$

The scattering length is taken to be a constant, independent of the neutron energy. This is valid at the low neutron energies used.

Now consider scattering from many fixed nuclei situated at lattice sites $\boldsymbol{n}$. If we have a compound or if there are isotopes present, the scattering amplitudes of the different nuclei may be different. In this case the total pseudopotential is

$$
\begin{equation*}
V(\boldsymbol{r})=\frac{2 \pi \hbar^{2}}{m_{0}} \sum_{\boldsymbol{n}} b_{\boldsymbol{n}} \sigma(\boldsymbol{r}-\boldsymbol{n}) \tag{10.10}
\end{equation*}
$$

This leads to the differential cross section

$$
\begin{equation*}
\left.\frac{d^{2} \sigma}{d \Omega^{\prime} d E^{\prime}}=\sum_{\alpha, m_{s}} P_{\alpha} P_{m_{s}} \sum_{\alpha^{\prime}, m_{s}^{\prime}} \frac{k^{\prime}}{k}\left|\left\langle\alpha^{\prime}, m_{s}^{\prime}\right| \sum_{\boldsymbol{n}} b_{\boldsymbol{n}} e^{i \boldsymbol{\kappa} \cdot \boldsymbol{n}}\right| \alpha, m_{s}\right\rangle\left.\right|^{2} \delta \quad \text { (energy) } . \tag{10.11}
\end{equation*}
$$

Here, $\alpha$ refers to all the quantum numbers necessary to describe the crystal. In particular, $\alpha$ and $\alpha^{\prime}$ might refer to the isotope distribution and the nuclearspin orientations. To a good approximation the energy is independent of these quantities. Thus,

$$
\begin{align*}
\frac{d \sigma}{d \Omega^{\prime}} & =\sum_{\alpha, m_{s}} P_{\alpha} P_{m_{s}} \sum_{n}, m \exp [i \boldsymbol{\kappa} \cdot(\boldsymbol{n}-\boldsymbol{m})]\left\langle\alpha, m_{s}\right| b_{m}^{*} b_{n}\left|\alpha, m_{s}\right\rangle \\
& =\sum_{n, m} \exp [i \boldsymbol{\kappa} \cdot(\boldsymbol{n}-\boldsymbol{m})]\left\langle b_{m}^{*} b_{n}\right\rangle . \tag{10.12}
\end{align*}
$$

Since there is no correlation between $b_{\boldsymbol{n}}$ and $b_{\boldsymbol{m}}^{*}$ for $\boldsymbol{n} \neq \boldsymbol{m}$,

$$
\left\langle b_{\boldsymbol{m}}^{*} b_{\boldsymbol{n}}\right\rangle=\left\langle b_{\boldsymbol{m}}^{*}\right\rangle\left\langle b_{\boldsymbol{n}}\right\rangle=|\langle b\rangle|^{2}
$$

Therefore we write

$$
\begin{equation*}
\left.\left\langle b_{\boldsymbol{m}}^{*} b_{\boldsymbol{n}}\right\rangle=|\langle b\rangle|^{2}+\left(\left.\langle | b\right|^{2}\right\rangle-|\langle b\rangle|^{2}\right) \Delta(\boldsymbol{n}-\boldsymbol{m}) \tag{10.13}
\end{equation*}
$$

This enables us to separate the cross section into two parts,

$$
\begin{equation*}
\frac{d \sigma}{d \Omega^{\prime}}=\left(\frac{d \sigma}{d \Omega^{\prime}}\right)_{\mathrm{coh}}+\left(\frac{d \sigma}{d \Omega^{\prime}}\right)_{\mathrm{incoh}} \tag{10.14}
\end{equation*}
$$

where the coherent cross section is

$$
\begin{equation*}
\left(\frac{d \sigma}{d \Omega^{\prime}}\right)_{\mathrm{coh}}=|\langle b\rangle|^{2}\left|\sum_{n} e^{i \boldsymbol{\kappa} \cdot \boldsymbol{n}}\right|^{2} \tag{10.15}
\end{equation*}
$$

and the incoherent cross section is

$$
\begin{equation*}
\left.\left(\frac{d \sigma}{d \Omega^{\prime}}\right)_{\text {incoh }}=N\left(\left.\langle | b\right|^{2}\right\rangle-|\langle b\rangle|^{2}\right) . \tag{10.16}
\end{equation*}
$$

We see that only the mean scattering potential $\langle b\rangle$ gives rise to interference effects and coherent scattering, while the incoherent scattering is proportional to the mean-square deviation $\left.\langle | b-\left.\langle b\rangle\right|^{2}\right\rangle$. If the nucleus possesses a nonzero spin, then the nuclear scattering amplitude will depend upon the relative orientation of this spin with the neutron spin. Since these nuclear spins are disordered, they lead to a large incoherent scattering. This is beautifully illustrated in Fig. 10.1, where the cross section for thorium hydride is compared with that of thorium deuteride. The large incoherent scattering observed in the $\mathrm{ThH}_{2}$ is associated with incoherent nuclear spin scattering.

### 10.2.1 Bragg Scattering

The coherent elastic scattering from a rigid lattice is also referred to as Bragg scattering. This involves the quantity.

$$
\sum_{n} e^{i \kappa \cdot n}
$$

which contains $N$ terms. It can be shown that


Fig. 10.1. Neutron diffraction patterns for polycrystalline $\mathrm{ThH}_{2}$ and $\mathrm{ThD}_{2}$ [241]

$$
\begin{equation*}
\left|\sum_{n} e^{i \boldsymbol{\kappa} \cdot \boldsymbol{n}}\right|^{2}=\frac{(2 \pi)^{2} N}{V_{0}} \sum_{G} \delta(\boldsymbol{\kappa}-\boldsymbol{G}) \tag{10.17}
\end{equation*}
$$

where $V_{0}$ is the volume of the unit cell and $\boldsymbol{G}$ is a reciprocal lattice vector. This is an important result which we shall encounter many times. The coherent, or Bragg, cross section then becomes

$$
\begin{equation*}
\left(\frac{d \sigma}{d \Omega^{\prime}}\right)_{\mathrm{coh}}=|\langle b\rangle|^{2} \frac{(2 \pi)^{3} N}{V_{0}} \sum_{\boldsymbol{G}} \delta(\boldsymbol{\kappa}-\boldsymbol{G}), \tag{10.18}
\end{equation*}
$$

If the lattice has more than one atom per unit cell, say $r$ atoms at $\rho_{1}, \rho_{2}, \ldots$, relative to some reference point in the unit cell, then

$$
\begin{equation*}
\left(\frac{d \sigma}{d \Omega^{\prime}}\right)_{\mathrm{coh}}=\frac{(2 \pi)^{3} N}{V_{0}} \sum_{G}|F(\boldsymbol{G})|^{2} \delta(\boldsymbol{\kappa}-\boldsymbol{G}), \tag{10.19}
\end{equation*}
$$

where

$$
F(\boldsymbol{G})=\sum_{i=1}^{r}\left\langle b_{i}\right\rangle \exp \left(i \boldsymbol{G} \cdot \boldsymbol{\rho}_{i}\right)
$$

is the unit cell structure factor. The important point is that there is no coherent scattering unless

$$
\begin{equation*}
\kappa=\boldsymbol{k}-\boldsymbol{k}^{\prime}=\boldsymbol{G} . \tag{10.20}
\end{equation*}
$$

By squaring this relation and making use of the fact that the magnitude of the reciprocal lattice vector in some direction hkl is equal to some multiple of $2 \pi$ times the inverse spacing of the planes in that direction, $d$ (hkl), we obtain the familiar Bragg law

$$
\begin{equation*}
\sin \theta=\frac{n \lambda}{2 d(\mathrm{hkl})} \tag{10.21}
\end{equation*}
$$

for the angle $2 \theta$ between the indicent beam and the diffracted beam.


Fig. 10.2. Time-of-flight diffraction pattern

Time-of-flight differaction provides a convenient technique for measuring the lattice parameters $d(\mathrm{hkl})$. In a pulsed neutron source the neutrons have a broad energy spectrum similar to the spectrum of fission neutrons. But since they are all created at the same time, time-of-flight techniques may be used to separate neutrons with different energies. In particular, combining the de Broglie relation $\lambda=h / m v$ with Bragg's law, $\lambda=2 d \sin \theta$, the $d$-spacing in $\AA$ at a given scattering angle is

$$
d=t / 252.8 L 2 \sin \theta,
$$

where $t$ is the time of flight in $\mu$ sec and $L$ is the flight path in $m$. Thus a time-of-flight diffraction pattern will look like the one in Fig. 10.2. One advantage of a time-of-flight measurement is that the resolution, $\Delta d / d$, is constant over the whole pattern.

### 10.2.2 Scattering of Phonons

Let us now consider the cross section when we allow the ions to deviate from their rigid lattice position $\boldsymbol{n}$ by an amount $\boldsymbol{u}_{n}$. The general position is then

$$
\begin{equation*}
\boldsymbol{R}_{n}=\boldsymbol{n}+\boldsymbol{u}_{n} \tag{10.22}
\end{equation*}
$$

and the cross section becomes

$$
\begin{align*}
\frac{d^{2} \sigma}{d \Omega^{\prime} d E^{\prime}}= & \sum_{a, m_{s}} P_{a} P_{m_{s^{\prime}}} \sum \frac{k^{\prime}}{k}  \tag{10.23}\\
& \left.\times\left|\left\langle\alpha^{\prime}, m_{s}^{\prime}\right| \sum_{n} b_{n} \exp (i \boldsymbol{\kappa} \cdot \boldsymbol{n}) \exp \left(i \boldsymbol{\kappa} \cdot \boldsymbol{u}_{n}\right)\right| \alpha, m_{s}\right\rangle\left.\right|^{2} \delta(\text { energy }) .
\end{align*}
$$

The system coordinates $a$ and $a^{\prime}$ now refer to phonon states as well as to the nuclear spin projections $m_{I}$ and $m_{I}^{\prime}$. Writing out the latter explicitly, we have for the matrix element above

$$
\begin{equation*}
\sum_{n}\left\langle m_{s}^{\prime}, m_{I}^{\prime}\right| b_{n}\left|m_{s}, m_{I}\right\rangle \exp (i \boldsymbol{\kappa} \cdot \boldsymbol{n})\left\langle\alpha^{\prime}\right| \exp \left(i \boldsymbol{\kappa} \cdot \boldsymbol{u}_{n}\right)|\alpha\rangle . \tag{10.24}
\end{equation*}
$$

The ionic displacement $\boldsymbol{u}_{n}$ may be expanded in boson operators corresponding to the creation and annihilation of phonons as [242].

$$
\begin{equation*}
\boldsymbol{u}_{\boldsymbol{n}}=\sum_{\boldsymbol{q}, s} \sqrt{\frac{\hbar}{2 N M \omega_{\boldsymbol{q} s}}}\left[a_{\boldsymbol{q} s} e^{i \boldsymbol{q} \cdot \boldsymbol{n}} \hat{\epsilon}_{\boldsymbol{q} s}+a_{\boldsymbol{q} s}^{\dagger} e^{-i \boldsymbol{q} \cdot \boldsymbol{n}} \hat{\epsilon}_{\boldsymbol{q} s}\right] \tag{10.25}
\end{equation*}
$$

$\hat{\epsilon}_{\boldsymbol{q} s}$ is the unit polarization vector associated with the phonon wave vector $\boldsymbol{q}$ and polarization $s$. The phonon coordinates $\alpha$ in the matrix element above may now be explicitly written as the number of phonons in each mode. Thus the factor involving $\boldsymbol{u}_{\boldsymbol{n}}$ becomes

$$
\begin{align*}
& \left\langle n_{\boldsymbol{q}_{1} s_{1}}^{\prime}, n_{\boldsymbol{q}_{2}, s_{2}, \ldots}^{\prime}\right| \\
& \quad \times \exp \left[i \sum_{\boldsymbol{q}, s} \sqrt{\frac{\hbar}{2 N M \omega_{\boldsymbol{q} s}}}\left(a_{\boldsymbol{q} s} e^{i \boldsymbol{q} \cdot \boldsymbol{n}} \hat{\epsilon}_{\boldsymbol{q} s} \cdot \boldsymbol{\kappa}+a_{\boldsymbol{q} s}^{\dagger} e^{-i \boldsymbol{q} \cdot \boldsymbol{n}} \hat{\epsilon}_{\boldsymbol{q} s} \cdot \boldsymbol{\kappa}\right)\right] \\
& \quad \times\left|n_{\boldsymbol{q}_{1} s_{1}}, n_{\boldsymbol{q}_{2}, s_{2}}, \ldots\right\rangle \tag{10.26}
\end{align*}
$$

Using the relation

$$
\begin{equation*}
e^{A+B}=e^{A} e^{B} e^{-(1 / 2)[A, B]}, \tag{10.27}
\end{equation*}
$$

where $A$ and $B$ are noncommuting operators, and expanding the exponentials involving the phonon amplitudes, the cross section may be written as the sum of multiphonon processes,

$$
\begin{equation*}
\frac{d^{2} \sigma}{d \Omega^{\prime} d E^{\prime}}=\sum_{n=-\infty}^{\infty} \frac{d^{2} \sigma_{n}}{d \Omega^{\prime} d E^{\prime}}, \tag{10.28}
\end{equation*}
$$

where $n$ is the net number of phonons created.
Elastic Scattering. Let us consider the case where the net number of phonons created is 0 . This corresponds to elastic scattering, but at a finite temperature. With $n_{\boldsymbol{q} \boldsymbol{s}}^{\prime}=n_{\boldsymbol{q} s}$, the matrix element $n=0$ in (10.28) becomes, to order $1 / N$,

$$
\begin{equation*}
\prod_{\boldsymbol{q} s}\left[1-\frac{\hbar}{2 N M \omega_{\boldsymbol{q} s}}\left(n_{\boldsymbol{q} s}+\frac{1}{2}\right)\left|\boldsymbol{\kappa} \cdot \hat{\varepsilon}_{\boldsymbol{q}, s}\right|^{2}\right] . \tag{10.29}
\end{equation*}
$$

If this is substituted into the expression for $d^{2} \sigma_{0} / d \Omega^{\prime} d E^{\prime}$, the sum over $\alpha$, which is the number of phons in each mode, converts $n_{\boldsymbol{q} s}$ into its thermal equilibrium value $\bar{n}_{\boldsymbol{q} s}$. In the limit $N \rightarrow \infty$ this may be written as

$$
\begin{equation*}
\exp \left[-\sum_{\boldsymbol{q}, s} \frac{\hbar}{2 N M \omega_{\boldsymbol{q} s}}\left(\bar{n}_{\boldsymbol{q} s}+\frac{1}{2}\right)\left|\boldsymbol{\kappa} \cdot \hat{\varepsilon}_{\boldsymbol{q} s}\right|^{2}\right] . \tag{10.30}
\end{equation*}
$$

Using this along with $(10.24,10.24)$ results in a total elastic cross section,

$$
\begin{align*}
\frac{d^{2} \sigma_{0}}{d \Omega^{\prime} d E^{\prime}}= & \sum_{m_{I}, m_{s}} P_{m_{s}} P_{m_{I}} \sum_{m_{I}^{\prime}, m_{s}^{\prime}} \frac{k^{\prime}}{k} \sum_{n, m}\left\langle m_{s}, m_{I}\right| b_{m}^{*}\left|m_{s}^{\prime}, m_{I}^{\prime}\right\rangle \\
& \times\left\langle m_{s}^{\prime}, m_{I}^{\prime}\right| b_{n}\left|m_{s}, m_{I}\right\rangle \exp [i \boldsymbol{\kappa} \cdot(\boldsymbol{n}-\boldsymbol{m})]  \tag{10.31}\\
& \times \exp \left[-\sum_{\boldsymbol{q}, s} \frac{\hbar}{N M \omega_{\boldsymbol{q} s}}\left(n_{\boldsymbol{q} s}+\frac{1}{2}\right)\left|\boldsymbol{\kappa} \cdot \hat{\varepsilon}_{\boldsymbol{q} s}\right|^{2}\right] \delta \text { (energy) } .
\end{align*}
$$

Removing the sum over ( $m_{s}^{\prime}, m_{I}^{\prime}$ ) by closure and integrating over energy, we obtain

$$
\begin{equation*}
\frac{d \sigma_{0}}{d \Omega^{\prime}}=\sum_{n, \boldsymbol{m}} \exp [i \boldsymbol{\kappa} \cdot(\boldsymbol{n}-\boldsymbol{m})]\left\langle b_{m}^{*} b_{n}\right\rangle \exp (-2 W) \tag{10.32}
\end{equation*}
$$

where

$$
\begin{equation*}
W=\sum_{\boldsymbol{q}, s} \frac{\hbar}{2 N M \omega_{\boldsymbol{q} s}}\left(\bar{n}_{\boldsymbol{q} s}+\frac{1}{2}\right)\left|\boldsymbol{\kappa} \cdot \hat{\varepsilon}_{\boldsymbol{q} s}\right|^{2} \tag{10.33}
\end{equation*}
$$

is called the Debye-Waller factor. Comparison of (10.32) and (10.12) shows that the coherent and incoherent cross sections are the same as those we obtained for the rigid lattice case except for the factor $\exp (-2 W)$. Notice that this is nonzero even at $T=0$ owing to zero-point vibrations.
One-Phonon Scattering. We now turn to inelastic processes involving one phonon. In particular, let us consider those processes in which the number of phonons annihilated exceeds by 1 the number of phonons created. The contribution to the matrix element given by $(10.26)$ for these processes is

$$
\begin{align*}
& \sum_{n}\left\langle m_{s}^{\prime}, m_{I}^{\prime}\right| b_{n}\left|m_{s}, m_{I}\right\rangle e^{i \boldsymbol{\kappa} \cdot \boldsymbol{n}} i \sqrt{\frac{\hbar}{2 N M \omega_{\boldsymbol{q} s}}} \sqrt{n_{\boldsymbol{q} s}} e^{i \boldsymbol{q} \cdot \boldsymbol{n} \boldsymbol{\kappa} \cdot \hat{\varepsilon}_{\boldsymbol{q} s}} \\
& \sum_{\boldsymbol{q}^{\prime}, s^{\prime}}\left[1-\frac{\hbar}{2 N M \omega_{\boldsymbol{q}^{\prime} s^{\prime}}}\left(n_{\boldsymbol{q}^{\prime} s^{\prime}}+\frac{1}{2}\right)\left|\boldsymbol{\kappa} \cdot \hat{\varepsilon}_{\boldsymbol{q} s}\right|^{2}\right], \tag{10.34}
\end{align*}
$$

In the computation of the corresponding cross section the sum over the distribution of occupation numbers again introduces the thermal averages of the $n_{\boldsymbol{q} s}$. Thus we obtain

$$
\begin{align*}
\frac{d^{2} \sigma_{-1}}{d \Omega^{\prime} d E^{\prime}}= & \sum_{\boldsymbol{q}, s}\left\langle b_{m}^{*} b_{n}\right\rangle \exp [i(\boldsymbol{\kappa}+\boldsymbol{q}) \cdot(\boldsymbol{n}-\boldsymbol{m})] \\
& \times \frac{\hbar}{2 N M \omega_{\boldsymbol{q} s}} \bar{n}_{\boldsymbol{q} s}\left|\boldsymbol{\kappa} \cdot \hat{\varepsilon}_{\boldsymbol{q} s}\right|^{2} e^{-2 W} \delta\left[\frac{\hbar^{2}}{2 m_{0}}\left(k^{2}-k^{\prime 2}\right)-\hbar \omega_{\boldsymbol{q}}\right] \tag{10.35}
\end{align*}
$$

From (10.10), (10.13), (10.15), (10.16) we may write

$$
\begin{equation*}
\left\langle b_{m}^{*} b_{n}\right\rangle=\frac{\sigma_{\mathrm{coh}}}{4 \pi}+\frac{\sigma_{\mathrm{incoh}}}{4 \pi} \Delta(\boldsymbol{m}-\boldsymbol{n}) \tag{10.36}
\end{equation*}
$$

where $\sigma_{\text {coh }}=4 \pi|\langle b\rangle|^{2}$ and $\left.\sigma_{\text {incoh }}=4 \pi\left\{\left.\langle | b\right|^{2}\right\rangle-|\langle b\rangle|^{2}\right\}$, so that the coherent part of the cross section becomes

$$
\begin{align*}
\left(\frac{d^{2} \sigma_{-1}}{d \Omega^{\prime} d E^{\prime}}\right)_{\mathrm{coh}}= & \frac{(2 \pi)^{3} N}{V_{0}} \frac{\sigma_{\mathrm{coh}}}{4 \pi} \sum_{\boldsymbol{q}, s} \frac{k^{\prime}}{k} \sum_{\boldsymbol{G}} \delta(\boldsymbol{\kappa}+\boldsymbol{q}-\boldsymbol{G}) \\
& \times \frac{\hbar}{2 N M \omega_{\boldsymbol{q} s}} \bar{n}_{\boldsymbol{q} s}\left|\boldsymbol{\kappa} \cdot \hat{\varepsilon}_{\boldsymbol{q} s}\right|^{2} e^{-2 W} \delta(\text { energy }) . \tag{10.37}
\end{align*}
$$



Fig. 10.3. Schematic diagram of a triple-axis spectrometer

Similarly, the incoherent part becomes

$$
\begin{equation*}
\left(\frac{d^{2} \sigma_{-1}}{d \Omega^{\prime} d E^{\prime}}\right)_{\mathrm{incoh}}=\frac{N \sigma_{\text {incoh }}}{4 \pi} \sum_{\boldsymbol{q}, s} \frac{k^{\prime}}{k} \frac{\hbar}{2 N M \omega_{\boldsymbol{q} s}} \bar{n}_{\boldsymbol{q} s}\left|\boldsymbol{\kappa} \cdot \hat{\varepsilon}_{\boldsymbol{q} s}\right|^{2} e^{-2 W} \delta(\text { energy }) \tag{10.38}
\end{equation*}
$$

We can obtain similar expressions for one-phonon creation processes. For more details we refer the reader to [239].

In summary, a typical neutron diffraction pattern will consist of Bragg peaks plus a diffuse background. The Bragg peaks enable us to determine the crystal structure. The diffuse background arises from three sources: incoherent elastic scattering, coherent inelastic scattering, and incoherent inelastic scattering. By using certain experimental techniques we may separate the coherent inelastic scattering contribution and thereby determine the phonon dispersion relation. If we can also separate the incoherent inelastic scattering, this leads directly to the phonon density of states. In the next section we shall see how magnetic scattering contributes to this spectrum.

A triple-axis spectrometer (Fig. 10.3) is often used to measure the energy and momentum transfer associated with the inelastic scattering of neutrons from a reactor source [243]. The high-energy neutrons are moderated down to thermal energies and emerge from the reactor with a Maxwellian distribution of energies. A single energy is selected by Bragg reflection from the first monochromator crystal in Fig. 10.3. This monoenergetic beam is incident on
the sample with the wave vector $\boldsymbol{k}$. The scattered beam $\boldsymbol{k}^{\prime}$ is Bragg reflected by the analyzer crystal into the detector.

### 10.3 Magnetic Scattering

We now turn our attention to the interaction between the magnetic moment of the neutron and those of the crystal. The vector potential at $\boldsymbol{r}_{\boldsymbol{e}}$ produced by a neutron's magnetic moment $\boldsymbol{\mu}$ at $\boldsymbol{r}$ is

$$
\begin{equation*}
\boldsymbol{A}=\frac{\boldsymbol{\mu} \times\left(\boldsymbol{r}_{\boldsymbol{e}}-\boldsymbol{r}\right)}{\left|\boldsymbol{r}_{\boldsymbol{e}}-\boldsymbol{r}\right|^{3}} \tag{10.39}
\end{equation*}
$$

As we saw in Sect. 2.2, the magnetic interaction between a vector potential $\boldsymbol{A}$ and an electron with momentum $\boldsymbol{p}$ is given by

$$
\begin{equation*}
\boldsymbol{V}(\boldsymbol{x})=-\frac{e}{2 m c}[\boldsymbol{p} \cdot \boldsymbol{A}(\boldsymbol{x})+\boldsymbol{A}(\boldsymbol{x}) \cdot \boldsymbol{p}]-\frac{e \hbar}{2 m c} \boldsymbol{\sigma} \cdot \boldsymbol{\nabla}_{x} \times \boldsymbol{A}(\boldsymbol{x}), \tag{10.40}
\end{equation*}
$$

where $\boldsymbol{x} \equiv \boldsymbol{r}_{\boldsymbol{e}}-\boldsymbol{r}$ and $\boldsymbol{p}$ operates on $\boldsymbol{r}_{\boldsymbol{e}}$. In the Born approximation we consider the matrix element of this interaction between the initial and final states. For the neutron these are just $\exp (i \boldsymbol{k} \cdot \boldsymbol{r})$ and $\exp \left(i \boldsymbol{k}^{\prime} \cdot \boldsymbol{r}\right)$, respectively. Therefore, if we integrate over the neutron coordinates, we have

$$
\begin{align*}
\left\langle\boldsymbol{k}^{\prime}\right| V(\boldsymbol{x})|\boldsymbol{k}\rangle= & -\frac{e}{2 m c} \int d \boldsymbol{r} e^{-i \boldsymbol{k}^{\prime} \cdot \boldsymbol{r}}[\boldsymbol{p} \cdot \boldsymbol{A}(\boldsymbol{x})+\boldsymbol{A}(\boldsymbol{x}) \cdot \boldsymbol{p}] e^{i \boldsymbol{k} \cdot \boldsymbol{r}} \\
& -\frac{e \hbar}{2 m c} \boldsymbol{\sigma} \cdot \int d \boldsymbol{r} e^{i \boldsymbol{k}^{\prime} \cdot \boldsymbol{r}} \nabla_{\boldsymbol{x}} \times \boldsymbol{A}(\boldsymbol{x}) e^{-i \boldsymbol{k} \cdot \boldsymbol{r}} \tag{10.41}
\end{align*}
$$

The Born approximation is valid in this case because the average interaction energy $\mu_{e} \mu_{N} / x^{3} \simeq 10^{-3} \mathrm{~K}$, which is very small compared with the kinetic energy of the neutron. If we write $\boldsymbol{r}=\boldsymbol{r}_{e}-\boldsymbol{x}$ and $\boldsymbol{\kappa}=\boldsymbol{k}-\boldsymbol{k}^{\prime}$, the partial matrix element (10.41) becomes

$$
\begin{array}{r}
-\frac{e}{2 m c} \int \boldsymbol{d} \boldsymbol{x} \exp (-i \boldsymbol{\kappa} \cdot \boldsymbol{x}) \exp \left(-i \boldsymbol{\kappa} \cdot \boldsymbol{r}_{e}\right)[\boldsymbol{p} \cdot \boldsymbol{A}(\boldsymbol{x})+\boldsymbol{A}(\boldsymbol{x}) \cdot \boldsymbol{p}] \\
-\frac{e \hbar}{2 m c} \boldsymbol{\sigma} \cdot \int d \boldsymbol{x} \exp (-i \boldsymbol{\kappa} \cdot \boldsymbol{x}) \exp \left(i \boldsymbol{\kappa} \cdot \boldsymbol{r}_{e}\right) \nabla_{x} \times \boldsymbol{A}(\boldsymbol{x}) \tag{10.42}
\end{array}
$$

From the explicit form of $\boldsymbol{A}(\boldsymbol{x})$ we have that $\boldsymbol{\nabla}_{\boldsymbol{x}} \cdot \boldsymbol{A}(\boldsymbol{x})=0$, as well as

$$
\begin{equation*}
\int d \boldsymbol{x} e^{i \boldsymbol{\kappa} \cdot \boldsymbol{x}} \boldsymbol{A}(\boldsymbol{x})=\frac{4 \pi i}{\kappa^{2}}(\boldsymbol{\mu} \times \boldsymbol{\kappa}) \tag{10.43}
\end{equation*}
$$

and

$$
\begin{equation*}
\int d \boldsymbol{x} e^{i \boldsymbol{\kappa} \cdot \boldsymbol{x}}\left[\nabla_{x} \times \boldsymbol{A}(\boldsymbol{x})\right]=\frac{4 \pi}{\kappa^{2}} \boldsymbol{\kappa} \times(\boldsymbol{\mu} \times \boldsymbol{\kappa})=4 \pi[\boldsymbol{\mu}-(\hat{\boldsymbol{\kappa}} \cdot \boldsymbol{\mu}) \hat{\boldsymbol{\kappa}}] . \tag{10.44}
\end{equation*}
$$

Therefore (10.41) reduces to

$$
\begin{equation*}
i \frac{4 \pi e}{m c} \frac{1}{\kappa^{2}}(\boldsymbol{\mu} \times \boldsymbol{\kappa}) \cdot \exp \left(i \boldsymbol{\kappa} \cdot \boldsymbol{r}_{e}\right) \boldsymbol{p}-\frac{4 \pi e \hbar}{2 m c}[\boldsymbol{\sigma} \cdot \boldsymbol{\mu}-(\boldsymbol{\sigma} \cdot \hat{\boldsymbol{\kappa}})(\boldsymbol{\mu} \cdot \hat{\boldsymbol{\kappa}})] \exp \left(i \boldsymbol{\kappa} \cdot \boldsymbol{r}_{e}\right) \tag{10.45}
\end{equation*}
$$

The first term represents the interaction between the neutron's moment and the orbital current, and the second term is the spin-spin interaction.

It is interesting to consider what happens when $\kappa \rightarrow 0$, that is, the case of forward scattering. We rewrite the first term as

$$
\begin{equation*}
i \frac{4 \pi e}{m c} \boldsymbol{\mu} \cdot\left[\frac{\exp \left(i \boldsymbol{\kappa} \cdot \boldsymbol{r}_{e}\right)}{\kappa^{2}} \boldsymbol{\kappa} \times \boldsymbol{p}\right] \tag{10.46}
\end{equation*}
$$

Expanding the exponential, we have

$$
\begin{equation*}
i \frac{4 \pi e}{m c} \boldsymbol{\mu} \cdot \frac{\boldsymbol{\kappa} \times \boldsymbol{p}}{\kappa^{2}}-\frac{4 \pi e}{m c} \boldsymbol{\mu} \cdot\left(\frac{\boldsymbol{\kappa} \cdot \boldsymbol{r}_{e}}{\kappa^{2}} \boldsymbol{\kappa} \times \boldsymbol{p}\right)+\ldots \tag{10.47}
\end{equation*}
$$

We take the mean value of the limit as $\boldsymbol{\kappa} \rightarrow 0$. In this limit the first term of (10.47) vanishes and the second term becomes

$$
\begin{equation*}
-\frac{4 \pi e}{m c} \boldsymbol{\mu} \cdot \frac{1}{3}\left(\boldsymbol{r}_{e} \times \boldsymbol{p}\right)=\frac{8 \pi}{3} \mu_{B} \boldsymbol{\mu} \cdot \boldsymbol{l} . \tag{10.48}
\end{equation*}
$$

The spin term of (10.45) becomes

$$
\begin{equation*}
4 \pi \mu_{B}\left[\boldsymbol{\sigma} \cdot \boldsymbol{\mu}-\frac{1}{3} \boldsymbol{\sigma} \cdot \boldsymbol{\mu}\right]=\frac{8 \pi}{3} \mu_{B} \boldsymbol{\mu} \cdot \boldsymbol{\sigma} . \tag{10.49}
\end{equation*}
$$

Thus the partial matrix element is

$$
\begin{equation*}
\frac{8 \pi}{3} \mu_{B} \boldsymbol{\mu} \cdot(\boldsymbol{l}+2 s) . \tag{10.50}
\end{equation*}
$$

This shows that the forward-scattering cross section is proportional to the total magnetic moment of the electron.

Let us return now to the case $\boldsymbol{\kappa} \neq 0$. In many materials the orbital momentum is quenched. Therefore let us consider only the spin term. The matrix element entering (10.1), which is essentially the magnetic scattering amplitude, is

$$
\begin{equation*}
4 \pi \mu_{B}\left\langle\alpha^{\prime}, m_{s}^{\prime}\right| \sum_{i}\left[\boldsymbol{\sigma}_{i} \cdot \boldsymbol{\mu}-\left(\boldsymbol{\sigma}_{i} \cdot \hat{\boldsymbol{\kappa}}\right)(\boldsymbol{\mu} \cdot \hat{\boldsymbol{\kappa}})\right] \exp \left(i \boldsymbol{\kappa} \cdot \boldsymbol{r}_{i}\right)\left|\alpha, m_{s}\right\rangle \tag{10.51}
\end{equation*}
$$

where the sum over $i$ includes all the electrons in the sample. The factor $\boldsymbol{\sigma}_{i} \exp \left(i \boldsymbol{\kappa} \cdot \boldsymbol{r}_{i}\right)$ may be written as $\int d \boldsymbol{r} \boldsymbol{\sigma}_{i} \delta\left(\boldsymbol{r}-\boldsymbol{r}_{i}\right) \exp (i \boldsymbol{\kappa} \cdot \boldsymbol{r})$. By analogy with (1.48),

$$
\sum_{i} \boldsymbol{\sigma}_{i} \delta\left(\boldsymbol{r}-\boldsymbol{r}_{i}\right)
$$

is the spin density at $\boldsymbol{r}$, which we shall write as $2 \boldsymbol{S}(\boldsymbol{r})$. Therefore, the total scattering amplitude is proporitional to the Fourier transform of the spin density. The neutron's magnetic moment is related to its spin by

$$
\boldsymbol{\mu}=-1.91 \frac{e \hbar}{m_{0} c} s
$$

and the scattering amplitude becomes

$$
\begin{equation*}
-1.91 \frac{4 \pi e^{2} \hbar^{2}}{m m_{0} c^{2}}\left\langle a^{\prime}, m_{s}^{\prime}\right| \boldsymbol{S}(-\boldsymbol{\kappa}) \cdot \boldsymbol{s}-[\boldsymbol{s} \cdot \hat{\boldsymbol{\kappa}}][\boldsymbol{S}(-\boldsymbol{\kappa}) \cdot \hat{\boldsymbol{\kappa}}]\left|a, m_{s}\right\rangle \tag{10.52}
\end{equation*}
$$

The cross section is given by

$$
\begin{align*}
\frac{d^{2} \sigma}{d \Omega^{\prime} d E^{\prime}}= & 4\left(\frac{1.91 e^{2}}{m c^{2}}\right)^{2} \sum_{\alpha, m_{s}} \sum_{\alpha^{\prime}, m_{s}^{\prime}} P_{\alpha} P_{m_{s}} \frac{k^{\prime}}{k}  \tag{10.53}\\
& \left.\times\left|\left\langle\alpha^{\prime}, m_{s}^{\prime}\right| \boldsymbol{s} \cdot \boldsymbol{S}(\boldsymbol{\kappa})-[\boldsymbol{s} \cdot \hat{\boldsymbol{\kappa}}][\boldsymbol{S}(\boldsymbol{\kappa}) \cdot \hat{\boldsymbol{\kappa}}]\right| \alpha, m_{s}\right\rangle\left.\right|^{2} \delta,(\text { energy })
\end{align*}
$$

Since the energy of the system does not depend on the neutron polarization, we may sum over $m_{s}^{\prime}$ to obtain

$$
\begin{align*}
\frac{d^{2} \sigma}{d \Omega^{\prime} d E^{\prime}}= & 4\left(\frac{1.91 e^{2}}{m c^{2}}\right)^{2} \sum_{\alpha, \alpha^{\prime}} P_{\alpha} \frac{k^{\prime}}{k} \\
& \times \sum_{\mu, \eta}\langle\alpha| S_{\nu}(\boldsymbol{\kappa})-\hat{\boldsymbol{\kappa}}_{\nu}[\boldsymbol{S}(\boldsymbol{\kappa}) \cdot \hat{\boldsymbol{\kappa}}]\left|\alpha^{\prime}\right\rangle\left\langle\alpha^{\prime}\right| S_{\mu}(-\boldsymbol{\kappa})-\hat{\boldsymbol{\kappa}}_{\mu}[\boldsymbol{S}(-\boldsymbol{\kappa}) \cdot \hat{\boldsymbol{\kappa}}]|\alpha\rangle \\
& \times \sum_{m_{s}} P_{m_{s}}\left\langle m_{s}\right| s_{\nu} s_{\mu}\left|m_{s}\right\rangle \delta \text { (energy) } . \tag{10.54}
\end{align*}
$$

Since

$$
\sum_{m_{s}} P_{m_{s}}\left\langle m_{s}\right| s_{\nu} s_{\mu}\left|m_{s}\right\rangle=\frac{1}{4} \delta_{\nu \mu},
$$

this becomes

$$
\begin{align*}
\frac{d^{2} \sigma}{d \Omega^{\prime} d E^{\prime}}= & \left(\frac{1.91 e^{2}}{m c^{2}}\right) \sum_{\mu, \nu}\left(\delta_{\nu \mu}-\hat{\kappa}_{\nu} \hat{\kappa}_{\mu}\right) \\
& \times \sum_{\alpha, \alpha^{\prime}} P_{\alpha} \frac{k^{\prime}}{k}\langle\alpha| S_{\nu}(\boldsymbol{\kappa})\left|a^{\prime}\right\rangle\left\langle\alpha^{\prime}\right| S_{\mu}(-\boldsymbol{\kappa})|\alpha\rangle \delta \text { (energy) } \tag{10.55}
\end{align*}
$$

Finally, we may incorporate the energy conservation into the matrix elements themselves by writing the delta function as

$$
\begin{equation*}
\delta(\text { energy })=\frac{1}{2 \pi} \int_{-\infty}^{\infty} d t \exp \left[i\left(\omega-E_{\alpha^{\prime}}+E_{\alpha}\right) t\right] \tag{10.56}
\end{equation*}
$$

where $\omega \equiv \hbar^{2}\left(k^{2}-k^{2}\right) / 2 m_{0}$. Then

$$
\begin{align*}
\frac{d^{2} \sigma}{d \Omega^{\prime} d E^{\prime}}= & \left(\frac{1.91 e^{2}}{m c^{2}}\right)^{2} \sum_{\mu, \nu}\left(\delta_{\nu \mu}-\hat{\kappa}_{\nu} \kappa_{\mu}\right) \frac{k^{\prime}}{k} \frac{1}{2 \pi} \int d t e^{i \omega t} \\
& \times \sum_{\alpha, \alpha^{\prime}} P_{\alpha}\langle\alpha| \exp (i \mathcal{H} t) S_{\nu}(\boldsymbol{\kappa}) \exp (-i \mathcal{H} t)\left|\alpha^{\prime}\right\rangle\left\langle\alpha^{\prime}\right| S_{\mu}(-\boldsymbol{\kappa})|\alpha\rangle . \tag{10.57}
\end{align*}
$$

The sum over $a^{\prime}$ may now be removed by closure. Furthermore, the sum over $\alpha$ is just what we mean by the thermal average. Therefore we have

$$
\begin{equation*}
\frac{d^{2} \sigma}{d \Omega^{\prime} d E^{\prime}}=\left(\frac{1.91 e^{2}}{m c^{2}}\right)^{2} \frac{k^{\prime}}{k} \sum_{\mu, \nu}\left(\delta_{\nu \mu}-\hat{\kappa}_{\nu} \hat{\kappa}_{\mu}\right) \frac{1}{2 \pi} \int d t e^{i \omega t}\left\langle S_{\nu}(\boldsymbol{\kappa}, t) S_{\mu}(-\boldsymbol{\kappa})\right\rangle \tag{10.58}
\end{equation*}
$$

It is convenient to separate the cross section into a Bragg part and a diffuse part:

$$
\begin{align*}
\left(\frac{d^{2} \sigma}{d \Omega^{\prime} d E^{\prime}}\right)_{\text {Bragg }}= & \left(\frac{1.91 e^{2}}{m c^{2}}\right)^{2} \sum_{\mu, \nu}\left(\delta_{\nu \mu}-\hat{\kappa}_{\nu} \hat{\kappa}_{\mu}\right) \delta(\omega)\left\langle S_{\nu}(\boldsymbol{\kappa})\right\rangle\left\langle S_{\mu}(-\boldsymbol{\kappa})\right\rangle  \tag{10.59}\\
\left(\frac{d^{2} \sigma}{d \Omega^{\prime} d E^{\prime}}\right)_{\text {diffuse }}= & \left(\frac{1.91 e^{2}}{m c^{2}}\right)^{2} \frac{k^{\prime}}{k} \sum_{\mu, \nu}\left(\delta_{\nu \mu}-\hat{\kappa}_{\nu} \hat{\kappa}_{\mu}\right) \frac{1}{2 \pi} \int d t e^{i \omega t} \\
& \times\left[\left\langle S_{\nu}(\boldsymbol{\kappa}, t) S_{\mu}(-\boldsymbol{\kappa})\right\rangle-\left\langle S_{\nu}(\boldsymbol{\kappa})\right\rangle\left\langle S_{\mu}(-\boldsymbol{\kappa})\right\rangle\right] \tag{10.60}
\end{align*}
$$

The operators $S_{\nu}(\boldsymbol{\kappa})$ entering the cross section are the Fourier transform of the spin density of the entire sample:

$$
\begin{equation*}
\boldsymbol{S}(\boldsymbol{\kappa})=\sum_{i} \exp \left(i \boldsymbol{\kappa} \cdot \boldsymbol{R}_{i}\right) \boldsymbol{s}_{i} \tag{10.61}
\end{equation*}
$$

The unpaired electrons on a given site will form a total spin $\boldsymbol{S}_{n}$ according to Hund's rule. The Wigner-Eckart theorem tells us that a matrix element of the form $\left\langle\alpha^{\prime}\right| s_{i}|\alpha\rangle$ is proportional to $\left\langle\alpha^{\prime}\right| \boldsymbol{S}_{n}|\alpha\rangle$. Thus

$$
\begin{equation*}
\left\langle a^{\prime}\right| \boldsymbol{S}(\boldsymbol{\kappa})|a\rangle=\sum_{\text {site } n} e^{-i \boldsymbol{\kappa} \cdot \boldsymbol{n}} f(\boldsymbol{\kappa})\left\langle\alpha^{\prime}\right| \boldsymbol{S}_{n}|\alpha\rangle . \tag{10.62}
\end{equation*}
$$

The coefficient of proportionality $f(\boldsymbol{\kappa})$ is the Fourier transform of the normalized spin density associated with the $n$th site and is referred to as the magnetic form factor.

In the paramagnetic state the magnetic Bragg contribution vanishes, leaving only the diffuse scattering:

$$
\begin{align*}
\left(\frac{d^{2} \sigma}{d \Omega^{\prime} d E^{\prime}}\right)_{\text {diffuse }}= & \left(\frac{1.91 e^{2}}{m c^{2}}\right)^{2}|f(\boldsymbol{\kappa})|^{2} \frac{k}{k^{\prime}} \sum_{\mu, \nu}\left(\delta_{\mu \nu}-\hat{\kappa}_{\mu} \hat{\kappa}_{\nu}\right)  \tag{10.63}\\
& \sum_{n, m} \exp [i \boldsymbol{\kappa} \cdot(\boldsymbol{n}-\boldsymbol{m})] \frac{1}{2 \pi} \int d t \exp (i \omega t)\left\langle S_{n, \nu}(t) S_{m, \mu}\right\rangle
\end{align*}
$$

In a paramagnet without exchange, we can integrate over the energy with the result that the diffuse peak becomes an elastic peak with a cross section

$$
\begin{equation*}
\left(\frac{d \sigma}{d \Omega^{\prime}}\right)_{\text {diffuse }}=N\left(\frac{1.91 e^{2}}{m c^{2}}\right)^{2}|f(\boldsymbol{\kappa})|^{2} \frac{2}{3} S(S+1) \tag{10.64}
\end{equation*}
$$

The angular dependence of this cross section enables us to determine the magnetic form factor.

Let us now consider the cross sections in ordered magnetic systems.

### 10.3.1 Bragg Scattering

Let us assume that in the ordered state, the moments are aligned along the $z$-axis,

$$
\left\langle S_{m, \nu}\right\rangle=\left\langle S_{z}\right\rangle \delta_{\nu z} .
$$

The cross section then becomes

$$
\begin{equation*}
\frac{d \sigma}{d \Omega^{\prime}}=\left(\frac{1.91 e^{2}}{m c^{2}}\right)^{2}|f(\boldsymbol{\kappa})|^{2}\left(1-\hat{\kappa}_{z}^{2}\right)\left\langle S^{z}\right\rangle^{2} \sum_{n, m} \exp [i \boldsymbol{\kappa} \cdot(\boldsymbol{n}-\boldsymbol{m})] . \tag{10.65}
\end{equation*}
$$

Or, from (10.17),

$$
\begin{equation*}
\left(\frac{d \sigma}{d \Omega^{\prime}}\right)_{\text {Bragg }}=\frac{(2 \pi)^{3} N}{V_{0}}\left(\frac{1.91 e^{2}}{m c^{2}}\right)^{2}\left\langle S^{z}\right\rangle^{2} \sum_{G}|f(\boldsymbol{G})|^{2}\left(1-G_{z}^{2}\right) \delta(\boldsymbol{\kappa}-\boldsymbol{G}), \tag{10.66}
\end{equation*}
$$

where $\boldsymbol{G}$ is a vector in the magnetic reciprocal lattice. Thus we see that this cross section consists of peaks at positions determined by the magnetic structure. Furthermore, the amplitudes of these peaks are proportional to the magnetic form factor.

As an example of Bragg scattering let us consider the spin arrangements in $\mathrm{MnF}_{2}$. Chemically, this crystal has the body-centered tetragonal lattice shown in Fig. 2.2. The unit cell has six ions at the following locations:

Mn:

$$
(0,0,0) \quad\left(\frac{a}{2}, \frac{a}{2}, \frac{c}{2}\right)
$$

F:

$$
\begin{array}{cc}
(a u, a u, 0) & (a-a u, a-a u, 0) \\
\left(\frac{a}{2}+a u, \frac{a}{2}-a u, \frac{c}{2}\right) & \left(\frac{a}{2}-a u, \frac{a}{2}+a u, \frac{c}{2}\right) .
\end{array}
$$

The reciprocal lattice vectors are given by

$$
\begin{equation*}
\boldsymbol{G}=2 \pi\left(\frac{l}{a}, \frac{m}{a}, \frac{n}{c}\right) \tag{10.67}
\end{equation*}
$$

where $l, m$, and $n$ are integers, and $u=0.31$. The unit cell structure factor for nuclear scattering is

$$
\begin{align*}
\mathrm{F}(\boldsymbol{G}) & =\sum_{i=1}^{r}\left\langle b_{i}\right\rangle \exp \left(i \boldsymbol{G} \cdot \boldsymbol{\rho}_{i}\right)  \tag{10.68}\\
& = \begin{cases}2\langle b\rangle_{\mathrm{Mn}}+4\langle b\rangle_{\mathrm{F}} \cos (2 \pi u l) \cos (2 \pi u m) & l+m+n=\text { even } \\
-4\langle b\rangle_{\mathrm{F}} \sin (2 \pi u l) \sin (2 \pi u m) & l+m+n=\mathrm{odd}\end{cases}
\end{align*}
$$

The experimental scattering intensity at a temperature above the magnetic ordering temperature is shown in Fig. 10.4b. Notice that there are no peaks corresponding to [100] and [001], in accordance with (10.69). Figure 10.4a shows that the scattering intensity in the magnetically ordered state. We


Fig. 10.4. Neutron diffraction pattern for $\mathrm{MnF}_{2}$ in (a) the antiferromagnetic state $(23 \mathrm{~K})$ and (b) the paramagnetic state ( 300 K ) [244]
immediately notice the presence of additional peaks. These are magnetic peaks. Since they can be indexed in the same way as the nuclear peaks, the magnetic unit cell is the same as the chemical unit cell. By their mere existence these peaks tell us that the spin density is different from the electronic charge density; this is, the spin arrangement is not ferromagnetic. Since there are two magnetic ions in the unit cell, we try an antiferromagnetic arrangement. This introduces a sign change into the magnetic form factor. If the up spins are on the corners of the unit cell and the down spins are at the centers, the magnetic structure factor is

$$
F_{M}(\boldsymbol{G})=\sum_{i}( \pm)_{i} \exp \left(i \boldsymbol{G} \cdot \boldsymbol{\rho}_{i}\right)=1-e^{i \pi(l+m+n)}= \begin{cases}0 & l+m+n=\text { even }  \tag{10.69}\\ 2 l+m+n=\text { odd }\end{cases}
$$

We see that a peak is expected at [100], as observed in Fig. 10.4a. However, we also expect one at [001]. The fact that this is not observed indicates that the spins are oriented in this direction since the factor $1-\hat{\kappa}_{z}^{2}$ then vanishes.

Izuyama et al. [245] have shown that in a metal the Bragg scattering cross section is essentially the same as that give by (10.66), except that $\left\langle S^{z}\right\rangle^{2}$ is replaced by $\left(N_{\uparrow}-N_{\downarrow}\right)^{2}$, where $N_{\sigma}$ is the total number of electrons with spin $\sigma$.

Neutron scattering is also particularly useful in studying structures which are not commensurate with the crystal lattice. The rare-earth metals listed in Fig. 4.3, for example, exhibit a variety of incommensurate structures. These were all determined by neutron scattering.

An interesting study of incommensurate structures is found in MnP. This orthorhombic material is ferromagnetic below 291 K , with an additional magnetic phase transition at 50 K . The lower temperature phase is characterized by a spiral spin structure with a wave vector along the $\alpha$-axis. Application of a magnetic field along the $b$-axis produces a fan structure with a periodicity governed by $\boldsymbol{q}=2 \pi(\delta / a) \boldsymbol{A}$. Figure 10.5 shows the phase diagram of MnP [246].

The point at which the three phases meet was recognized as a possible Lifshitz point. This particular multicritical point is characterized by three features: (1) it is the meeting point of three phases: a paramagnetic phase, an ordered phase whose order parameter has a fixed wave vector (zero in the ferromagnetic case), and an ordered phase (the fan phase) whose wave vector varies continuously with the thermodynamic variables; (2) the transitions from the paramagnetic phase to both ordered phases must be second order; and (3) the wave vector in the fan phase must approach zero continuously as the Lifshitz point is approached.

Neutron scattering was essential in verifying the last condition. Figure 10.6 shows a triple-axis scan through the (200) position of MnP , indicating the magnetic satellites due to the fan structure. The smooth decrease of $\delta$ to zero as shown in the insert in Fig. 10.5 confirms that this is indeed a Lifshitz point [247].


Fig. 10.5. Phase diagram of MnP near the Lifshitz point. The magnetic field is parallel to the $b$-axis. The insert shows the temperature dependence of the fan wave vector along the fan-para phase boundary

From the amplitudes of the Bragg peaks we obtain the magnetic form factor $f(\boldsymbol{\kappa})$. The experimental values for $f(\boldsymbol{\kappa})$ for metallic iron are shown in Fig. 10.7. The arrows indicate pairs of reflections for which the scattering angle is the same for the pair. Since the experimental errors are indicated by the size of the circles, these pairs tell us that the form factor, and hence the spin density, is not spherically symmetric. The curves are the theoretical results of a Hartree-Fock calculation which includes exchange effects by Watson and Freeman. The deviations from these spherical calculations are also apparent. By Fourier transforming such data it is possible to construct a spin-density "contour map" of the unit cell. This is illustrated for iron in Fig. 10.8.

Thus we find that from the Bragg scattering we can obtain information about the static magnetic state of the crystal-the spin configuration and the spin-density distribution as well as temperature and field dependence of the magnetic moment. Let us now turn to the diffuse-scattering contribution. We shall find that this contains information about the dynamic properties of the system-spin waves and critical fluctuations.


Fig. 10.6. An elastic triple-axis scan through the (200) position of MnP showing first- and second-order magnetic satellites. Note that the central (200) peak is shown on a reduced scale


Fig. 10.7. Comparison between experimental and calculated values of the magnetic form factor for iron. The solid curve is that calculated for the spherically symmetric free atom [248]


Fig. 10.8. Model of the magnetization distribution in the body-centered-cubic unit cell of iron. The concentration of the very large positive $3 d$-shell magnetization along the cube edges is overemphasized to show its relationship to the negative magnetization ring [249]

### 10.3.2 Spin Dynamics

Let us consider the diffuse-scattering cross section (10.60). The sum over $\nu$ and $\mu$ enables us to replace $\left\langle S_{\nu}(\boldsymbol{\kappa}, t) S_{\mu}(-\boldsymbol{\kappa})\right\rangle$ by the correlation function $\left\langle\left\{S_{\nu}(\boldsymbol{\kappa}, t) S_{\mu}(-\boldsymbol{\kappa})\right\}\right\rangle$. In deriving the fluctuation-dissipation theorem, (1.87), we neglected long-range order. When this is included, the correlation function in (1.87) is identical to the quantity in brackets in (10.60). Therefore,

$$
\begin{align*}
\left(\frac{d^{2} \sigma}{d \Omega^{\prime} d E^{\prime}}\right)_{\text {diffuse }}= & \left(\frac{1.91 e^{2}}{m c^{2}}\right)^{2} \frac{k^{\prime}}{k} \sum_{\mu, \nu}\left(\delta_{\nu \mu}-\hat{\kappa}_{\nu} \hat{\kappa}_{\mu}\right) \\
& \times\left(1 / \pi g^{2} \mu_{B}^{2}\right) \hbar V \operatorname{coth}(\beta \hbar \omega / 2) \chi_{\nu \mu}^{\prime \prime}(\kappa, \omega)_{s} \tag{10.70}
\end{align*}
$$

The importance of the generalized susceptibility has been emphasized throughout this text. Now we see that the diffuse scattering of neutrons provides us with a direct measure of this quantity. This is why neutron scattering plays such an important role in magnetism.

The susceptibility appearing in (10.70) is the susceptibility associated with the total spin density of the system. In deriving explicit expressions from this quantity we have assumed throughout that the spin density was either localized or completely itinerant. This gave us what we might call a reduced susceptibility. In order to apply these results, we must relate this reduced
susceptibility to the total susceptibility. From (10.62) it readily follows that for localized spins

$$
\begin{equation*}
\chi(\boldsymbol{q}, \omega)_{\text {total }}=|f(\boldsymbol{q})|^{2} \chi(\boldsymbol{q}, \omega)_{\text {reduced }} \tag{10.71}
\end{equation*}
$$

where $f(\boldsymbol{q})$ is the atomic magnetic form factor.
The corresponding relation for an itinerant system is essentially the same. To see this, let us second quantize the magnetic-moment operator in terms of Bloch states. The field operator (1.115) then becomes

$$
\begin{equation*}
\psi(\boldsymbol{r})=\frac{1}{\sqrt{V}} \sum_{\boldsymbol{k}, \sigma} e^{i \boldsymbol{k} \cdot \boldsymbol{r}} u_{\boldsymbol{k}}(\boldsymbol{r}) \eta_{\sigma} c_{\boldsymbol{k} \sigma} . \tag{10.72}
\end{equation*}
$$

The Bloch function may be expanded in terms of the Wannier functins introduced in (2.78) as

$$
\begin{equation*}
e^{i \boldsymbol{k} \cdot \boldsymbol{r}} u_{\boldsymbol{k}}(\boldsymbol{r})=\sum_{\alpha} e^{i \boldsymbol{k} \boldsymbol{R}_{\alpha}} \phi\left(\boldsymbol{r}-\boldsymbol{R}_{\alpha}\right) . \tag{10.73}
\end{equation*}
$$

In terms of these functions the field operator may be written

$$
\begin{equation*}
\psi(\boldsymbol{r})=\frac{1}{\sqrt{V}} \sum_{\boldsymbol{k}, \sigma} \sum_{\alpha} e^{i \boldsymbol{k} \cdot \boldsymbol{R}_{\alpha}} \phi\left(\boldsymbol{r}-\boldsymbol{R}_{\alpha}\right) \eta_{\sigma} c_{\boldsymbol{k} \sigma} \tag{10.74}
\end{equation*}
$$

The magnetization operator is

$$
\begin{equation*}
\mathcal{M}(\boldsymbol{r})=-\mu_{B} \psi^{\dagger}(\boldsymbol{r}) \sigma \psi(\boldsymbol{r}) . \tag{10.75}
\end{equation*}
$$

Using (10.74) and taking the Fourier transform we obtain, for example,

$$
\begin{equation*}
\mathcal{M}_{+}(\boldsymbol{q})=-2 \mu_{B} \sum_{\boldsymbol{k}} F(\boldsymbol{q}, \boldsymbol{k}) c_{\boldsymbol{k}-\boldsymbol{q}, \uparrow}^{\dagger} c_{\boldsymbol{k} \downarrow} \tag{10.76}
\end{equation*}
$$

where

$$
\begin{equation*}
F(\boldsymbol{q}, \boldsymbol{k}) \equiv \frac{N}{V} \sum_{l} e^{-\boldsymbol{k} \cdot \boldsymbol{l}} \int d \boldsymbol{r} e^{-i \boldsymbol{q} \cdot \boldsymbol{r}} \phi^{*}(\boldsymbol{r}) \phi(\boldsymbol{r}+\boldsymbol{l}) \tag{10.77}
\end{equation*}
$$

Here $\boldsymbol{l}$ is the vector connecting lattice sites, that is, $\boldsymbol{l}=\boldsymbol{R}_{\alpha}-\boldsymbol{R}_{\alpha^{\prime}}$. Since the Wannier function $\phi\left(\boldsymbol{r}-\boldsymbol{R}_{\alpha}\right)$ is strongly peaked around the site $\boldsymbol{R}_{\alpha}$, the dominant contribution to (10.72) arises from the $\boldsymbol{l}=0$ term. The function $F(\boldsymbol{q}, \boldsymbol{k})$ is then independent of $\boldsymbol{k}$. By comparing $\mathcal{M}_{+}(\boldsymbol{q})$ in this case to the free-electron expression, we again obtain the relation (10.71).

Spin-Wave Scattering. There are several applications of diffuse scattering which are particularly interesting. One is the very low temperature region where one has inelastic spin-wave scattering. As we saw in Chap. 8, the susceptibilities of both localized spin systems and metals contain poles which correspond to spin-wave excitations. Therefore at low temperatures the differential diffuse-scattering cross section is proportional to $|f(\boldsymbol{q})|^{2} \delta(\omega-\omega \boldsymbol{q})$.


Fig. 10.9. Antiferromagnetic spin-wave dispersion in $\mathrm{MnF}_{2}$ at 4.2 K observed by neutron inelastic scattering. The solid lines are obtained from spin-wave theory, with the parameters $J_{1}=0.32 \mathrm{~K}$ (ferromagnetic), $J_{2}=-1.76 \mathrm{~K}$ (antiferromagnetic), $J_{3}=0 \mathrm{~K}$, and an anisotropy field $H_{A}=1.06 \mathrm{~K}$ (at zero wave vector) [250]

By measuring the energy loss of those neutrons scattered at direction $\boldsymbol{q}$ with respect to the incident beam we can thus obtain the spin-wave spectrum. The spin-wave spectrum of the antiferromagnet $\mathrm{MnF}_{2}$ obtained in this way is shown in Fig. 10.9. An example of a metallic spin-wave spectrum which also reveals the presence of phonons is that of the rate earth terbium, shown in Fig. 10.10. We saw in Sect. 7.1 that the exchange interaction between localized moments in rare-earth metals arises through the conduction electrons and therefore depends upon the band structure. Thus from a spin-wave spectrum such as that shown in Fig. 10.10 we can obtain information about the band structure.
Critical Scattering. Diffuse scattering is also interesting in the vicinity of the magnetic phase transition. At the Curie point the Bragg peak transforms to a sharply peaked diffuse intensity, and then when the temperature in increased this diffuse intensity spreads out to approach the paramagnetic limit. The temperature dependence of diffuse scattering at a fixed angle is dramatically illustrated in Fig. 10.11. This is what is referred to as critical scattering.

The origin of this critical scattering in a localized spin system is contained in our result (4.12). The quantity measured is $d \sigma / d \Omega^{\prime}$, obtained by integrating (10.70) over $\omega$. If we assume that the major frequency response occurs for frequencies below $k_{B} T / \hbar$, then $d \sigma / d \Omega^{\prime}$ is proportional, by the Kramers-Kronig relation (1.64), to the static susceptibility $\chi(\boldsymbol{q})$. In the vicinity of a Bragg peak momentum transfer is very small. In the limit $q \rightarrow 0$ the susceptibility


Fig. 10.10. Neutron excitation energies in the $c$ direction of $\mathrm{Tb}-10 \%$ Ho at 110 K . The scan used for these measurements was such that transverse phonons were not observed [251]


Fig. 10.11. Critical scattering by Ni. Curve gives total intensity of $4.75-\AA \AA^{\text {n }}$ neutrons scattered at an angle of $2^{\circ}$ [252]
(4.12), and hence the cross section, varies as $\left(\kappa^{2}+\boldsymbol{q}^{2}\right)^{-1}$, where $\kappa$ is given by (4.49). Therefore the critical scattering should increase, in the mean field approximation, as $\left(T-T_{c}\right)^{-1}$. The correlation-range parameter $\kappa^{2}$ is found to diverge more like $\left(T-T_{c}\right)^{-4 / 3}$, which is in agreement with a more sophisticated theoretical treatment of the correlation function.

In principle, we can measure $\chi(\boldsymbol{q}, \omega)$ for every point in Fourier space and for all temperatures. An example of this is the work of Lowde and coworkers on nickel [253]. Such results enable us to study the complete evolution of the magnetic state.
Diffuse Elastic Scattering. Finally, let us mention the use of diffuse scattering to study binary alloys. Shull and Wilkinson [254] were among the first to employ neutrons in the fashion. Consider an alloy containing $N_{1}=c N$ atoms of type 1 and $N_{2}=(1-c) N$ atoms of type 2 . If we assume that all atoms of type 1 have a moment $\mu_{1}$, independent of their environment, while all atoms of type 2 have a moment $\mu_{2}$, then the elastic diffuse cross section becomes

$$
\begin{equation*}
\left(\frac{d \sigma}{d \Omega^{\prime}}\right)_{\text {diffuse }}=\frac{N}{4}\left(\frac{1.91 e^{2}}{m c^{2}}\right)^{2}\left(1-\kappa_{z}^{2}\right) c(1-c)\left[f_{1}(\boldsymbol{\kappa}) \mu_{1}-f_{2}(\boldsymbol{\kappa}) \mu_{2}\right] \tag{10.78}
\end{equation*}
$$

Marshall [255] extended this formula to include environmental effects. From an analysis of the elastic diffuse scattering one can obtain the moments and their form factors. In Ni-Cu alloys, for example, Medina and Cable [256] found that the reduction in the net moment of the alloy is associated with a negative polarization of the Ni sites, and that there is no polarization of the Cu atoms.

### 10.4 Example: Manganese Oxides

Neutron scattering has proven particularly useful in illuminating the magnetic properties of the manganese oxides, or "manganites", $\mathrm{AMnO}_{3}$ where $\mathrm{A}=\mathrm{La}, \mathrm{Ca}, \mathrm{Ba}, \mathrm{Sr}, \mathrm{Pb}, \mathrm{Nd}$, or Pr. In $\mathrm{LaMnO}_{3}$ the manganese is trivalent, $\mathrm{Mn}^{3+}$, with a $\mathrm{d}^{4}$ configuration. In a cubic crystal field the energy levels have the form shown on the left in Fig. 10.12. An orthorhombic distortion splits these states as shown on the right. If the resulting gain in electronic energy exceeds the elastic energy system will spontaneously distort. This is known as a coopertative Jahn-Teller distortion. $\mathrm{LaMnO}_{3}$ is indeed an orthorhombic insulating antiferromagnet with a Néel temperature $T_{N}=140 \mathrm{~K}$. In $\mathrm{CaMnO}_{3}$ the manganese is tetravalent, $\mathrm{Mn} 4+. \mathrm{CaMnO}_{3}$ has the cubic perovskite structure and is also an antiferromagnetic insulator.

What makes the manganites so interesting is when $A$ consists of a mixture of trivalent and divalent ions, such as $\mathrm{La}^{3+}$ and $\mathrm{Ca}^{2+}$. This results in the presence of both $\mathrm{Mn}^{3+}$ and $\mathrm{Mn}^{4+}$ with very interesting electrical properties. Figure 10.13 , for example shows the resistivity as a function of temperture for $\mathrm{La}_{0.67} \mathrm{Ca}_{0.33} \mathrm{MnO}_{3}$. We see that there is a metal-insulator transition as a function of temperature and a large magnetoresistance. These materials are


Fig. 10.12. Splitting of the $e_{g}$ and $t_{z g}$ orbitals as the result of a Jahn-Teller distortion. (After [257])


Fig. 10.13. Resistivity of $\mathrm{La}_{0.67} \mathrm{Ca}_{0.33} \mathrm{MnO}_{3}$ thin film as a function of temperature [258]
referred to as "colossal" magnetoresistance oxides. Magnetization measurements indicate that $\mathrm{La}_{0.67} \mathrm{Ca}_{0.33} \mathrm{MnO}_{3}$ is ferromagnetic below $T_{c}=257 \mathrm{~K}$.

What makes this system so interesting and, at the same time, so challenging, is the interplay among the charge, the magnetic, and the lattice (orbital) degrees of freedom. J.W. Lynn and his colleagues have made extensive neutron measurements using a triple-axis spectrometer on $\mathrm{La}_{0.7} \mathrm{Ca}_{0.3} \mathrm{MnO}_{3}$ and related materials in an effort to understand their properties [259].

Figure 10.14 shows the diffuse magnetic scattering as a function of energy at a momentum transfer of $\boldsymbol{q}=(0.09,0,0)$ (the nuclear incoherent scattering has been subtracted out). This magnetic fluctuation spectrum shows spinwave peaks at $\pm 2 \mathrm{meV}$ as well as a quasielastic peak centered at $E=0$. What makes this peak unusual is that if one fits the intensity of this peak to a Lorentzian shape, $I \sim\left(q^{2}+\kappa^{2}\right)^{-1}$ the correlation length $\xi\left(=\frac{1}{\kappa}\right)$ does not


Fig. 10.14. Constant-Q scan taken at $T=240 \mathrm{~K}$, well below Curie temperature of $T_{c}=257 \mathrm{~K}$, at a reduced wave vector of $(0.09,0,0)$


Fig. 10.15. Temperature dependence of the central peak in Fig. 10.14 and the satellite peaks compared with the resistivity. The data has been scaled so the peak heights match
diverge as one approaches $\mathrm{T}_{c}$ from above as it would for a conventional ferromagnet. Another interesting revelation from the neutron measurements is the development of nuclear peaks above $\mathrm{T}_{c}$ at the non-Bragg locations $\left(\frac{1}{4}, \frac{1}{4}, 0\right)$. The intensities of these satellite lines as well as the central peak in the magnetic spectrum have the same temperature dependence as the resistivity as shown in Fig. 10.15.

These neutron results, combined with the electrical and magnetic measurements [260] lead to the following picture. At low temperatures the material is a ferromagnetic metal. The "extra" electron on a $\mathrm{Mn}^{3+}$ hops freely to a neighboring $\mathrm{Mn}^{4+}$. This gives rise to the ferromagnetism through the double exchange mechanism discussed in Sects. 2.2.10. At high temperatures there is a Jahn-Teller distortion that traps the $\mathrm{e}_{g}$ electron forming a "small polaron". This gives a hopping conductivity with an activation energy of the order of


Fig. 10.16. Orbital ordering


Fig. 10.17. Field dependence of the intensity of the satellite peaks associated with the polaron-polaron correlations
$1000 \mathrm{~K}_{B}$ [258]. At a Ca concentration of the order of $\frac{1}{3}$ the polarons interact with each other through the Coulomb interaction which leads to ordering of both the $\mathrm{Mn}^{3+}$, i.e., charge ordering, as well as ordering of the direction of the $\mathrm{e}_{g}$ orbitals, i.e., orbital ordering. It is this ordering that gives rise to the $\left(\frac{1}{4}, \frac{1}{4}, 0\right)$ peaks. An illustration of the sort of ordering that might occur is shown in Fig. 10.16. Notice that this ordering produces charge stripes running along the $(1,1,0)$ diagonal. The intensity of the $\left(\frac{1}{4}, \frac{1}{4}, 0\right)$ satellite peaks decreases with magnetic field as shown in Fig. 10.17. The alignment of the spins makes it easier for the $\mathrm{e}_{g}$ electrons to hop onto neighboring $\mathrm{Mn}^{4+}$ sites destroying the order. This also reduces the resistivity giving rise to the colossal magnetoresistance.

### 10.5 Example: Quantum Phase Transitions

Another example where neutron scattering plays a critical role is that of identifying the mechanism responsible for magnetic field-induced transitions in certain magnetic insulators.

The magnetic phase transitions we described in Sect. 4.5 were characterized by a coherence length $\xi$ which diverged as one approaches the transition temperature from above. As these "islands" of long range order grow the spins within them will remain ordered longer and longer. That is, their fluctuation frequency, $\omega_{f}$ will become smaller and smaller. This is referred to as "critical slowing down". If the transition occurs at a finite temperature, Tc, then there will always come a point at which these characteristic fluctuations $\hbar \omega_{f}$ become less than the thermal fluctuations, $\mathrm{k}_{B} \mathrm{~T}_{c}$. In such case the critical behavior is always governed by the thermal fluctuations and we refer to these transitions as "classical". At $T=0$, on the other hand, it is possible to envision a situation where one can induce a transition by varying some parameter of the system, such as the strength of the exchange interaction. In such a transition the zero-point, or quantum, fluctuations dominate and we refer to these as quantum phase transitions. It turns out that a vestige of such transitions extends into the finite temperature regime where they can be studied.

A good example of a quantum phase transition is found in $\mathrm{TlCuCl}_{3}$. The phase diagram for this material is shown in Fig. 10.18. At low magnetic fields the material is magnetically not ordered. Some refer to this as a quantum spin liquid. Above a critical field the material has a uniform magnetization parallel to the field as well as antiferromagnetic ordering perpendicular to the field. What is happening as one increases the field at $T \simeq 0$ ?

The crystal structure of $\mathrm{TlCuCl}_{3}$ consists of coupled two-leg ladders with rungs formed by pairs of $\mathrm{Cu}^{2+}$ ions. The $S=\frac{1}{2}$ spins of these ions are coupled by an antiferromagnetic exchange along the rungs leading to dimers with singlet ground states and triplet excited states. The singlet wavefunction has


Fig. 10.18. The phase diagram of $\mathrm{TlCuCl}_{3}[261]$
the form $(|\uparrow \downarrow\rangle-|\downarrow \uparrow\rangle) / \sqrt{2}$, i.e. $S=0$. There are weaker exchange couplings along the legs of the ladders and between ladders, but the quantum fluctuations inherent in the singlet state of the dimer prevent long range magnetic order even at $\mathrm{T}=0$. The additional exchange interactions lead to propagation of the $S=1$ triplet states among the dimers with dispersion as shown in Fig. 10.19. When a magnetic field is applied the triplet states split as shown by the neutron data in Fig. 10.20. The lowest component at $\boldsymbol{Q}=(0,0,2 \pi)$ "goes soft" at $\mathrm{H}_{c}=5.6 \mathrm{~T}$. When one of these triplet "magnons" is excited it creates magnetization in the transverse direction. This is different from the magnons described in Chap. 8 which decrease the magnetization. Because these magnons are bosons, and because the transverse magnetization above $\mathrm{H}_{c}$ is macroscopic this has led some to suggest that the transition at $\mathrm{H}_{c}$ is a Bose-Einstein condensation (BEC) $[265,266]$.

One piece of evidence that the field-induced transition is associated with Bose condensation comes from the shape of the phase boundary in Fig. 10.18. Since, in our case, we cannot have more than one triplet on a site, we have a Bose system with hard core interactions. It is this feature that limits the number of triplet bosons and makes it possible to introduce a chemical potential,


Fig. 10.19. Zero-field triplet dispersion relations for $\mathrm{TlCuCl}_{3}$ at $T=1.5 \mathrm{~K}[262]$


Fig. 10.20. Field dependence of the energy gap of the three magnon modes in $\mathrm{TlCuCl}_{3}$. Points are data from the neutron experiment of [267] and [269], and solid lines the results of thoery [264]. Inset: field dependence at high fields
$\mu=g \mu_{B}\left(H-H_{c}\right)$. Ordinary magnons, like photons and phonons, have zero chemical potential [268]. It can be shown that the value of the chemical potential at which Bose condensation occurs for such a system varies with temperature as $\mathrm{T}^{\frac{3}{2}}$. This implies that $H_{c}(T)-H(0) \sim \mathrm{T}^{\frac{3}{2}}$. In Fig. 10.18 we see that the boundary varies as $\mathrm{T}^{2.2}$. A later analysis of the experimental data down to lower temperatures shows that the critical exponent is consistent with the predicted value of $3 / 2$ [263]. In our discussion of classical phase transitions we mentioned that different systems may be characterized by the same critical exponents, defining a "universality class". Thus, proponents of the BEC model would say that $\mathrm{TlCuCl}_{3}$ belongs to the Bose-Einstein condensation universality class.

Neutron scattering provides additional evidence for the existence of Bose condensation. As mentioned above, the theory of the field-induced condensate [264] predicts a transverse staggered magnetization. If the low field phase has rotational symmetry, i.e., $0(z)$, then the transition involves breaking this symmetry. As we described in Sect. 4.5, one of the consequences of a broken symmetry is the appearance of modes associated with variations in the order parameter, Goldstone modes. In the case of $\mathrm{TlCuCl}_{3}$ this Goldstone mode is predicted to be a phase mode with zero energy gap and a linear wavevector dependence, i.e., a rotation of the ordered moment in the plane perpendicular to the field. Figure 10.21 shows the inelastic neutron scattering results around the Bragg point (0,4, 0). Rüegg et al. [269] suggest that $\omega \rightarrow 0$ as $k \rightarrow 0$, consistent with a Goldstone mode. However, the data does not extend below 0.2 meV . Glazkov et al. [270] have carried out magnetic resonance measurements in the range $9-80 \mathrm{GHz}$ and found a gap of 0.08 meV for this field geometry. This indicates that the system has an anisotropy of the order of $1 \%$ of the exchange and is not completely rotationally symmetric. This would argue against a BEC. There are other dimeric copper systems


Fig. 10.21. Energy dispersion of low-lying magnetic excitations in $\mathrm{TlCuCl}_{3}[269]$
that exhibit signature of a magnon BEC . In particular, $\mathrm{BaCuSiO}_{6}$ [273] and $\mathrm{Cs}_{2} \mathrm{CuCl}_{4}[274]$ are other good candidates.

This quantum phase transition can also be induced by pressure. In this case the full $0(3)$ symmetry is broken with the result that one expects two degenerate Goldstone modes and a characteristic amplitude mode related to the condensate [271]. Evidence for such modes have been reported by Rüegg et al. [272] in inelastic neutron scattering performed on a triple-axis spectrometer at the Swiss spallation neutron source.

## References

## Chapter 1

1. J.H. Van Vleck, "The Theory of Electric and Magnetic Susceptibilities". Chaps. 1 and 4 (Oxford University Press, London 1932)
2. J.D. Jackson, "Classical Electrodynamics". 3rd edn. (John Wiley \& Sons, New York 1999) Sect. 6.6
3. J.D. Jackson, "Classical Electrodynamics". 3rd edn. (John Wiley \& Sons, New York 1999) Sect. 5.16
4. C. Kittel, "Thermal Physics". (John Wiley \& Sons, New York 1969) Sect. 23
5. See, for example, K. Huang, "Statistical Mechanics". 2nd edn. (Wiley, New York 1987)

## Chapter 2

6. L.I. Schiff: Quantum Mechanics. 3rd edn. (McGraw-Hill, New York 1968) Chap. 8
7. J.D. Bjorken, S.D. Drell: Relativistic Quantum Mechanics (McGraw-Hill, New York 1965) Chap. 4
8. A. Abragam: The Principles of Nuclear Magnetism (Oxford University Press, London 1961) p. 165
9. C.P. Slichter: Principles of Magnetic Resonance. 2nd edn. Springer Series in Solid-State Sciences, Vol. 1 (Springer, Berlin Heidelberg New York 1980) Chap. 9
10. J.S. Griffiths: The Theory of Transition-Metal Ions (Cambridge University Press, Cambridge 1961)
11. C.J. Ballhausen: Introduction to Ligand Field Theory (McGraw-Hill, New York 1962)
12. M.T. Hutchings: "Point-Charge Calculations of Energy Levels of Magnetic Ions in Crystalline Electric Fields". In Solid State Physics, Vol. 16, ed. by F. Seitz, D. Turnbull (Academic Press, New York 1964)
13. M. Tinkham: Group Theory and Quantum Mechanics (McGraw-Hill, New York 1964)
14. C. Herring: In Magnetism, Vols. IIB, IV, ed. by G. . Rado, H. Suhl (Academic Press, New York 1966)
15. W. Heitler, F. London, Z. Phys. 44, 455 (1927)
16. J.H. Van Vleck, Rev. Univ. Nac Tucuman Ser. A 14, 189 (1962)
17. J.B. Goodenough: Magnetism and the Chemical Bond (Interscience, New York 1963) Chap. 3
18. J. Kanamori, Phys. Chem. Solids 10, 87 (1959)
19. K. Ueda, H. Tabata, T. Kawai, Science 280, 1064 (1998)
20. P.W. Anderson: In Magnetism, Vol. I, ed. by G.T. Rado, H. Suhl (Academic Press, New York 1963)
21. P.J. Hay, J.C. Thibeault, R. Hoffmann, J. Am. Chem. Soc. 974884 (1975)
22. R.D. Willett, C.P. Landee, J. Appl. Phys. 52, 2004 (1981)
23. H.G. Bohn, W. Zinn, B. Dorner, A. Kollmar, J. Appl. Phys., 2228 (1981)
24. H.M. Mc Connell: Proc. Robert Welch Foundation Conference on Chemical Research, Houston, Texas (1968) p. 144
25. J.S. Miller, A.J. Epstein, Angew. Chem. Int. Ed. Engl. 33, 385 (1994)
26. C. Zener, Phys. Rev. 82, 403 (1951)
27. P.W. Anderson, H. Hasegawa, Phys. Rev. 100, 675 (1955)
28. P.-G. deGennes, Phys. Rev. 18, 141 (1960)
29. C.F. Hirjibehedin, C.P. Lutz, and A.J. Heinrich, Science 312, 1021 (2006)
30. J.W. Corbett, G.D. Watkins, Phys. Rev. Lett. 1, 314 (1961)
31. D.K. Biegelsen: Nuclear and Electron Resonoance Spectroscopies Applied to Materials Science. Materials Research Society Symposia Proceedings, Vol. 3 (Elsevier, North-Holland, Amsterdam 1981) p. 85
32. M. Tachiki, J. Phys. Soc. Jpn. 25, 686 (1968)
33. I. Dzialoshinski, Phys. and Chem. Solids 4, 241 (1958); T. Moriya, Phys. Rev. 120, 91 (1960)
34a. E.O. Kane: Semiconductos and Semimetals, Physics of III-V Compounds, Vol. 1 (Academic Press, New York 1966) pp. 75-100
34b. L.M. Roth, B. Lax, S. Zwerdling, Phys. Rev. 114, 90 (1959)
34. Y. Yafet: In Solid State Physics, Vol. 14, ed. by F. Seitz, D. Turnbull (Academic Press, New York, 1943) p. 93

## Chapter 3

36. See, for example, K. Huang, "Statistical Mechanics", 2nd Edn. (Wiley, New York 1987)
37. J.H. Van Vleck: The Theory of Electric and Magnetic Susceptibilities (Oxford University Press, London 1932) p. 276
38. J.S. Griffith: The Theory of Transition-Metal Ions (Cambridge University Press, Cambridge 1961) pp. 437-439
39. M. Tinkham: Group Theory and Quantum Mechanics (McGraw-Hill, New York 1964) p. 132, Eq. (5.69)
40. L.D. Landau, Z. Phys. 64, 629 (1930) [English transl.: In Collected Papers of L.D. Landau, ed. by D. ter Haar (Gordon and Breach, New York (1965)]
41. R. Peierls, Z. Phys. 80, 763 (1933); 81, 186 (1933)
42. A.H. Wilson, Proc. Cambridge Philos. Soc. 49, 292 (1953)
43. E.H. Sondheimer, A.H. Wilson, Proc. R. Soc. London A210, 173 (1951)
44. J. Bardeen: In Handbuch der Physik, Vol. 15, Low Temperature Physics II, ed. by S. Flügge (Springer, Berlin Göttingen Heidelberg 1956) p. 305
45. H. Fukuyana, Phys. Lett. A 32, 111 (1970)
46. R. Kubo, Y. Obata, J. Phys. Soc. Jpn. 11, 547 (1956)
47. W.J. de Haas, P.M. van Alphen, Proc. Amsterdam Acad. 33, 1106 (1936)
48. J.M. Ziman: "Principles of the Theory of Solids". (Cambridge Univ. Press, Cambridge 1964) p. 275
49. K.V. Klitzing, G. Dorda, M. Pepper, Phys. Rev. Lett. 45, 494 (1981)
50. D.C. Tsui, A.C. Gossard, Appl. Phys. Lett. 38, 550 (1981)
51. R.E. Prange, Phys. Rev. B 23, 4802 (1981)
52. D.C. Tsui, S.J. Allen, Phys. Rev. B 24, 4082 (1981)
53. R.B. Laughlin, Phys. Rev. B 23, 5632 (1981)
54. D.C. Tsui, H.L. Stormer, A.C. Gossard, Phys. Rev. Lett. 48, 1559 (1982)
55. R.B. Laughlin, Phys. Rev. Lett. 50, 1395 (1983)
56. "Landolt-Börnstein Zahlenwerte und Funktionen aus Physik, Chemie, Astronomie, Geophysik und Technik". 6th edn., Vol. 2, Part 9 Magnetic Properties I (Springer, Berlin Heidelberg New York 1962)
57. C.J. Krissman, H.B. Callen, Phys. Rev. 94, 837 (1954)
58. R.M. Bozorth, H.J.W. Williams, D.E. Walsh, Phys. Rev. 103, 572 (1956)
59. S. Foner, Rev. Sci. Instrum. 30, 548 (1959); S. Foner, E.J. McNiff, Jr., Rev. Sci. Instrum. 39, 171 (1968)
60. F.R. Kim, W.P. Wolf, J. Sci. Intrum. 34, 64 (1957)
61. R.T. Schumacher, C.P. Slichter, Phys. Rev. 101, 58 (1956)
62. A.M. Clogston, V. Jaccarino, Y. Yafet, Phys. Rev. A134, 1650 (1964)
63. J. Friedel, Nuovo Cimento Suppl. 2, 287 (1958)
64. A. Clogston, B. Matthias, M. Peter, H. Williams, E. Corenzwit, R. Sherwood, Phys. Rev 125, 541 (1962)
65. P.W. Anderson, Phys. Rev. 124, 41 (1961)
66. In alkali-metal hosts: Phys. Rev. Lett. 57, 388 (1986); in sp-band hosts: Phys. Rev. Lett. 61, 2129 (1988); in noble- and transition-metal hosts: Phys. Rev. Lett. 62, 316 (1989)
67. P.A. Wolff, Phys. Rev. 124, 1030 (1961)

68a. G.T. Rado, H. Suhl (Eds.): "Magnetism", Vol. V (Academic Press, New York 1973)

68b. G. Grüner, A. Zawadowski, Rep. Prog. Phys. 37, 1497 (1974); Prog. Low Temp. Phys. B 7, 591 (1978)
69. J.R. Schrieffer, P.A. Wolff, Phys. Rev. 149, 491 (1966)
70. J. Kondo, Prog. Theor. Phys. 32, 37 (1964)
71. N. Andre, Phys. Rev. Lett. 45, 379 (1980)
72. P.B. Wiegmann, J. Phys. C 14, 1463 (1981)
73. K. Yosida, A. Yoshimori: In "Magnetism", Vol. V, ed. by G.T. Rado, H. Suhl (Academic Press, New York 1973)
74. P.W. Anderson, Phys. Rev. 164, 352 (1967)
75. C. Lacroix, J. Phys. F11, 2389 (1981)

## Chapter 4

76. J.S. Smart: Effective Field Theories of Magnetism (Saunders, Philadelphia 1966)

77a. L.D. Landau, E.M. Lifshitz: Statistical Physics (Pergamon, Oxford 1958) Sect. 149
77b. E. Lieb and D. Mattis, Phys. Rev. 125, 164 (1962)
77c. See, for example, R. Crook et al. Science 312, 1359 (2006)
78. R.J. Elliott (Ed.): Magnetic Properties of Rare-Earth Metals (Plenum, New York 1972)
79. A. Yoshimori, J. Phys. Soc. Jpn. 14, 807 (1959)
80. G. Low, Proc. Phys. Soc. 82, 992 (1963)
81. S. Geller, J.P. Remeika, R.C. Sherwood, H.J. Williams, G.P. Espinosa, Phys. Rev. 137, 1034 (1965)
82. S.F. Andrews, P.W. Anderson, J. Phys. F 5, 965 (1975)
83. C.A.M. Mulder, A.J. van Duyneveldt, J.A. Mydosh, Phys. Rev. B 23, 1384 (1981)
84. R.V. Chamberlin, M. Hardiman, R. Orbach, J. Appl. Phys. 52, 1771 (1981)
85. R.B. Griffiths, Phys. Rev. Lett. 24, 715 (1970)
86. K. Huang: Statistical Mechanics 2nd Edn. (Wiley, New York 1987)
87. P. Pfeuty, G. Toulouse: Introduction to the Renormalization Group and to Critical Phenomena (Wiley, New York 1977)
88. M. Fisher, Rev. Mod. Phys. 46, 597 (1974)
89. N. Mermin, H. Wagner, Phys. Rev. Lett. 17, 1133 (1966)
90. J. Kötzler, W. Scheithe, K. Knorr, W.B. Yelon, J. Phys. C 9, 1291 (1974)
91. J.C. Norvell, W.P. Wolf, L.M. Corliss, J.M. Hastings, R. Nathans, Phys. Rev. 186, 557 (1969)
92. R.J. Birgeneau, J. Skalyo, G. Shirane, J. Appl. Phys. 41, 1303 (1970)
93. P. Heller, Phys. Rev. 146, 403 (1966)
94. A. Kastner, R.J. Birgeneau, G. Shirane, Y. Endoh, Rev. Mod. Phys. 70, 897 (1998)
95. S. Chakravarty, B.I. Halperin, D.R. Nelson, Phys. Rev. Lett. 60, 1057 (1988)
96. B. Keimer, N. Belk, R.J. Birgeneau, A. Cassanho, C.Y. Chen, M. Greven, M.A. Kastner, A. Aharony, Y. Endoh, R.W. Erwin, G. Shirane, Phys. Rev. B 46, 14034 (1992)
97. V.L. Berezinskii, Sov. Phys. JETP 32, 493 (1970)
98. J.M. Kosterlitz, D.J. Thouless, J. Phys. C6, 1181 (1973)
99. E.C. Stoner, E.P. Wohlfarth: Phil Trans. R. Soc. Lond., Ser. A, 240, 599 (1948)
100. M.P. Sharrock, J. Appl. Phys. 76(10), 6413 (1994)
101. S.M. Stinnett, W.D. Doyle, P.J. Flanders, C. Dawson, IEEE Trans. Magn. 34, 1828 (1998)
102. See, for example, R. Street, S.D. Brown, J. Appl. Phys. 76, 6386 (1994)
103. S.M. Stinnett, W.D. Doyle, O. Koshkina, L. Zhang, J. Appl. Phys. 85, 5009 (1999)

## Chapter 5

104. H. Kanazawa, N. Matsudaira, Prog. Theor. Phys. 23, 433 (1960)
105. P. Weiss, R. Forrer, Ann. Phys. 5, 153 (1926)
106. L.D. Landau, Sov. Phys. JETP 2, 920 (1956); 5, 101 (1957)
107. V.P. Silin, Sov. Phys. JETP 6, 945 (1958)
108. C. Herring: In Magnetism, Vol. 4, ed. by G.T. Rado, H. Suhl; (Academic Press, New York 1966)
109. P. Fulde, V. Zevin, G. Zwicknagl, Z. Phys. B 92, 133 (1993)
110. J.C. Slater, Phys. Rev. 49, 537 (1936)
111. E.C. Stoner, Proc. R. Soc. London A 165, 372 (1938)
112. P.A. Wolff, Phys. Rev. 120, 814 (1960)
113. A.W. Overhauser, Phys. Rev. 128, 1437 (1962)
114. D. Wohlleben, Phys. Rev. Lett. 21, 1343 (1968)
115. J.C. Slater, Phys. Rev. 81, 385 (1951)
116. W. Kohn, L.J. Sham, Phys. Rev. A 140, 1133 (1965)
117. T.M. Hattox, J.B. Conklin, Jr., J.C. Slater, S.B. Trickey, J. Phys. Chem. Solids 34, 1627 (1973)
118. P. Hohenberg, W. Kohn, Phys. Rev. B 136, 864 (1964)
119. P. Thiry, D. Chandesris, J. Lecante, C. Guillot, R. Pinchaux, Y. Pétroff, Phys. Rev. Lett. 43, 82 (1979)
120. F.J. Himpsel, P. Heimann, D.E. Eastman, J. Appl. Phys. 52, 1658 (1981)
121. J.C. Slater, J. Appl. Phys. 8, 385 (1937)
122. L. Pauling, Phys. Rev. 54, 899 (1938)
123. H.A. Mook, Phys. Rev. 148, 495 (1966)
124. R.M. Moon, Phys. Rev. A 136, 195 (1964)
125. J. Hubbard, J. Appl. Phys. 52, 1654 (1981)
126. M.V. You, V. Heine, A.J. Holden, P.J. Lin-Chung, Phys. Rev. Lett. 44, 1282 (1980)
127. J. Hubbard, Proc. R. Soc. London A 276, 238 (1963); Ibid., 277, 237; Ibid., 281, 401

## Chapter 6

128. F. Bloch, Phys. Rev. 70, 460 (1946)

129a. F. Bloch, W.W. Hansen, M. Packard, Phys. Rev. 70, 474 (1946)
129b. N. Bloembergen, Phys. Rev. 78, 572 (1950).
129c. H.W. Schumacher, C. Chappert, R.C. Sousa, P.P. Freitas, J.M. Itat, Phys. Rev. Lett. 90, 017204 (2003)
130. J.H. Van Vleck, Phys. Rev. 74, 1168 (1948)
131. R. Kubo, K. Tomita, J. Phys. Soc. Jpn. 9, 888 (1954)
132. See G.E. Pake, "Paramagnetic Resonance". (W.A. Benjamin, New York 1962) p. 142
133. A. Abragam: The Principles of Nuclear Magnetism (Oxford University Press, New York 1961) Chap. 10
134. R.E. Dietz, F.R. Merritt, R. Dingle, D. Hone, G.G. Silbernagel, P.M. Richards, Phys. Rev. 26, 1186 (1971)
135. T. Moriya, Prog. Theor. Phys. 16, 23, 641 (1956)
136. C.P. Slichter: Principles of Magnetic Resonance. 2nd edn. Springer Series in Solid-State Sciences, Vol. 1 (Springer, Berlin Heidelberg New York 1980)
137. E. Hahn, Phys. Rev. 80, 580 (1950)
138. N. Bloembergen, E.M. Purcell, R.V. Pound, Phys. Rev. 73, 679 (1948)
139. V.L. Safonov, H.N. Bertram, Phys. Rev. B 71, 224402 (2005)

## Chapter 7

140. S. Doniach, Proc. Phys. Soc. London 91, 86 (1967)
141. N.F. Berk, J.R. Schrieffer, Phys. Rev. Lett. 17, 433 (1966); S. Doniach, S. Engelsberg, Phys. Rev. Lett. 17, 750 (1966)
142. N.D. Mermin, Phys. Rev. B1, 2362 (1970)
143. V.P. Silin, Sov. Phys. JETP 8, 870 (1959)
144. P.M. Platzman, P.A. Wolff, Phys. Rev. Lett. 18, 280 (1967)
145. F.J. Dyson, Phys. Rev. 98, 349 (1955); G. Feher, A.F. Kip, Phys. Rev. 98, 337 (1955)
146. S. Schultz, G. Dunifer, Phys. Rev. Lett. 18, 283 (1967)
147. H. Hasegawa, Prog. Theor. Phys. 21, 483 (1959)
148. S. Schultz, M.R. Shanabarger, P.M. Platzman, Phys. Rev. Lett. 19, 749 (1967)
149. P.S. Pershan, J. Appl. Phys. 38, 1482 (1967)

## Chapter 8

150. F. Keffer: In Handbuch der Physik, Vol. 18, Part 2, Ferromagnetism, ed. by S. Flügge (Springer, Berlin Heidelberg New York 1966)
151. R.M. White, M. Sparks, I. Ortenberger, Phys. Rev. A 139, 450 (1965)
152. C. Kittel, Phys. Rev. 73, 155 (1948)
153. N. Zagury, S. Rezende, Phys. Rev. B 4, 201 (1971)
154. L.R. Walker, J. Applied Phys. 29, 318 (1958)
155. R.L. White, I.H. Solt, Jr., Phys. Rev. 104, 56 (1956)
156. J.F. Dillon, Jr., J. Appl. Phys. 31, 1605 (1960)
157. R.W. Damon, J.R. Eshbach, J. Phys. Chem. Solids 19, 308 (1981)
158. M. Chen, M.A. Tsankov, J. Nash, C. Patton, Phys. Rev. B 49, 12773 (1994)
159. F. Bloch, Z. Phys. 61, 206 (1930)
160. G. Low, Proc. Phys. Soc. London 82, 992 (1963)
161. F.J. Dyson, Phys. Rev. 102, 1217 (1956)
162. M. Sparks: "Ferromagnetic Relaxation Theory" (McGraw-Hill, New York 1964)
163. M. Sparks, R. Loudon, C. Kittel, Phys. Rev. 122, 791 (1961)
164. N. Bloembergen, R.W. Damon, Phys. Rev. 85, 699 (1952)
165. H. Suhl, Proc. IRE 44, 1270 (1957)
166. G. Gibson, C. Jeffries, Phys. Rev. A 19, 811 (1984)
167. S.M. Rezende, F.M. de Aguiar, Proc. IEEE 78, 893 (1990)
168. S.J. Allen, R. Loudon, P.L. Richards, Phys. Rev. Lett. 16, 463 (1966)
169. R.L. Greene, D.D. Sell, W.M. Yen, A.L. Schawlow, R.M. White, Phys. Rev. Lett. 15, 656 (1965); D.D. Sell, R.L. Greene, R.M. White, Phys. Rev. 158, 489 (1967)
170. P.A. Fleury, R. Loudon, Phys. Rev. 166, 514 (1968)
171. P.M. Richards, unpublished
172. R. Kubo, J. Phys. Soc. Jpn. 12, 570 (1957)
173. P.M. Richards, P.K. Leichner, Phys. Rev. B7, 453 (1973)
174. J.C. Burgiel, M.W.P. Strandberg, J. Appl. Physics 35, 852 (1964)
175. L.D. Landau, E.M. Lifshitz, Phys. Z. Sowjet 8, 153 (1935). [English translation: L.D. Landau, Collected Papers, ed. by D. ter Haar (Gordon and Breach, New York 19676) p. 101
176. W.F. Brown, Phys. Rev. 58, 736 (1940)
177. J.-G. Zhu, Y. Sheng, "Spin Dynamics in Confined Magnetic Structure I", ed. by B. Hillebrands, K. Ounadjela (Springer, Berlin Heidelberg New York 2002) pp. 289-325
178. G. Binning, C.F. Quate, C. Gerber, Phys. Rev. Lett. 56, 930 (1986)
179. C. Mao, Ph.D. Thesis, Carnegie Mellon University (1999)
180. C.Y. Mao, J.-G. Zhu, R.M. White, J. Appl. Phys. 87, 5416 (2000)
181. See T.L. Gilbert, IEEE Trans. Mag. 40, 3443 (2004)
182. T. Izuyama, E.J. Kim, R. Kubo: J. Phys. Soc. Jpn. 18, 1025 (1963)
183. C. Herring: In "Magnetism", ed. by G.T. Rado, H. Suhl (Academic Press, New York 1966) Vol. IV, Sect. XIV,3
184. G. Barnea, G. Horwitz, J. Phys. C6, 738 (1973)
185. R. Lowde, Proc. R. Soc. London A235, 305 (1956)
186. J. Lynn, Phys. Rev. B 11, 2624 (1975)
187. Mook, J. Lynn, Nicklow, Phys. Rev. Lett. 30, 556 (1973)
188. X. Tao, D.P. Landau, T.C. Schulthess, G.M. Stocks, Phys. Rev. Lett. 95, 08707 (2005)
189. M.H. Seavey, P.E. Tannenwald, Phys. Rev. Lett. 1, 168 (1958)
190. J.R. Sandercock, W. Wettling, IEEE Trans. M-14, 442 (1978)

## Chapter 9

191. W.H. Meiklejohn, C.P. Bean, Phys. Rev. 102, 1413 (1956)
192. A.P. Malozemoff, J. Appl. Phys. 63, 3874 (1988)
193. Imry, Ma, Phys. Rev. Lett. 35, 1399 (1975)
194. S.M. Rezende, A. Azevedo, M.A. Lucena, F.M. de Aguir, Phys. Rev. B 63, 214418 (2001)
195. C.F. Majkrzak, J.W. Cable, J. Kwo, M. Hong, D.B. McWhan, Y. Yafet, J.V. Waszcczak, C. Vettier, Phys. Rev. Lett. 56, 2700 (1986)
196. P. Grünberg, R. Schreiber, Y. Pang, M.B. Brodsky, H. Sowers, Phys. Rev. Lett. 57, 2442 (1986)
197. H. Fröhlich, F.R.N. Nabarro, Proc. R. Soc. London A175, 382 (1940)
198. M.A. Ruderman, C. Kittel, Phys. Rev. 96, 99 (1954)
199. C. Zener, Phys. Rev. 81, 440 (1951)
200. T. Kasuya, Prog. Theor. Phys. 16, 45, 58 (1956)
201. K. Yosida, Phys. Rev. 106, 893 (1957)
202. J.B. Boyce, C.P. Slichter, Phys. Rev. B B3, 379 (1976)
203. P. Bruno, Phys. Rev. 52, 411 (1995)
204. J. Unquris, R. Celotta, D. Pierce, J. Appl. Phys. 75, 6437 (1994); Phys. Rev. Lett 67, 140 (1991)
205. M. Stiles, Phys. Rev. B 48, 7238 (1993)
206. M.N. Baibich, J.M. Broto, A. Fert, F. Nguyen Van Dau, F. Petroff, P. Etienne, P. Creuzet, A. Friederich, J. Chazelas, Phys. Rev. Lett. 61, 2472 (1988)
207. E.Y. Tsymbal, D.G. Pettifor, Solid State Physics 56, 113 (2001)
208. G. Mahan: "Many-Particle Physics", 3rd Edn. (Kluwer Academic/Plenum, New York 2000) pp. 163-165
209. W.H. Butler, X.-G. Zhang, D.M.C. Nicholson, J.M. MacLaren, Phys. Rev. B 52, 13399 (1995)
210. R.E. Camley, J. Barnaś, Phys. Rev. Lett. 63, 664 (1989)
211. B.L. Johnson, R.E. Cmley, Phys. Rev. 44, 9997 (1991)
212. R.E. Camley, R.L. Stamps, J. Phys.: Condensed Matter 5, 3727 (1993)
213. H.E. Camblong, P.M. Levy, Phys. Rev. Lett. 69, 2835 (1992)
214. B. Dieny, Europhys. Lett. 17, 261 (1992)
215. Bardeen, Phys. Rev. Lett. 6, 57 (1961)
216. M. Julliere, Phys. Lett. A 54, 225 (1975)
217. R. Meservey, P.M. Tedrow, Phys. Rep. 238, 174 (1994)
218. R.J. Soulen et al., Science 282, 85 (1998)
219. D.J. Monsma and S.S.P. Parkin, Appl. Phys. Lett. 77, 720 (2000); J.S. Moodera, J. Nassar, and G. Mathon, Ann. Rev. Mater. Sci. 29, 381 (1999)
220. J.H. Park et al., Nature 392, 794 (1998); Y.S. Dedkov et al., Phys. Rev. B 65, 064417-1 (2002)
221. J.C. Slonezewski, Phys. Rev. G 39, 6995 (1989)
222. W.H. Butler, X.-G. Zhang, T.C. Schulthess, J.M. MacLaren, Phys. Rev. B 63 054416 (2001); J. Mathon, A. Umerski, Phys. Rev. B 63 220403(R) (2001)
223. S.S. Parkin, C. Kaiser, A. Panchula, P.M. Rice, B. Hughes, M. Samant, S.-H. Yang, Nature Mater. 3, 862 (2004)
224. J.C. Slonczewski, J. Mag. Mag. Mat. 159, 67 (1996)
225. L. Berger, Phys. Rev. B54, 9353 (1996)
226. M. Tsoi, A.G.M. Jansen, J. Bass, W.-C. Chiang, M. Seck, V. Tsoi, P. Wyder, Phys. Rev. Lett. 980, 4281 (1998)
227. J.Z. Sun, Mag. Mag. Mat. 202, 157 (1999)
228. J.A. Katine, F.J. Albert, R.A. Buhrman, E.B. Meyers, D.C. Ralph, Phys. Rev. Lett. 84, 3149 (2000)
229. M.D. Stiles, A. Zangwill, J. Appl. Phys. 91, 6812 (2002)
230. J.Z. Sun, Phys. Rev. B 62, 570 (2000)
231. S.M. Rezende, F.M. de Aguiar, A. Azevedo, Phys. Rev. Lett. 94, 037202 (2005)
232. X. Zhu, J.-G. Shu, R.M. White, J. Appl. Phys. 95, 6630 (2004); J.-G. Zhu, X. Zhu, IEEE Trans. Mag. 40, 182 (2004)
233. See, for example, S. Zhang, Phys. Rev. B 51, 3632 (1995)
234. J.E. Hirsch, Phys. Rev. Lett. 83, 1834 (1999)
235. S. Zhang, Phys. Rev. Lett. 85, 393 (2000)
236. Y.K. Kato. R.C. Myers, A.C. Gossard, D.D. Awschalom, Science 306, 1910 (2004)
237. P.-G. deGennes, J. Phys. Radium 23, 630 (1962)

## Chapter 10

238. P.A. Egelstaff (Ed.): Thermal Neutron Scattering (Academic Press, New York 1965)
239. W. Marshall, S.W. Lovesey: Theory of Thermal Neutron Scattering (Oxford University Press, Oxford 1971)
240. S.W. Lovesey, T. Springer (Eds.): Dynamics of Solids and Liquids by Neutron Scattering. Topics in Current Physics, Vol. 3 (Springer, Berlin Heidelberg New York 1977)
241. R.E. Rundle, C.G. Shull, E.O. Wollen, Acta Crystallogr. 5, 22 (1952)
242. N.W. Ashcroft, N.D. Mermin: Solid State Physics (Holt, Rinehort, and Winston, New York 1974) Appendix L
243. R.M. Moon, T. Riste, W.C. Koehler, Phys. Rev. 181, 920 (1969)
244. R.A. Erickson, Phys. Rev. 90, 779 (1953)
245. T. Izuyama, D. Kim, R. Kubo, J. Phys. Soc. Jpn. 18, 1025 (1963)
246. C.C. Becerra, Y. Shapira, N.F. Oliveira, T.S. Chang, Phys. Rev. Lett. 44, 1692 (1980)
247. R.M. Moon, J.W. Cable, Y. Shapira, J. Appl. Phys. 52, 2025 (1981)
248. C.G. Shull, Y. Yamada, J. Phys. Soc. Jpn. 17, Suppl. B-III, 1 (1962)
249. C.G. Shull, H.A. Mook, Phys. Rev. Lett. 16, 184 (1966)
250. G.C. Low, A. Okazaki, R.W.H. Stevenson, K.C. Tuberfield, J. Appl. Phys. 35, 998 (1964)
251. H. Möller, J. Houmann, A. Mackintosh, J. Appl. Phys. 39, 807 (1968)
252. D. Cribier, T. Jacrot, G. Parette, J. Phys. Soc. Jpn. 17, Suppl. B-III 67 (1962)
253. R.D. Lowde, C.G. Windsor, Adv. Phys. 19, 813 (1970)
254. C.G. Shull, M.K. Wilkinson, Phys. Rev. 97, 304 (1955)
255. W. Marshall, J. Phys. C1, 88 (1968)
256. R.A. Medina, J.W. Cable, Phys. Rev. B 15, 1539 (1977)
257. Y. Tokura, Y. Tomioka, J. Mag. Mag. Mat. 200, 1 (1999)
258. D.C. Worledge, Ph.D. Thesis, Stanford University (2000)
259. J.W. Lynn, C.P. Adams, Y.M. Mukovskii, A.A. Arsenov, D.A. Shulyatev, J. Appl. Phys. 89, 6846 (2001)
260. M.B. Salamon, M. Jaime, Rev. Mod. Phys. 73, 583 (2001)
261. A. Oosawa, M. Ishii, H. Tanaka, J. Phys. Condens. Matter 11, 265 (1999)
262. N. Cavadini et al., Phys. Rev. B 63, 172414 (2001)
263. O. Nohadani, et al., Phys. Rev. B 69, 220402 (2004)
264. M. Matsumoto, B. Normand, T.M. Rice, M. Sigrist, Phys. Rev. Lett. 89, 077203 (2002)
265. T. Nikuni, M. Oshikawa, A. Oosawa, H. Tanaka, Phys. Rev. Lett. 84, 5868 (2000)
266. For a short summary of Bose condensation see A.L. Fetter, J.D. Walecka, "Quantum Theory of Many-Particle Systems". (McGraw-Hill, New York, 1971) Chap. 1
267. C. Rüegg, N. Cavadini, A. Furrer, K. Krämer, H.U. Güdel, P. Vorderwisch, H. Mutka, Appl. Phys. A 74 [suppl.] S840 (2002)
268. L. Landau, E.M. Lifshitz: Statistical Physics, 3rd edn., Sect. 71
269. C. Rüegg, et al., Nature (London) 423, 62 (2003)
270. V.N. Glazkov, A.I. Smirnov, H. Tanaka, A. Oosawa, Phys. Rev. B 69, 184410 (2004)
271. M. Matsumoto, B. Normand, T.M. Rice, M. Sigrist, Phys. Rev. B 69, 054423 (2004)
272. C. Rüegg, et al., Phys. Rev. Lett. 93, 257201 (2004)
273. S.E. Sebastion, P.A. Sharma, M. Jaime, N. Harrison, V. Correa, L. Balicas, N. Kawashima, C.D. Batista, I.R. Fisher, Phys. Rev. B 72, 100404R (2005)
274. T. Radu et al., Phys. Rev. Lett. 95, 127202 (2005)

## Index

Abrikosov-Suhl resonance, 129
adiabatic rapid passage, 201
Ag, 111
Ag:Mn, 145
$\mathrm{Al}_{2} \mathrm{O}_{3}, 300$
$\mathrm{Al}-\mathrm{Al}_{2} \mathrm{O}_{3}-\mathrm{Ni}, 303$
alloys, 185
aluminum, 118, 123
Anderson Hamiltonian, 120
Andreev reflection, 304
anisotropic exchange, 74
anisotropic magnetoresistance, 292
anisotropy, 71, 146
anisotropy constant, 146
anomalous Hall effect, 310
antiferromagnetism, 137
antisymmetric exchange, 74
$\mathrm{Au}, 111,124$
$\mathrm{BaCuSiO}_{6}, 344$
biquadratic exchange, 284
bismuth, 97
Bitter magnet, 115
Bloch $T^{3 / 2}$ law, 254
Bloch equations, 197
Bohr magneton, 36
Boltzmann equation, 296
Bose-Einstein condensation, 342

## BPP, 216

Bragg scattering, 318
Brillouin function, 91, 146
Brillouin scattering, 266
broken symmetry, 153, 237
$\left(\mathrm{CH}_{3}\right)_{4} \mathrm{NMnCl}_{3}, 210$
$\mathrm{CaMnO}_{3}, 59$
canonical distribution, 86
canonical ensemble, 11
causality, 196
$\mathrm{CeCu}_{2} \mathrm{Si}_{2}, 176$
chaos, 259, 310
character table, 48
chemical potential, 100
chromium, 182
$\mathrm{Co}_{50} \mathrm{Fe}_{50}, 304$
Co/Cr/Co, 293
$\mathrm{Co} / \mathrm{Cu}$ multilayer, 310
cobalt(Co), 112, 186, 282, 304
$\mathrm{CoCl}_{2} \cdot 2 \mathrm{H}_{2} \mathrm{O}, 72$
$\mathrm{CoF}_{2}, 58$
CoFe, 202
coherent magnon state, 248
coherent scattering, 318
colossal magnetoresistance, 338
compensation temperature, 143
conduction-electron spin resonance, 227, 228
contact hyperfine interaction, 43
CoO, 281, 284
copper(Cu), 111, 123, 125, 185
correlation, 175
correlation function, 18
correlation length, 150
$\mathrm{CrBr}_{3}, 269$
critical exponents, 153
critical scattering, 335
$\mathrm{CrO}_{2}, 166$
crystal field theory, 44
Cs, 124
$\mathrm{Cs}_{2} \mathrm{CuCl}_{4}, 344$
$\mathrm{Cu} \mathrm{Mn}, 234$
Cu:Mn, 145
CuFe, 287
Curie temperature, 136
Curie's law, 91
cyclotron frequency, 99, 227
damping, 273
de Haas-van Alphen, 292
Debye-Waller factor, 322
delta function, 198, 326
demagnetization factor, 245
demagnetization field, 160
density matrix, 11
de Haas-van Alphen effect, 98
diagmagnetic susceptibility, 89
diamagnetism, 88
differential scattering cross section, 316
diffusion equation, 210
Dirac equation, 33
double exchange, 65
dynamic coercivity, 162
dynamic form factor, 31
$\mathrm{DyPO}_{4}, 148$
Dysonian lineshape, 229
dysprosium aluminum garnet, 154
Dzialoshinski-Moriya exchange, 74
Dzyaloshinski-Moriya interaction, 156
europium oxide(EuO), 62, 143, 255
EuS, 62
EuSe, 62
EuTe, 62
exchange, 51
exchange bias, 281
exchange enhancement, 173
exchange hole, 182
exchange narrowing, 206, 207, 257
exchange splitting, 182
exchange stiffness, 153
exchangestriction, 163

Faraday balance, 113
Faraday effect, 235
$\mathrm{Fe}_{3} \mathrm{O}_{4}, 284,304$
$\mathrm{Fe}-\mathrm{Au}-\mathrm{Fe}, 286$
$\mathrm{Fe}-\mathrm{Cr}-\mathrm{Fe}, 286$
$\mathrm{Fe} / \mathrm{Cr} / \mathrm{Fe}, 293$
$\mathrm{Fe} / \mathrm{Ge} / \mathrm{Co}, 302$
$\mathrm{FeCl}_{2}, 148$
$\mathrm{FeF}_{2}, 58$
FeMn, 300
FeO, 138
Fermi liquid theory, 169, 223
ferrimagnetism, 140
ferromagnetism, 136
fixed point, 261
fluctuation-dissipation theorem, 15, 203, 217, 219
fractional quantum Hall effect, 106
Friedel sum rule, 117
frustration, 144
$g$ tensor, 68
Ga-YIG, 260
GaAs, 78, 106, 137
gadolinium iron garnet, 143
gallium arsenide, 104
Gaussian, 204
Gaussian lineshape function, 200
Gd-Co, 142
$\mathrm{GdCl}_{3}, 154$
generalized susceptibility, 12
GMR, 292
gold, 291
Goldstone modes, 238
grand canonical distribution, 100
Green's function, 18, 121, 152, 195, 198
group theory, 46

Hamiltonian, 7
Hartree-Fock approximation, 120
heavy fermion, 176
Heisenberg exchange, 58
helimagnetism, 138
Hf, 111
Holstein-Primakoff, 241
Hubbard model, 187
Hund's rule, 52
hydrogen molecule, 53
hyperfine field, 41
hysteresis loop, 159
incoherent scattering, 318
inhomogeneous broadening, 201
InSb, 78, 79
Ir, 124
iron(Fe), 101, 111, 112, 118, 119, 123, $131,146,266,278,304,332,333$
irreducible representation, 48
irreducible tensor operator, 39
Ising model, 149
Jahn-Teller distortion, 337
Johnson noise, 20
K, 124
$\mathrm{K}_{2} \mathrm{NiF}_{4}, 154$
Kittel frequency, 247
Knight shift, 114
Kondo effect, 124
Kondo lattices, 176
Kondo temperature, 129
Korringa relaxation, 232
Kosterlitz-Thouless temperature, 159
Kramers doublet, 77
Kramers-Kronig relations, 14
Kubo Formula, 295
$\mathrm{La}_{0} .7 \mathrm{Sr}_{0.3} \mathrm{CrO}_{3}, 304$
$\mathrm{La}_{2} \mathrm{CuO}_{4}, 156$
$\mathrm{La}_{z-x} \mathrm{Sr}_{x} \mathrm{CuO}_{4}, 175$
$\mathrm{LaMnO}_{3}, 337$
Landé $g$ value, 75
Landau levels, 102, 104
Landau susceptibility, 95
Landau-Lifshitz-Gilbert equation, 308
Langevin susceptibility, 90
Lifshitz point, 330
ligand field theory, 44
light scattering, 264
lithium, 114
$\mathrm{LiV}_{2} \mathrm{O}_{4}, 176$
local density approximation, 184
London penetration length, 98
Lorentz field, 245
Lorentzian, 204
Lorentzian lineshape, 200
Luttinger liquid, 176
magnetic cooling, 131
magnetic energy, 5
magnetic force microscope, 270
magnetic form factor, 327
magnetic moment, 1, 2, 4, 9
magnetic point group, 136
magnetic susceptibility, 1
magnetic viscosity, 165
magnetization, 1,7
magnetostatic modes, 249
magnetostriction, 163
magnetostrictive effect, 136
magnons, 239
mean-field approximation, 134
metamagnetism, 148
method of moments, 202
MgO, 306
microcanonical ensemble, 11
micromagnetics, 269
Miss van Leeuwen's theorem, 9, 94
Mn, 112
$\mathrm{MnF}_{2}, 58,262,269,329,335$
MnO, 138
MnP, 331
Mo, 124
molecular magnets, 62
Mossbauer effect, 80
Néel temperature, 137
$\mathrm{Nd}_{2} \mathrm{CuO}_{4}, 176$
$\mathrm{Ni}_{80} \mathrm{Fe}_{20}, 304$
nickel(Ni), 111, 112, 146, 170, 185, 186, 278, 304
NiO, 138, 300
noble metals, 123
noise power, 217
Nyquist theorem, 20
Onsager reaction field, 152
Onsager relation, 20
operator equivalent, 37, 45
orange peel coupling, 286
order parameter, 153
Os, 124
palladium, 109, 180
parallel pumping, 259
paramagnons, 221
partition function, 8
Pauli susceptibility, 108, 310
Pd, 124

Peierls susceplitiy, 97
pendulum galvanometer, 112
permalloy, 271, 278
perovskites, 61
phonons, 320
plasma frequency, 98
platinum(Pt), 115, 124
polaron, 339
precessional switching, 202
quadrupole term, 37
quantized Hall conductance, 102
quantum phase transitions, 341
quasiparticle, 171
quenching, 49
Raman scattering, 266
random-phase approximation, 134, 239
rare-earth, 139
Rb, 124
Re, 124
relaxation function, 202, 209
relaxation-function method, 206
response function, 18
RKKY interaction, 286, 314
s-d exchange interaction, 67, 307
scaling, 154
scattering amplitude, 116
scattering length, 317
second quantization, 21
second-order phase transitions, 153
SEMPA, 292
Sharrock's law, 164
short-range order, 149
side jump, 311
silicon, 70, 104
skew scattering, 311
sodium, 114, 231
solitons, 250
spallation, 315
spherical harmonics, 37
spin accumulation, 307, 312
spin diffusion, 210
spin echoes, 211
spin filtering effect, 300
spin fluctuation, 179, 222
spin glasses, 143
spin Hall effect, 310
spin Hamiltonian, 67
spin polarization, 304
spin transfer, 306
spin valve, 295
spin-density functional, 183
spin-density waves, 180
spin-dependent tunneling, 303
spin-lattice relaxation, 214
spin-orbit, 34
spin-wave, 239
spin-wave sidebands, 263
spinor, 38
Stokes line, 266
Stoner criterion, 180
Stoner excitations, 275
Stoner model, 177
Stoner-Wohlfarth model, 159
strange attractor, 262
structure factor, 319
Suhl instabilities, 258
superconductor, 98, 108
superexchange, 58
superparamagnetism, 164
synthetic antiferromagnet, 294

Ta, 124
Tb-Fe, 142
thermal conductivity, 279
$\mathrm{ThH}_{2}, 318$
Ti, 111
Time-of-flight diffraction, 320
$\mathrm{TlCuCl}_{3}, 341,343$
topological defects, 158
transition metals, 109, 110
transition-metal ions, 90
triple-axis spectrometer, 323
tunneling, 300
tunneling Hamiltonian, 300
$\mathrm{UBe}_{13}, 176$
universality, 154
$\mathrm{UPt}_{3}, 176$

Van Vleck susceptibility, 71, 89
vanadium, 183
vibrating-sample magnetometer, 113 vortex, 158

Walker modes, 250
Wannier functions, 56
Wigner-Eckhart theorem, 39, 86
yttrium iron garnet(YIG), 253,
257, 284

Zr, 111
$\mathrm{ZrZn}_{2}, 277$

## Springer Series in

## SOLID-STATE SCIENCES

## Series Editors:

M. Cardona P. Fulde K. von Klitzing R. Merlin H.-J. Queisser H. Störmer

90 Earlier and Recent Aspects of Superconductivity
Editor: J.G. Bednorz and K.A. Müller
91 Electronic Properties and Conjugated Polymers III
Editors: H. Kuzmany, M. Mehring, and S. Roth

92 Physics and Engineering
Applications of Magnetism Editors: Y. Ishikawa and N. Miura

93 Quasicrystals
Editor: T. Fujiwara and T. Ogawa
94 Electronic Conduction in Oxides 2nd Edition By N. Tsuda, K. Nasu, A. Fujimori, and K. Siratori

95 Electronic Materials
A New Era in MaterialsScience
Editors: J.R. Chelikowski and A. Franciosi
96 Electron Liquids 2nd Edition By A. Isihara
97 Localization and Confinement of Electrons in Semiconductors Editors: F. Kuchar, H. Heinrich, and G. Bauer
98 Magnetism and the Electronic Structure of Crystals By V.A. Gubanov, A.I. Liechtenstein, and A.V. Postnikov
99 Electronic Properties of High-T ${ }_{c}$ Superconductors and Related Compounds Editors: H. Kuzmany, M. Mehring, and J. Fink
100 Electron Correlations in Molecules and Solids 3rd Edition By P. Fulde
101 High Magnetic Fields in Semiconductor Physics III Quantum Hall Effect, Transport and Optics By G. Landwehr

101 High Magnetic Fields in Semiconductor Physics III Quantum Hall Effect, Transport and Optics By G. Landwehr
102 Conjugated Conducting Polymers Editor: H. Kiess
103 Molecular Dynamics Simulations Editor: F. Yonezawa

104 Products of Random Matrices in Statistical Physics By A. Crisanti, G. Paladin, and A. Vulpiani

105 Self-Trapped Excitons 2nd Edition By K.S. Song and R.T. Williams
106 Physics of High-Temperature Superconductors Editors: S. Maekawa and M. Sato
107 Electronic Properties of Polymers Orientation and Dimensionality of Conjugated Systems
Editors: H. Kuzmany, M. Mehring, and S. Roth
108 Site Symmetry in Crystals Theory and Applications 2nd Edition
By R.A. Evarestov and V.P. Smirnov
109 Transport Phenomena in Mesoscopic Systems Editors: H. Fukuyama and T. Ando
110 Superlattices
and Other Heterostructures
Symmetry and Optical Phenomena 2nd Edition By E.L. Ivchenko and G.E. Pikus
111 Low-Dimensional Electronic Systems New Concepts
Editors: G. Bauer, F. Kuchar, and H. Heinrich

112 Phonon Scattering in Condensed Matter VII Editors: M. Meissner and R.O. Pohl

## Springer Series in

## SOLID-STATE SCIENCES

Series Editors:
M. Cardona
M. Cardona P. Fulde K. von Klitzing R. Merlin H.-J. Queisser H. Störmer

113 Electronic Properties of High- $\mathrm{T}_{\mathrm{c}}$ Superconductors Editors: H. Kuzmany, M. Mehring, and J. Fink
114 Interatomic Potential and Structural Stability Editors: K. Terakura and H. Akai
115 Ultrafast Spectroscopy of Semiconductors and Semiconductor Nanostructures By J. Shah
116 Electron Spectrum of Gapless Semiconductors By J.M. Tsidilkovski
117 Electronic Properties of Fullerenes Editors: H. Kuzmany, J. Fink, M. Mehring, and S. Roth

118 Correlation Effects in LowDimensional Electron Systems Editors: A. Okiji and N. Kawakami
119 Spectroscopy of Mott Insulators and Correlated Metals Editors: A. Fujimori and Y. Tokura
120 Optical Properties of III-V Semiconductors The Influence of Multi-Valley Band Structures By H. Kalt
121 Elementary Processes in Excitations and Reactions on Solid Surfaces Editors: A. Okiji, H. Kasai, and K. Makoshi
122 Theory of Magnetism By K. Yosida
123 Quantum Kinetics in Transport and Optics of Semiconductors By H. Haug and A.-P. Jauho
124 Relaxations of Excited States and Photo-Induced Structural Phase Transitions Editor: K. Nasu

125 Physics and Chemistry of Transition-Metal Oxides
Editors: H. Fukuyama and N. Nagaosa
126 Physical Properties of Quasicrystals Editor: Z.M. Stadnik
127 Positron Annihilation in Semiconductors Defect Studies By R. Krause-Rehberg and H.S. Leipner
128 Magneto-Optics Editors: S. Sugano and N. Kojima
129 Computational Materials Science From Ab Initio to Monte Carlo Methods. By K. Ohno, K. Esfarjani, and Y. Kawazoe
130 Contact, Adhesion and Rupture of Elastic Solids By D. Maugis
131 Field Theories for Low-Dimensional Condensed Matter Systems Spin Systems and Strongly Correlated Electrons By G. Morandi, P. Sodano, A. Tagliacozzo, and V. Tognetti

132 Vortices in Unconventional Superconductors and Superfluids Editors: R.P. Huebener, N. Schopohl, and G.E. Volovik
133 The Quantum Hall Effect By D. Yoshioka
134 Magnetism in the Solid State By P. Mohn
135 Electrodynamics of Magnetoactive Media By I. Vagner, B.I. Lembrikov, and P. Wyder


[^0]:    Volumes 90-135 are listed at the end of the book.

[^1]:    ${ }^{1}$ The magnetic field $\boldsymbol{H}$ is understood to be the field in vacuum. Strictly speaking, this is the magnetic induction on flux density, $\boldsymbol{B}$. But in vacuum and in cgs units, $\boldsymbol{B}=\boldsymbol{H}$. It has become common practice to denote the field in vacuum as $\boldsymbol{H}$.

[^2]:    ${ }^{1}$ Feher and Kip [145] denote the spin relaxation time as $T_{1}$. In a metal the rapid orbital relaxation $(\tau)$ results in $T_{1} \approx T_{2}$.

[^3]:    ${ }^{1}$ In real devices the design is slightly more complex. The pinned layer has magnetic charge at its edges which produces a demagnetization field which can affect this free layer. To minimize this effet a third magnetic layer is placed next to the pinned layer with a nonmagnetic spacer having a thickness that gives an antiferromagnetic coupling. This third layer is, in turn, pinned by the antiferromagnet. The two antiferromagnetically coupled ferromagnetic layers are called a "synthetic antiferromagnet" (SAF).

